

# SEMANTICS OF PROBABILISTIC PROGRAMS

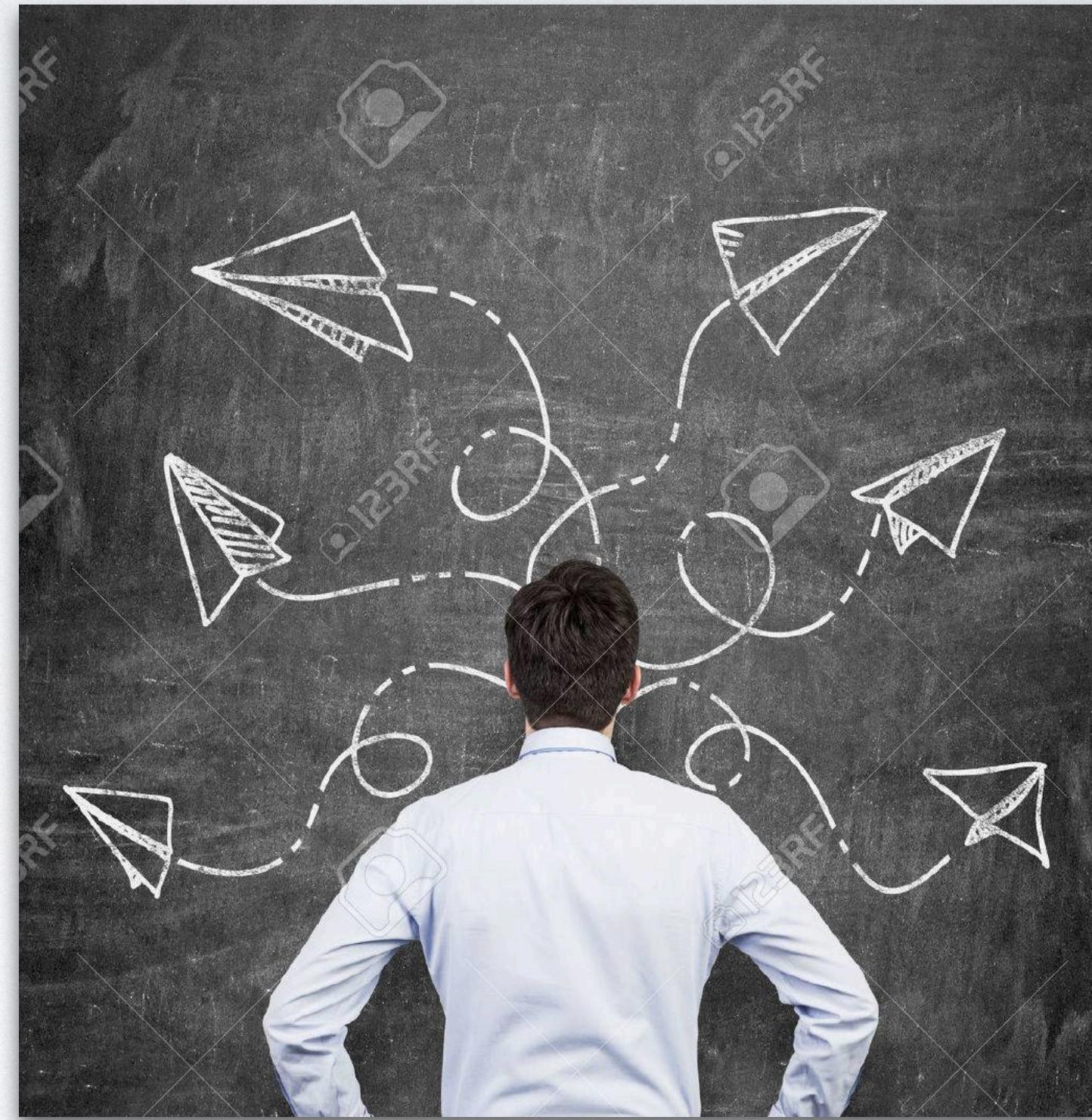
## AN ALGEBRAIC APPROACH

Di Wang  
Carnegie Mellon University

# PROBABILISTIC PROGRAMS



Draw random **data** from distributions



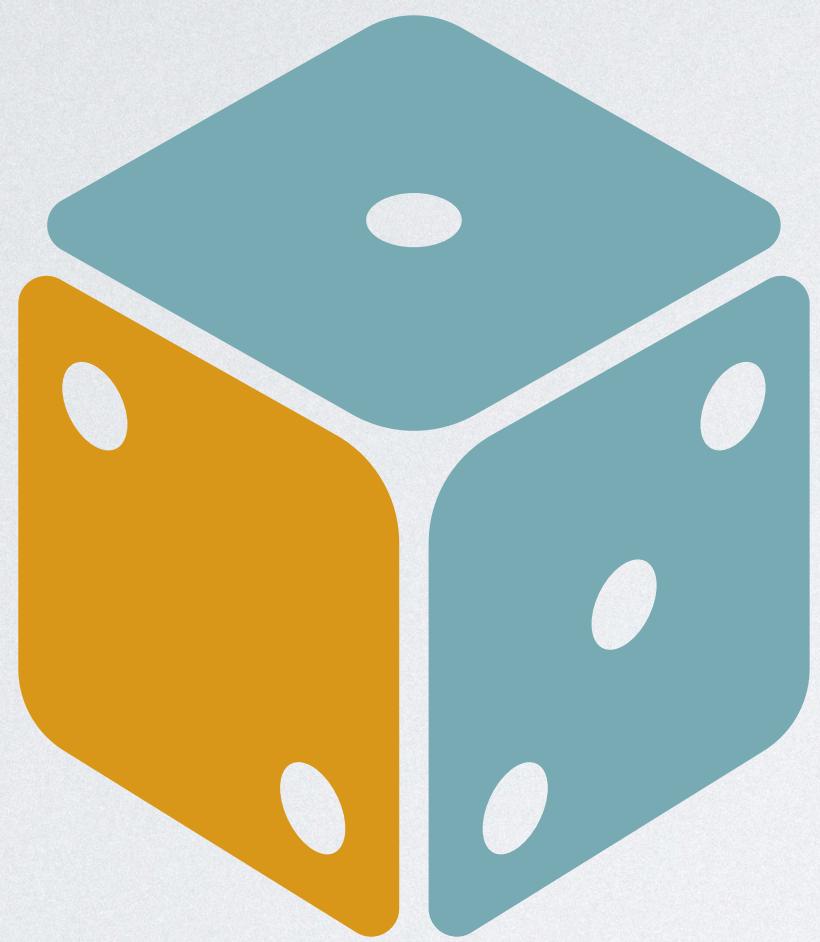
Condition **control-flow** at random

# PROBABILISTIC PROGRAMS

- ◆ True randomness
- ◆ Distributions on executions

```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```

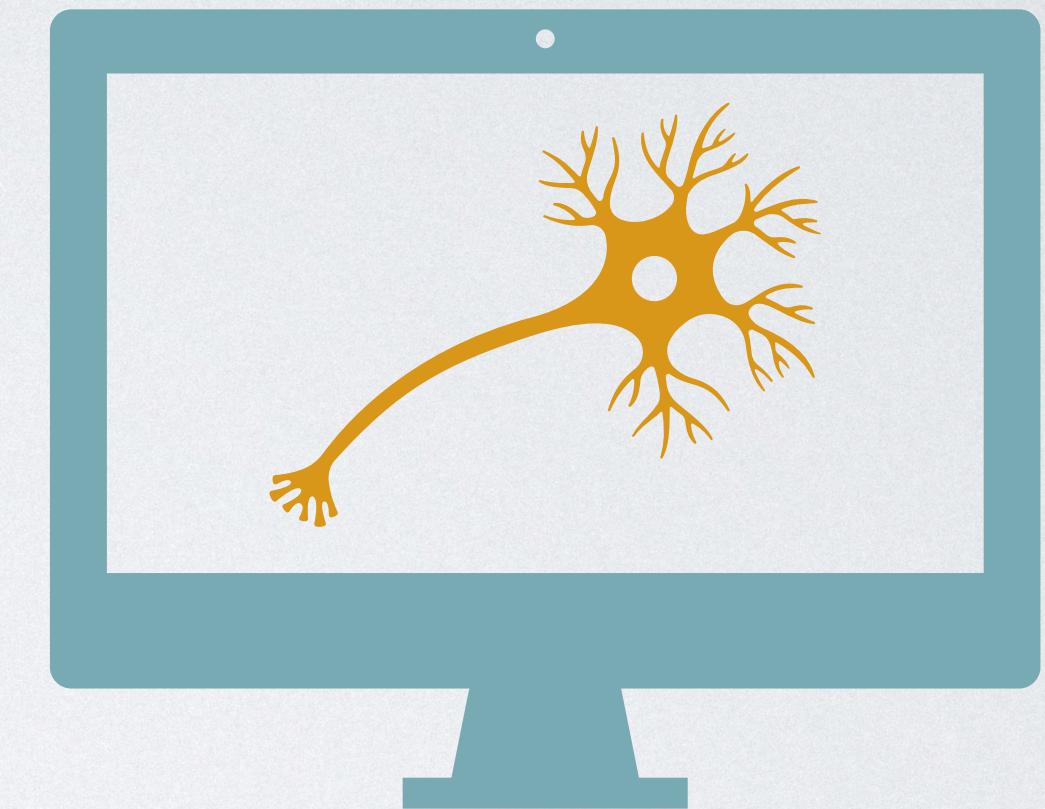
# APPLICATIONS OF PROB. PROG.



Randomized Algorithms  
(improve efficiency)



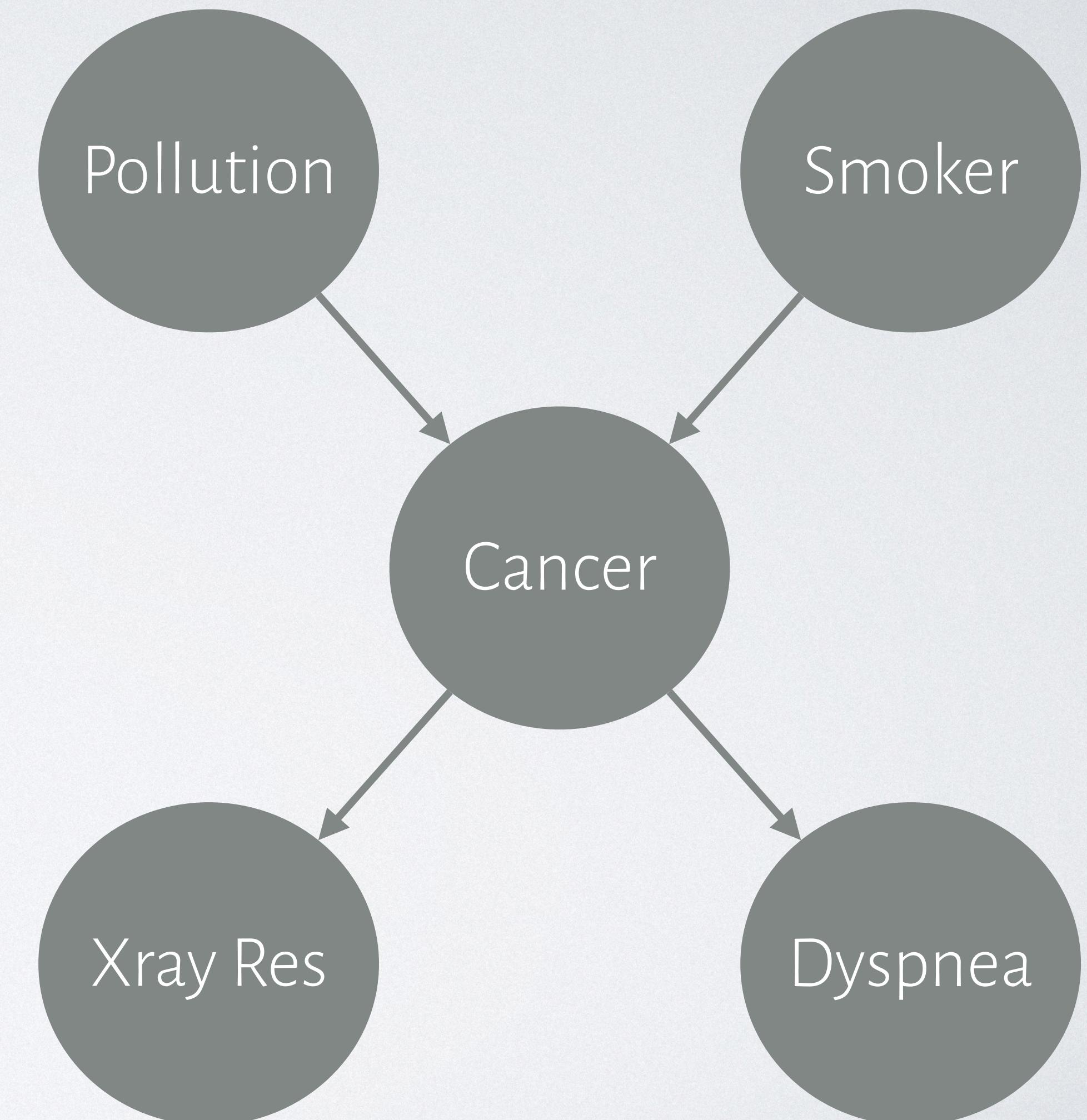
Cyber-Physical Systems  
(model uncertainty)



Machine Learning Algorithms  
(describe statistical models)

# BAYESIAN NETWORKS

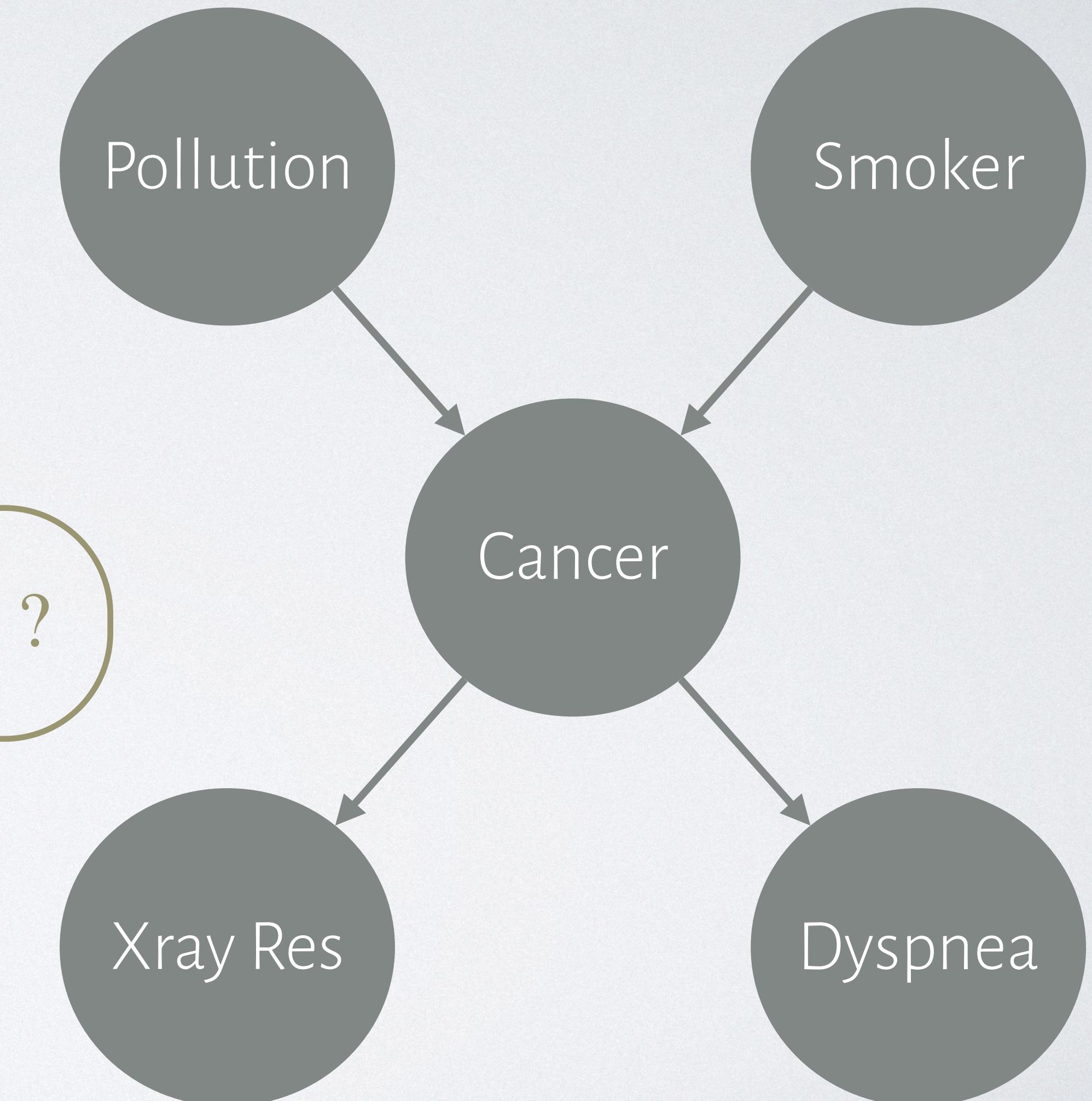
- ◆ Conditional distributions
- ◆ Query about the posterior



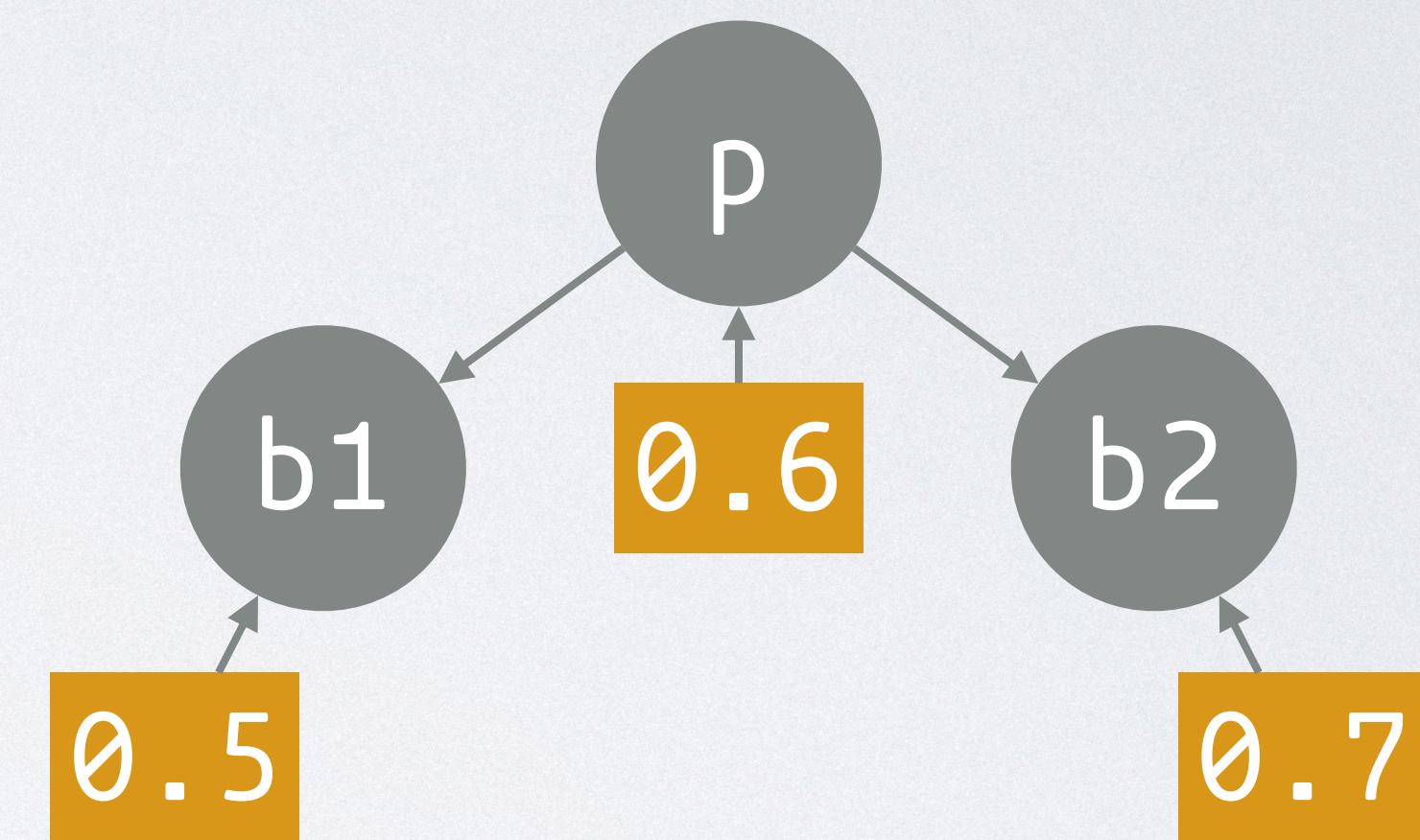
# BAYESIAN NETWORKS

- ◆ Conditional distributions
- ◆ Query about the posterior

**Prob**[Cancer | Smoker  $\wedge$  Xray Res] = ?

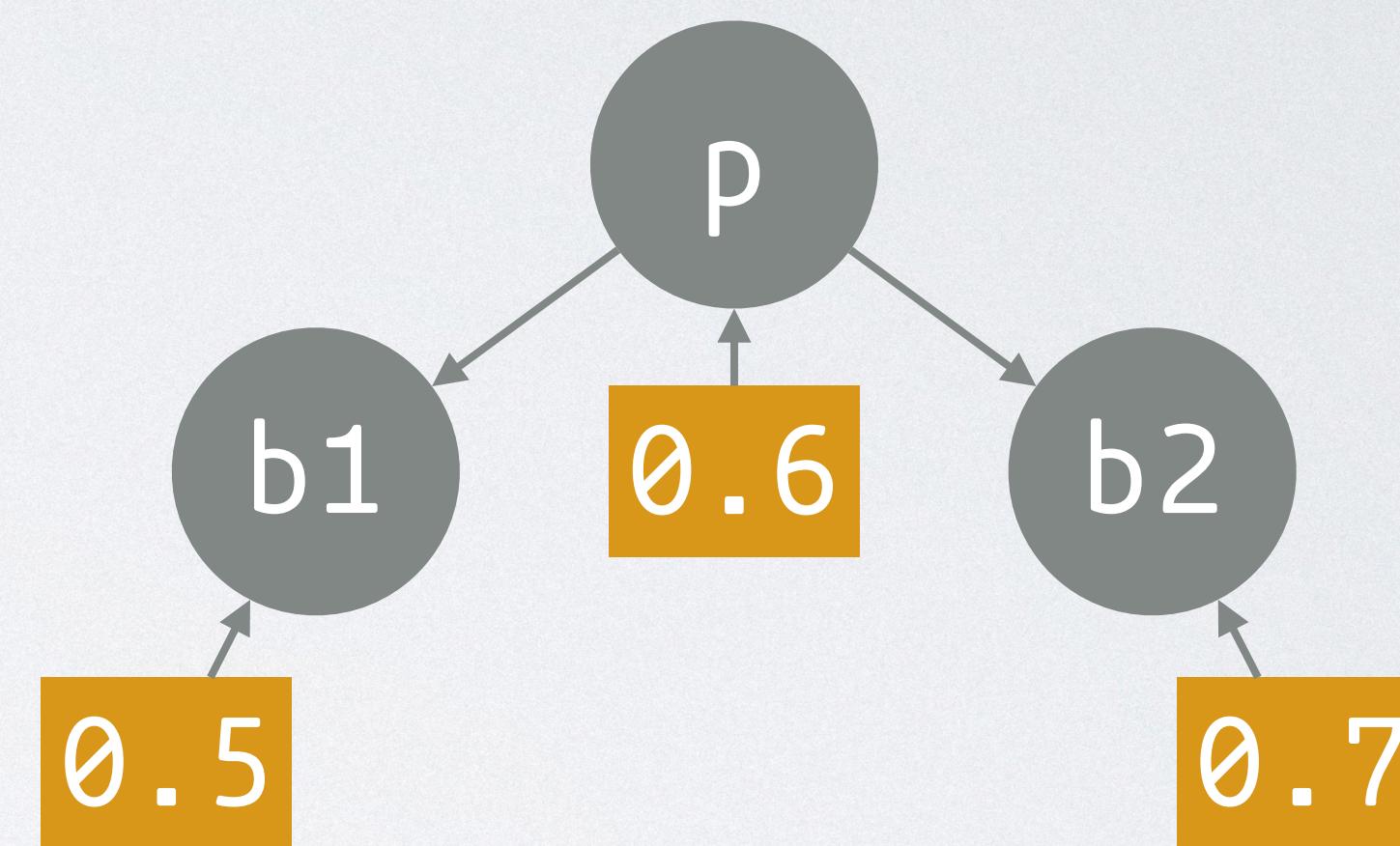


# BAYESIAN NETWORKS AS PROB. PROG.



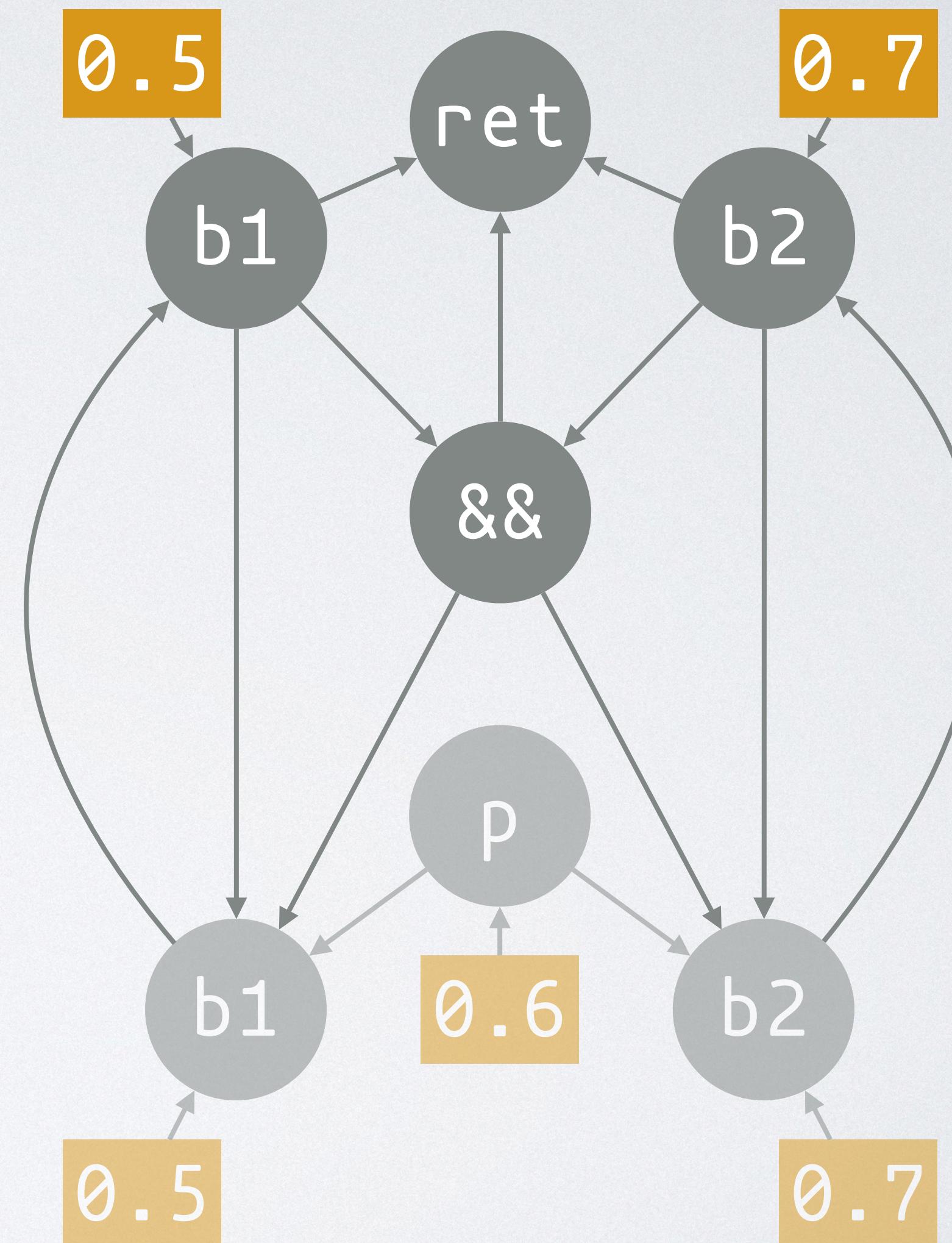
# BAYESIAN NETWORKS AS PROB. PROG.

