



Algebraic Program Analysis of Probabilistic Programs

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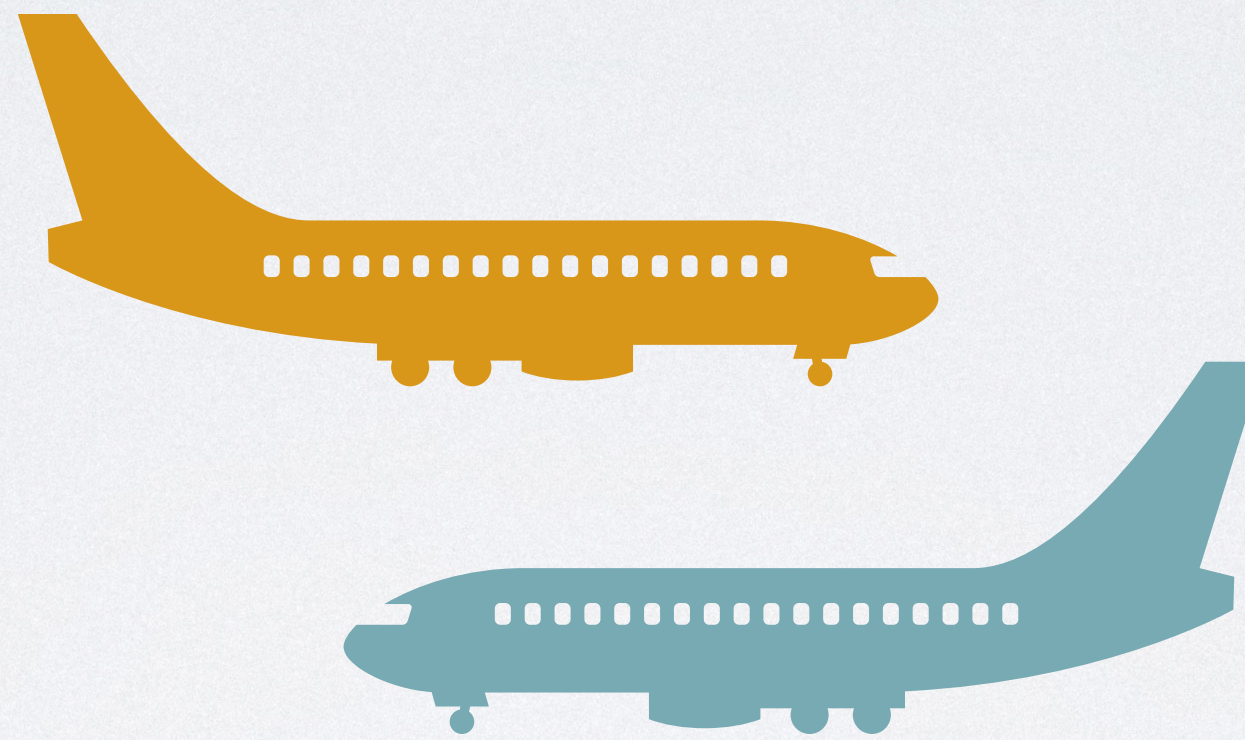
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Joint Work with Jan Hoffmann and Thomas Reps

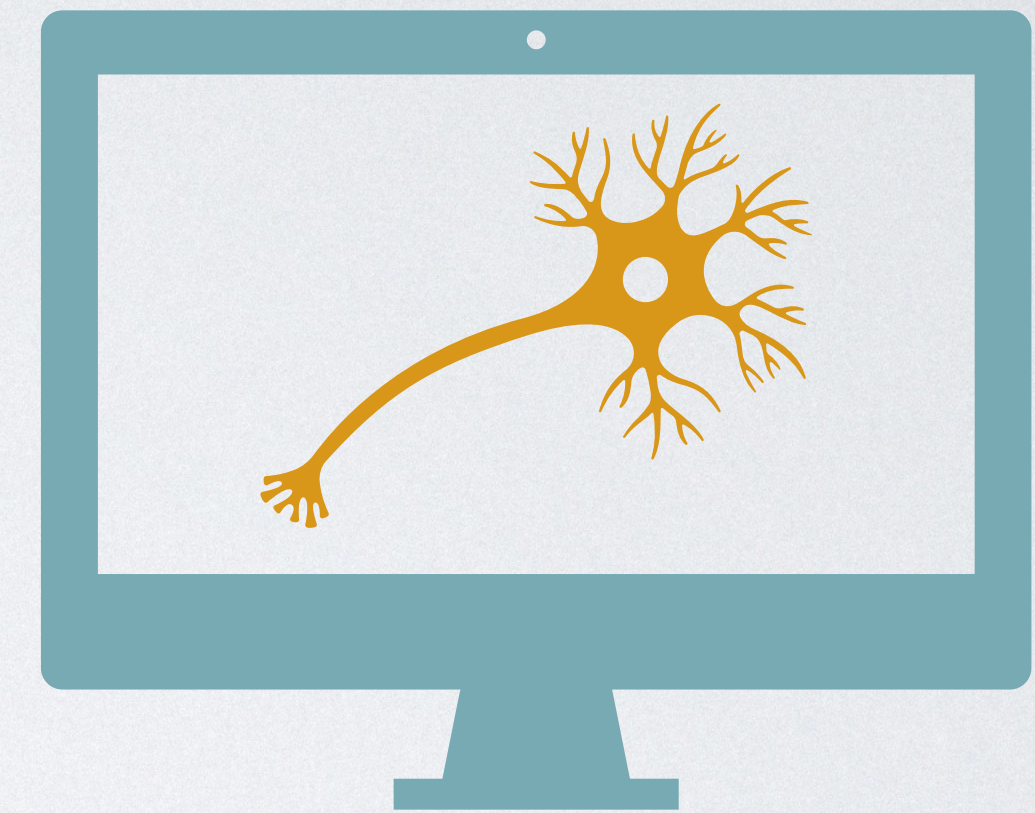
Probabilistic Systems are Becoming Pervasive



Randomized Algorithms
(improve efficiency)



Cyber-Physical Systems
(model uncertainty)



Artificial Intelligence
(describe statistical models)

Application: Randomized Quicksort

- Improve efficiency
- From $\Theta(n^2)$ to $\Theta(n \log n)$ (expected)
- Samplesort
 - Use >1 random samples as pivots

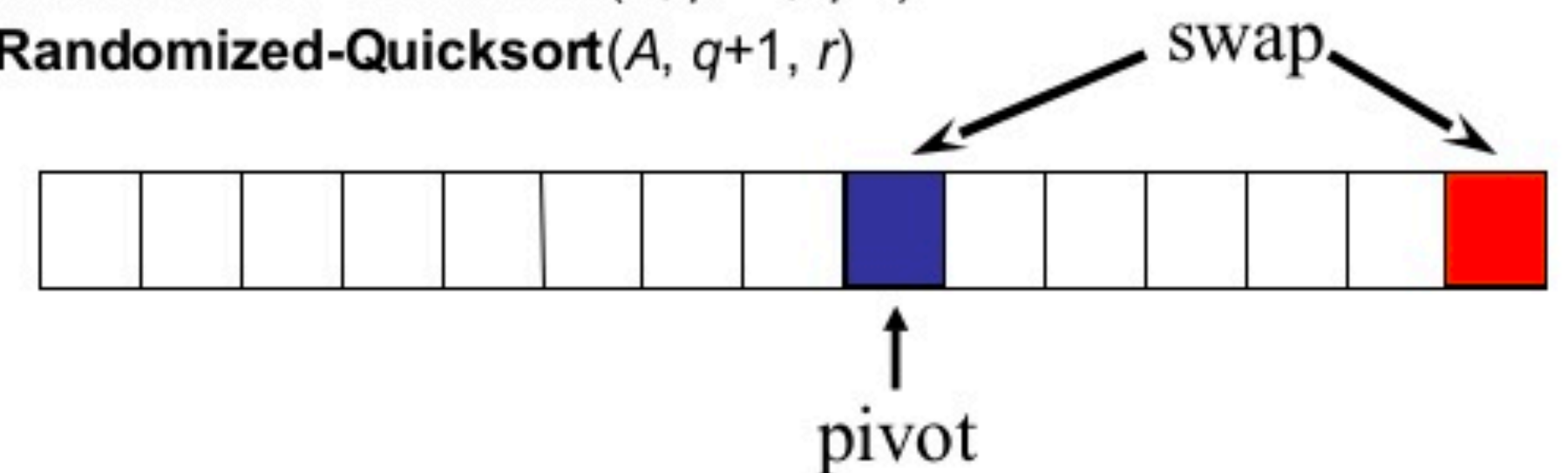
Randomized Quicksort

Randomized-Partition(A, p, r)