```
if prob(0.6) then  
    b1 ~ Bernoulli(0.5)  
else  
    b2 ~ Bernoulli(0.7)  
fi
```



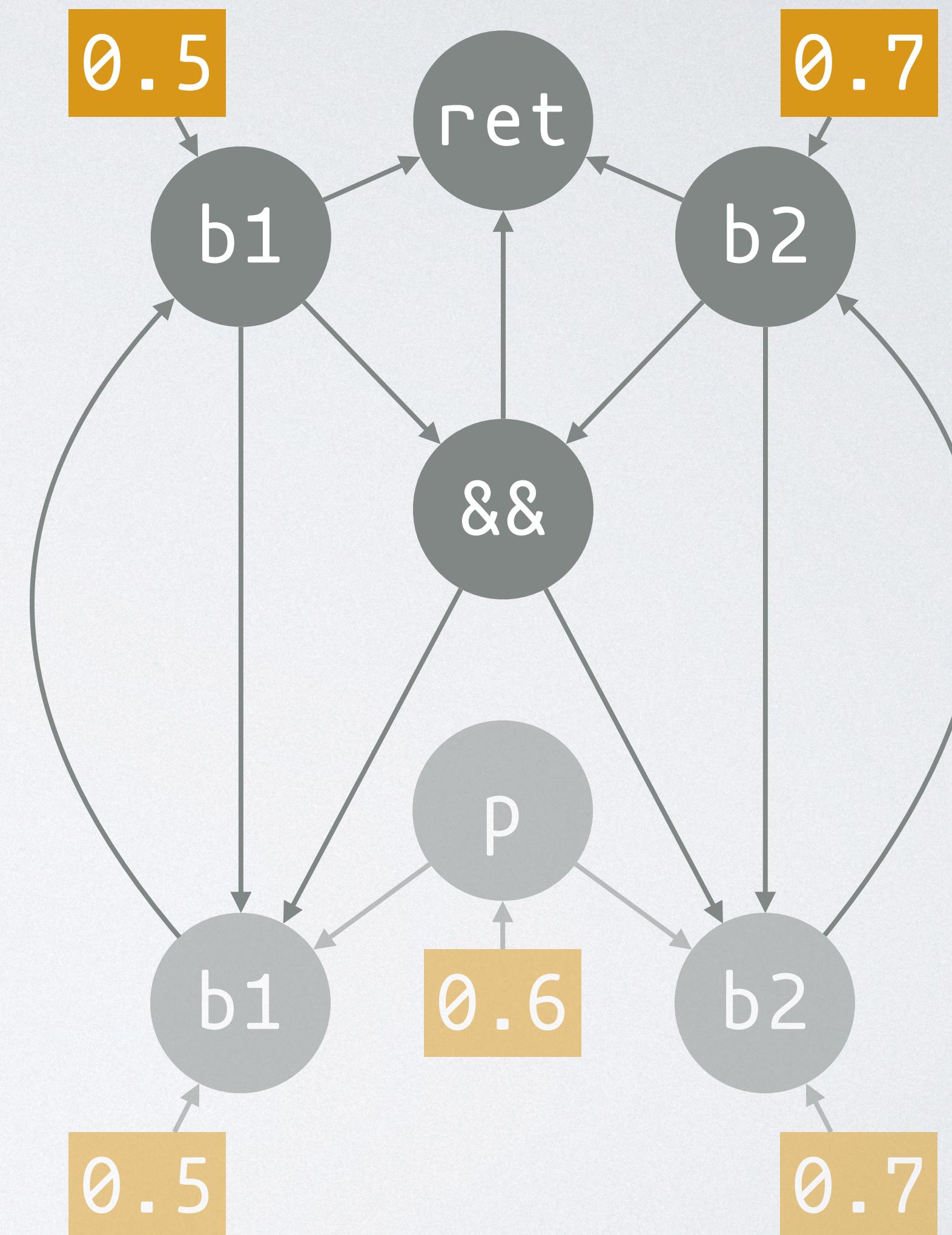
# BAYESIAN NETWORKS AS PROB. PROG.

```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```



# QUANTITATIVE REASONING ABOUT PROB. PROG.

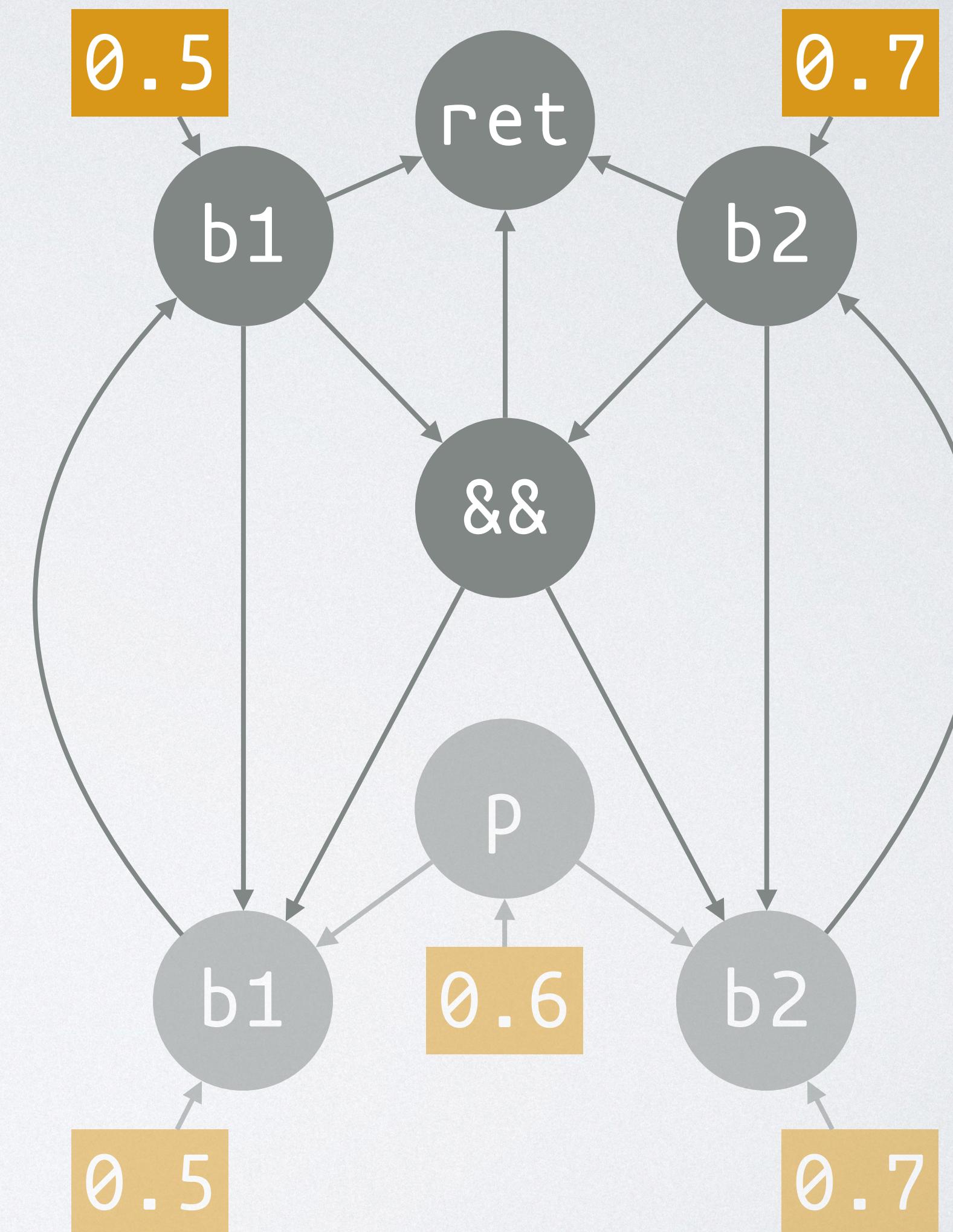
```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```



# QUANTITATIVE REASONING ABOUT PROB. PROG.

```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```

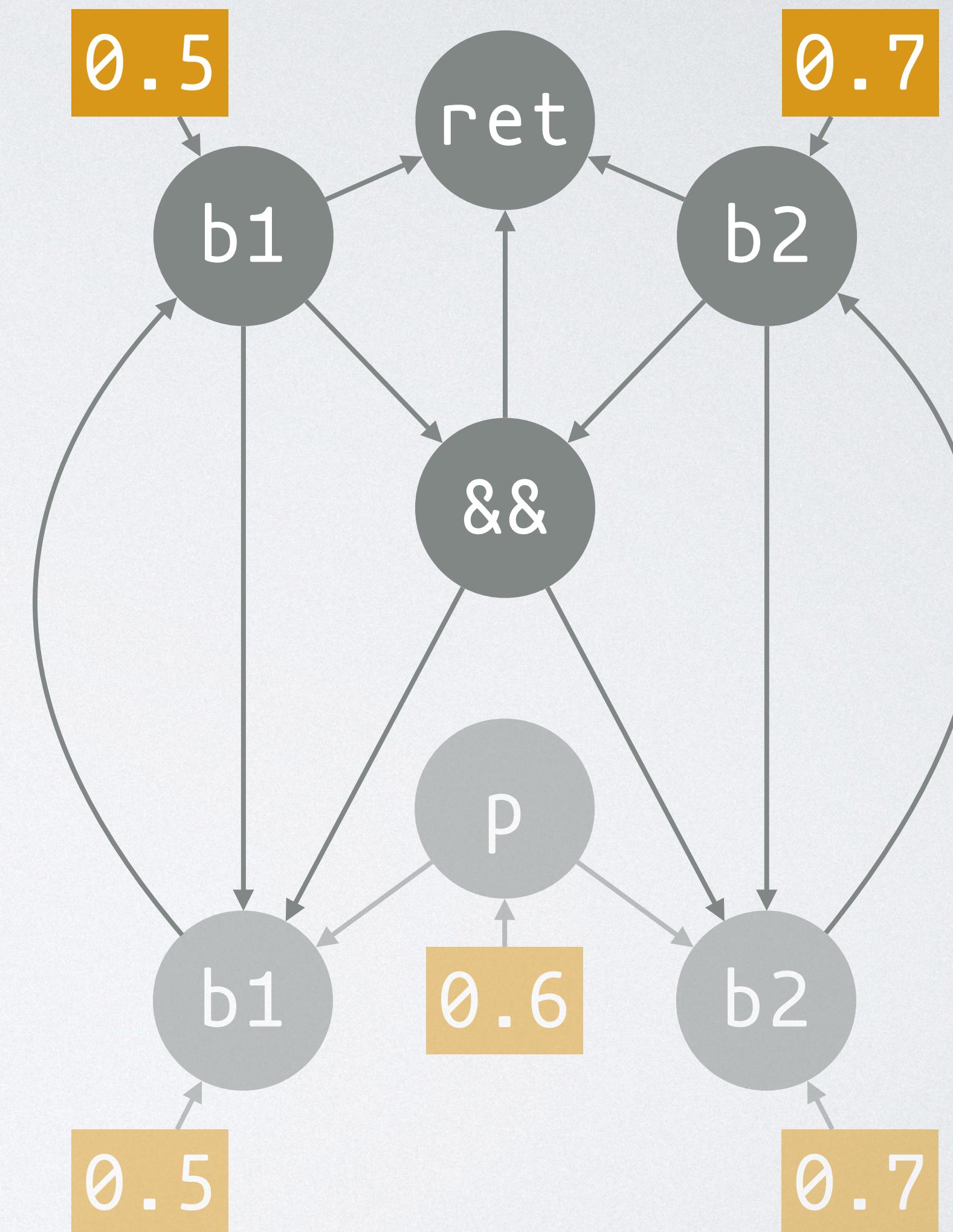
- ◆ **Query:** probability that **b1** and **b2** are both **false**?



# QUANTITATIVE REASONING ABOUT PROB. PROG.

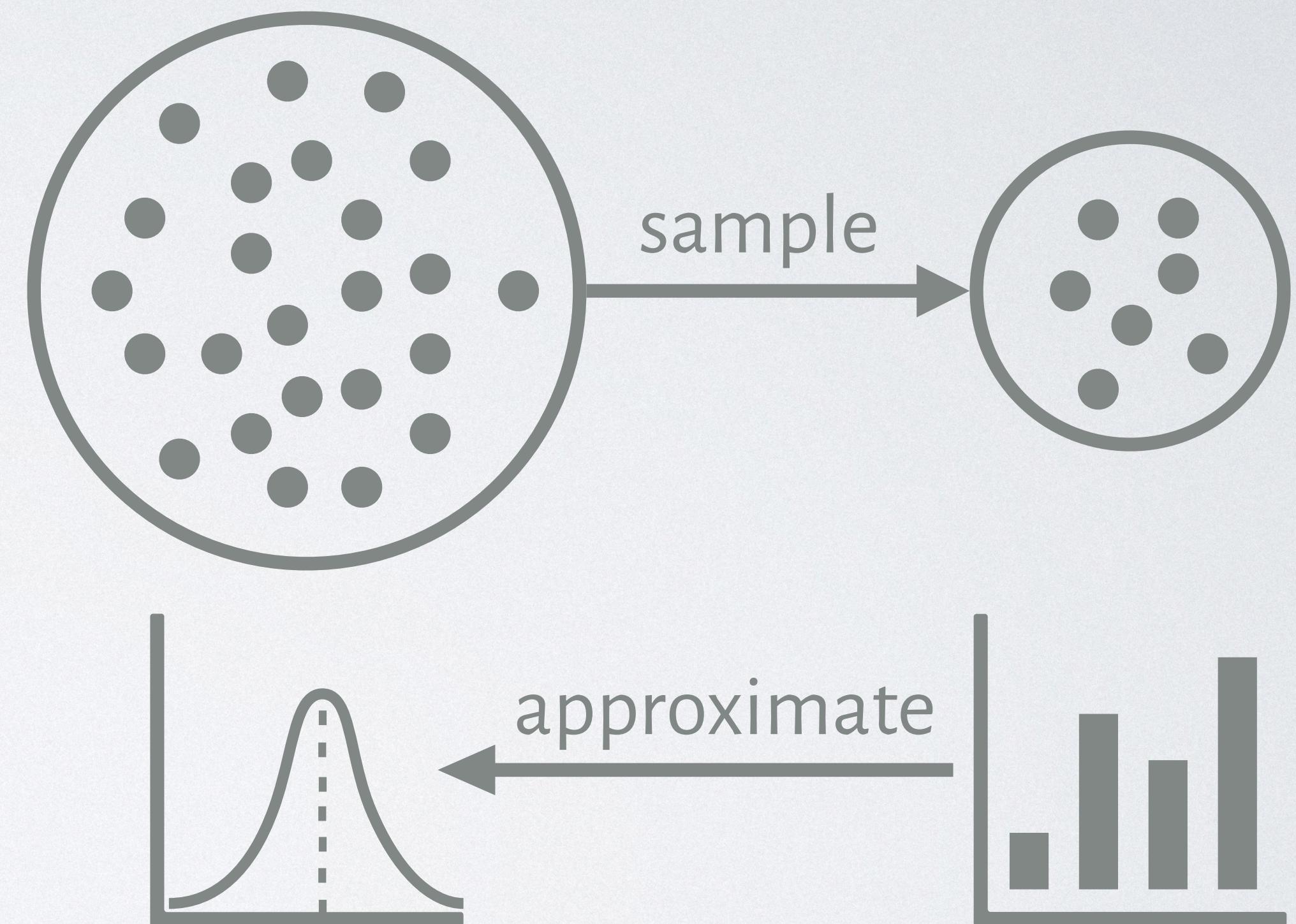
```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```

◆ **Query:** expected termination time?



# SAMPLING-BASED TECHNIQUES

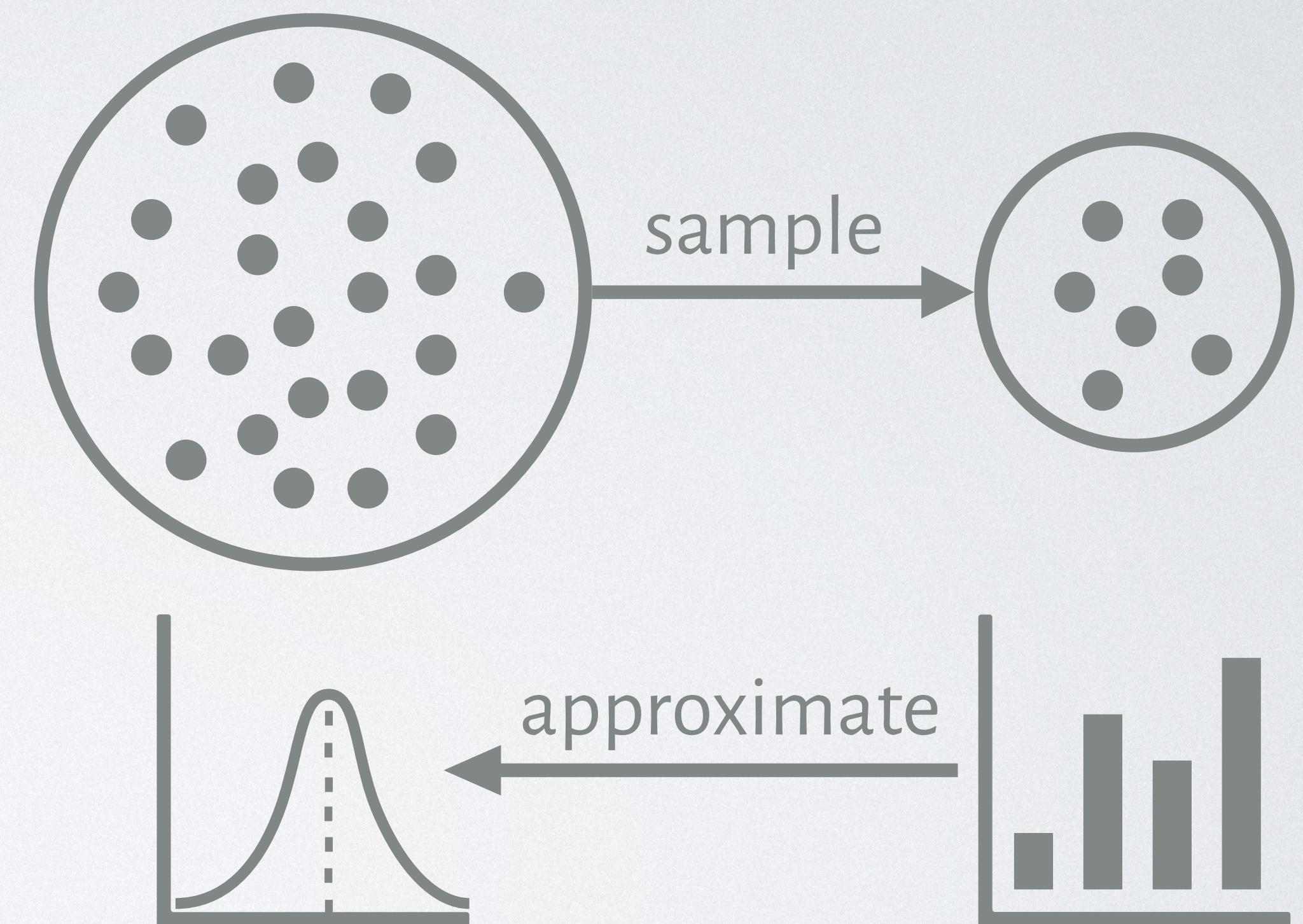
- ◆ Simulation & frequency count
- ◆ Flexible & universal
- ◆ Potentially unsound & inefficient



# SAMPLING-BASED TECHNIQUES

- ◆ Simulation & frequency count
- ◆ Flexible & universal
- ◆ Potentially unsound & inefficient

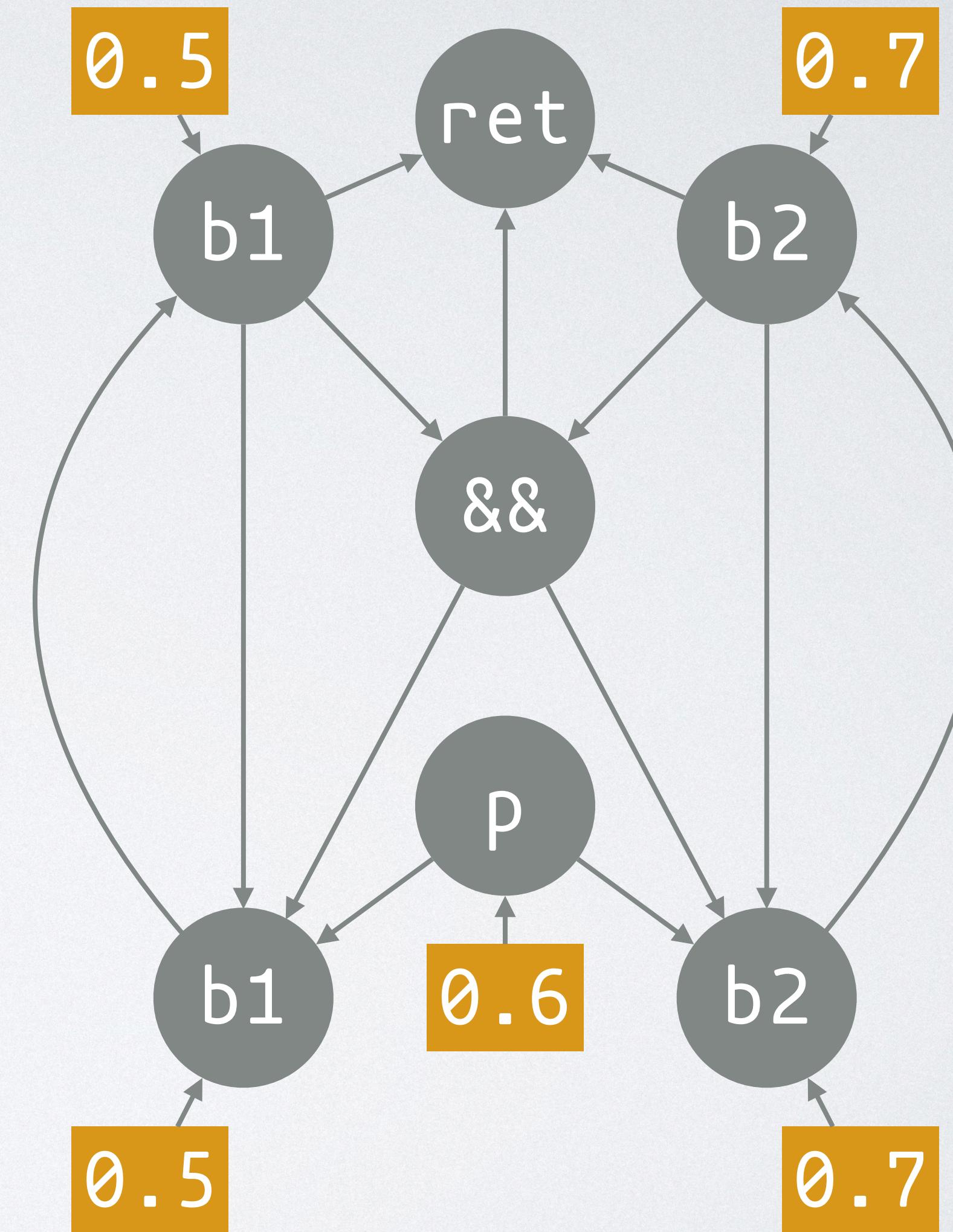
What about static analysis?



# SEMANTICS OF PROB. PROG.

```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```

- To develop static analysis, we need to first define a proper semantics



# SEMANTICS OF PROB. PROG.

<sup>1</sup>J. Borgström, U. D. Lago, A. D. Gordon, and M. Szymczak. A Lambda-Calculus Foundation for Universal Probabilistic Programming. In *ICFP’16*.

<sup>2</sup>F. Ferrer, M. Luis, and H. Hermanns. Probabilistic Termination: Soundness, Completeness, and Compositionality. In *POPL’15*.

<sup>3</sup>S. Staton, H. Yang, C. Heunen, and O. Kammar. Semantics for Probabilistic Programming: Higher-Order Functions, Continuous Distributions, and Soft Constraints. In *LICS’16*.

<sup>4</sup>C. Heunen, O. Kammar, S. Staton, and H. Yang. A Convenient Category for Higher-Order Probability Theory. In *LICS’17*.

# SEMANTICS OF PROB. PROG.

## Existing Operational Semantics

- ◆ Untyped lambda calculus<sup>1</sup>
- ◆ Markov chains<sup>2</sup>

<sup>1</sup>J. Borgström, U. D. Lago, A. D. Gordon, and M. Szymczak. A Lambda-Calculus Foundation for Universal Probabilistic Programming. In *ICFP'16*.

<sup>2</sup>F. Ferrer, M. Luis, and H. Hermanns. Probabilistic Termination: Soundness, Completeness, and Compositionality. In *POPL'15*.

<sup>3</sup>S. Staton, H. Yang, C. Heunen, and O. Kammar. Semantics for Probabilistic Programming: Higher-Order Functions, Continuous Distributions, and Soft Constraints. In *LICS'16*.

<sup>4</sup>C. Heunen, O. Kammar, S. Staton, and H. Yang. A Convenient Category for Higher-Order Probability Theory. In *LICS'17*.

# SEMANTICS OF PROB. PROG.

## Existing Operational Semantics

- ◆ Untyped lambda calculus<sup>1</sup>
- ◆ Markov chains<sup>2</sup>

## What was Missing?

- ◆ Compositionality

<sup>1</sup>J. Borgström, U. D. Lago, A. D. Gordon, and M. Szymczak. A Lambda-Calculus Foundation for Universal Probabilistic Programming. In *ICFP'16*.

<sup>2</sup>F. Ferrer, M. Luis, and H. Hermanns. Probabilistic Termination: Soundness, Completeness, and Compositionality. In *POPL'15*.

<sup>3</sup>S. Staton, H. Yang, C. Heunen, and O. Kammar. Semantics for Probabilistic Programming: Higher-Order Functions, Continuous Distributions, and Soft Constraints. In *LICS'16*.

<sup>4</sup>C. Heunen, O. Kammar, S. Staton, and H. Yang. A Convenient Category for Higher-Order Probability Theory. In *LICS'17*.

# SEMANTICS OF PROB. PROG.

## Existing Operational Semantics

- ◆ Untyped lambda calculus<sup>1</sup>
- ◆ Markov chains<sup>2</sup>

## Existing Denotational Semantics

- ◆ First-order programs<sup>3</sup>
- ◆ Higher-order programs<sup>4</sup>

## What was Missing?

- ◆ Compositionality

<sup>1</sup>J. Borgström, U. D. Lago, A. D. Gordon, and M. Szymczak. A Lambda-Calculus Foundation for Universal Probabilistic Programming. In *ICFP'16*.

<sup>2</sup>F. Ferrer, M. Luis, and H. Hermanns. Probabilistic Termination: Soundness, Completeness, and Compositionality. In *POPL'15*.

<sup>3</sup>S. Staton, H. Yang, C. Heunen, and O. Kammar. Semantics for Probabilistic Programming: Higher-Order Functions, Continuous Distributions, and Soft Constraints. In *LICS'16*.

<sup>4</sup>C. Heunen, O. Kammar, S. Staton, and H. Yang. A Convenient Category for Higher-Order Probability Theory. In *LICS'17*.

# SEMANTICS OF PROB. PROG.

## Existing Operational Semantics

- ◆ Untyped lambda calculus<sup>1</sup>
- ◆ Markov chains<sup>2</sup>

## Existing Denotational Semantics

- ◆ First-order programs<sup>3</sup>
- ◆ Higher-order programs<sup>4</sup>

## What was Missing?

- ◆ Compositionality

## What was Missing?

- ◆ A general treatment of nondeterminism

<sup>1</sup>J. Borgström, U. D. Lago, A. D. Gordon, and M. Szymczak. A Lambda-Calculus Foundation for Universal Probabilistic Programming. In *ICFP'16*.