1. $i \leftarrow \text{Random}(p, r)$
2. exchange $A[r] \leftrightarrow A[i]$
3. **return** $\text{Partition}(A, p, r)$

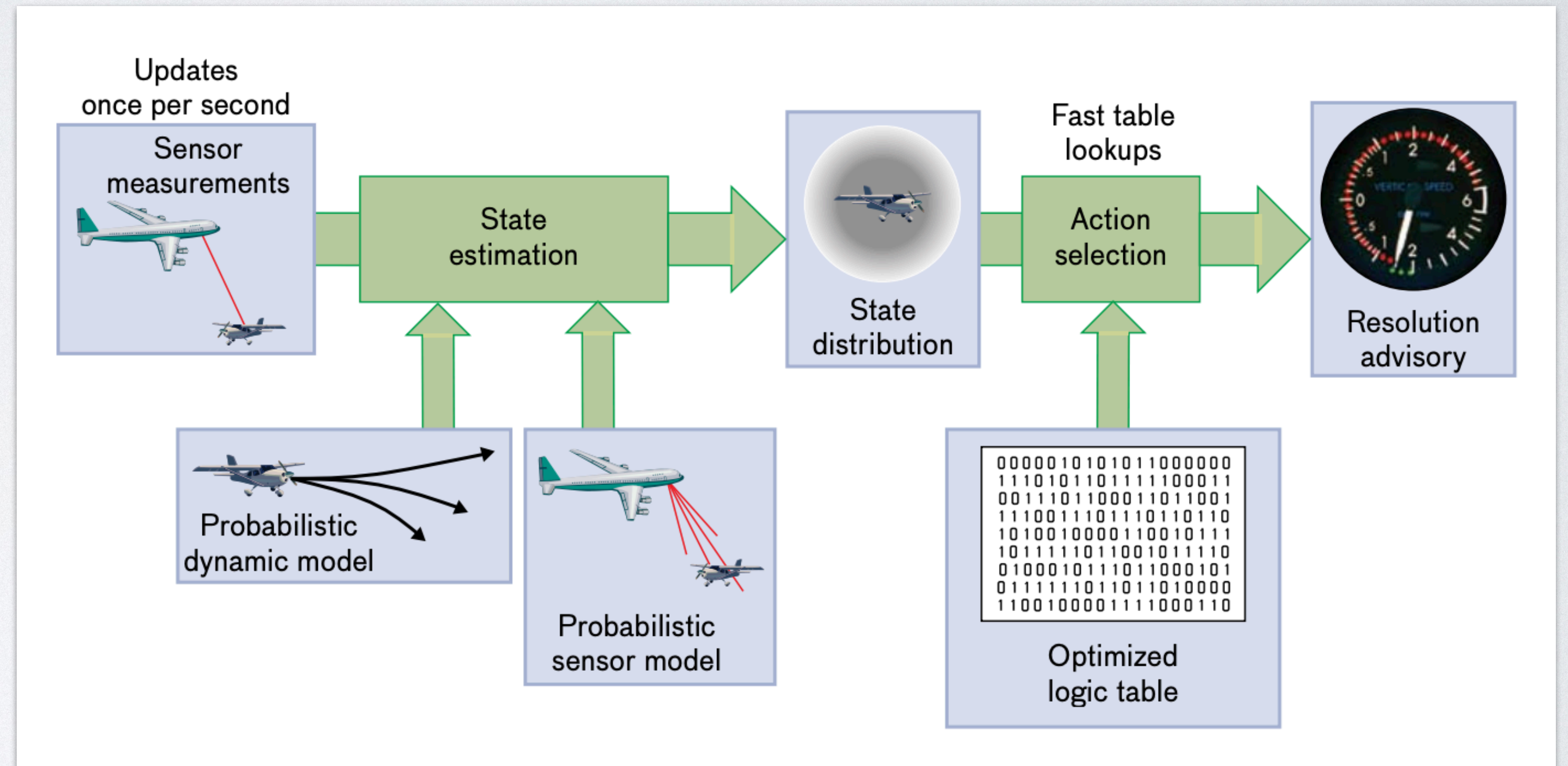
Randomized-Quicksort(A, p, r)

1. **if** $p < r$
2. **then** $q \leftarrow \text{Randomized-Partition}(A, p, r)$
3. **Randomized-Quicksort**($A, p, q-1$)
4. **Randomized-Quicksort**($A, q+1, r$)



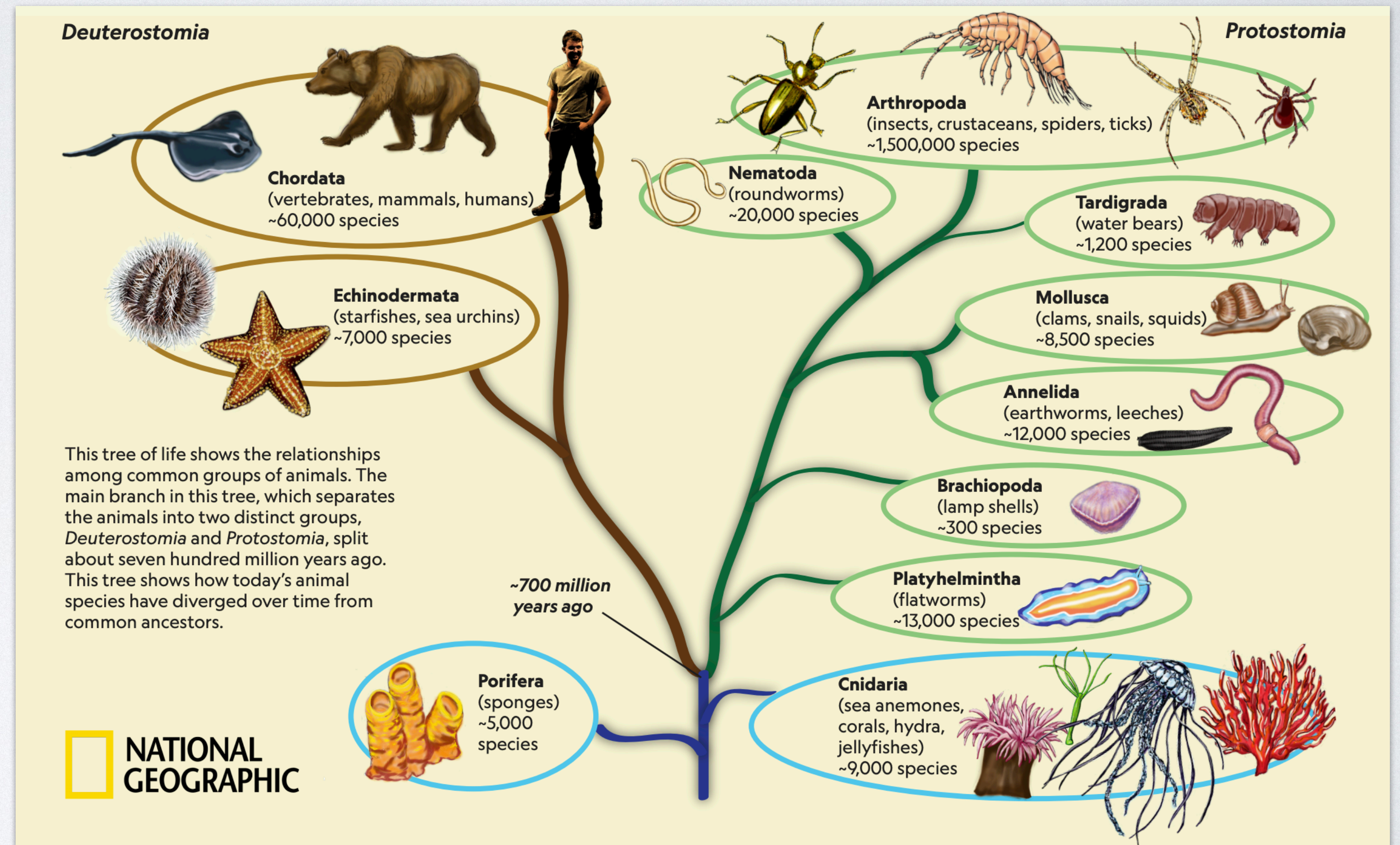
Application: Airborne Collision Avoidance

- Model uncertainty
- Probabilistic dynamics
- Probabilistic sensors
- High-confidence system



Application: Statistical Phylogenetics

- Describe statistical models
- Automated reasoning
- Apply Bayesian inference to infer evolutionary history
- Solve previously intractable problems



Probabilistic Programs



Draw random **data** from distributions



Change **control-flow** at random



Probabilistic Programs

- True randomness
- A distribution on execution paths
- Probabilistic nondeterminism

```
if
| prob(1/3) → choice := 1
| prob(1/3) → choice := 2
| prob(1/3) → choice := 3
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```



Probabilistic Programs

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if
| prob(1/3) → choice := 1
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```
choice : $\epsilon_p$  (1 @ 1/3 | 2 @ 1/3 | 3 @ 1/3)
```




Demonic Programs

- Dijkstra's **Guarded Command Language** (GCL)
- A set of execution paths
- Demonic nondeterminism

```
if
| true → prize := 1
| true → prize := 2
| true → prize := 3
fi
```



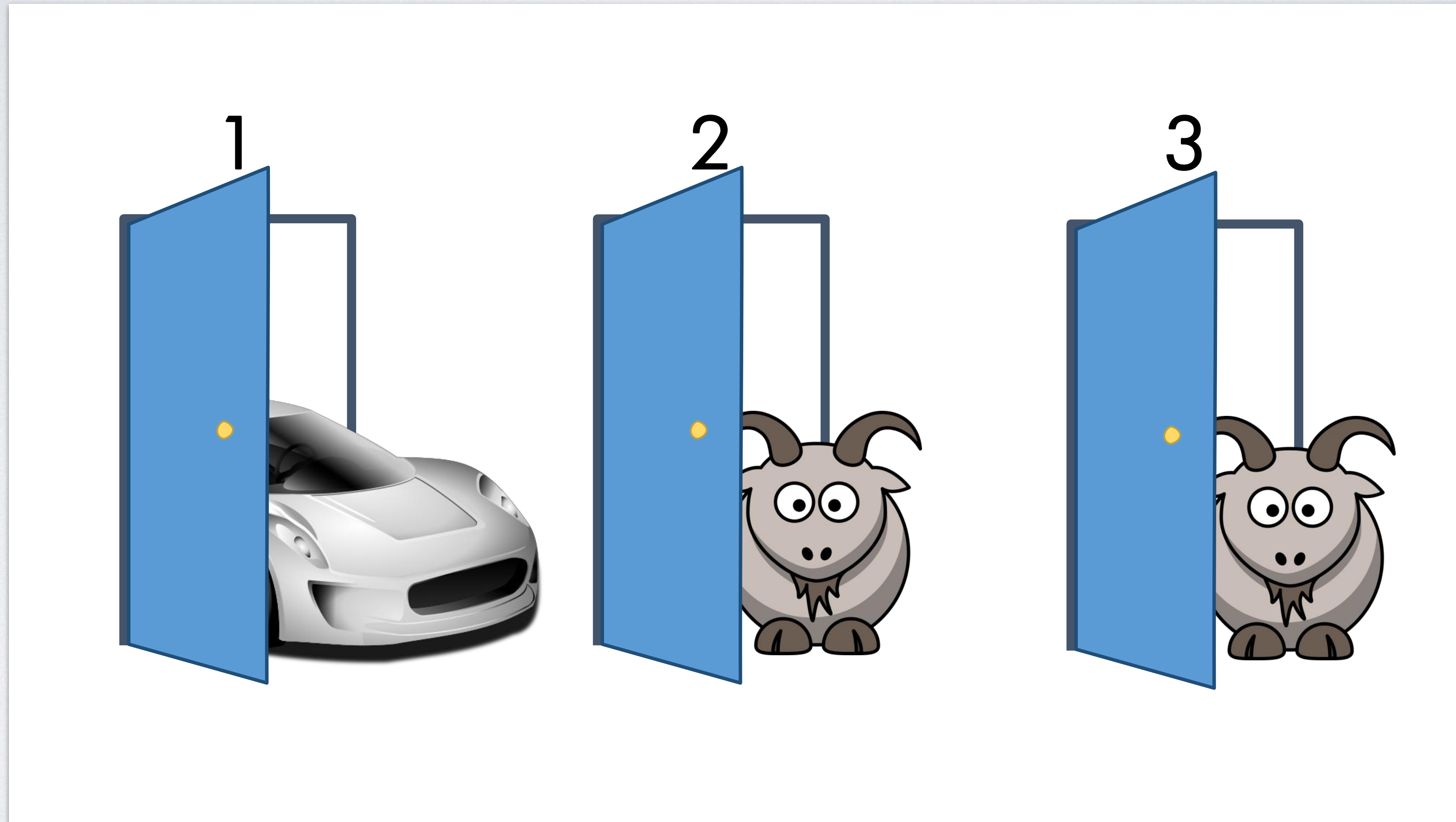
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| true → prize := 3  
fi
```

```
prize : $\in_d$  {1, 2, 3}
```

Example: Monty Hall





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- McIver and Morgan's **probabilistic Guarded Command Language** (pGCL)

- Combine two forms of nondeterminism:
 - Probabilistic
 - Demonic

```
prize : $\epsilon_d$  {1,2,3};  
choice : $\epsilon_p$  (1 @ 1/3 | 2 @ 1/3 | 3 @ 1/3);  
host : $\epsilon_d$  {1,2,3} \ {prize,choice};  
if switch then  
    choice : $\epsilon_d$  {1,2,3} \ {choice,host}  
fi
```



Example: Monty Hall

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$\mathbb{P}(\textit{choice} = \textit{prize}) = ?$



Example: Monty Hall

- McIver and Morgan's **probabilistic Guarded Command Language** (pGCL)

- Combine two forms of nondeterminism:

- Probabilistic
- Demonic

- “Demons” minimize the probability

```
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Example: Failure Modeling



Example: Failure Modeling

- An example of **probabilistic modeling checking**

- Send c messages, each with a failure probability 0.1

```
fail := FALSE;  
c : $\in_d$  {0,1,2};  
while not(fail) and c > 0 do  
    fail : $\in_p$  (TRUE @ 0.1 | FALSE @ 0.9 );  
    c := c - 1  
od
```



Example: Failure Modeling

- An example of **probabilistic modeling checking**
- Send c messages, each with a failure probability 0.1
- What is the probability of success?

```
fail := FALSE;  
c :=d {0,1,2};  
while not(fail) and c > 0 do  
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od
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Example: Abstraction



Example: Abstraction

● Program analysis introduces **abstraction**

● **Predicate Abstraction**

● $[c=0]$ is a Boolean variable