<sup>2</sup>F. Ferrer, M. Luis, and H. Hermanns. Probabilistic Termination: Soundness, Completeness, and Compositionality. In *POPL'15*.

<sup>3</sup>S. Staton, H. Yang, C. Heunen, and O. Kammar. Semantics for Probabilistic Programming: Higher-Order Functions, Continuous Distributions, and Soft Constraints. In *LICS'16*.

<sup>4</sup>C. Heunen, O. Kammar, S. Staton, and H. Yang. A Convenient Category for Higher-Order Probability Theory. In *LICS'17*.

# STATIC ANALYSIS OF PROB. PROG.

# STATIC ANALYSIS OF PROB. PROG.

## Existing Approaches

- ◆ Static analysis of different kinds of program properties for prob. prog.
- ◆ Probabilistic Abstract Interpretation (**PAI**)<sup>5</sup>

<sup>5</sup> P. Cousot and M. Monerau. Probabilistic Abstract Interpretation. In *ESOP'12*.

# STATIC ANALYSIS OF PROB. PROG.

## Existing Approaches

- ◆ Static analysis of different kinds of program properties for prob. prog.
- ◆ Probabilistic Abstract Interpretation (**PAI**)<sup>5</sup>

## What was Missing?

- ◆ A **unifying** framework that covers multiple analyses
- ◆ **Compositionality** and **flexibility**
- ◆ **PAI**'s treatment of nondeterminism sometimes turns out to be **not desirable**

<sup>5</sup> P. Cousot and M. Monerau. Probabilistic Abstract Interpretation. In *ESOP'12*.

# ALGEBRAIC PROGRAM ANALYSIS<sup>6</sup>

<sup>6</sup>Z. Kincaid, T. Reps, and J. Cyphert. Algebraic Program Analysis. In CAV'21.

# ALGEBRAIC PROGRAM ANALYSIS<sup>6</sup>

- ◆ A flexible framework for understanding **compositional** static analyses

<sup>6</sup>Z. Kincaid, T. Reps, and J. Cyphert. Algebraic Program Analysis. In CAV'21.

# ALGEBRAIC PROGRAM ANALYSIS<sup>6</sup>

- ◆ A flexible framework for understanding **compositional** static analyses
- ◆ Usually set up with an **algebraic semantics**, e.g., a **Kleene algebra**

<sup>6</sup>Z. Kincaid, T. Reps, and J. Cyphert. Algebraic Program Analysis. In CAV'21.

# ALGEBRAIC PROGRAM ANALYSIS<sup>6</sup>

- ◆ A flexible framework for understanding **compositional** static analyses
- ◆ Usually set up with an **algebraic semantics**, e.g., a **Kleene algebra**

$A \oplus B$  for **branching** between  $A$  and  $B$

<sup>6</sup>Z. Kincaid, T. Reps, and J. Cyphert. Algebraic Program Analysis. In CAV'21.

# ALGEBRAIC PROGRAM ANALYSIS<sup>6</sup>

- ◆ A flexible framework for understanding **compositional** static analyses
- ◆ Usually set up with an **algebraic semantics**, e.g., a **Kleene algebra**

$A \oplus B$  for **branching** between  $A$  and  $B$

$A \otimes B$  for **sequencing** of  $A$  and  $B$

<sup>6</sup>Z. Kincaid, T. Reps, and J. Cyphert. Algebraic Program Analysis. In CAV'21.

# ALGEBRAIC PROGRAM ANALYSIS<sup>6</sup>

- ◆ A flexible framework for understanding **compositional** static analyses
- ◆ Usually set up with an **algebraic semantics**, e.g., a **Kleene algebra**

$A \oplus B$  for **branching** between  $A$  and  $B$

$A \otimes B$  for **sequencing** of  $A$  and  $B$

$A^*$  for the Kleene-star (a **loop**) of  $A$

<sup>6</sup>Z. Kincaid, T. Reps, and J. Cyphert. Algebraic Program Analysis. In CAV'21.

# ALGEBRAIC PROGRAM ANALYSIS<sup>6</sup>

- ◆ A flexible framework for understanding **compositional** static analyses
- ◆ Usually set up with an **algebraic semantics**, e.g., a **Kleene algebra**

$A \oplus B$  for **branching** between  $A$  and  $B$

$A \otimes B$  for **sequencing** of  $A$  and  $B$

$A^*$  for the Kleene-star (a **loop**) of  $A$

- ◆ Different algebras yield different semantics, e.g., a **concrete semantics**, or an **abstract semantics for static analysis**

<sup>6</sup>Z. Kincaid, T. Reps, and J. Cyphert. Algebraic Program Analysis. In CAV'21.

# THESIS

- ◆ **Algebraic** static analysis helps people reason about prob. prog. at compile time in a **compositional** and **flexible** way
- ◆ **Markov algebras** provide a natural way to define a **denotational semantics** of prob. prog. with **nondeterminism**
- ◆ **An algebraic framework for static analysis** can cover multiple existing analyses and lay the foundation for new analyses

# OVERVIEW

## Motivation

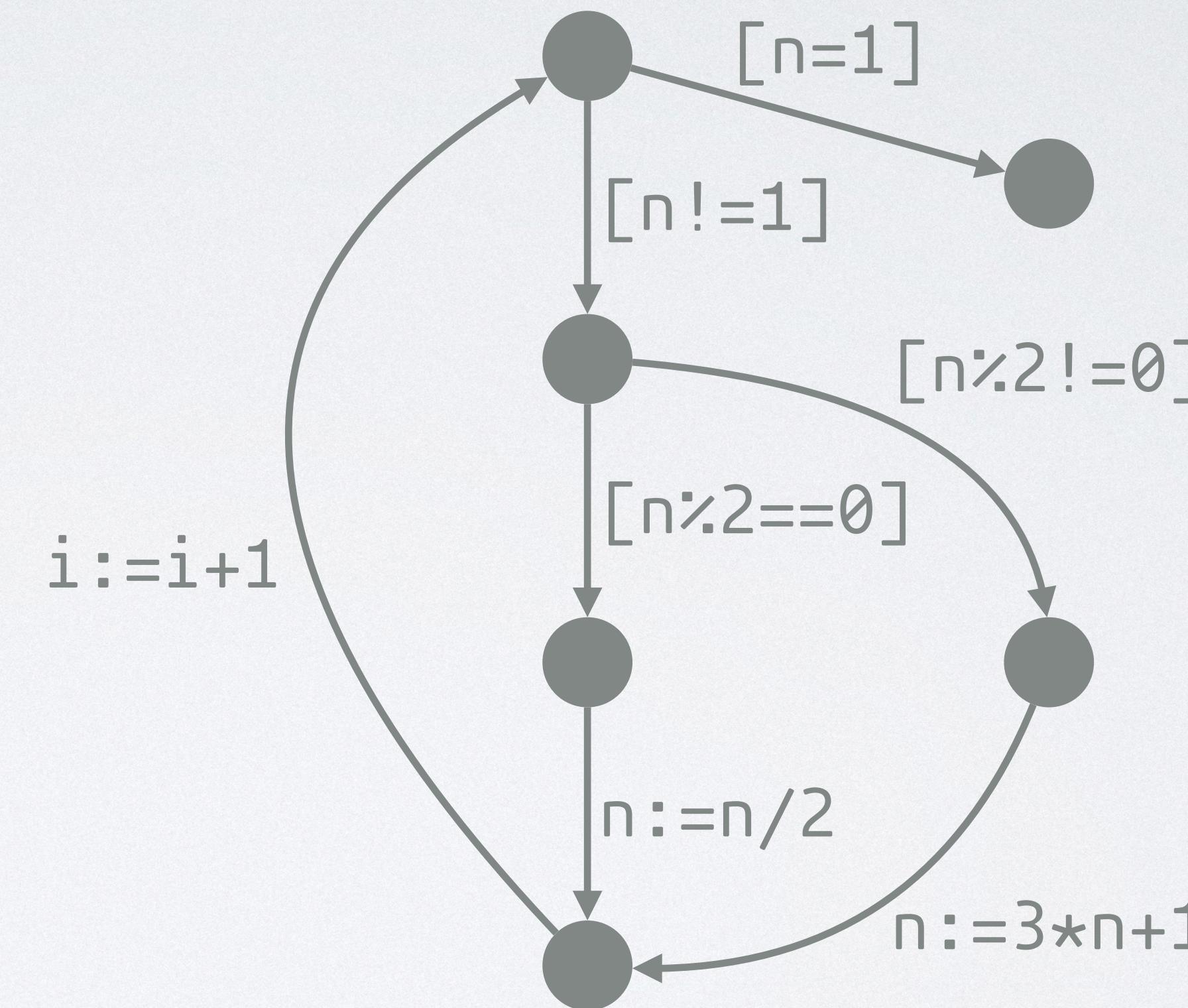
- An Algebraic Denotational Semantics
- Pre-Markov Algebra Framework (PMAF)

# AN ALGEBRAIC DENOTATIONAL SEMANTICS

## Contributions

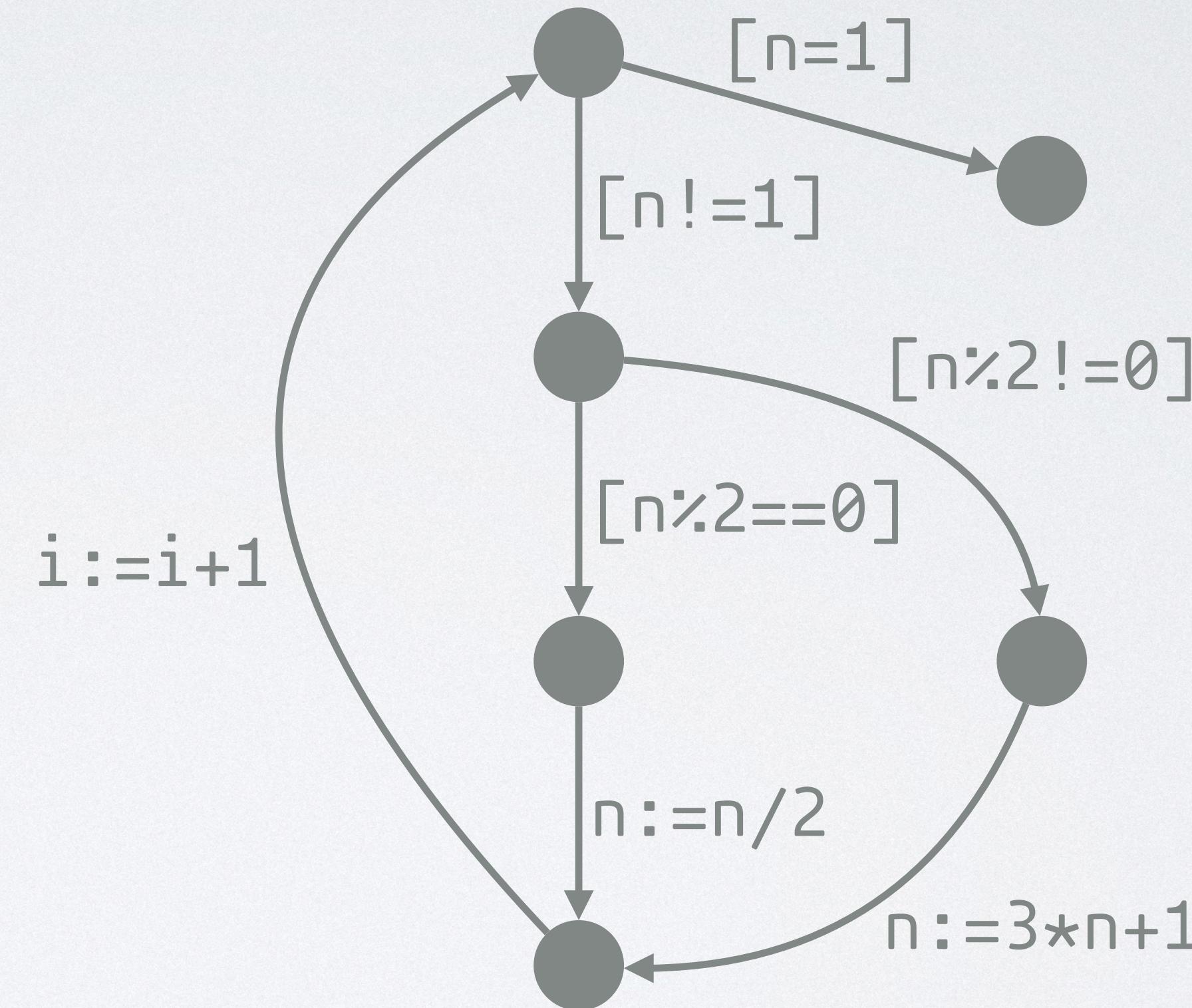
- ◆ A **hyper-path** semantics for low-level prob. prog.
- ◆ **Markov algebras** for understanding prob. prog. with nondeterminism
- ◆ A new model for resolving **nondeterminism**
- ◆ Published as **A Denotational Semantics for Low-Level Probabilistic Programs with Nondeterminism** in *MFPS'19*

# PATH SEMANTICS OF NON-PROB. PROG.



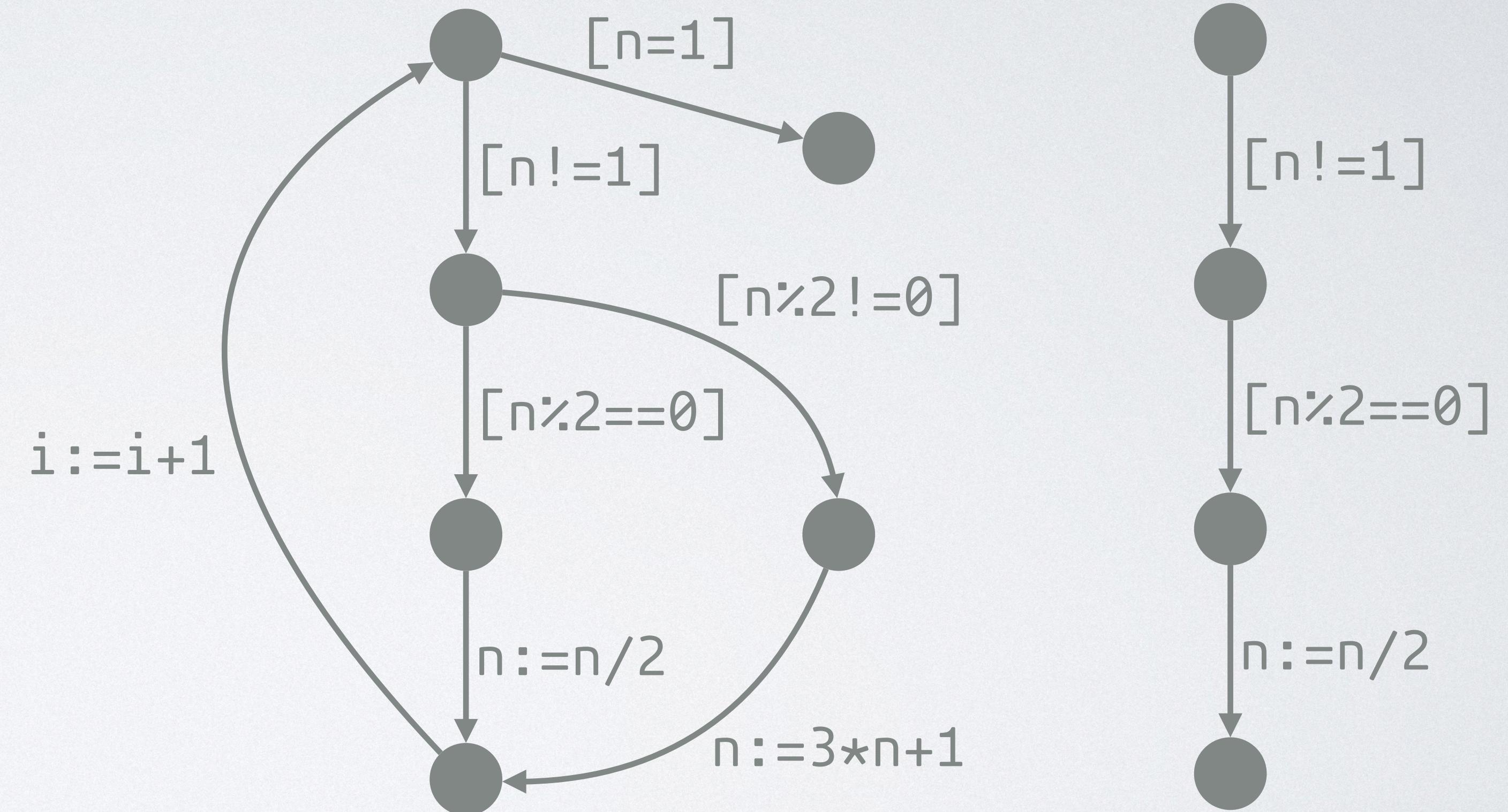
# PATH SEMANTICS OF NON-PROB. PROG.

- Control-flow graphs



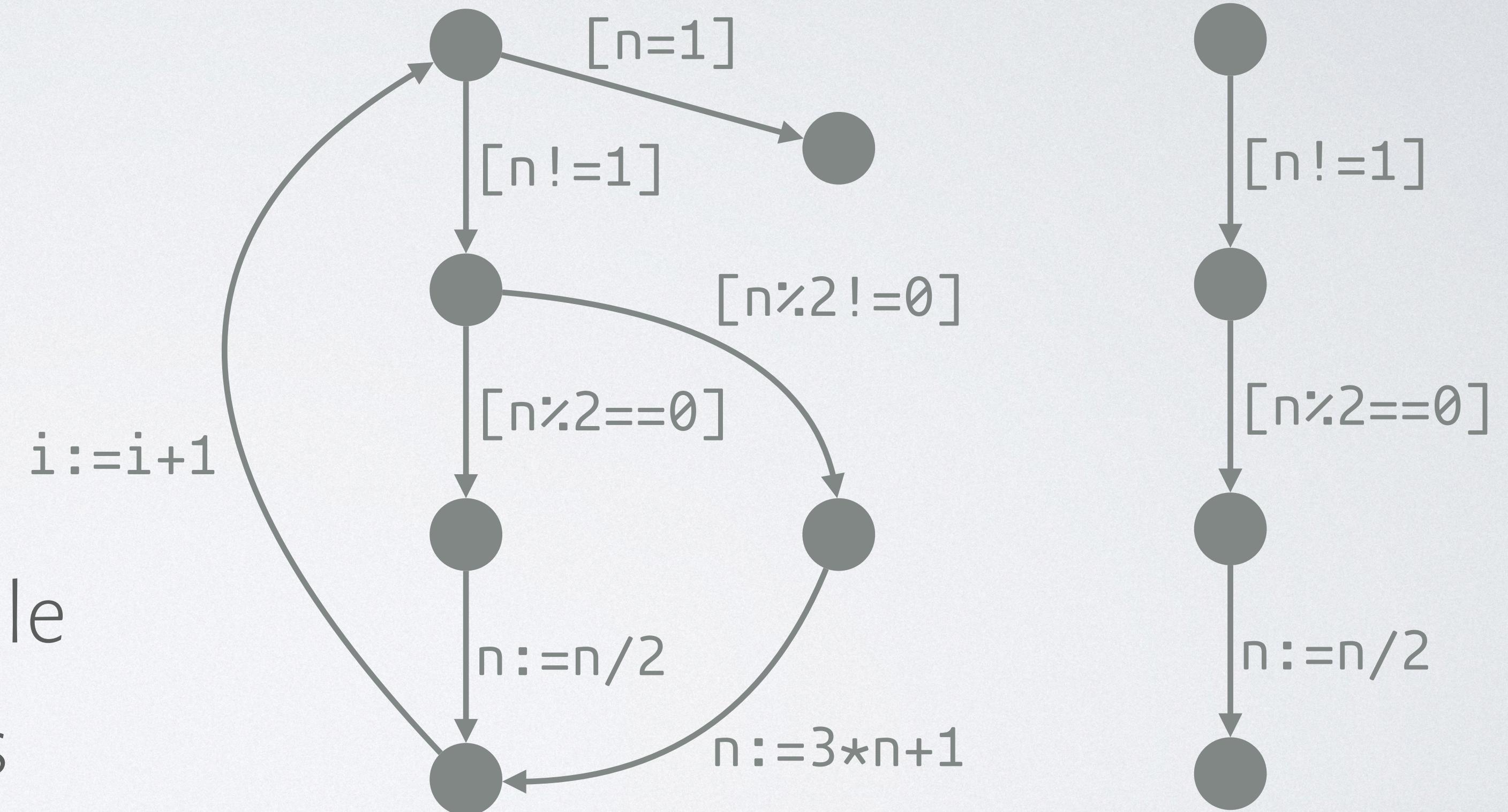
# PATH SEMANTICS OF NON-PROB. PROG.

- ◆ Control-flow graphs
- ◆ Reason about **paths**



# PATH SEMANTICS OF NON-PROB. PROG.

- ◆ Control-flow graphs
- ◆ Reason about **paths**
- ◆ Kleene algebras are suitable to describe path semantics



# CONTROL-FLOW GRAPHS AND PATH SEMANTICS

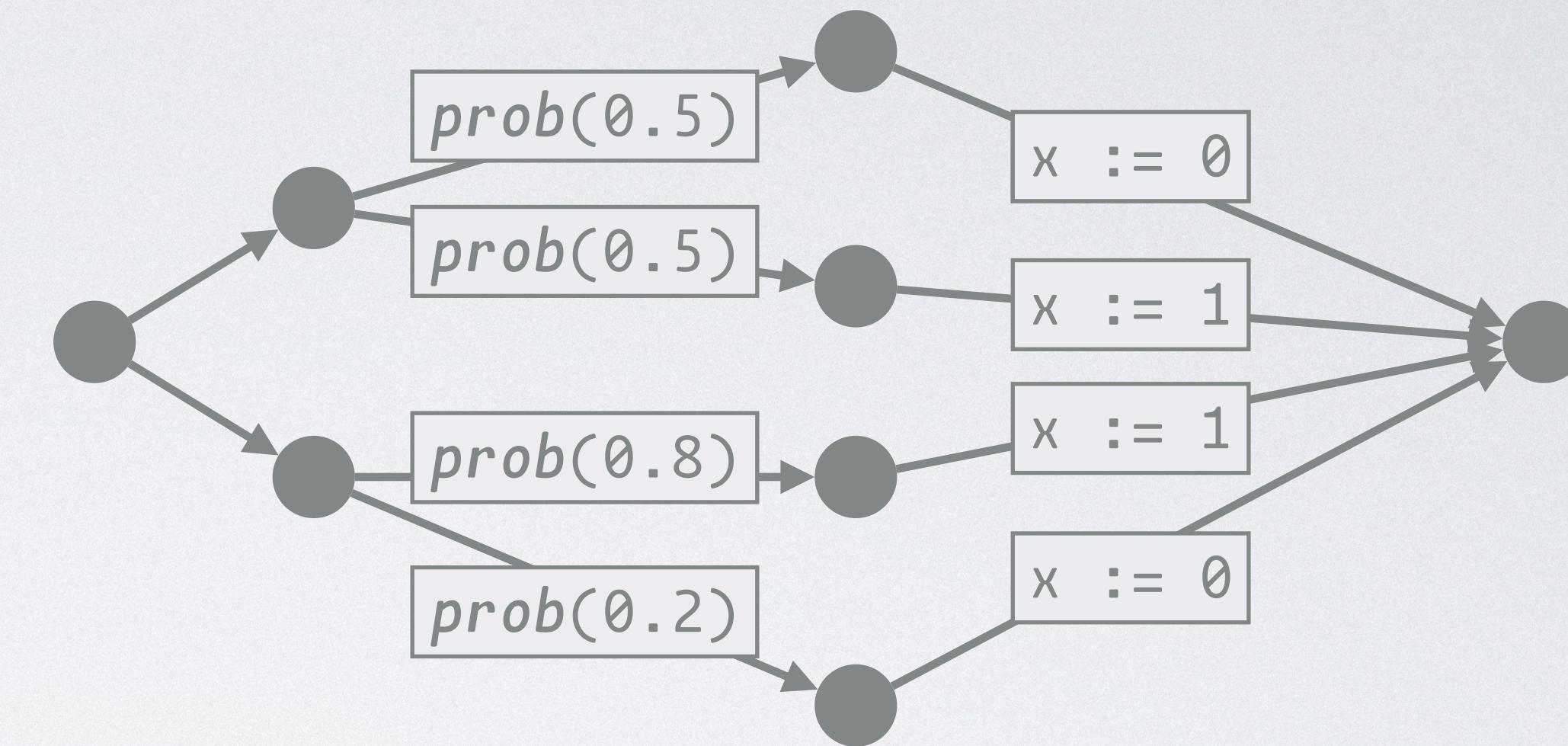
\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then
    x := 0
  else
    x := 1
  fi
else
  if prob(0.8) then
    x := 1
  else
    x := 0
  fi
fi
```

# CONTROL-FLOW GRAPHS AND PATH SEMANTICS

\* denotes nondeterministic-choice

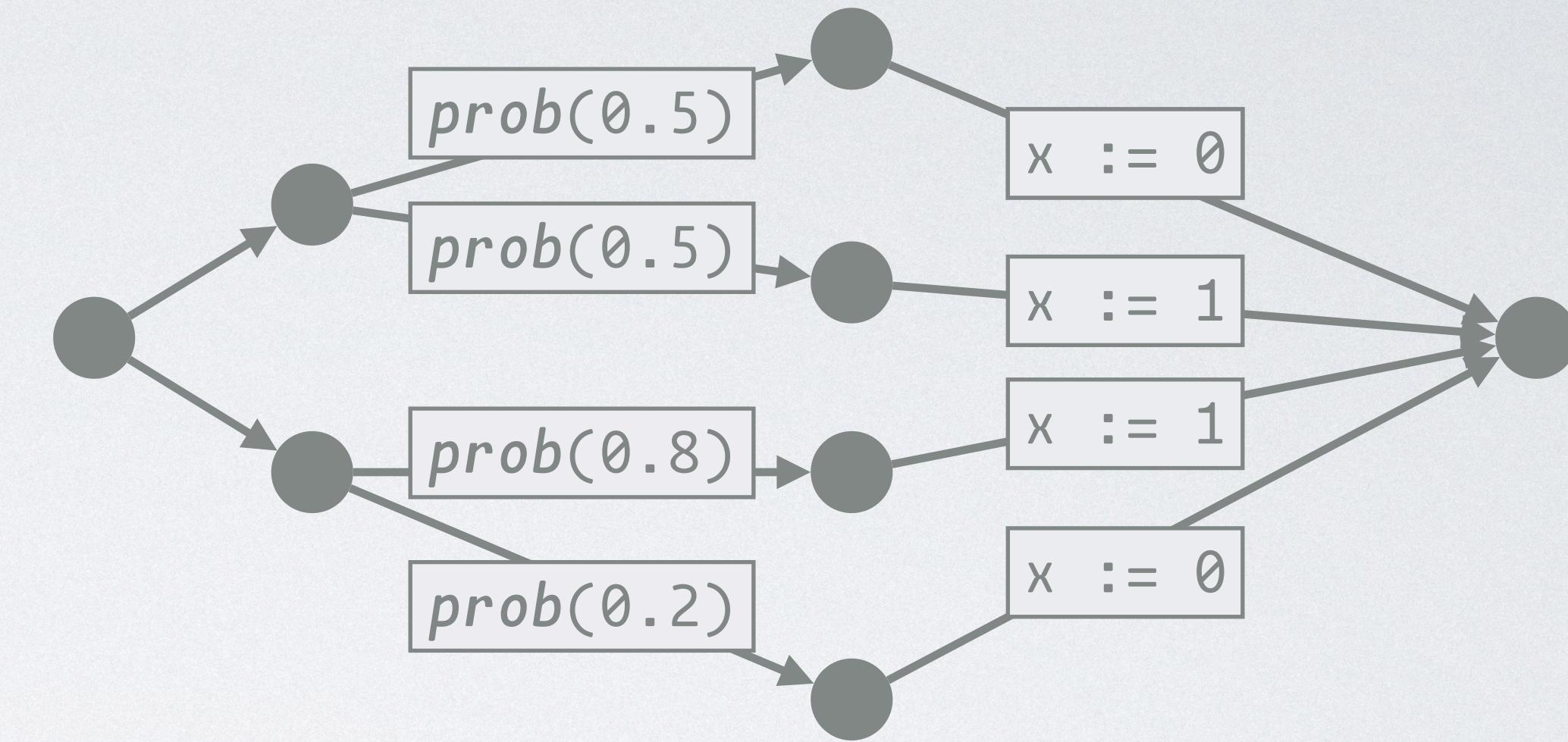
```
if * then
  if prob(0.5) then
    x := 0
  else
    x := 1
  fi
else
  if prob(0.8) then
    x := 1
  else
    x := 0
  fi
fi
```



# CONTROL-FLOW GRAPHS AND PATH SEMANTICS

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then
    x := 0
  else
    x := 1
  fi
else
  if prob(0.8) then
    x := 1
  else
    x := 0
  fi
fi
```