```
fail := FALSE;  
 $[c=0] : \in_d \{TRUE, FALSE\};$   
while not(fail) and not( $[c=0]$ ) do  
    fail  $: \in_p (TRUE @ 0.1 \mid FALSE @ 0.9 )$ ;  
     $[c=0] : \in_a \{TRUE, FALSE\}$   
od;
```



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Example: Abstraction

- Program analysis introduces **abstraction**

- Predicate Abstraction**

- $[c=0]$ is a Boolean variable

- Abstraction nondeterminism**

- Maximize \longrightarrow Upper bound

- Minimize \longrightarrow Lower bound

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How to automate such **quantitative** reasoning
about probabilistic programs?



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Examples

What is the probability that an assertion holds?



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What is the probability that an assertion holds?

What is the expected value of an expression?



How to automate such **quantitative** reasoning
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Examples

What is the probability that an assertion holds?

What is the expected value of an expression?

What is the expected time complexity of a program?



Challenge I: How to support multiple confluence operations?

... $\vdash \in_p$...

... $\vdash \in_d$...

... $\vdash \in_a$...



Semantic Algebras

- **Kleene Algebras**: A **compositional** and **flexible** framework for program semantics

Program Construct

Algebraic Representation

A program S

An interpretation \mathcal{S} of S into the algebra

Branching between A and B

$A \oplus B$

Sequencing of A and B

$A \otimes B$

Iteration (i.e., loop) of A

A^*

“abort”, “skip”

0, 1



Do Kleene Algebras Suffice?



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$([\mathbf{true}] \otimes x := 1)$

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fi

$$\begin{aligned} & (([\mathbf{prob}(1/2)] \otimes x := 1) \oplus ([\mathbf{prob}(1/2)] \otimes x := 2)) \\ \oplus & (([\mathbf{prob}(1/2)] \otimes x := 3) \oplus ([\mathbf{prob}(1/2)] \otimes x := 4)) \end{aligned}$$



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 \end{aligned}$$

Probabilities sum up to 2!



Our Approach: Markov Algebras

- Key observation: Probabilistic programs have **multiple confluence operations**

$$\langle M, \sqsubseteq, \otimes, \phi \oplus, \sqcap, \underline{0}, \underline{1} \rangle$$

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Program denotations
form a CPO

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Sequencing, branching, and
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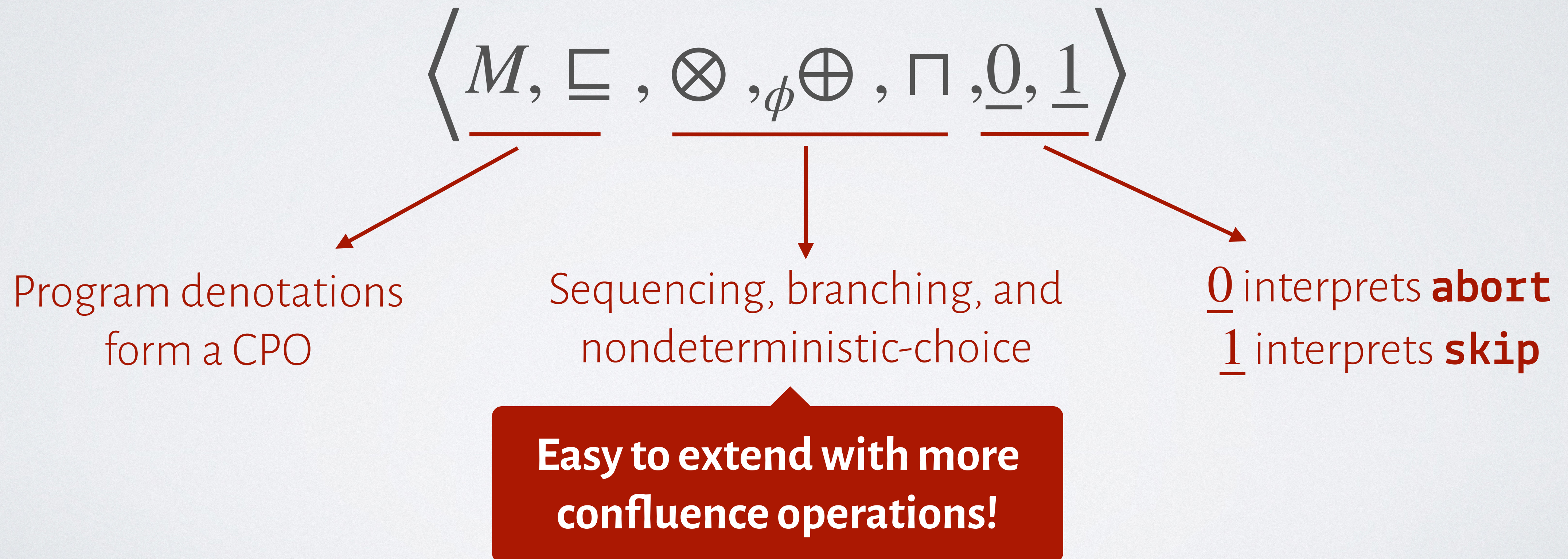
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$$\begin{aligned} (a \otimes b) \otimes c &= a \otimes (b \otimes c) \\ a \otimes \underline{1} &= \underline{1} \otimes a = a \\ a_{\phi} \oplus b &= b_{\bar{\phi}} \oplus a \\ a \sqcap a &= a \\ &\dots \end{aligned}$$



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while x>0 do  
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Recursive Program Scheme



Flexibility: Different Semantics

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Standard: *State* \rightarrow *State*



Flexibility: Different Semantics

Standard: $State \rightarrow State$

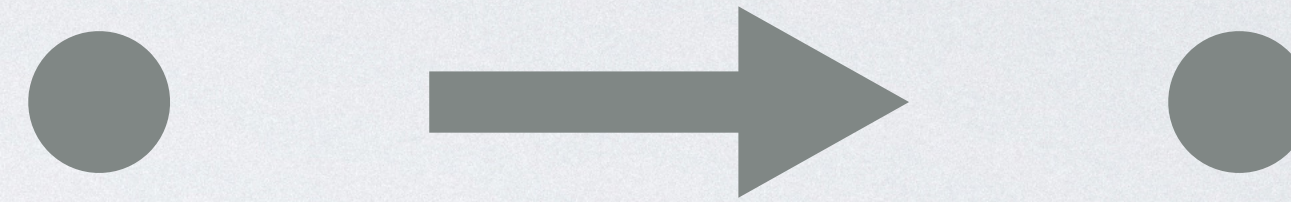