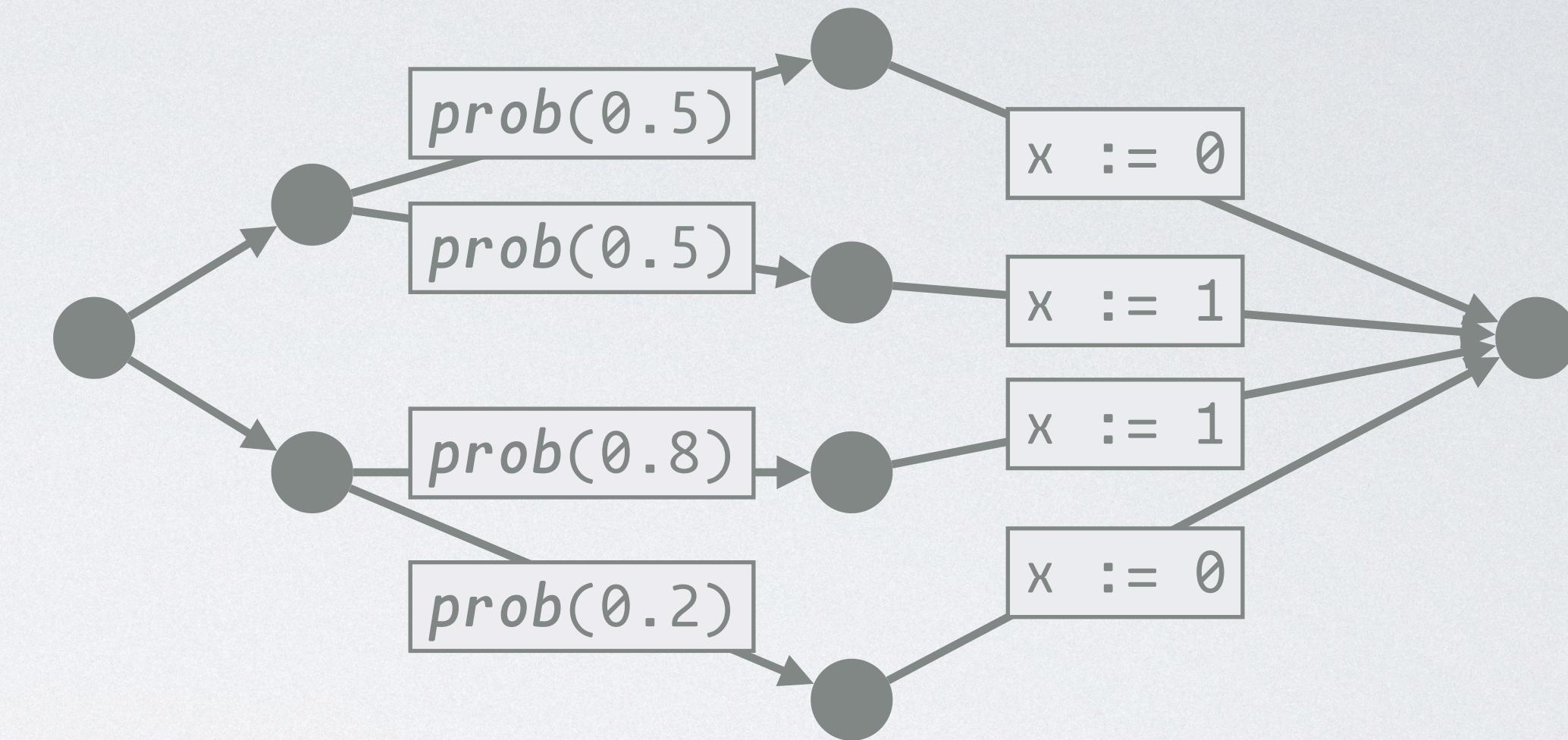
◆ Paths annotated with probabilities:



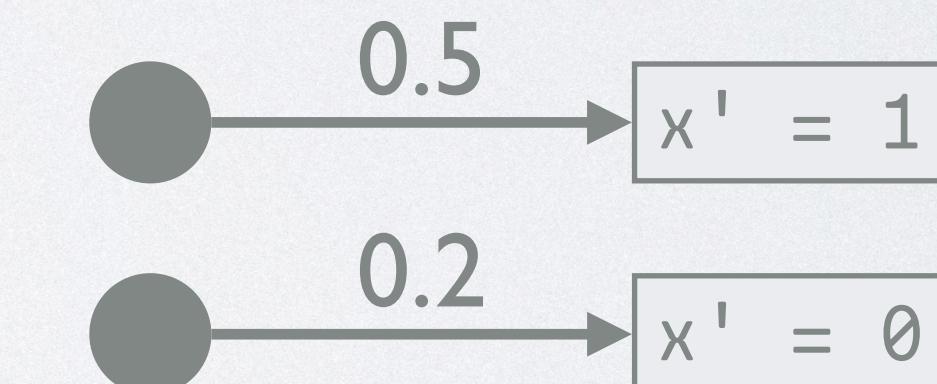
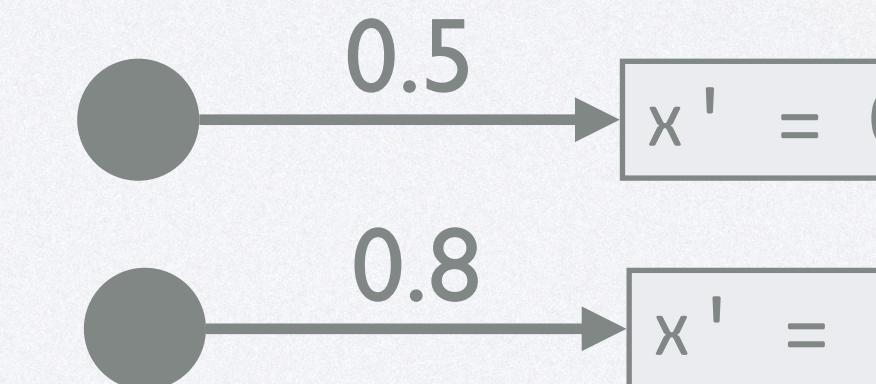
# CONTROL-FLOW GRAPHS AND PATH SEMANTICS

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then
    x := 0
  else
    x := 1
  fi
else
  if prob(0.8) then
    x := 1
  else
    x := 0
  fi
fi
```



- Paths annotated with probabilities:



- Prob[ $x' = 1$ ] = 1.3?

# HYPER-PATH SEMANTICS

\* denotes nondeterministic-choice

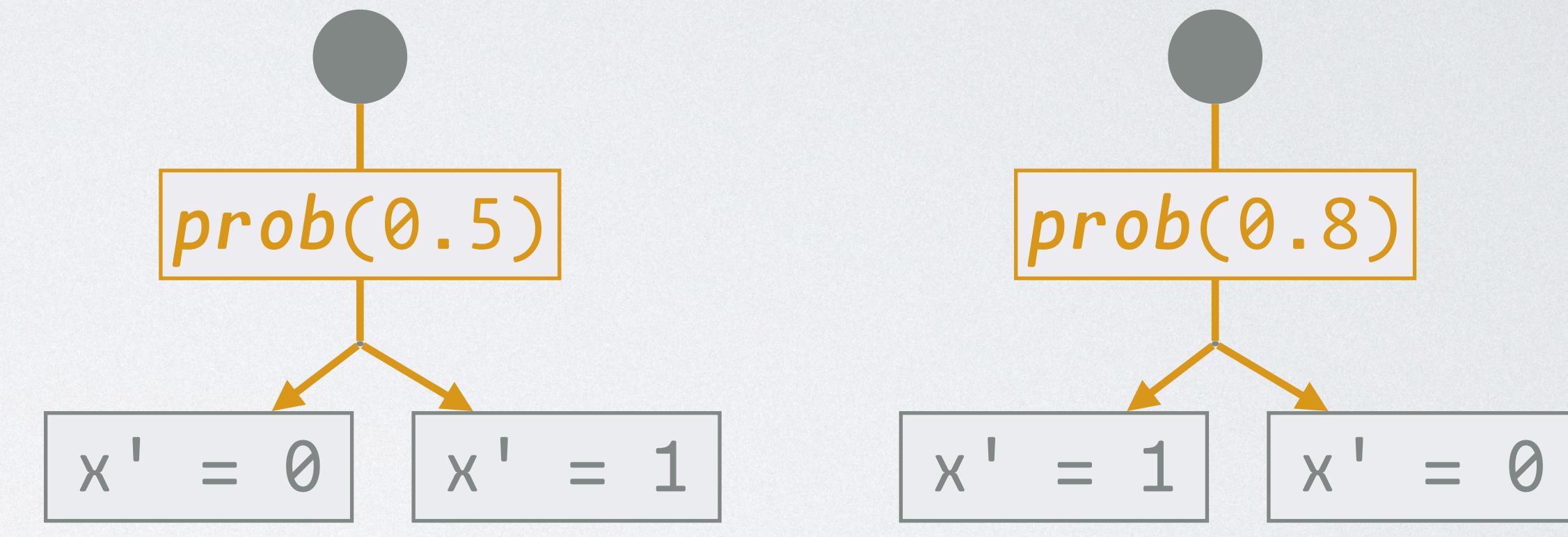
```
if * then
  if prob(0.5) then
    x := 0
  else
    x := 1
  fi
else
  if prob(0.8) then
    x := 1
  else
    x := 0
  fi
fi
```

# HYPER-PATH SEMANTICS

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then
    x := 0
  else
    x := 1
  fi
else
  if prob(0.8) then
    x := 1
  else
    x := 0
  fi
fi
```

- ◆ *prob()* introduces **distributions on executions**, and \*
- collects such distributions



# HYPER-PATH SEMANTICS

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then
    x := 0
  else
    x := 1
  fi
else
  if prob(0.8) then
    x := 1
  else
    x := 0
  fi
fi
```

- ◆ **prob()** introduces **distributions on executions**, and \*
- collects such distributions



- ◆ A **hyper-path** represents a **distribution on paths**

# HYPER-PATH SEMANTICS

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then
    x := 0
  else
    x := 1
  fi
else
  if prob(0.8) then
    x := 1
  else
    x := 0
  fi
fi
```

- ◆ **prob()** introduces **distributions on executions**, and \*
- collects such distributions



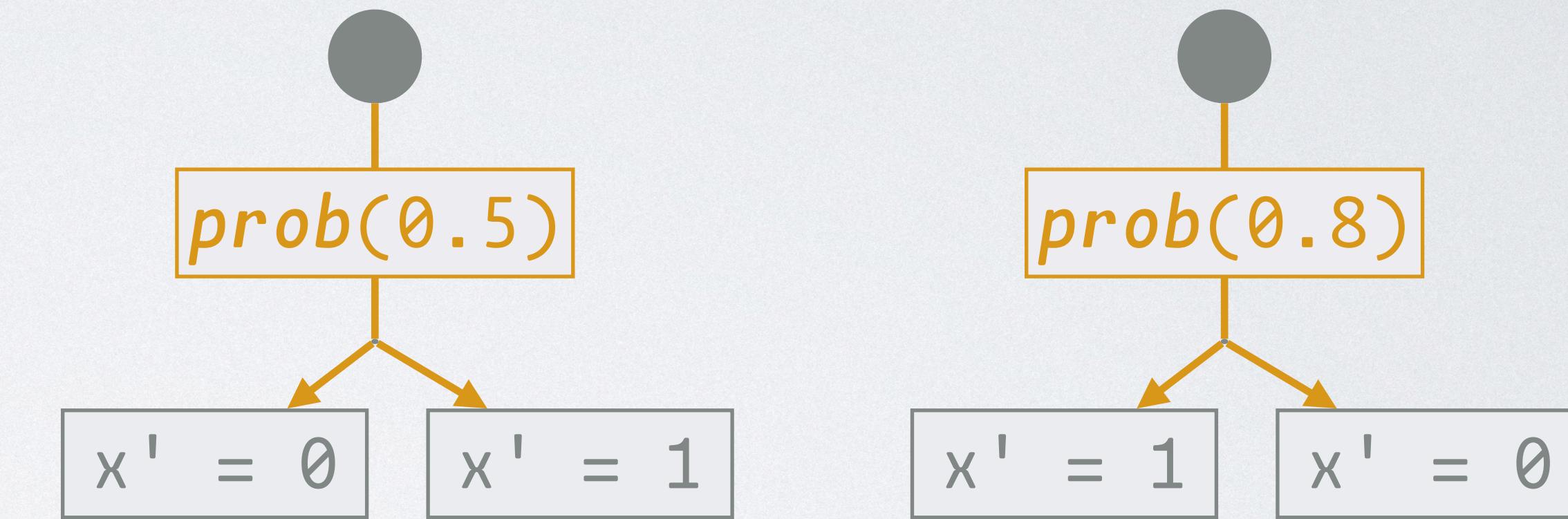
- ◆ A **hyper-path** represents a **distribution on paths**
- ◆ **Nondeterminism** is modeled by **collections** of hyper-paths

# HYPER-PATH SEMANTICS

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then
    x := 0
  else
    x := 1
  fi
else
  if prob(0.8) then
    x := 1
  else
    x := 0
  fi
fi
```

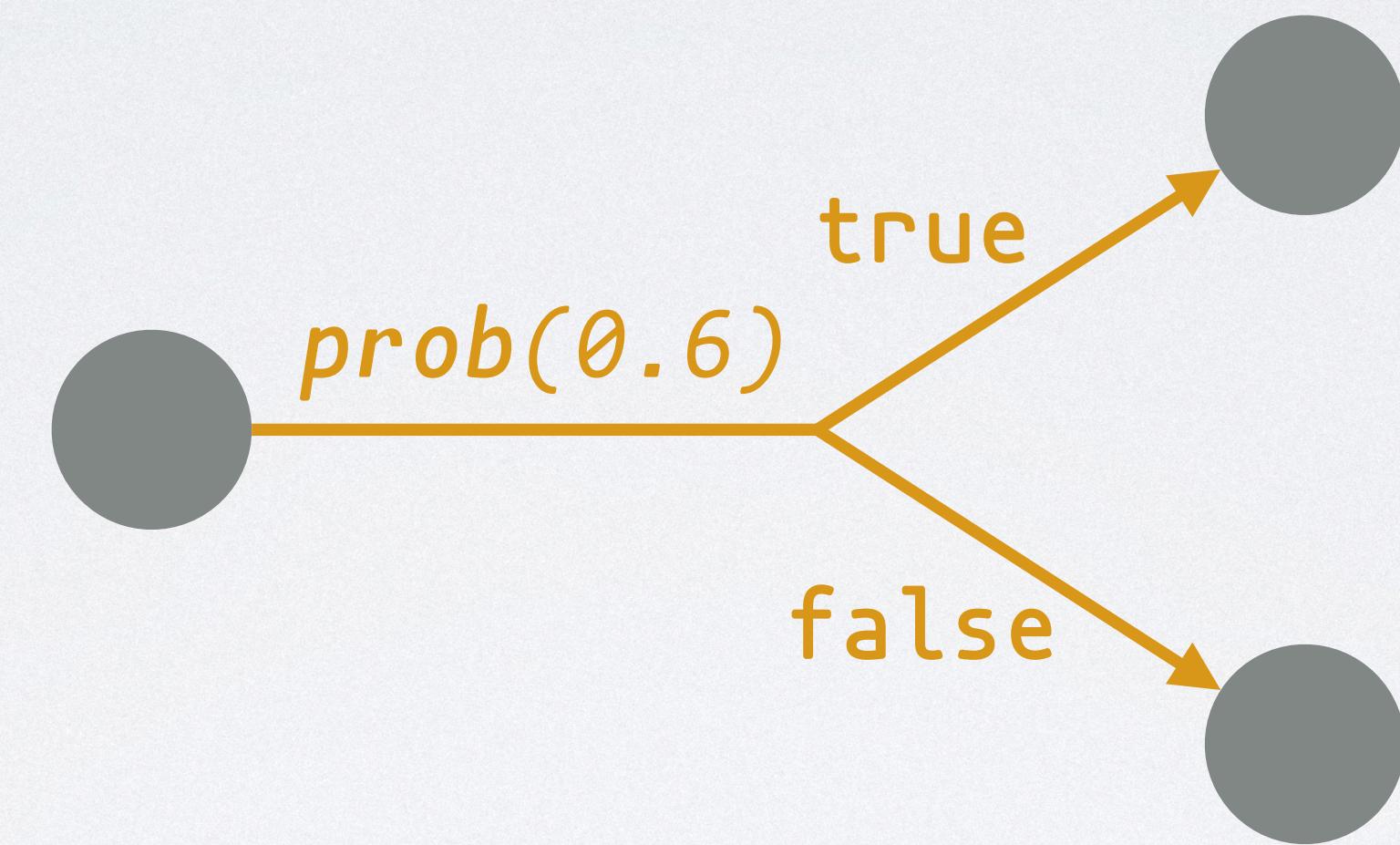
- ◆ **prob()** introduces **distributions on executions**, and \*
- collects such distributions



- ◆ A **hyper-path** represents a **distribution on paths**
- ◆ **Nondeterminism** is modeled by **collections** of hyper-paths
- ◆ **Kleene algebras** are suitable for path semantics, but are **not** suitable for hyper-path semantics

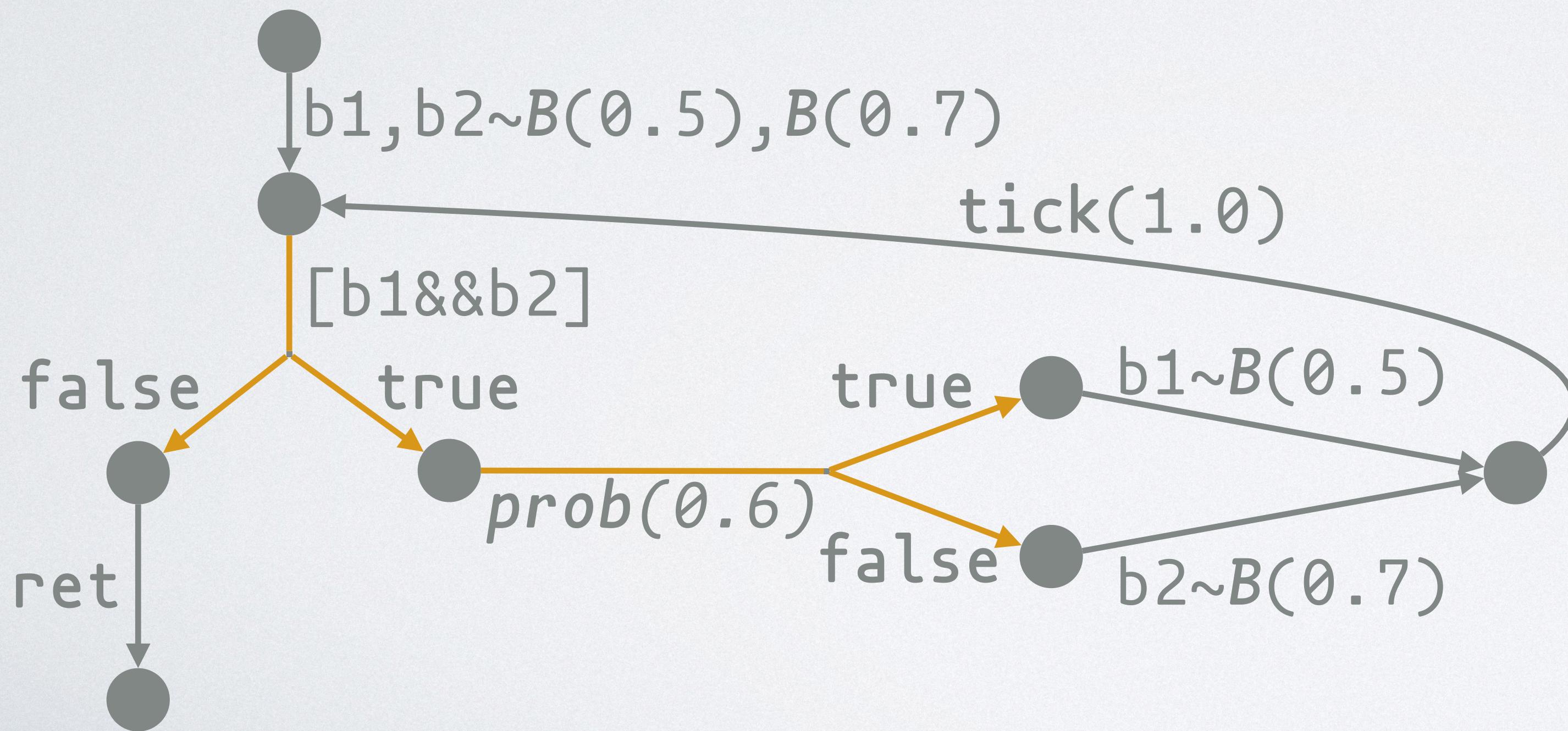
# CONTROL-FLOW HYPER-GRAPHS (CFHGs)

A **hyper**-edge can have multiple destinations



# CONTROL-FLOW HYPER-GRAPHS (CFHGs)

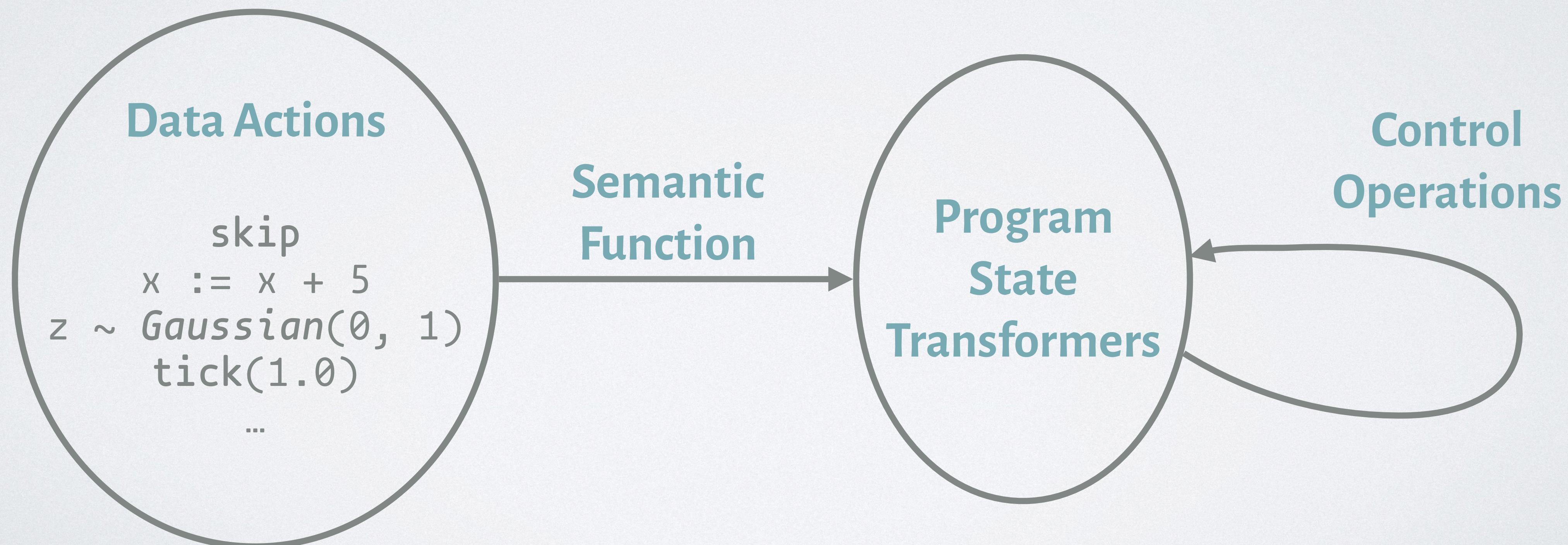
- Directed graphs with **hyper**-edges
- Branching are **hyper**-edges
- Support nondeterminism, unstructured control flow, and recursion



```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```

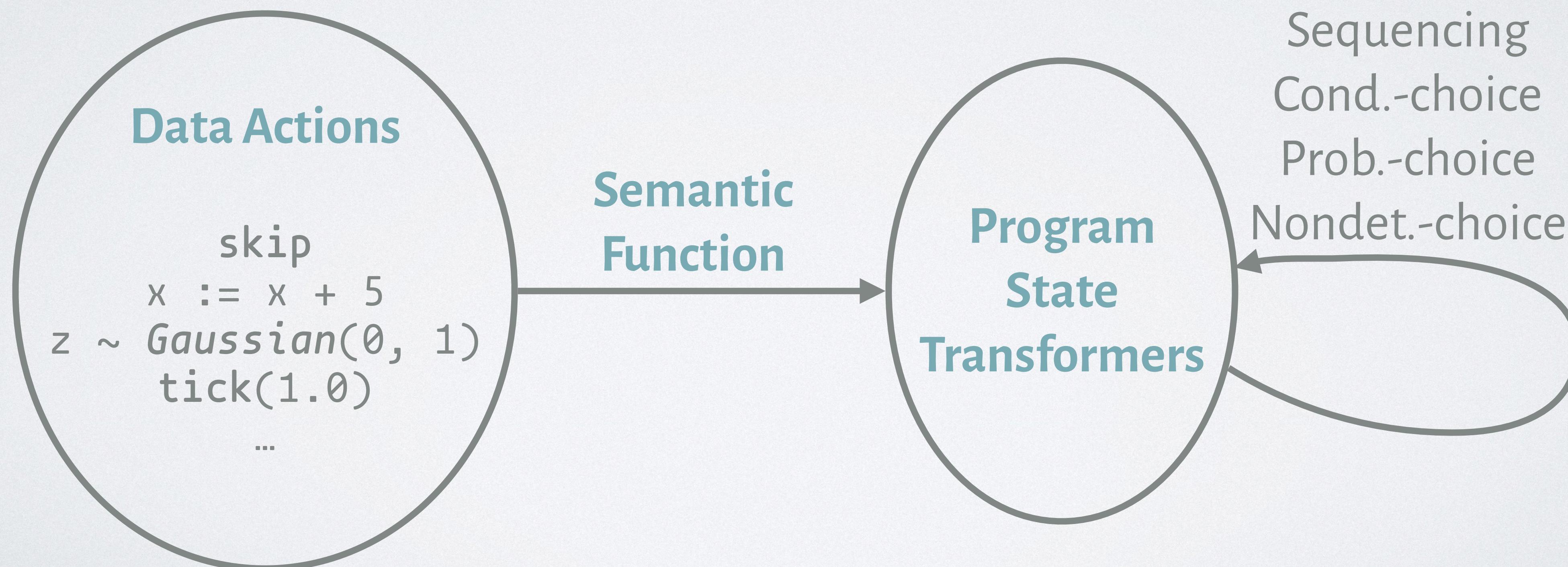
# AN ALGEBRAIC DENOTATIONAL SEMANTICS

- ◆ Perform reasoning in some abstract space of program-state transformers
- ◆ The transformers and associated operations obey some algebraic laws



# AN ALGEBRAIC DENOTATIONAL SEMANTICS

- ◆ Perform reasoning in some abstract space of program-state transformers
- ◆ The transformers and associated operations obey some algebraic laws



# MARKOV ALGEBRAS

- ◆ Characterize state transformers and associated operations by **algebraic laws**

$$\left\langle M, \sqsubseteq, \otimes, {}_\varphi\Diamond, \vdash, \perp, 1 \right\rangle$$

# MARKOV ALGEBRAS

- Characterize state transformers and associated operations by **algebraic laws**

$$\left\langle M, \sqsubseteq, \otimes, \varphi^\diamond, \vdash, \perp, 1 \right\rangle$$



Program state transformers  
form a complete partial order

# MARKOV ALGEBRAS

- Characterize state transformers and associated operations by **algebraic laws**

$$\left\langle M, \sqsubseteq, \otimes, \varphi^\diamond, \wp, \perp, 1 \right\rangle$$

Program state transformers  
form a complete partial order

Sequencing, branching (cond.  
and prob.), and nondet.-choice

# MARKOV ALGEBRAS

- Characterize state transformers and associated operations by **algebraic laws**

$$\left\langle M, \sqsubseteq, \otimes, \varphi^\diamond, \wp, \perp, 1 \right\rangle$$

A diagram illustrating the components of a Markov Algebra. At the top, there is a set enclosed in black brackets:  $\left\langle M, \sqsubseteq, \otimes, \varphi^\diamond, \wp, \perp, 1 \right\rangle$ . A horizontal green line passes through the middle of the set. Below the set, three green arrows point downwards to the corresponding elements:  $M$  points to "Program state transformers form a complete partial order";  $\varphi^\diamond$  points to "Sequencing, branching (cond. and prob.), and nondet.-choice"; and  $1$  points to "The bottom element and the identity element". A single green arrow also points downwards from the entire set to the text in the center.