GCL: $State \rightarrow \wp(State)$



Flexibility: Different Semantics

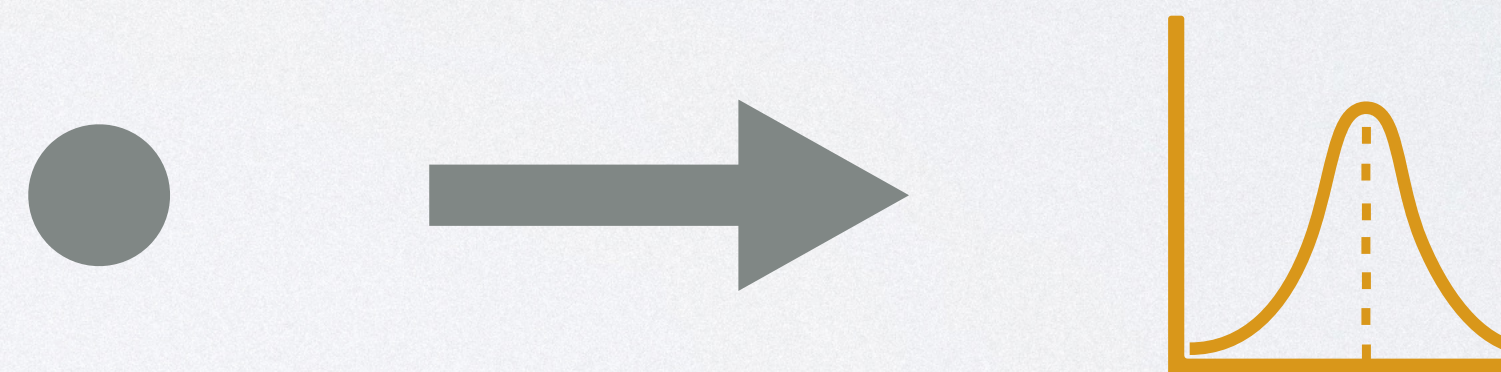
Standard: $State \rightarrow State$



GCL: $State \rightarrow \wp(State)$



Probabilistic: $State \rightarrow \mathbb{D}(State)$

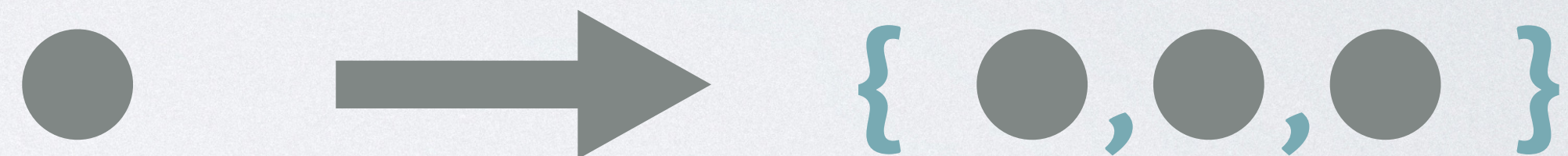


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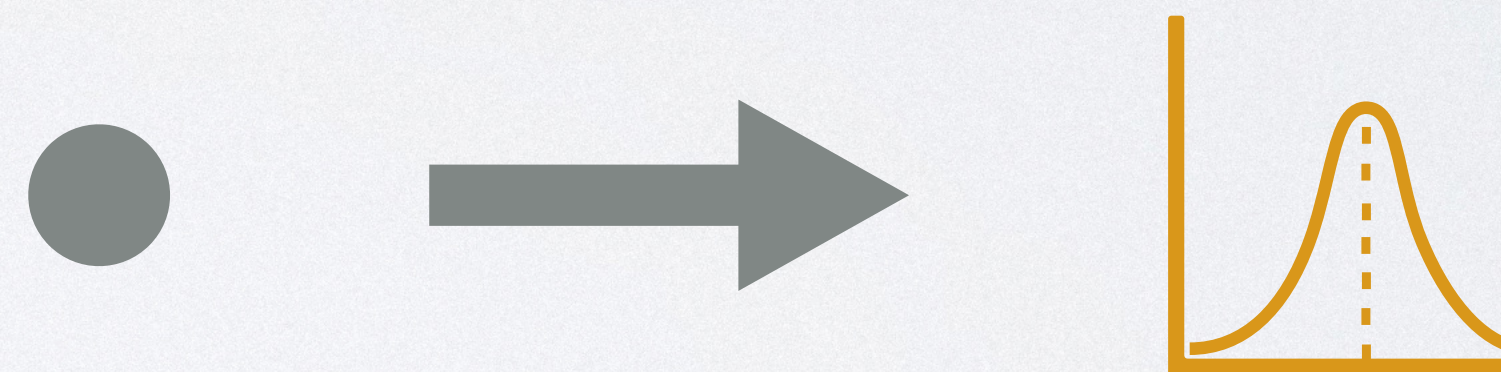
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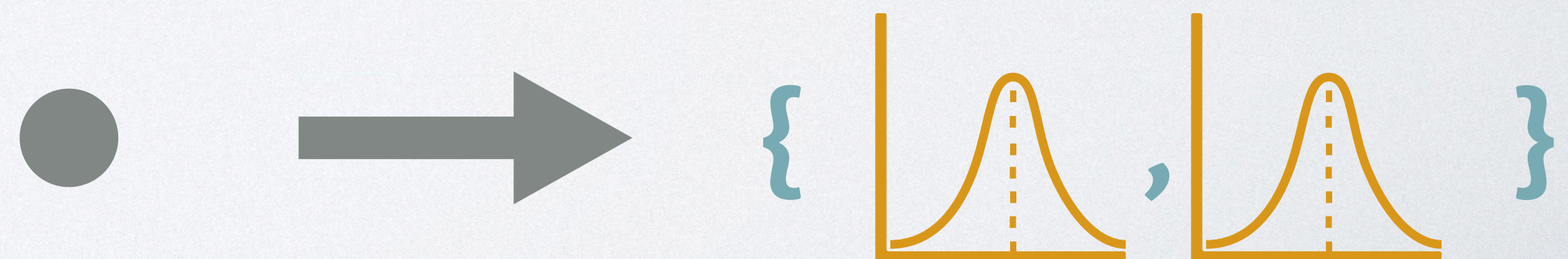
GCL: $State \rightarrow \wp(State)$



Probabilistic: $State \rightarrow \mathbb{D}(State)$



pGCL: $State \rightarrow \wp(\mathbb{D}(State))$

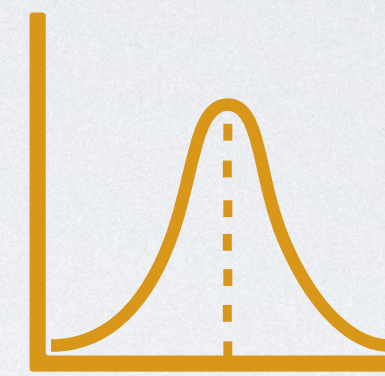
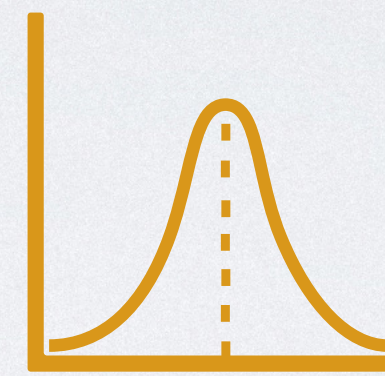
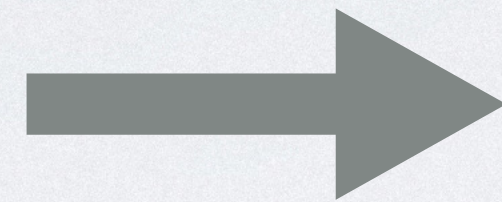
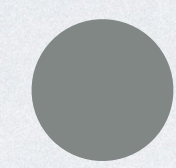




Flexibility: Different Models for Nondeterminism

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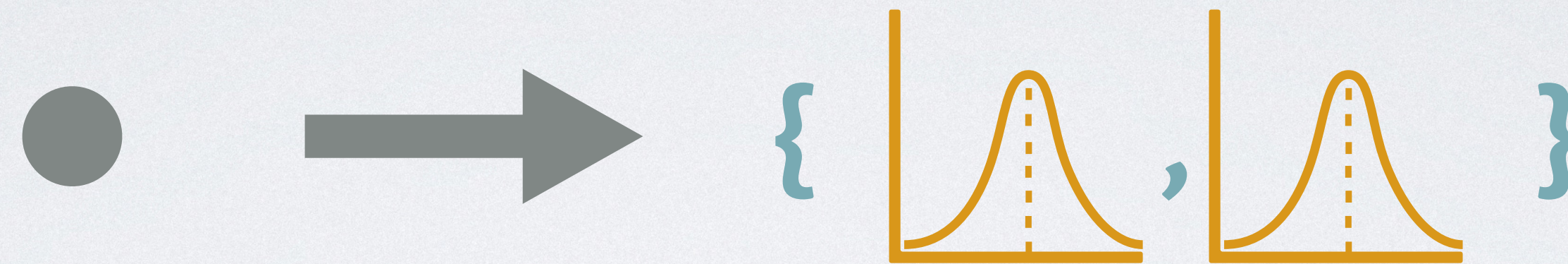
● pGCL:



$$State \rightarrow \wp(\mathbb{D}(State))$$

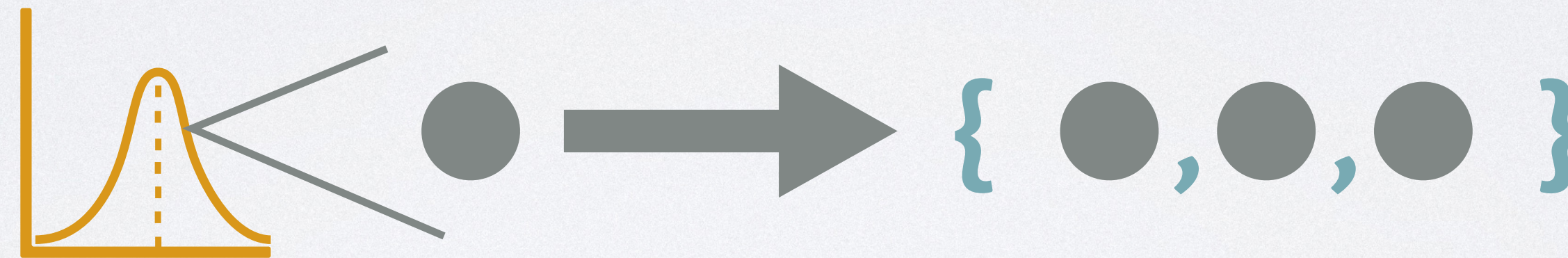
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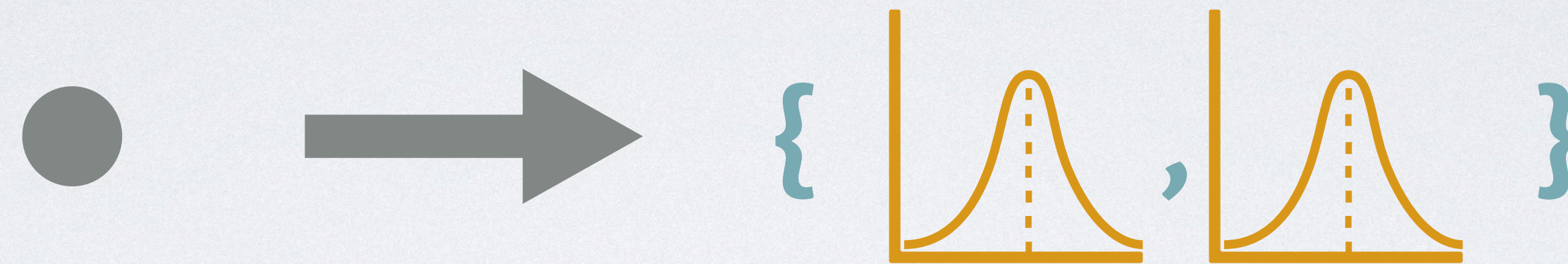
● Cousot's **Probabilistic Abstract Interpretation** (PAI):



$$\mathbb{D}(State) \rightarrow \wp(State)$$

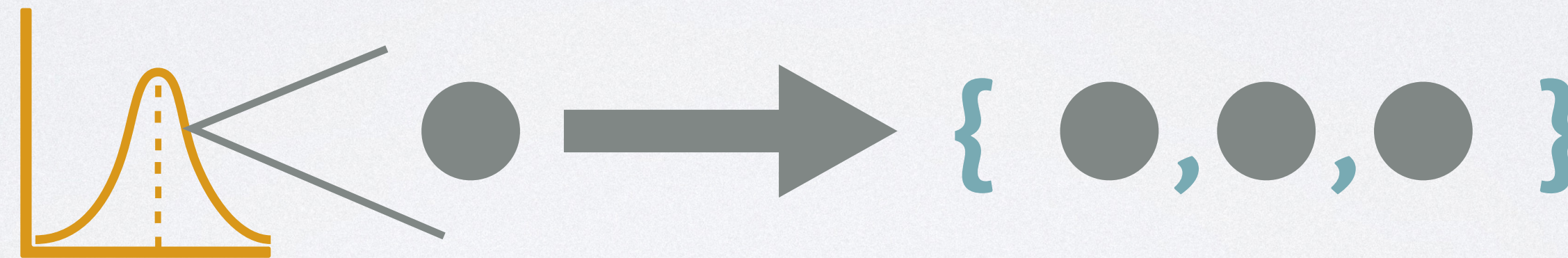
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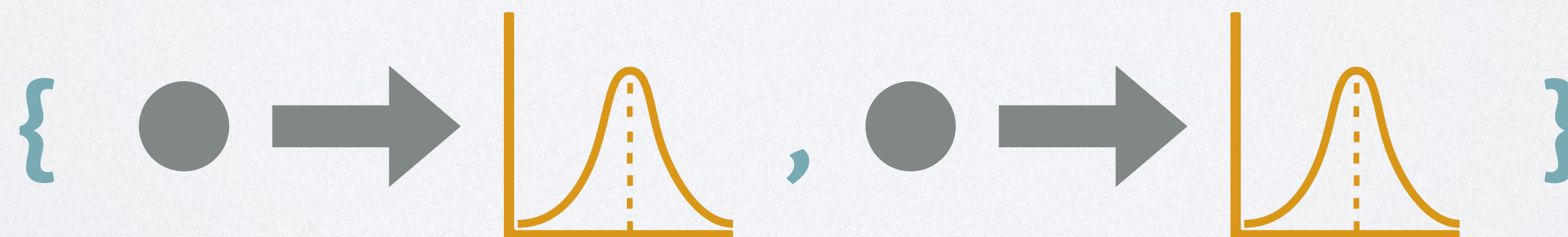
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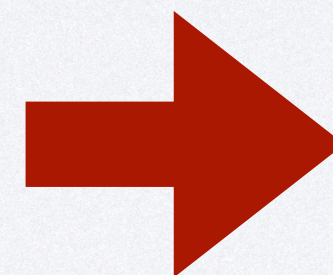
● **Compile-Time/Relational** Nondeterminism:



$$\wp(State) \rightarrow \mathbb{D}(State)$$

Challenge II: How to construct recursive program schemes?

```
while x>0 do  
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A Control-Flow-Graph's Perspective

- **Kleene Algebras** are compatible with **control-flow graphs** via **regular expressions**

Program Construct

Algebraic Representation

A program S

An interpretation \mathcal{S} of S into the algebra

The **control-flow graph** of S

A **regular expression** over $\underline{0}$, $\underline{1}$, \oplus , \otimes , and $*$

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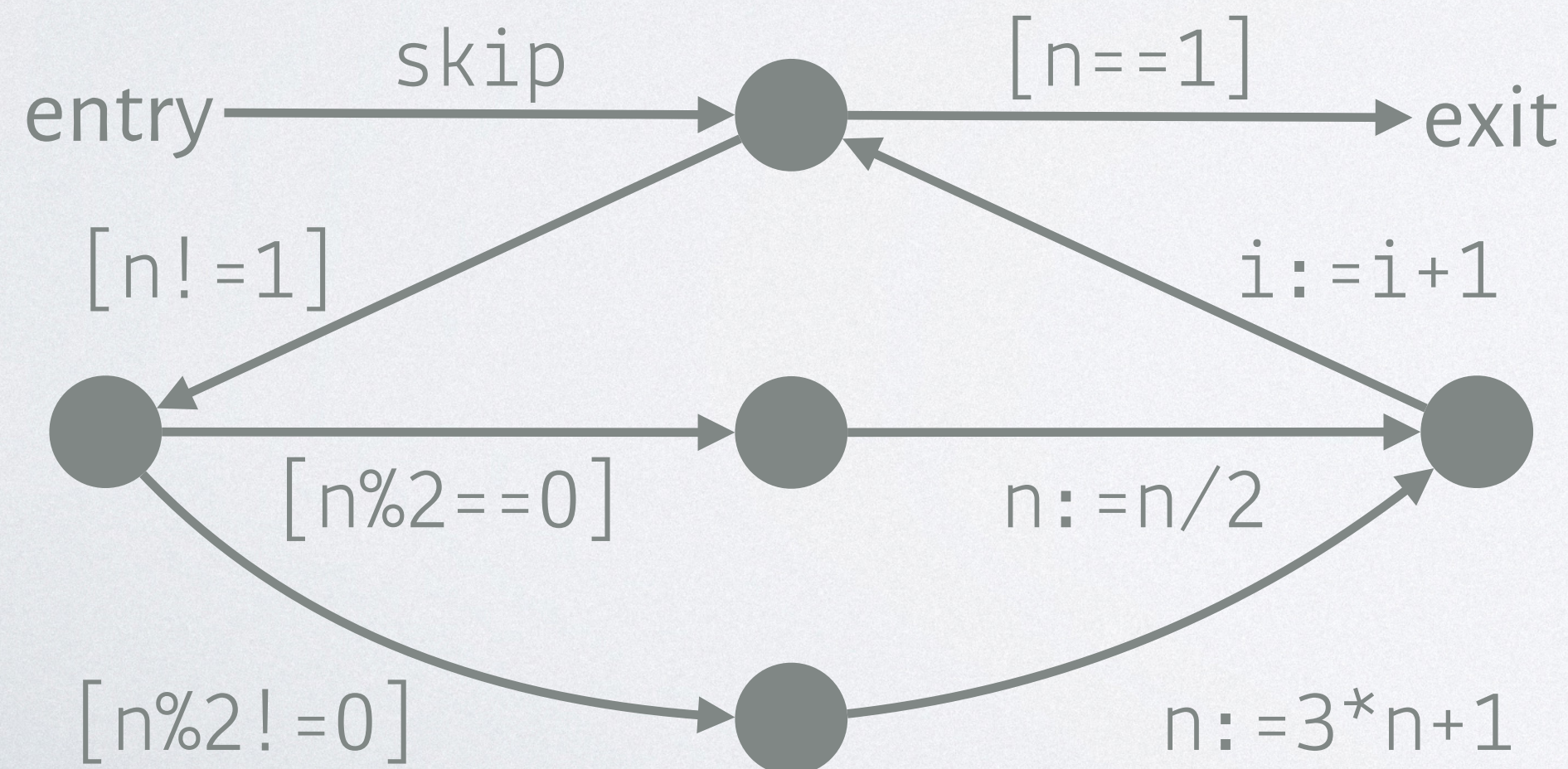
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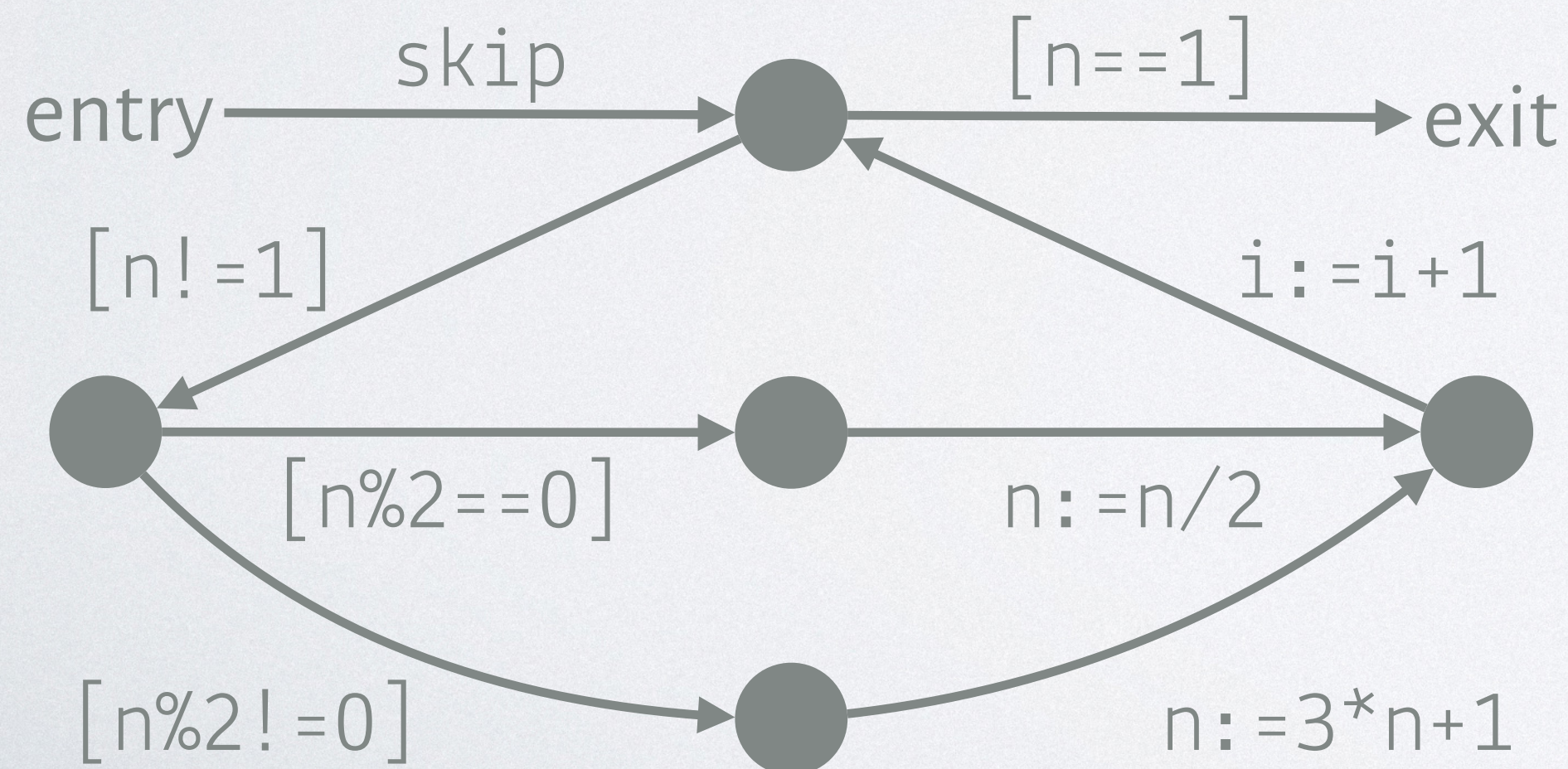
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$$\left([n!=1] \otimes \left(\begin{array}{c} [n\%2==0] \otimes n:=n/2 \\ [n\%2!=0] \otimes n:=3*n+1 \end{array} \oplus \right) \otimes i:=i+1 \right)^* \otimes [n==1]$$