Program state transformers  
form a complete partial order

Sequencing, branching (cond.  
and prob.), and nondet.-choice

The bottom element  
and the identity element  
 $\perp$  interprets `abort`  
 $1$  interprets `skip`

# MARKOV ALGEBRAS

- Characterize state transformers and associated operations by **algebraic laws**

$$\left\langle M, \sqsubseteq, \otimes, \varphi^\diamond, \wp, \perp, 1 \right\rangle$$

Program state transformers  
form a complete partial order

Sequencing, branching (cond.  
and prob.), and nondet.-choice

# MARKOV ALGEBRAS

- Characterize state transformers and associated operations by **algebraic laws**

$$\left\langle M, \sqsubseteq, \otimes, \varphi^\diamond, \wp, \perp, 1 \right\rangle$$

Program state transformers  
form a complete partial order

Sequencing, branching (cond.  
and prob.), and nondet.-choice

$$(a \otimes b) \otimes c = a \otimes (b \otimes c)$$

$$a \otimes 1 = 1 \otimes a$$

$$a \varphi^\diamond b = b \negvarphi^\diamond a$$

$$a \wp a = a$$

$\otimes, \varphi^\diamond, \wp$  continuous w.r.t.  $\sqsubseteq$

...

# A NEW MODEL FOR RESOLVING NONDETERMINISM

# A NEW MODEL FOR RESOLVING NONDETERMINISM

- We want to resolve nondeterminacy **among state transformers** instead of states

```
if prob(*) then t := t + 1 else t := t - 1 fi
```

# A NEW MODEL FOR RESOLVING NONDETERMINISM

- We want to resolve nondeterminacy **among state transformers** instead of states

```
if prob(*) then t := t + 1 else t := t - 1 fi
```

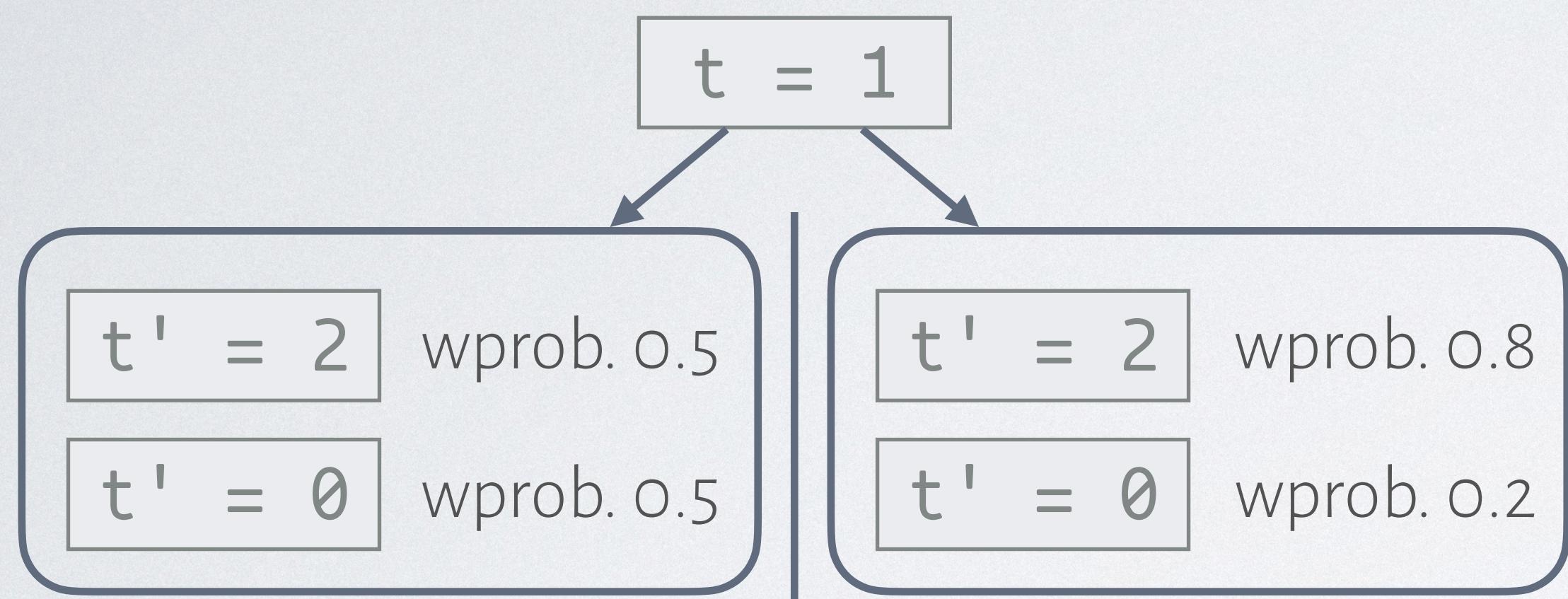
```
t = 1
```

\* resolved **after** t is given

# A NEW MODEL FOR RESOLVING NONDETERMINISM

- We want to resolve nondeterminacy **among state transformers** instead of states

```
if prob(*) then t := t + 1 else t := t - 1 fi
```

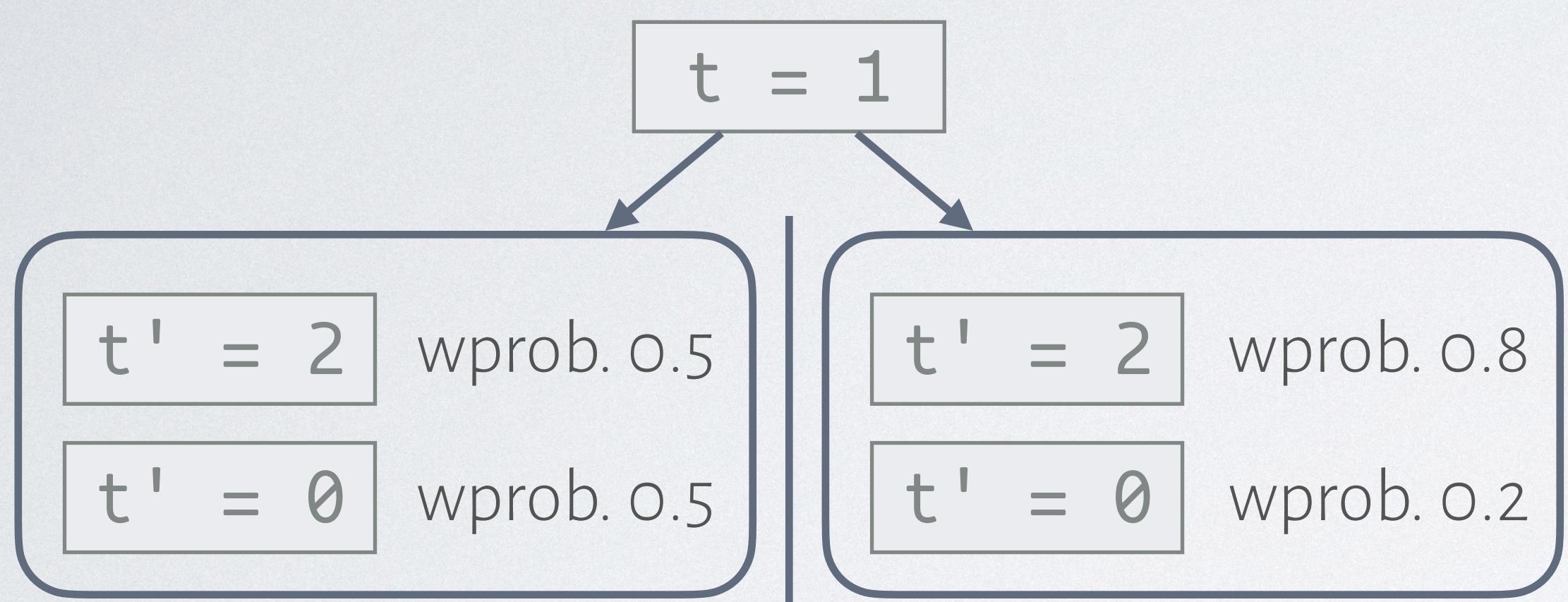


\* resolved **after**  $t$  is given

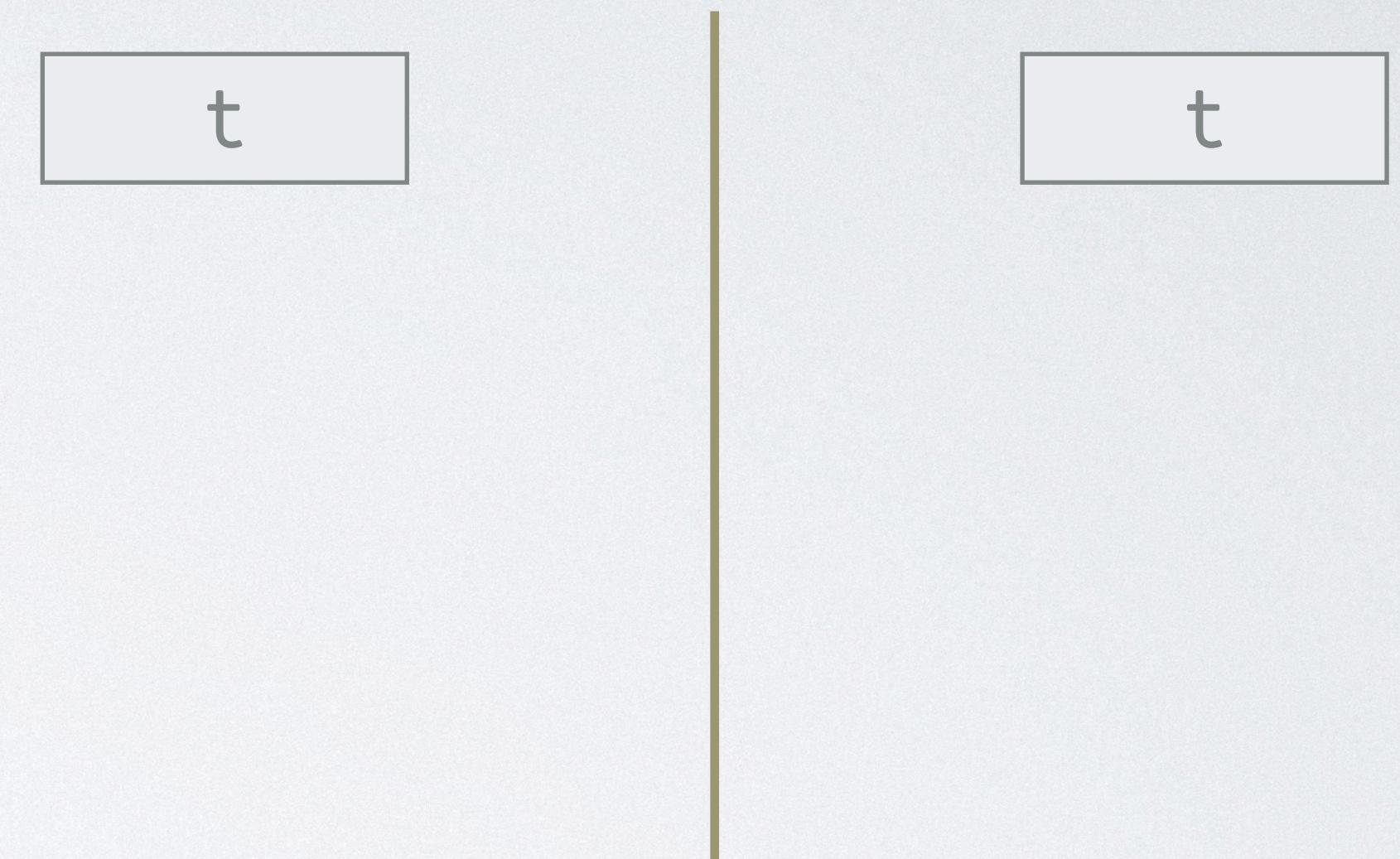
# A NEW MODEL FOR RESOLVING NONDETERMINISM

- We want to resolve nondeterminacy **among state transformers** instead of states

```
if prob(*) then t := t + 1 else t := t - 1 fi
```



\* resolved **after**  $t$  is given

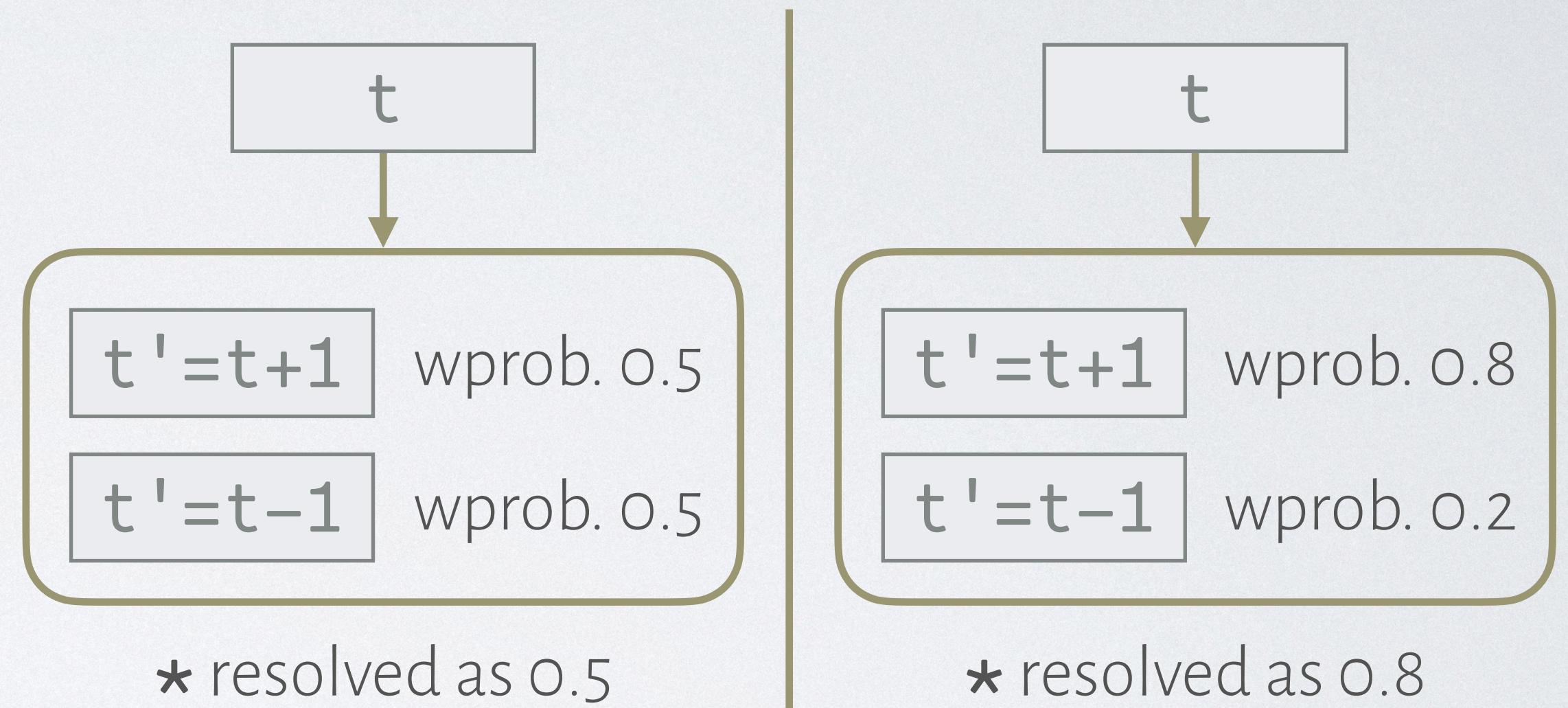
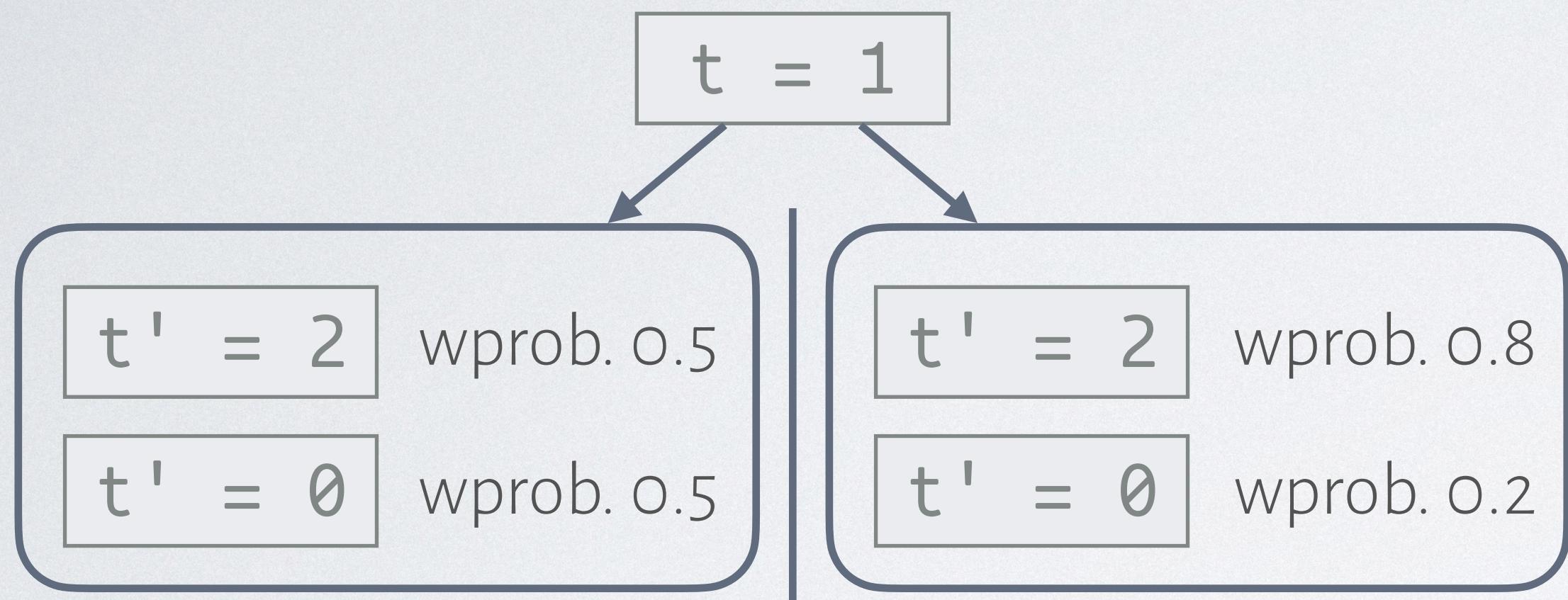


\* resolved **before**  $t$  is given

# A NEW MODEL FOR RESOLVING NONDETERMINISM

- We want to resolve nondeterminacy **among state transformers** instead of states

```
if prob(*) then t := t + 1 else t := t - 1 fi
```



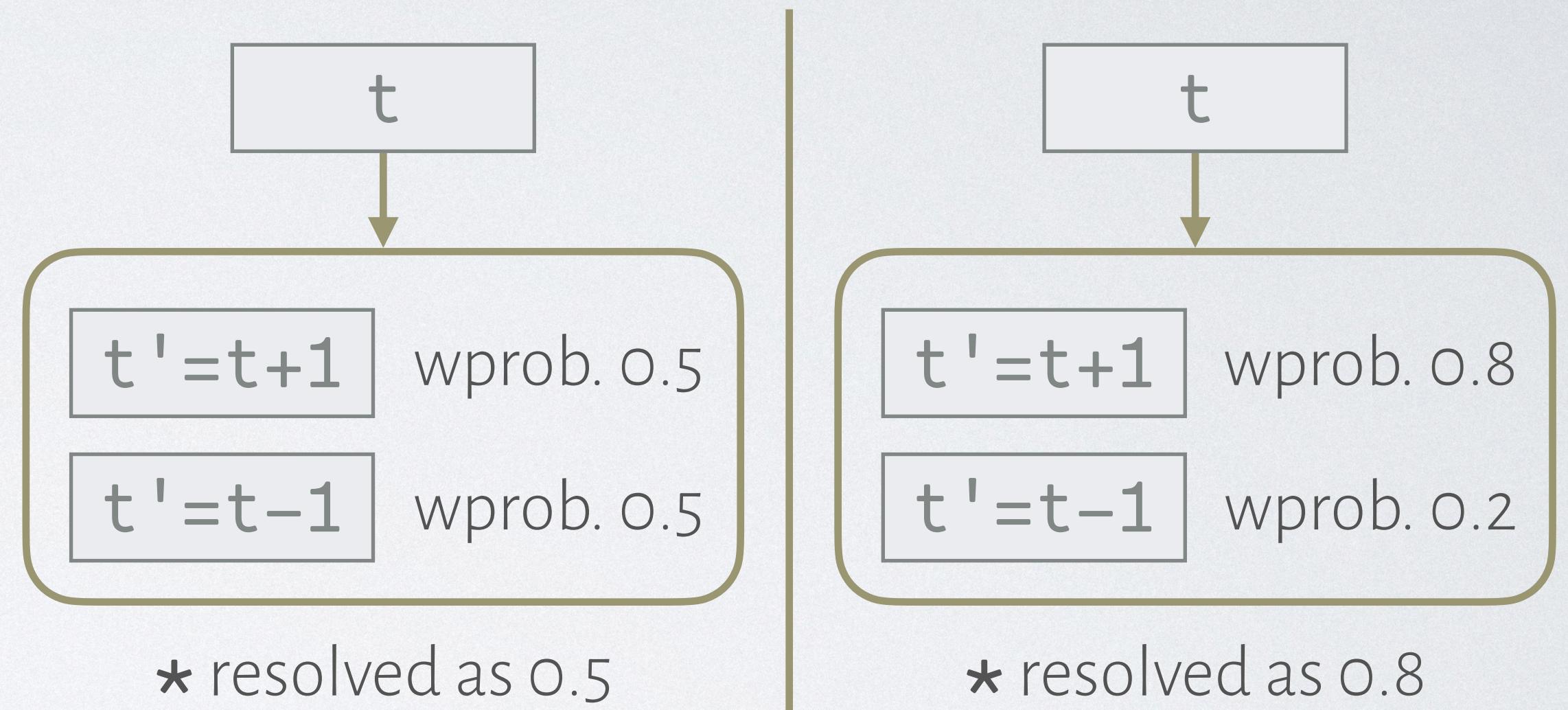
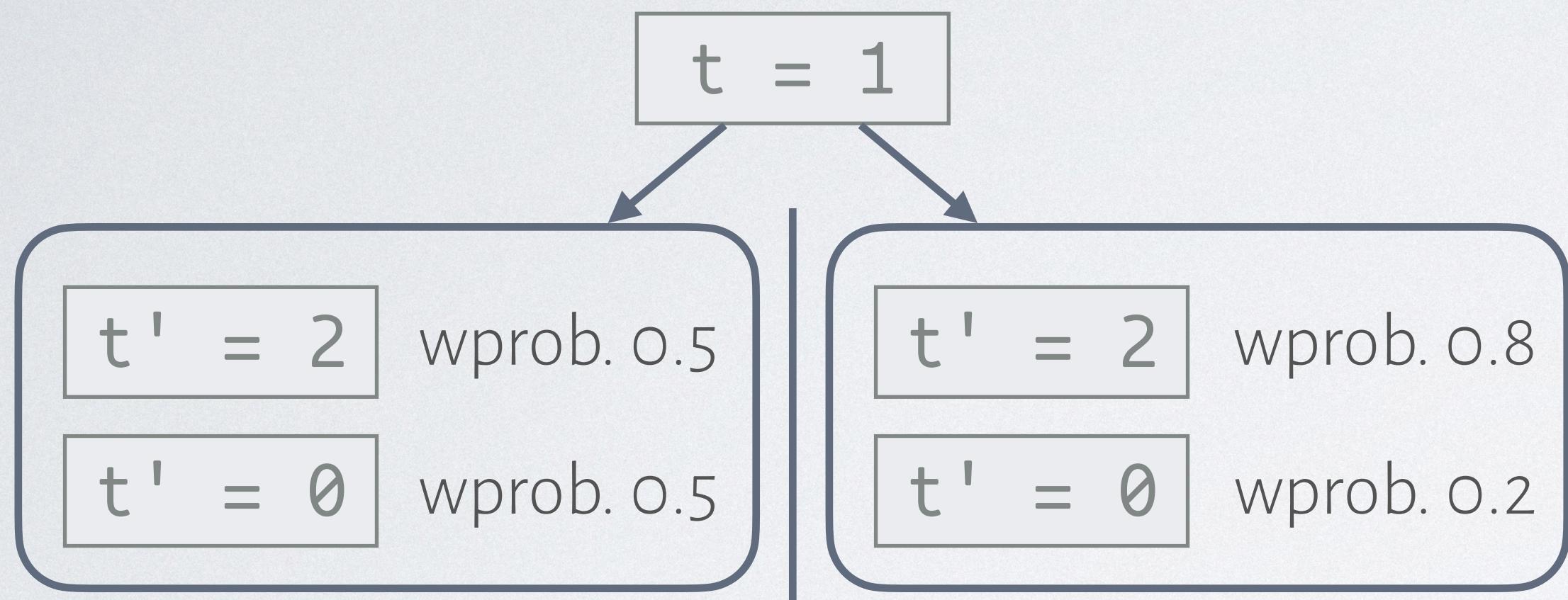
\* resolved **after**  $t$  is given

\* resolved **before**  $t$  is given

# A NEW MODEL FOR RESOLVING NONDETERMINISM

- We want to resolve nondeterminacy **among state transformers** instead of states

```
if prob(*) then t := t + 1 else t := t - 1 fi
```



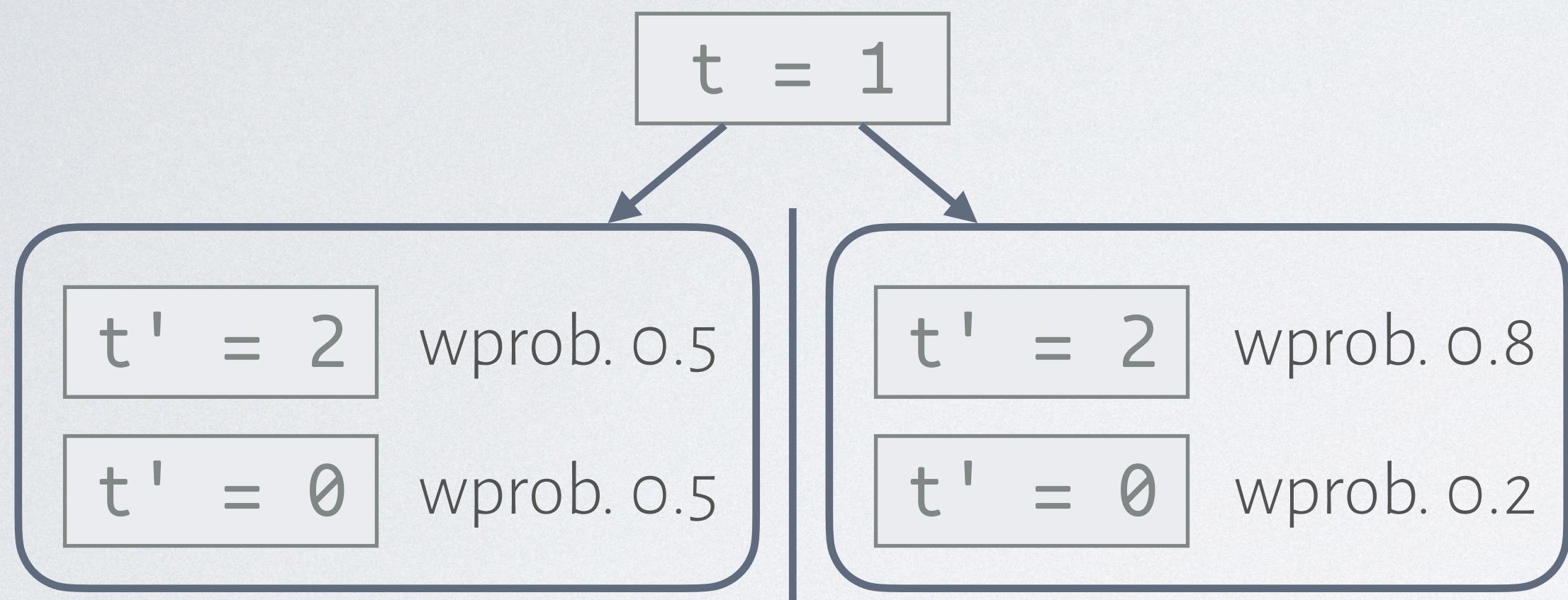
\* resolved **after**  $t$  is given

$M := \text{State} \rightarrow \wp(\text{Dist(State)})$

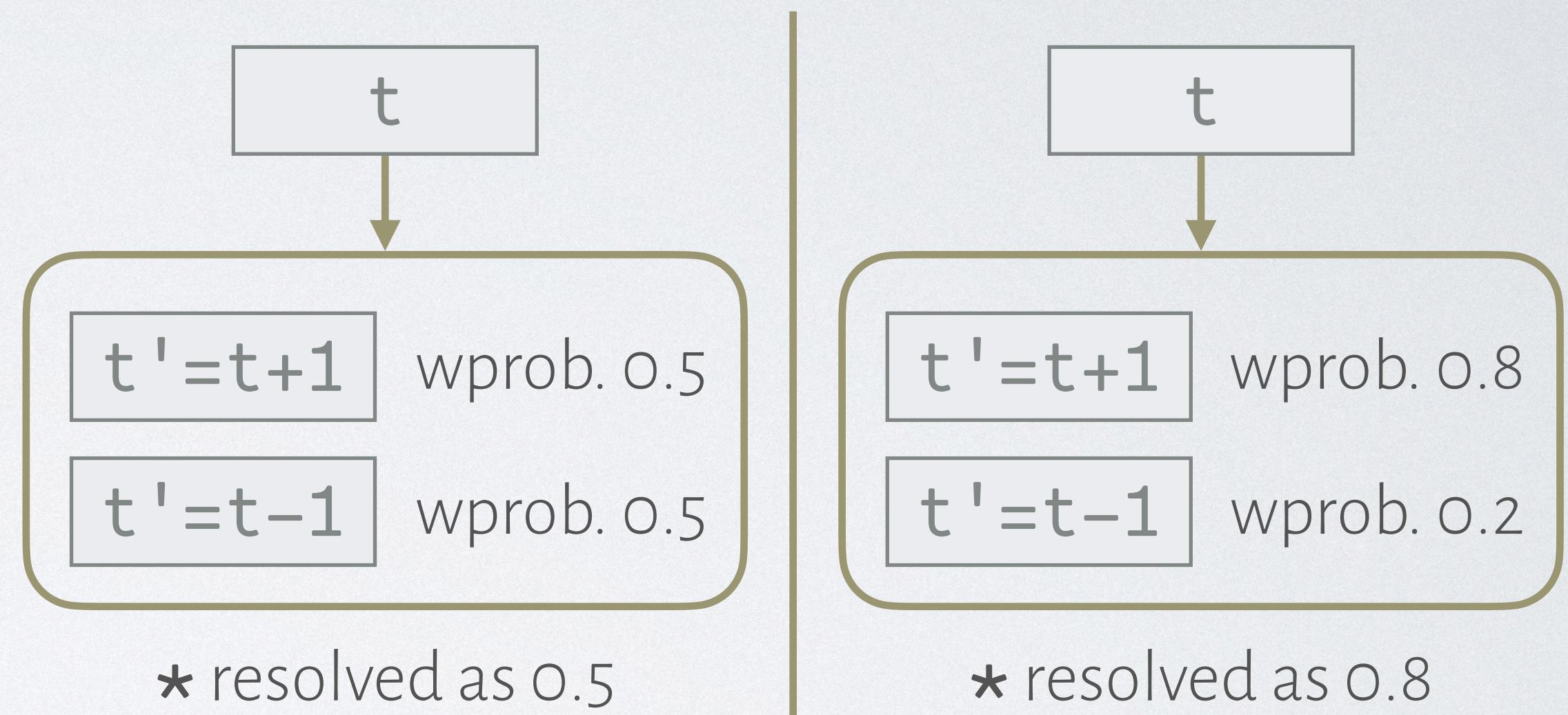
# A NEW MODEL FOR RESOLVING NONDETERMINISM

- We want to resolve nondeterminacy **among state transformers** instead of states

```
if prob(*) then t := t + 1 else t := t - 1 fi
```



\* resolved **after**  $t$  is given

$$M := \text{State} \rightarrow \wp(\text{Dist(State)})$$


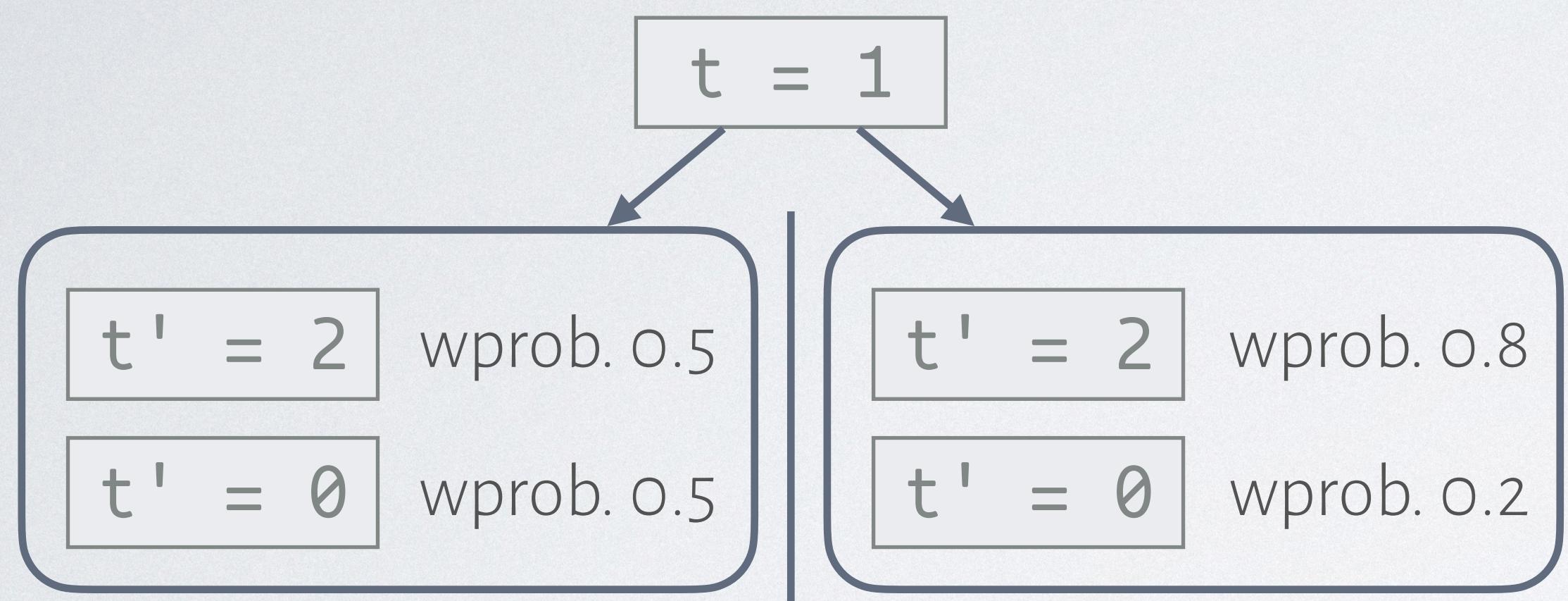
\* resolved **before**  $t$  is given

$$M := \wp(\text{State} \rightarrow \text{Dist(State)})$$

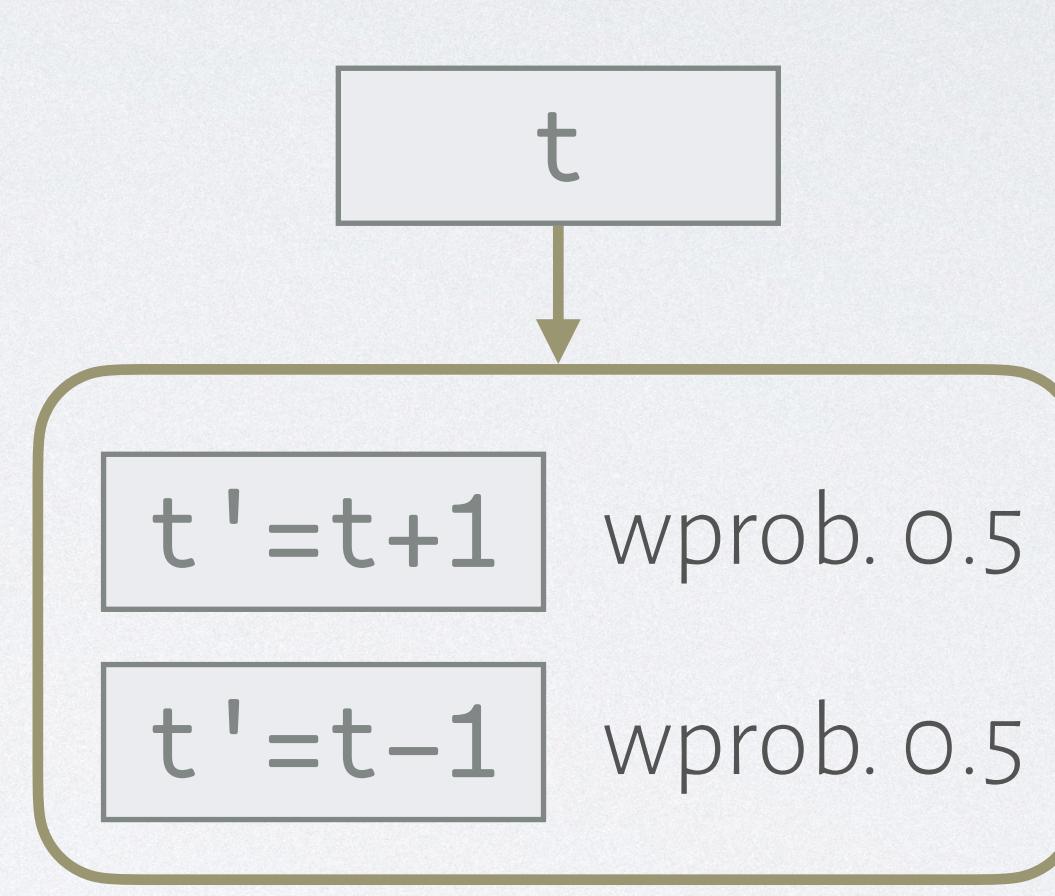
# A NEW MODEL FOR RESOLVING NONDETERMINISM

- ◆ We want to resolve nondeterminacy **among state transformers** instead of states

```
if prob(*) then t := t + 1 else t := t - 1 fi
```

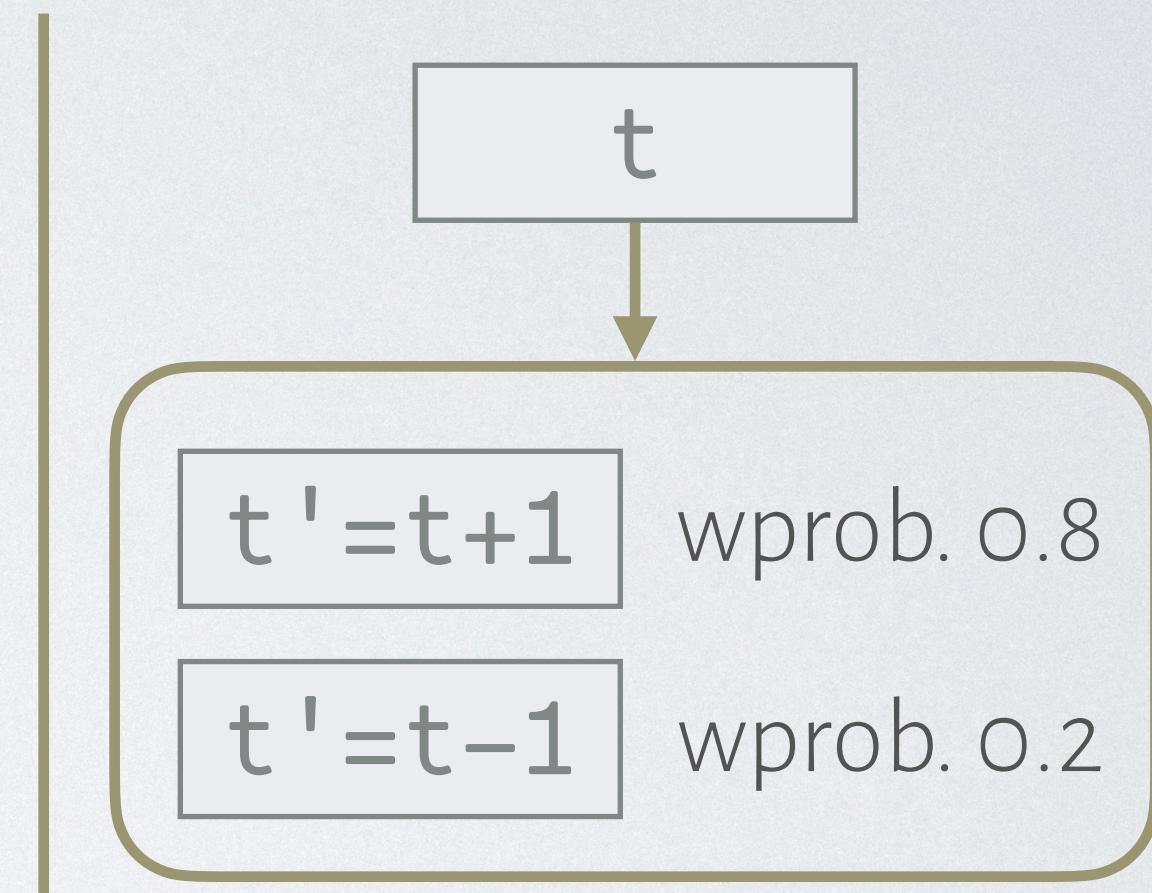


\* resolved after t is given



resolved as 0.5

\* resolved before t is given



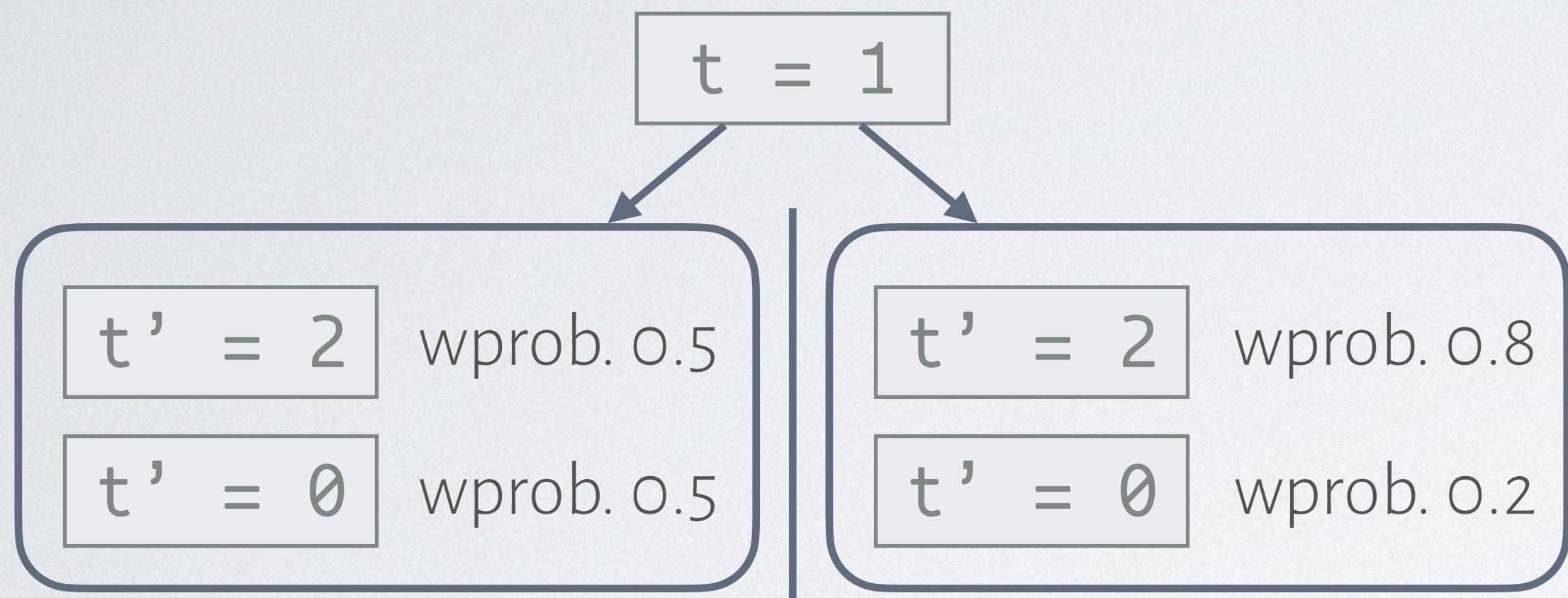
\* resolved as 0.8

- ◆ **Relational reasoning:** for any concretization  $P$  of the program, for any inputs  $t_1, t_2$ , it holds that  $\mathbb{E}_{t'_1 \sim P(t_1), t'_2 \sim P(t_2)}[t'_1 - t'_2] = t_1 - t_2$

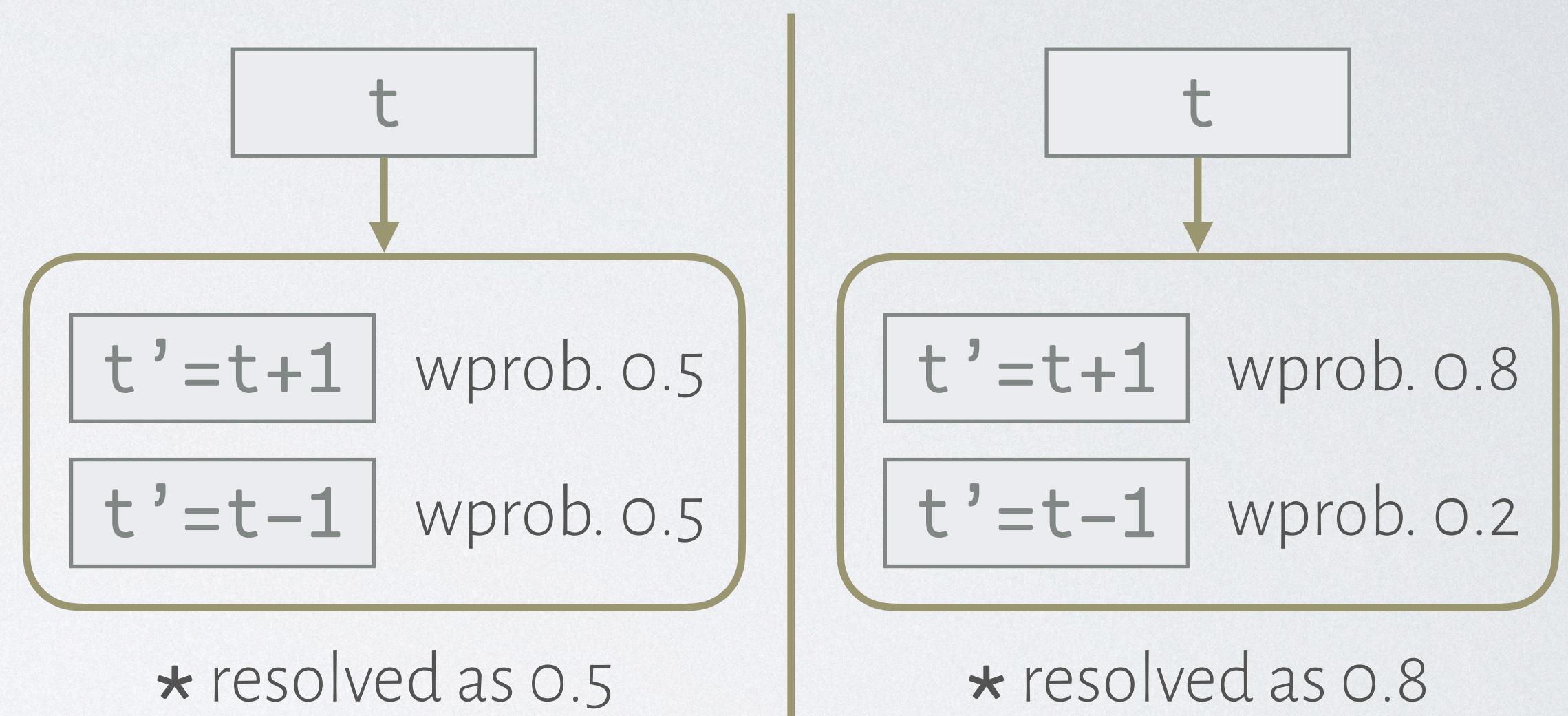
# A NEW MODEL FOR RESOLVING NONDETERMINISM

- We want to resolve nondeterminacy **among state transformers** instead of states

```
if prob(*) then t := t + 1 else t := t - 1 fi
```



\* resolved **after** `t` is given



\* resolved as 0.5

\* resolved as 0.8

- We developed a domain-theoretic characterization of the **nondeterminism-first** resolution

# OVERVIEW

- ❑ Motivation
- ❑ An Algebraic Denotational Semantics
- ❑ Pre-Markov Algebra Framework (PMAF)

# PRE-MARKOV ALGEBRA FRAMEWORK (PMAF)

## Contributions

- ◆ An **algebraic framework** for **interprocedural dataflow analysis** of **first-order probabilistic programs**
- ◆ Published as PMAF: An Algebraic Framework for Static Analysis of Probabilistic Programs in *PLDI'18*



Recursion  
Unstructured control-flow  
Divergence  
Nondeterminism

...

# PRE-MARKOV ALGEBRA FRAMEWORK (PMAF)

## Contributions

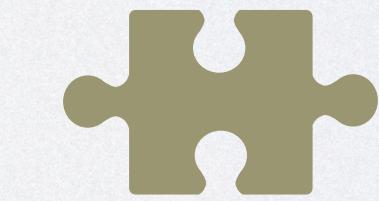
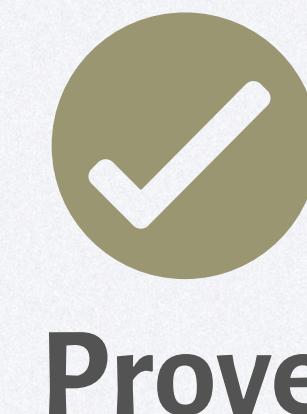
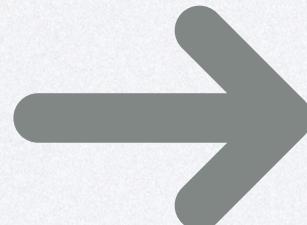
- ◆ An **algebraic framework** for **interprocedural dataflow analysis** of **first-order probabilistic programs**
- ◆ Published as PMAF: An Algebraic Framework for Static Analysis of Probabilistic Programs in *PLDI'18*



# PRE-MARKOV ALGEBRA FRAMEWORK (PMAF)

## Contributions

- ◆ An **algebraic framework** for **interprocedural dataflow analysis** of **first-order probabilistic programs**
- ◆ Published as PMAF: An Algebraic Framework for Static Analysis of Probabilistic Programs in *PLDI'18*



**Implement**

# PRE-MARKOV ALGEBRA FRAMEWORK (PMAF)

## Contributions

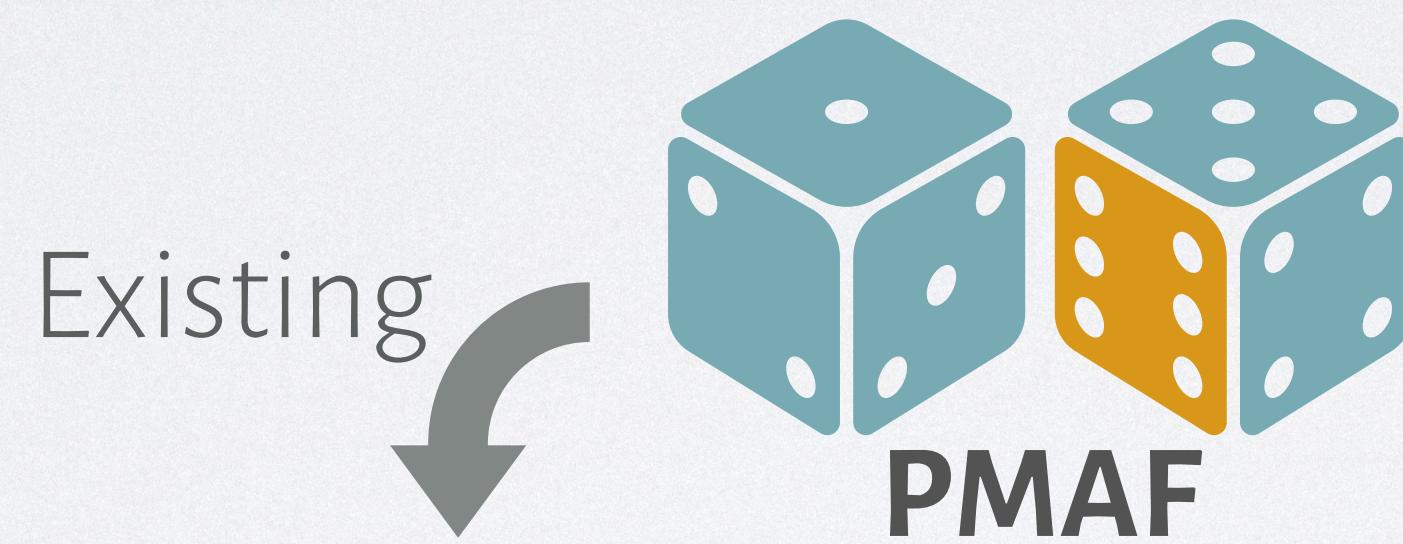
- ◆ An **algebraic framework** for **interprocedural dataflow analysis** of **first-order probabilistic programs**
- ◆ Published as PMAF: An Algebraic Framework for Static Analysis of Probabilistic Programs in *PLDI'18*



# PRE-MARKOV ALGEBRA FRAMEWORK (PMAF)

## Contributions

- ◆ An **algebraic framework** for **interprocedural dataflow analysis** of **first-order probabilistic programs**
- ◆ Published as PMAF: An Algebraic Framework for Static Analysis of Probabilistic Programs in *PLDI'18*

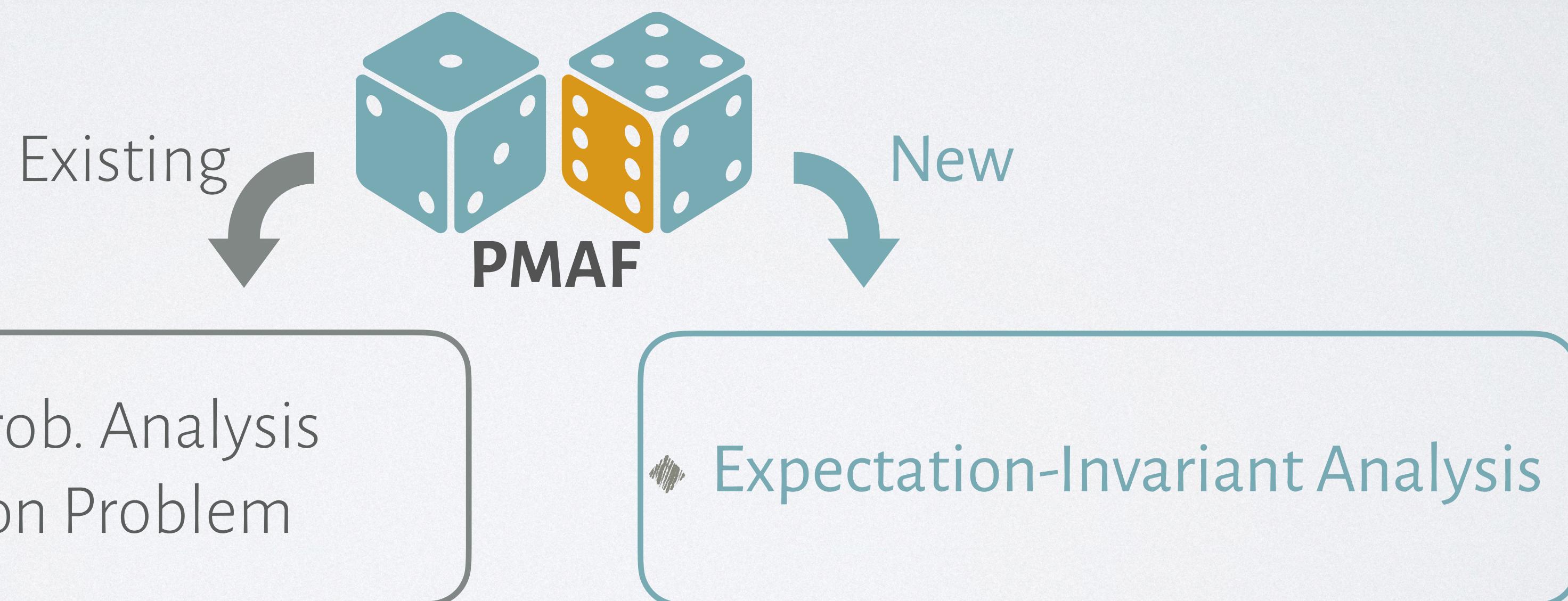


- ◆ Reachability Prob. Analysis
- ◆ Markov Decision Problem

# PRE-MARKOV ALGEBRA FRAMEWORK (PMAF)

## Contributions

- ◆ An **algebraic framework** for **interprocedural dataflow analysis** of **first-order probabilistic programs**
- ◆ Published as PMAF: An Algebraic Framework for Static Analysis of Probabilistic Programs in *PLDI'18*



# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

tick(q) increases  $T$  by q

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then
else
  if prob(0.5) then
fi
```

tick(q) increases  $T$  by q

```
  tick(1.0) else tick(2.0) fi
  tick(1.0) else tick(2.0) fi
```

with prob.  $\frac{1}{4}$

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

tick(q) increases  $T$  by q

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

tick(q) increases  $T$  by q

with prob.  $\frac{1}{4}$

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

tick(q) increases  $T$  by q

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

tick(q) increases  $T$  by q

with prob.  $\frac{1}{4}$

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

tick(q) increases  $T$  by q

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

tick(q) increases  $T$  by q

with prob.  $\frac{1}{4}$

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

tick(q) increases  $T$  by q

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

tick(q) increases  $T$  by q

- ◆ Their concrete semantics yields

$$\mathbb{E}[T] \in \frac{1}{4} \cdot \{1\} + \frac{1}{4} \cdot \{2\} + \frac{1}{4} \cdot \{1,2\} + \frac{1}{4} \cdot \{1,2\} = \{1.25, 1.5, 1.75\}$$

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

tick(q) increases  $T$  by q

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

Identical!

- ◆ Their concrete semantics yields

$$\mathbb{E}[T] \in \frac{1}{4} \cdot \{1\} + \frac{1}{4} \cdot \{2\} + \frac{1}{4} \cdot \{1,2\} + \frac{1}{4} \cdot \{1,2\} = \{1.25, 1.5, 1.75\}$$

# WHY NOT PROBABILISTIC ABSTRACT INTERPRETATION?

\* denotes nondeterministic-choice

tick(q) increases  $T$  by q

```
if * then
  if prob(0.5) then tick(1.0) else tick(2.0) fi
else
  if prob(0.5) then tick(1.0) else tick(2.0) fi
fi
```

Identical!

- ◆ Their concrete semantics yields

$$\mathbb{E}[T] \in \frac{1}{4} \cdot \{1\} + \frac{1}{4} \cdot \{2\} + \frac{1}{4} \cdot \{1,2\} + \frac{1}{4} \cdot \{1,2\} = \{1.25, 1.5, 1.75\}$$

whereas our semantics yields  $\mathbb{E}[T] = 1.5$

# EXAMPLE ANALYSES

```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
    if prob(0.6) then
        b1 ~ Bernoulli(0.5)
    else
        b2 ~ Bernoulli(0.7)
    fi;
    tick(1.0)
od;
return (b1, b2)
```

# EXAMPLE ANALYSES

- ◆ Our **framework** can be instantiated to **prove**:

```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```

# EXAMPLE ANALYSES

- ◆ Our **framework** can be instantiated to **prove**:
- ◆ the probability that **b1** and **b2** are both **false** at the end of the program = 0.15

```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```

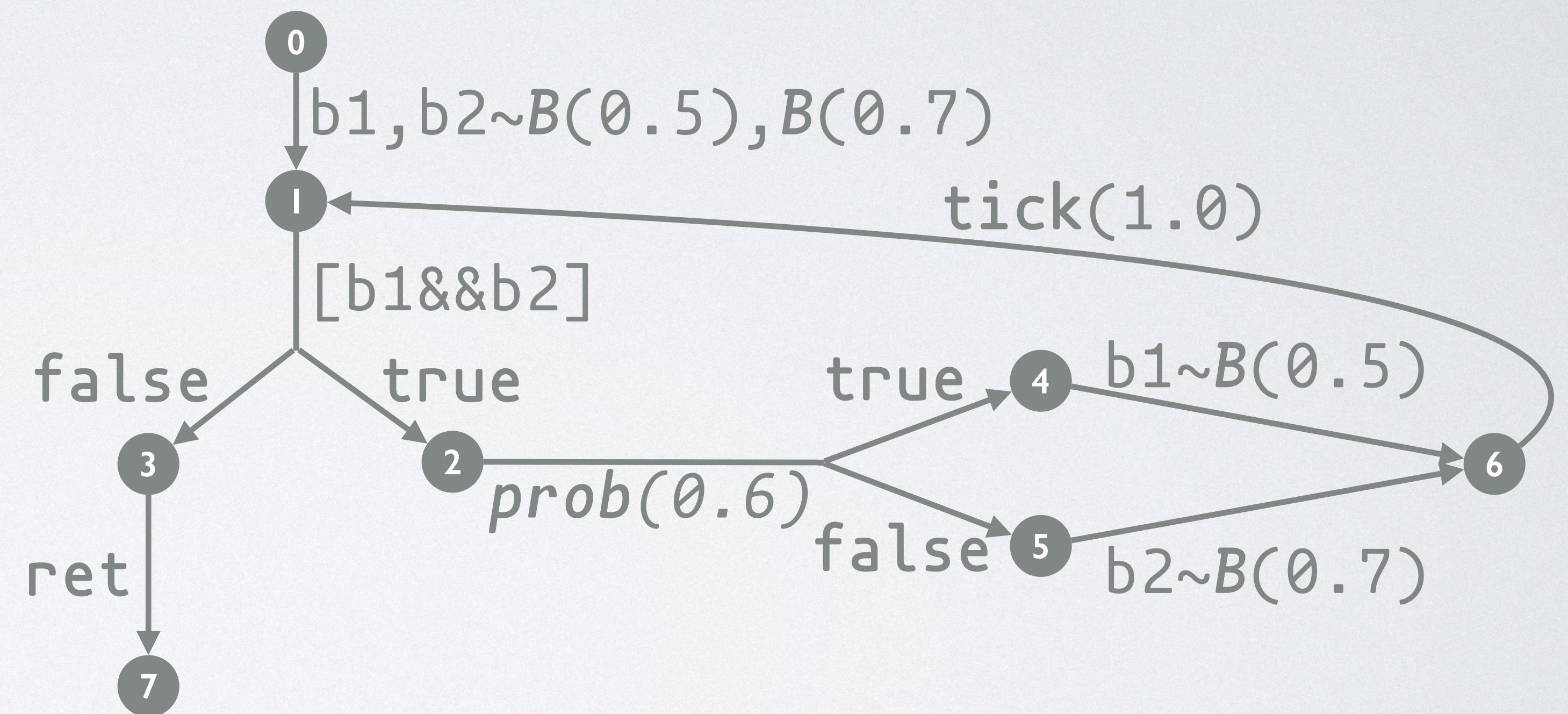
# EXAMPLE ANALYSES

- ◆ Our **framework** can be instantiated to **prove**:
- ◆ the probability that **b1** and **b2** are both **false** at the end of the program = 0.15
- ◆ the expected termination time (ticks) = 5/6

```
b1 ~ Bernoulli(0.5);
b2 ~ Bernoulli(0.7);
while (b1 && b2) do
  if prob(0.6) then
    b1 ~ Bernoulli(0.5)
  else
    b2 ~ Bernoulli(0.7)
  fi;
  tick(1.0)
od;
return (b1, b2)
```

# HYPER-GRAPH SEMANTICS

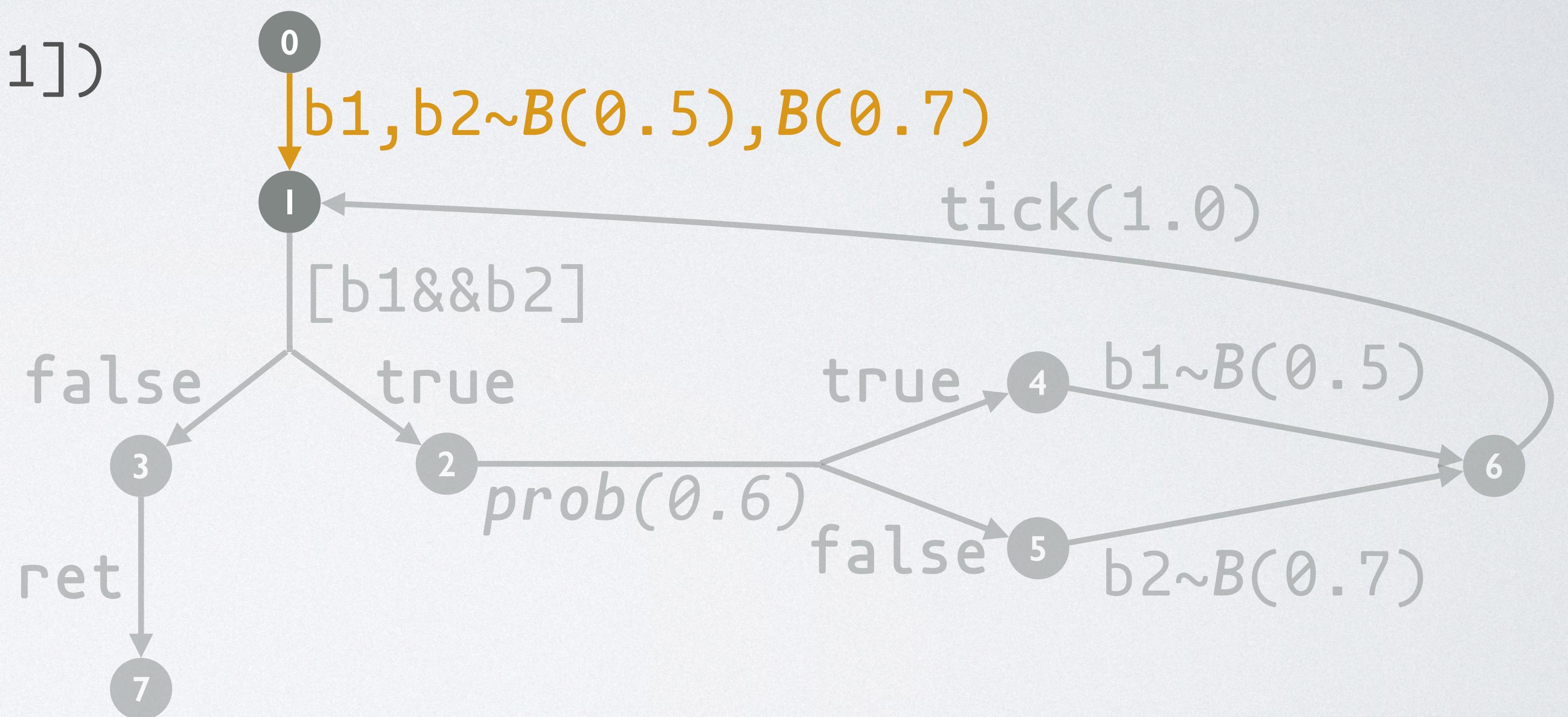
- The hyper-graph semantics is formulated by an equation system



# HYPER-GRAFH SEMANTICS

- The hyper-graph semantics is formulated by an equation system

$s[0] = \text{seq}[b1, b2 \sim B(0.5), B(0.7)](s[1])$

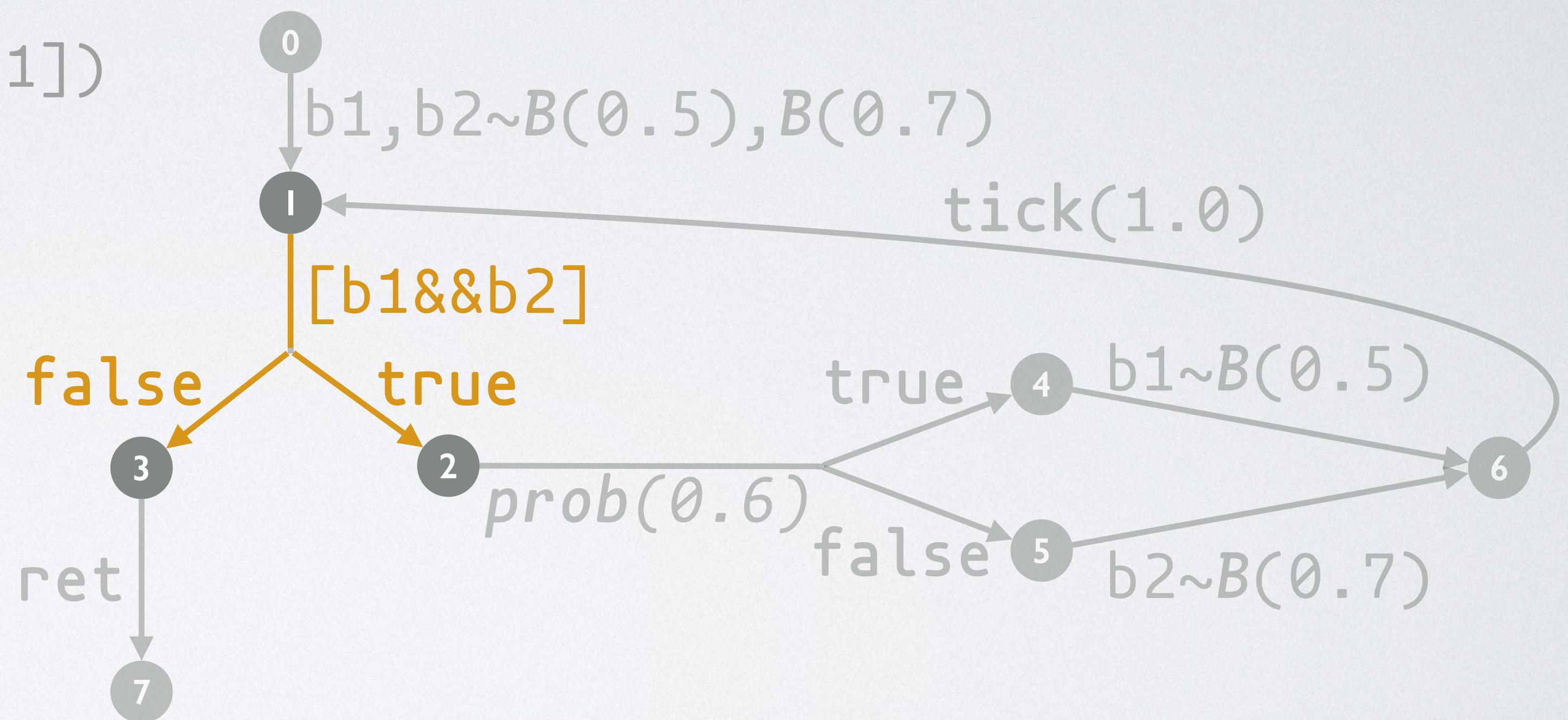


# HYPER-GRAF SEMANTICS

- The hyper-graph semantics is formulated by an equation system

$S[0] = \text{seq}[b1, b2 \sim B(0.5), B(0.7)](S[1])$

$S[1] = \text{cond}[b1 \& \& b2](S[2], S[3])$



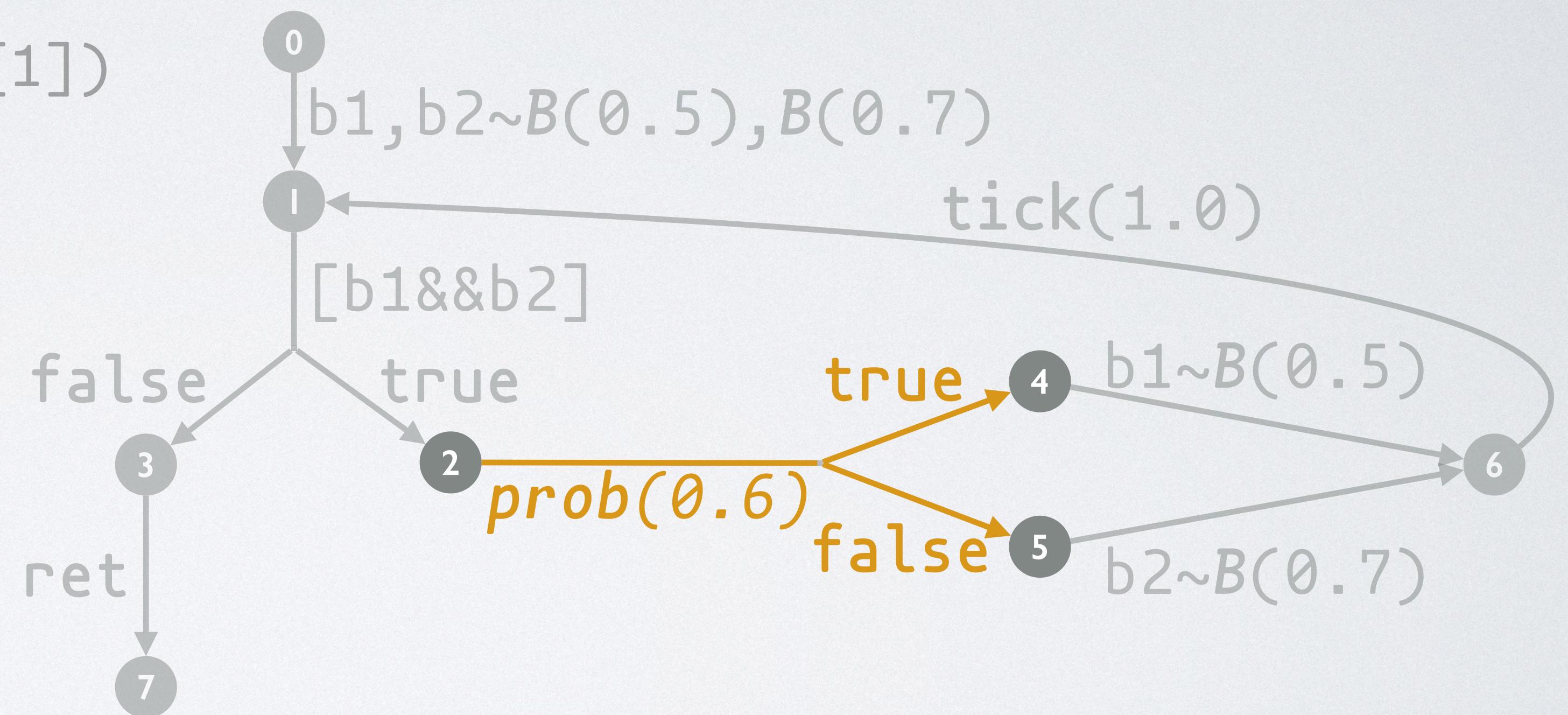
# HYPER-GRAFH SEMANTICS

- The hyper-graph semantics is formulated by an equation system

$S[0] = \text{seq}[b1, b2 \sim B(0.5), B(0.7)](S[1])$

$S[1] = \text{cond}[b1 \& b2](S[2], S[3])$

$S[2] = \text{prob}[0.6](S[4], S[5])$



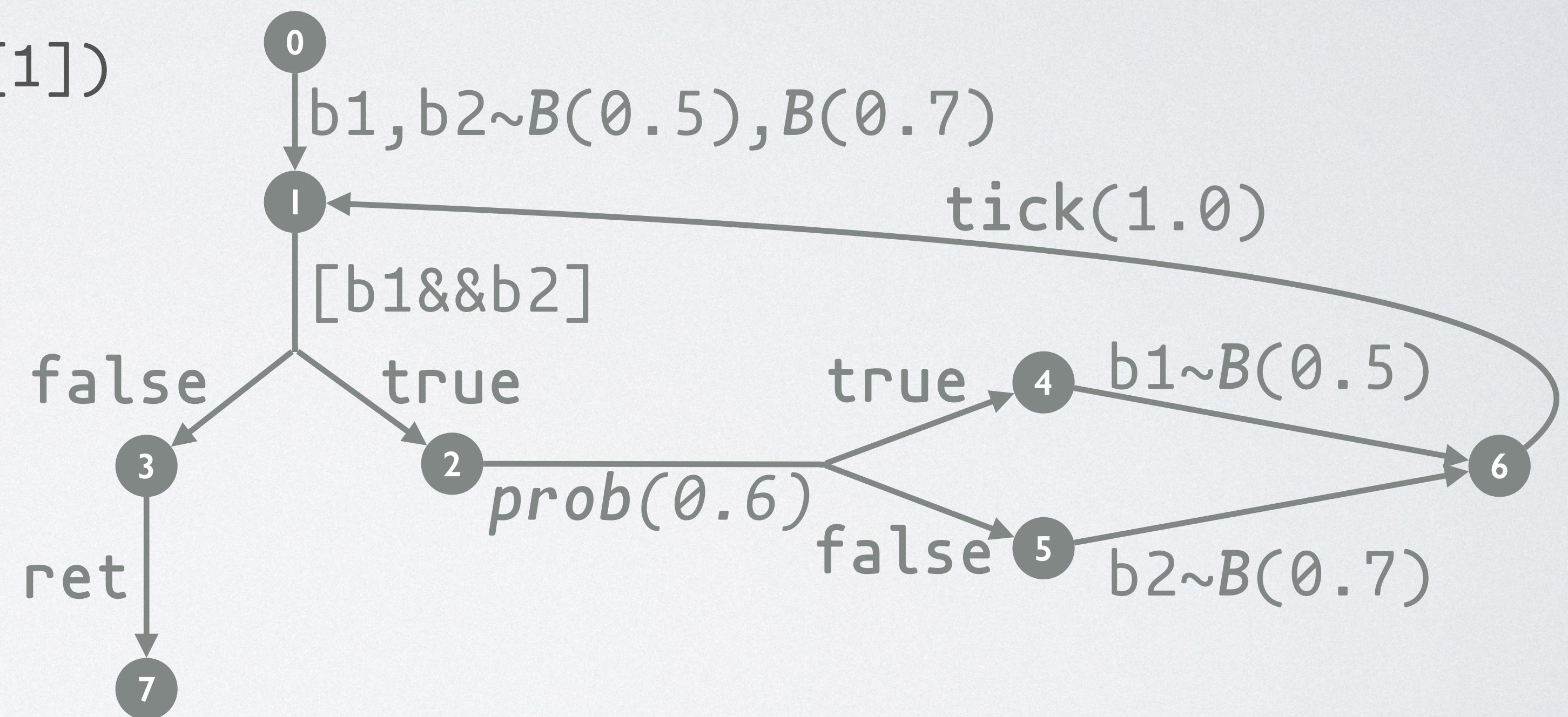
# HYPER-GRAF SEMANTICS

- The hyper-graph semantics is formulated by an equation system

$S[0] = \text{seq}[b1, b2 \sim B(0.5), B(0.7)](S[1])$

$S[1] = \text{cond}[b1 \& \& b2](S[2], S[3])$

$S[2] = \text{prob}[0.6](S[4], S[5])$



# HYPER-GRAF SEMANTICS

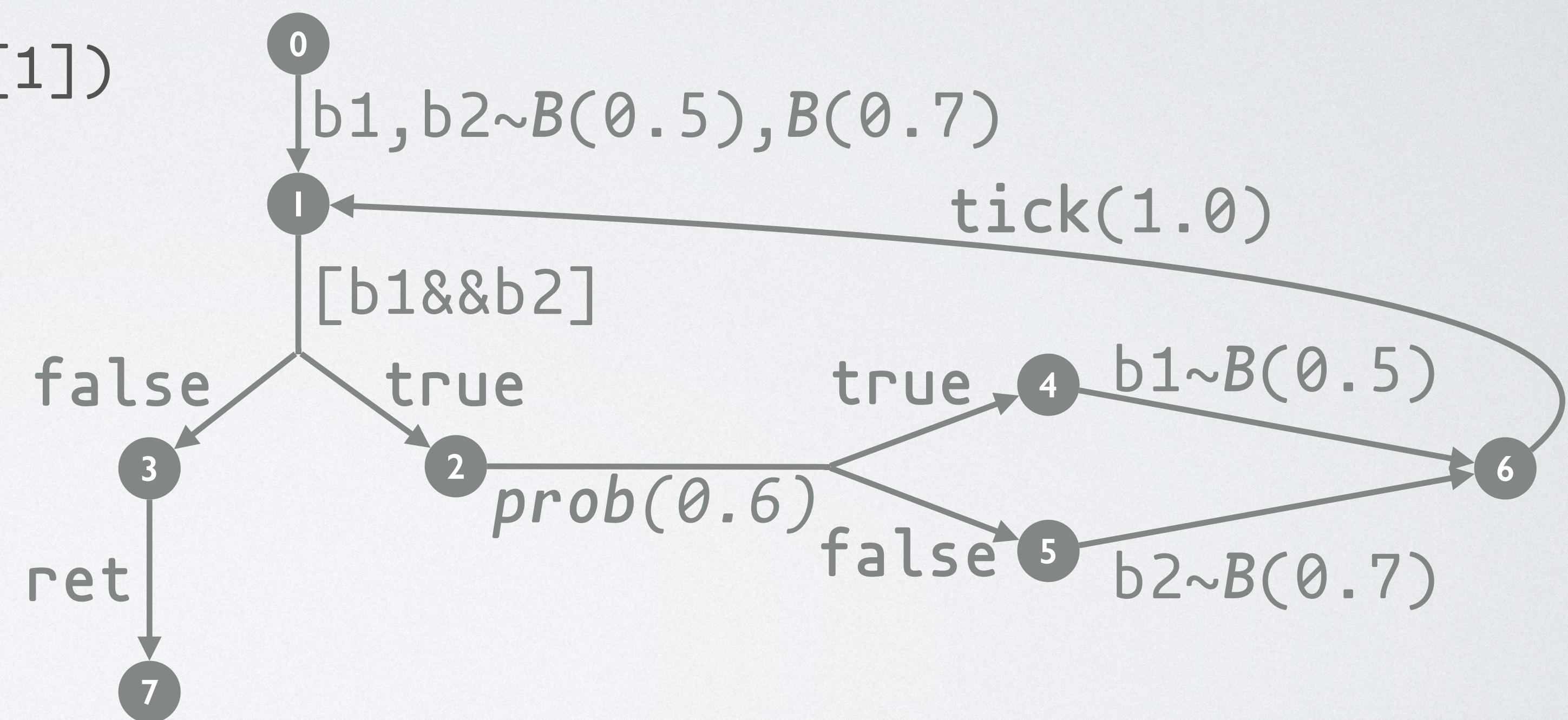
- The hyper-graph semantics is formulated by an equation system

$S[0] = \text{seq}[b1, b2 \sim B(0.5), B(0.7)](S[1])$

$S[1] = \text{cond}[b1 \& b2](S[2], S[3])$

$S[2] = \text{prob}[0.6](S[4], S[5])$

Use a **Markov algebra** to interpret seq, cond, prob



# HYPER-GRAPH SEMANTICS

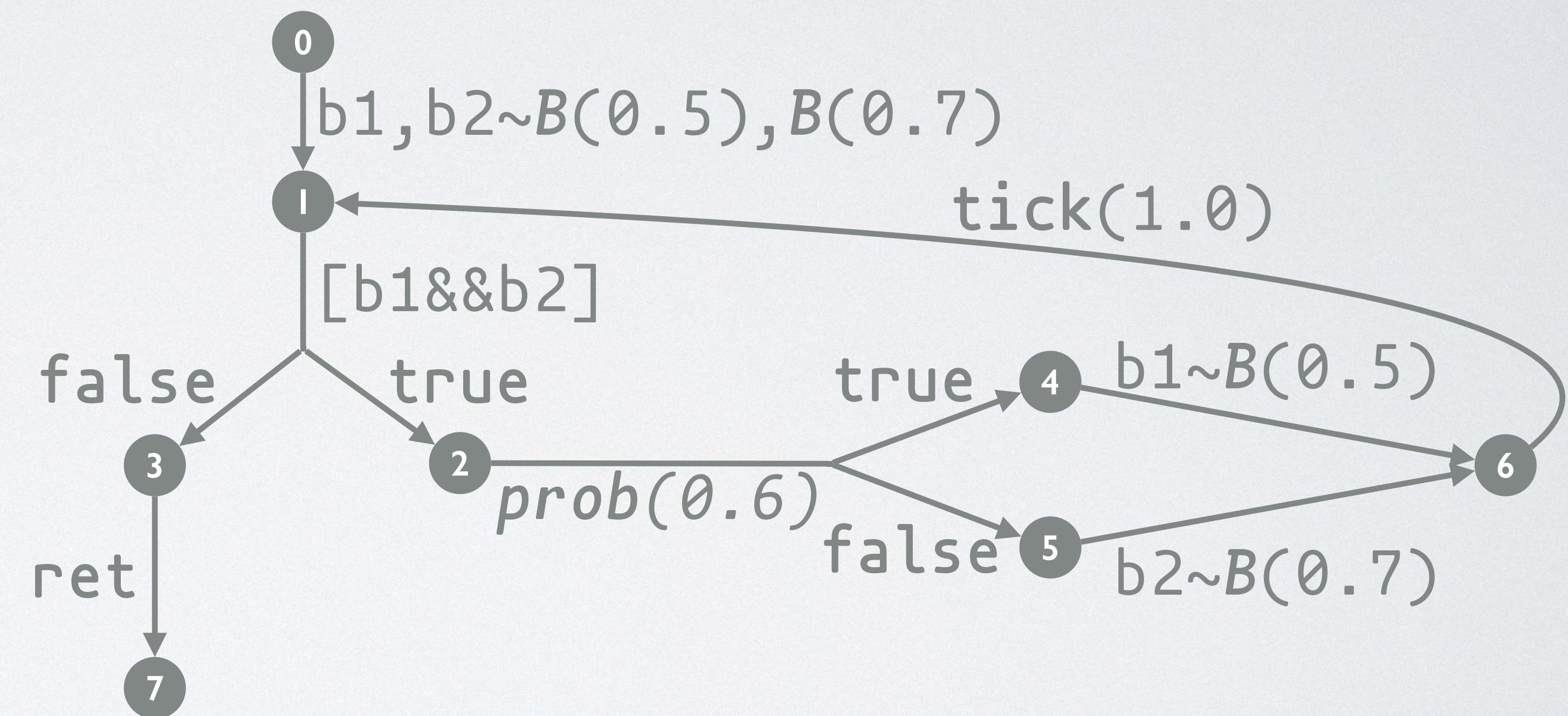
- The hyper-graph semantics is formulated by an equation system

$$S[0] = [b1, b2 \sim B(0.5), B(0.7)] \otimes S[1]$$

$$S[1] = S[2]_{b1 \& \& b2} \diamond S[3]$$

$$S[2] = S[4]_{0.6} \oplus S[5]$$

Use a **Markov algebra** to interpret seq, cond, prob



# HYPER-GRAPH SEMANTICS

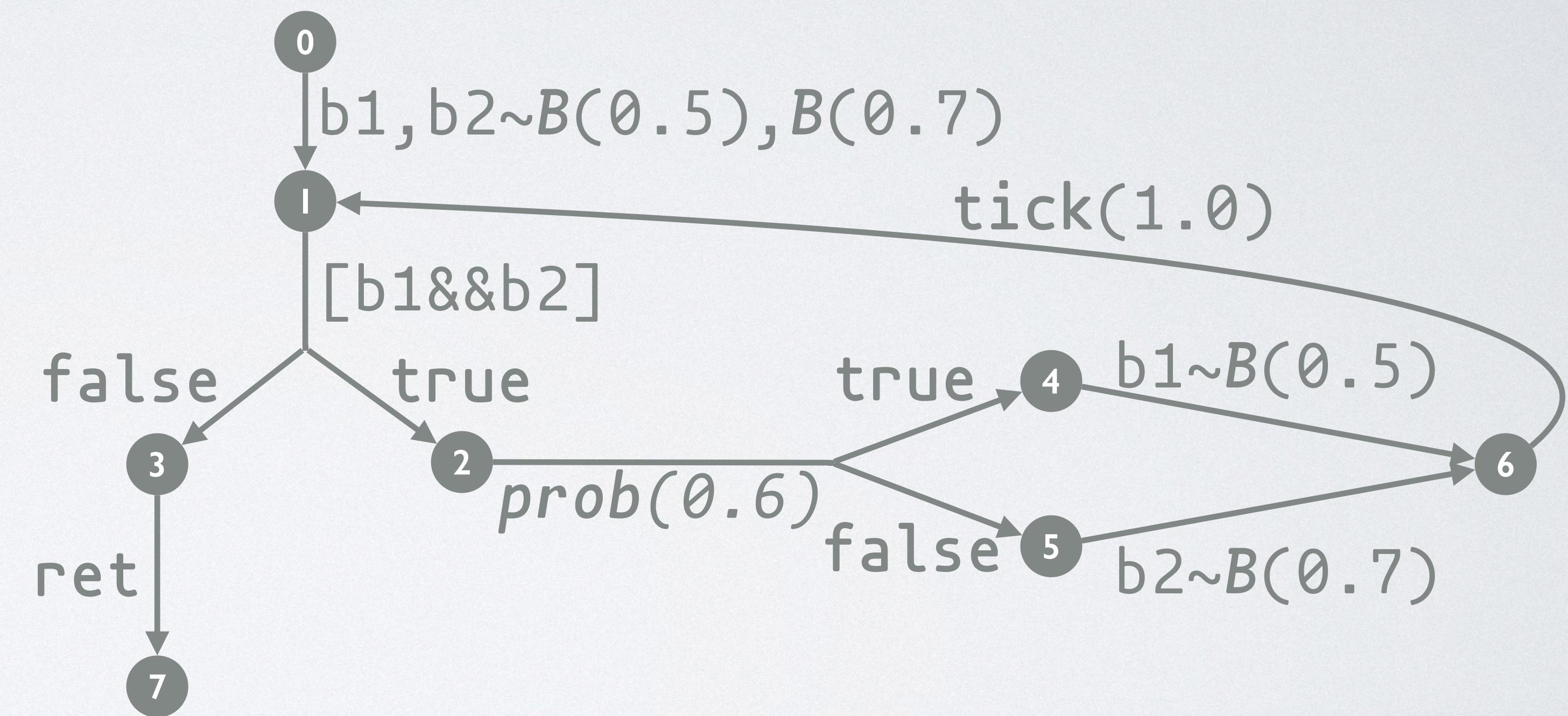
- The hyper-graph semantics is formulated by an equation system

$$S[0] = [b1, b2 \sim B(0.5), B(0.7)] \otimes S[1]$$

$$S[1] = S[2]_{b1 \& \& b2} \diamond S[3]$$

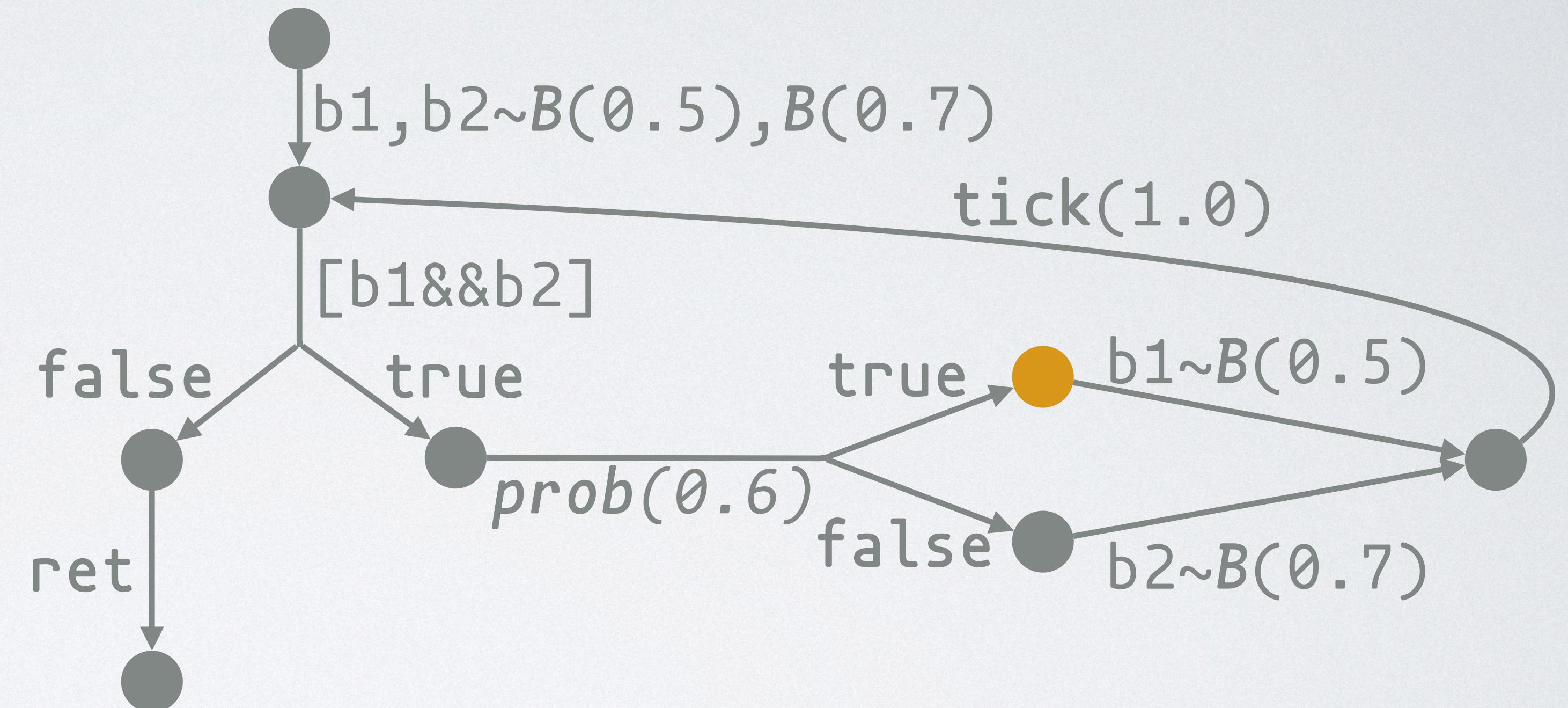
$$S[2] = S[4]_{0.6} \oplus S[5]$$

If using **abstract** semantics,  
we obtain an equation system for  
**static analysis**



# HYPER-GRAPH ANALYSIS

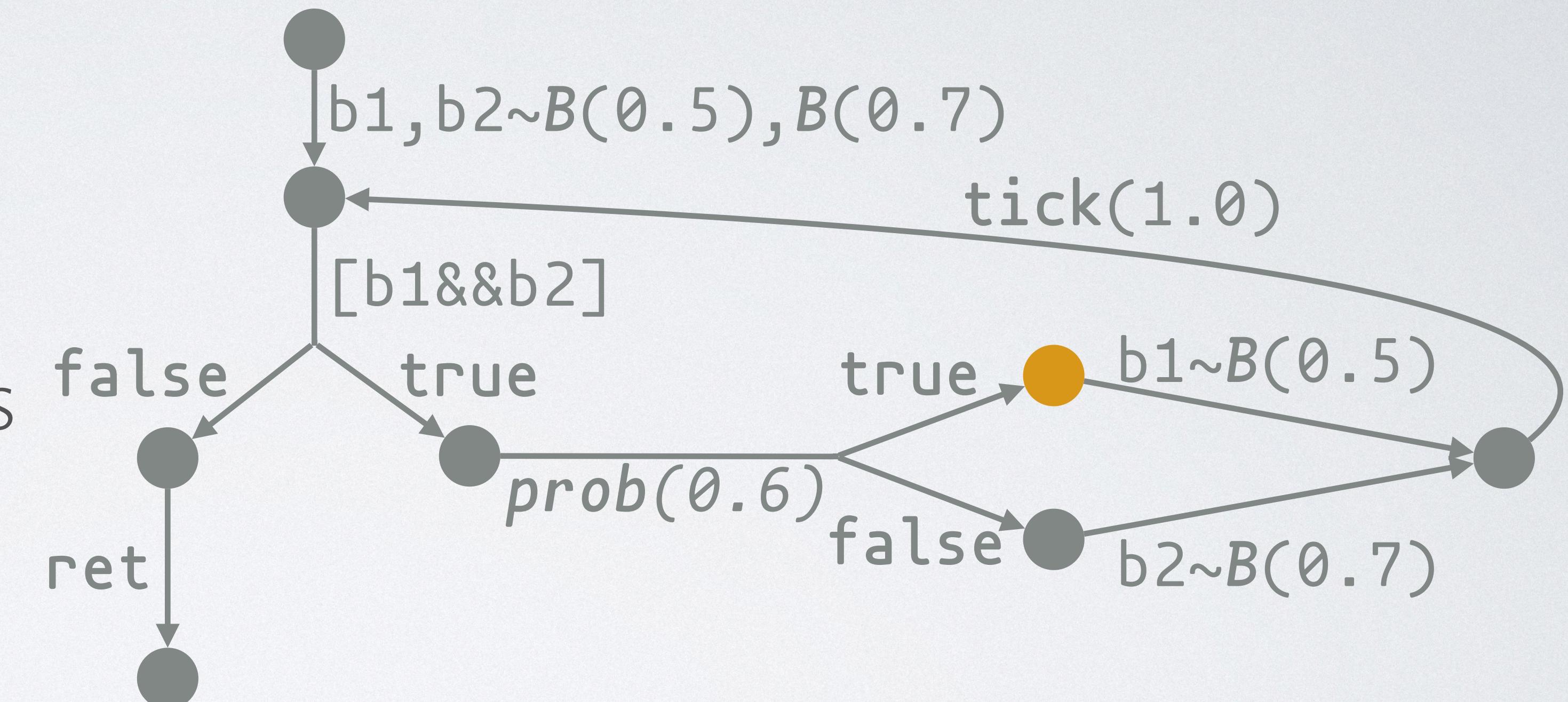
- ◆ **Forward assertions**
- ◆ The property of a node is a summary of the computation that continues from the node



# HYPER-GRAPH ANALYSIS

- ◆ **Forward assertions**

- ◆ The property of a node is a summary of the computation that continues from the node



e.g. the property represented by the **node** is

$$\lambda(b1, b2). \text{if } b2 \text{ then } \frac{1}{7}[b1' = T, b2' = F] + \frac{6}{7}[b1' = F, b2' = T]$$
$$\text{else } \frac{1}{2}[b1' = T, b2' = F] + \frac{1}{2}[b1' = F, b2' = F]$$

# PRE-MARKOV ALGEBRAS (PMA)

- ◆ A PMA is basically a **Markov algebra**, but we assume a different set of axioms that are suitable for **formulating static analysis**

$$\langle M, \sqsubseteq, \otimes, \varphi^\diamond, p^\oplus, \top, 1 \rangle$$

# PRE-MARKOV ALGEBRAS (PMA)

- ◆ A PMA is basically a **Markov algebra**, but we assume a different set of axioms that are suitable for **formulating static analysis**

$$\left\langle M, \sqsubseteq, \otimes, \varphi^\diamond, p^\oplus, \top, 1 \right\rangle$$

Program properties form a  
complete lattice

# PRE-MARKOV ALGEBRAS (PMA)

- ◆ A PMA is basically a **Markov algebra**, but we assume a different set of axioms that are suitable for **formulating static analysis**

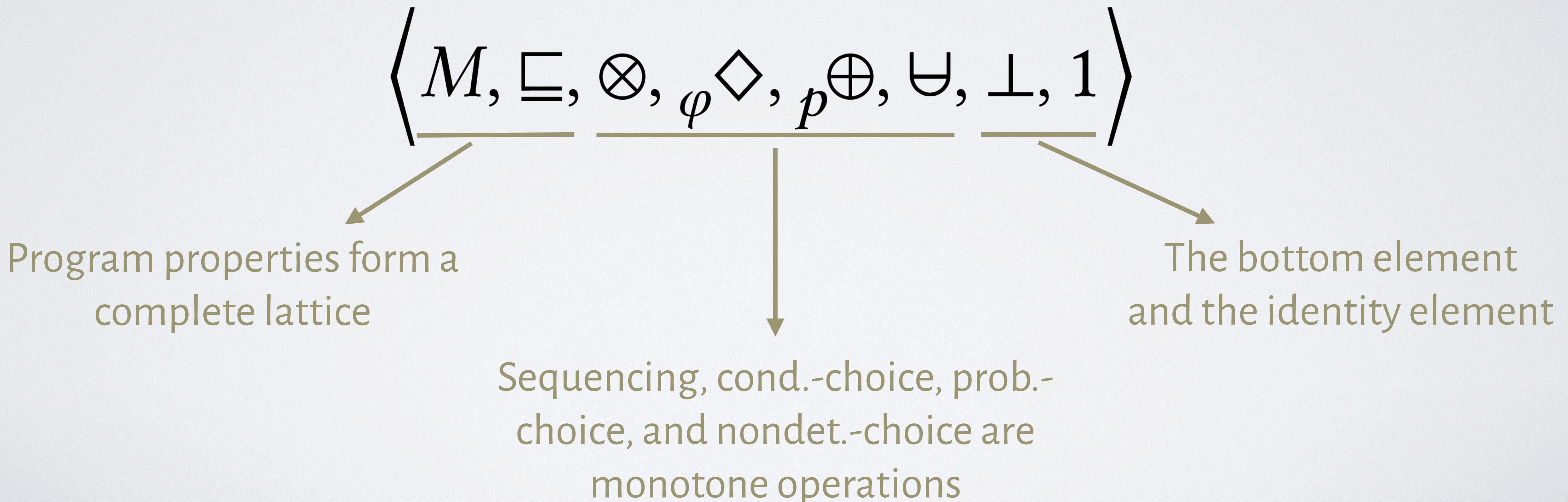
$$\left\langle M, \sqsubseteq, \otimes, \varphi^\diamond, p^\oplus, \top, 1 \right\rangle$$

Program properties form a complete lattice

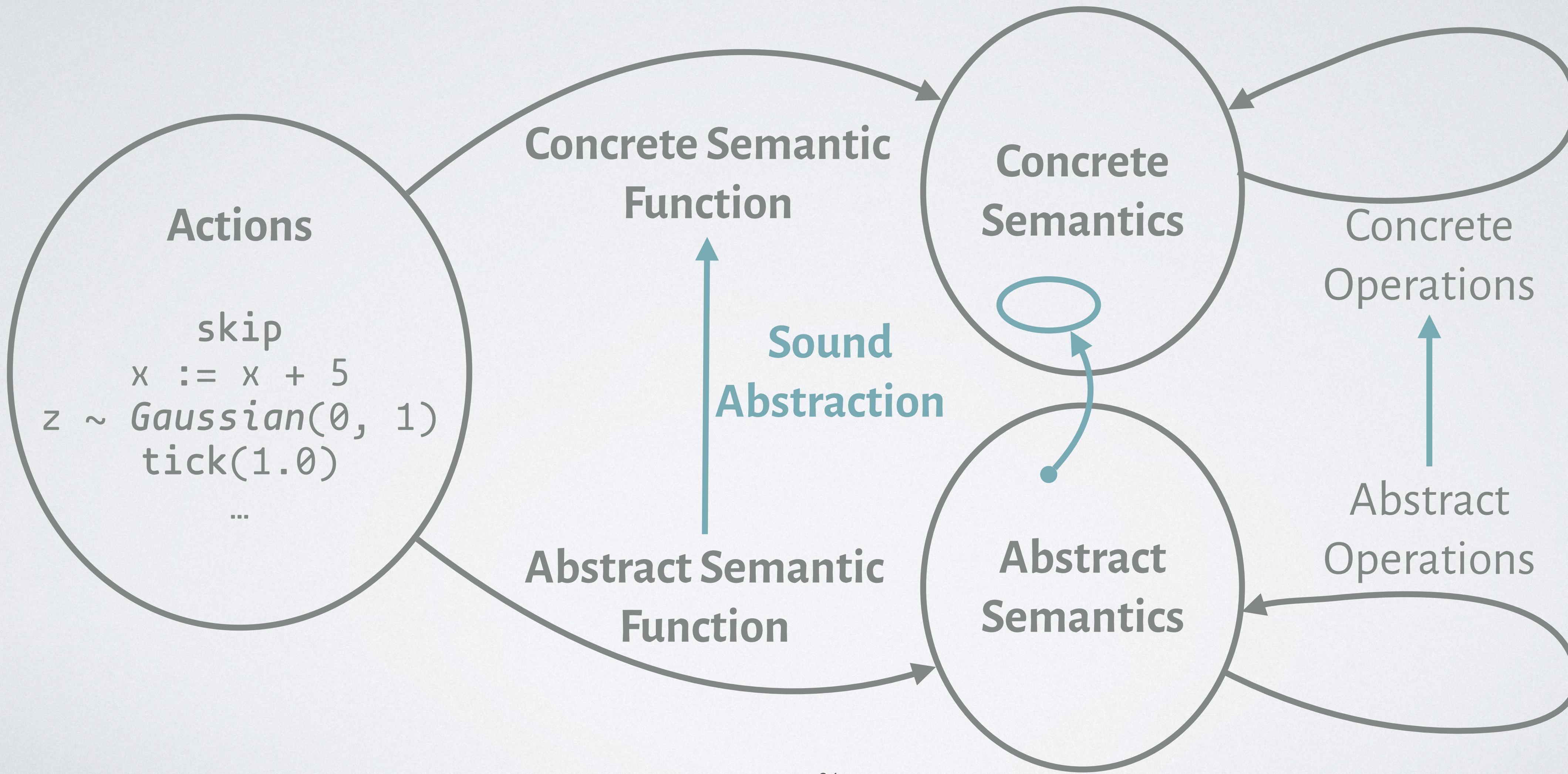
Sequencing, cond.-choice, prob.-choice, and nondet.-choice are monotone operations

# PRE-MARKOV ALGEBRAS (PMA)

- ◆ A PMA is basically a **Markov algebra**, but we assume a different set of axioms that are suitable for **formulating static analysis**



# SOUNDNESS VIA ABSTRACT INTERPRETATION



# INSTANTIATIONS



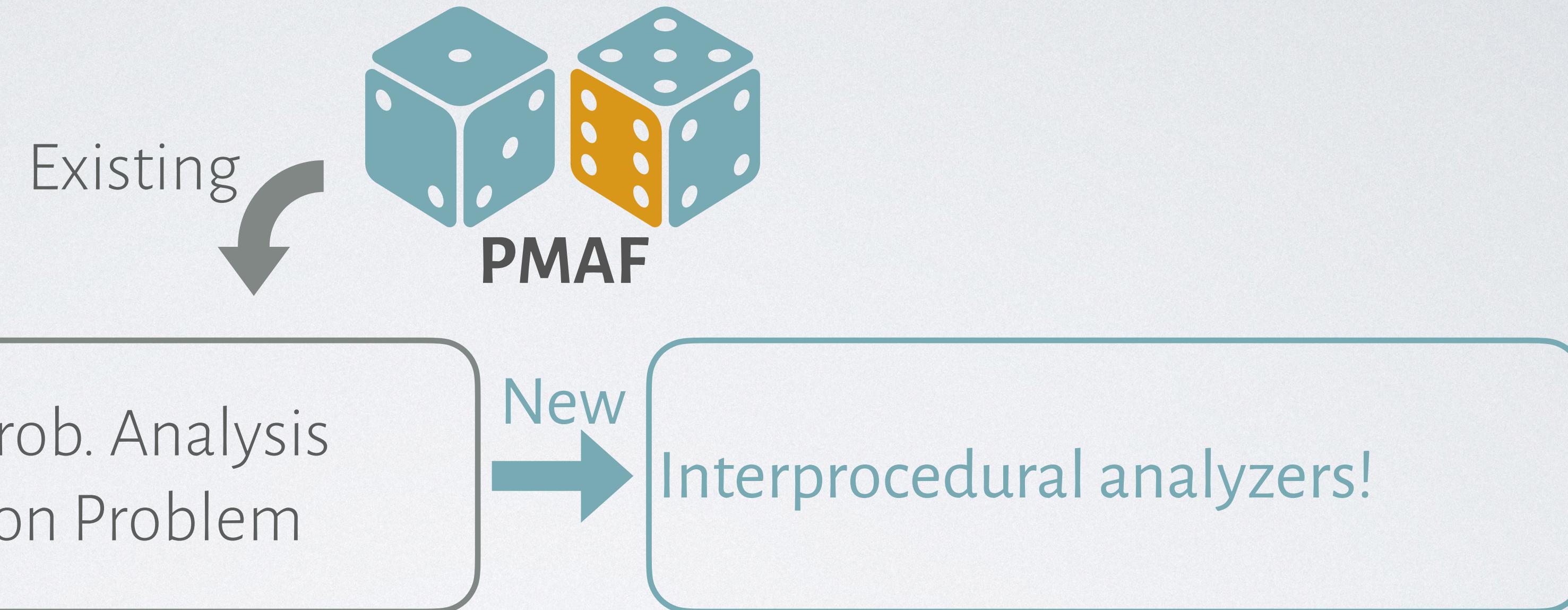
# INSTANTIATIONS

Existing



- ▶ Reachability Prob. Analysis
- ▶ Markov Decision Problem

# INSTANTIATIONS



# INSTANTIATIONS

Existing



- ▶ Reachability Prob. Analysis
- ▶ Markov Decision Problem

# INSTANTIATIONS



- ▶ Reachability Prob. Analysis
- ▶ Markov Decision Problem

- ▶ Expectation-Invariant Analysis

# INSTANTIATIONS



- Reachability Prob. Analysis
- Markov Decision Problem

- Expectation-Invariant Analysis

Prove invariants among **initial values**  
and **expected final values**

# EXPECTATION-INVARIANT ANALYSIS

- Benchmark collected from the literature<sup>7,8</sup> and also handcrafted by us
- Derive expectation invariants as least as precise as them in most case

Expectation-Invariant Analysis

Program	#loc	time (sec)	Expectation Invariants
binom-update	14	0.06	$E[4x'-n']=4x-n$ , $E[x'] \leq x+1/4$
eg	8	0.89	$E[x'+y']=x+y+4$ , $E[z']=1/4z+3/4$
recursive	13	0.37	$E[x']=x+9$
mot-ex	16	0.06	$E[2x'-y']=2x-y$ , $E[4x'-3c']=4x-3c$ , $E[x'] \leq x+3/4$

<sup>7</sup>A. Chakarov and S. Sankaranarayanan. Expectation Invariants for Probabilistic Loops as Fixed Points. In SAS'14.

<sup>8</sup>J.-P. Katoen, A. K. McIver, L. A. Meinicke, and C. C. Morgan. Linear-Invariant Generation for Probabilistic Programs. In SAS'10.