Do Control-Flow Graphs Suffice?

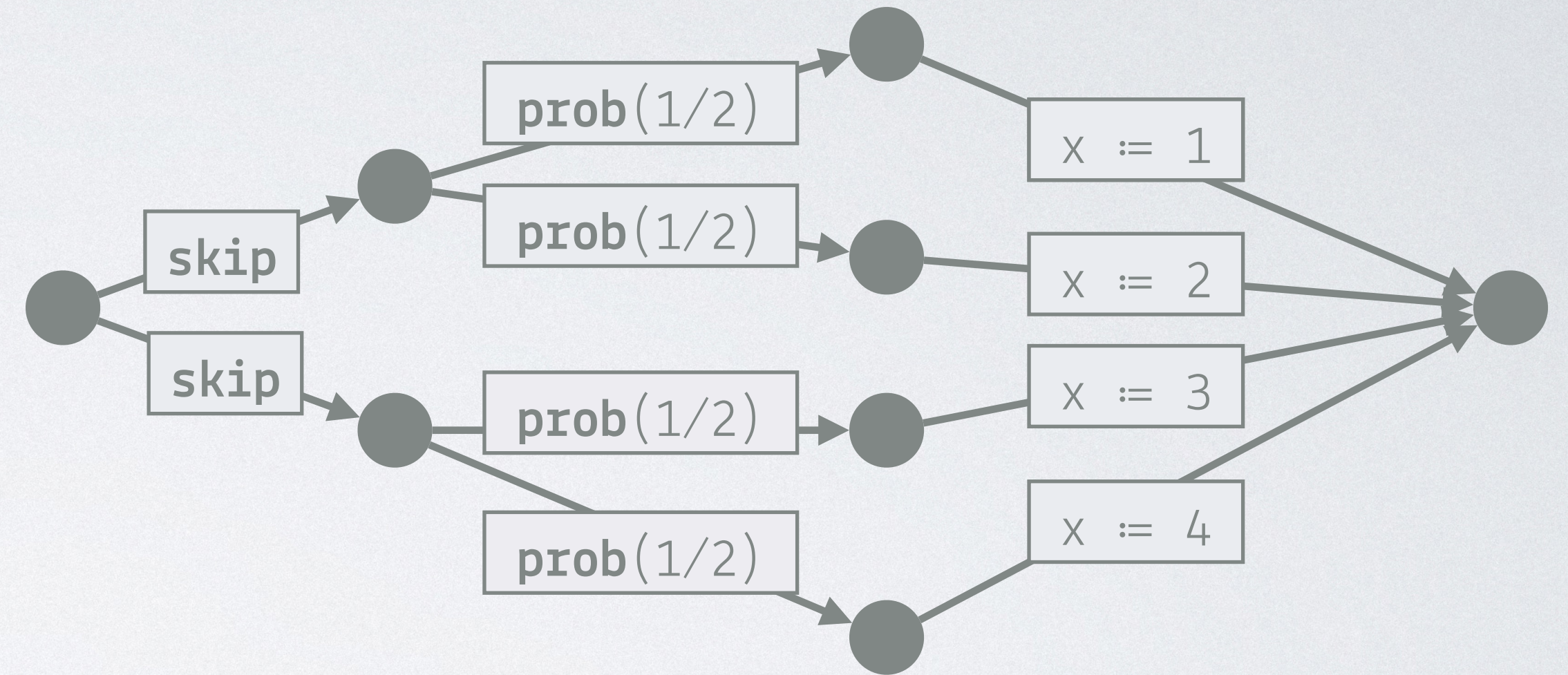


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| true → x : $\epsilon_p$  (3 @ 1/2 | 4 @ 1/2)  
fi
```

Do Control-Flow Graphs Suffice?

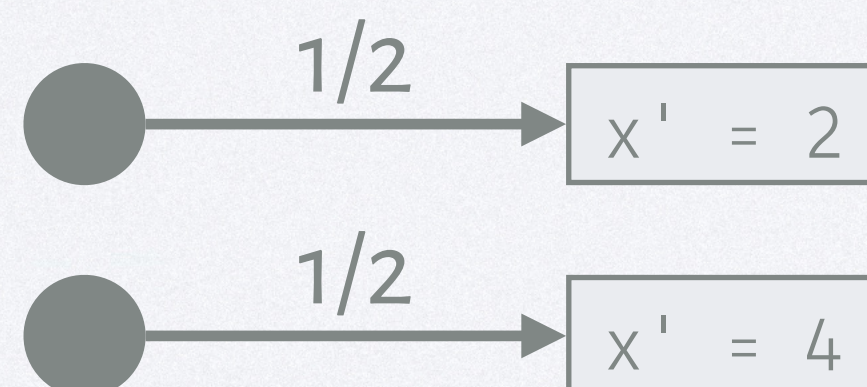
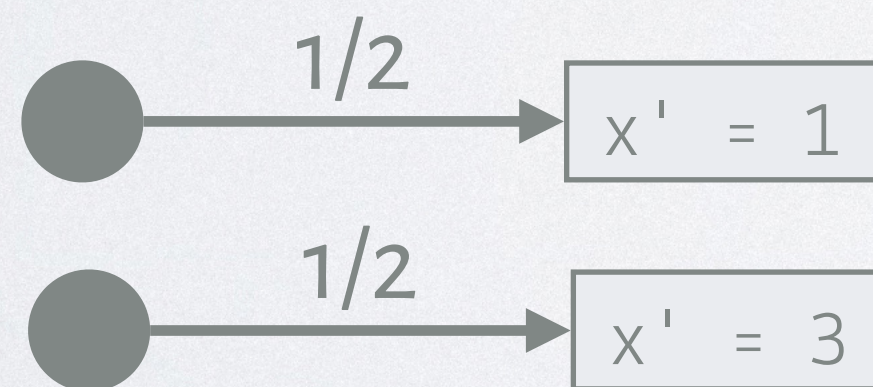
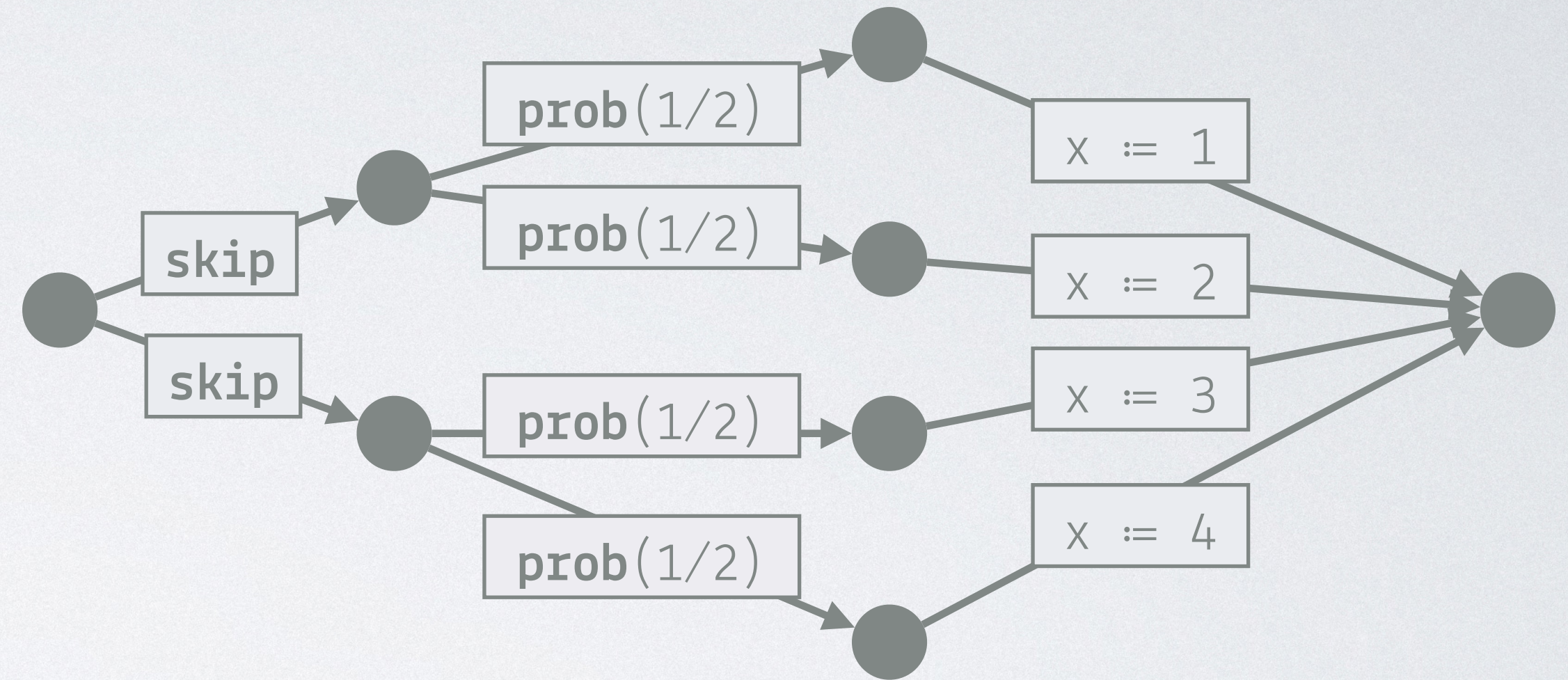
```
if  
| true → x :=p (1 @ 1/2 | 2 @ 1/2)  
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```



Do Control-Flow Graphs Suffice?

```

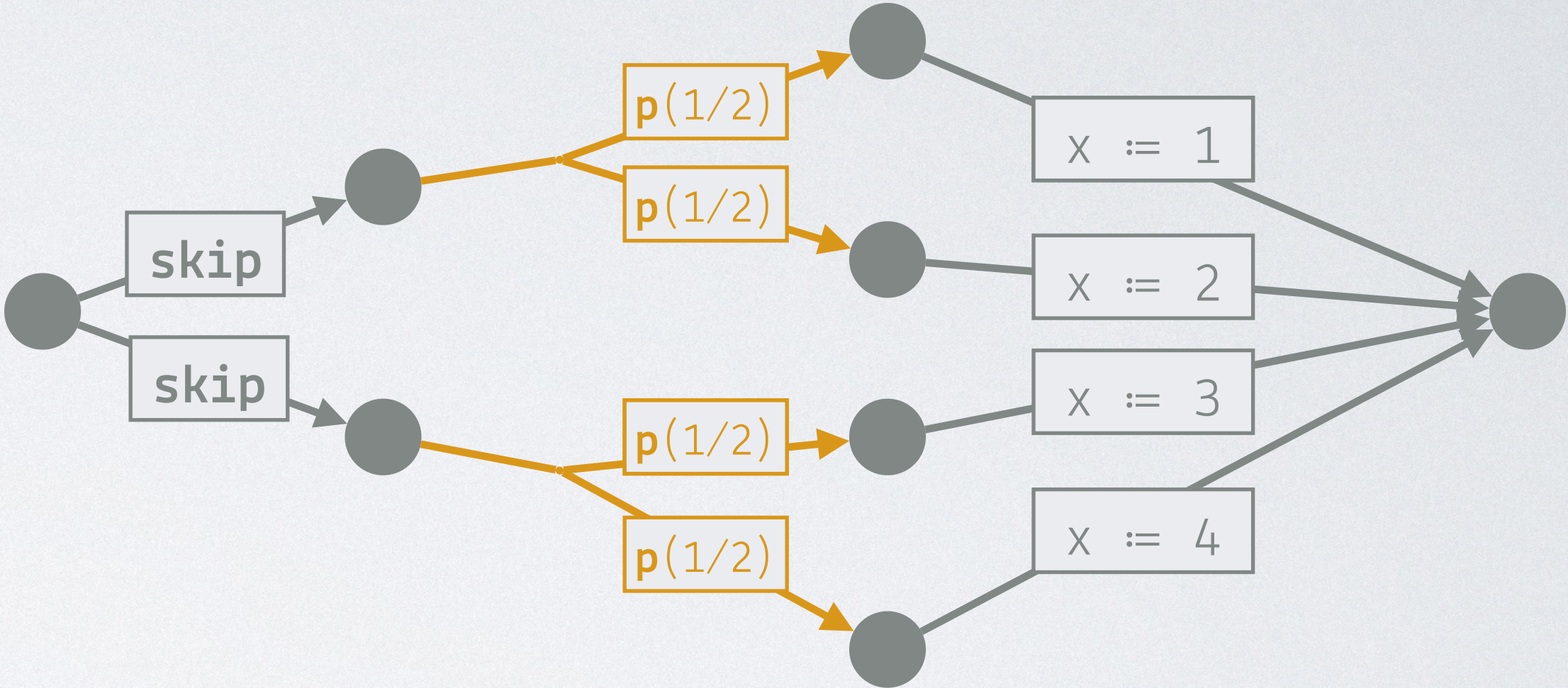
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| true →  $x := \epsilon_p$  (3 @ 1/2 | 4 @ 1/2)
fi
  
```



Probabilities sum up to 2!

Our Approach: Control-Flow Hyper-Graphs

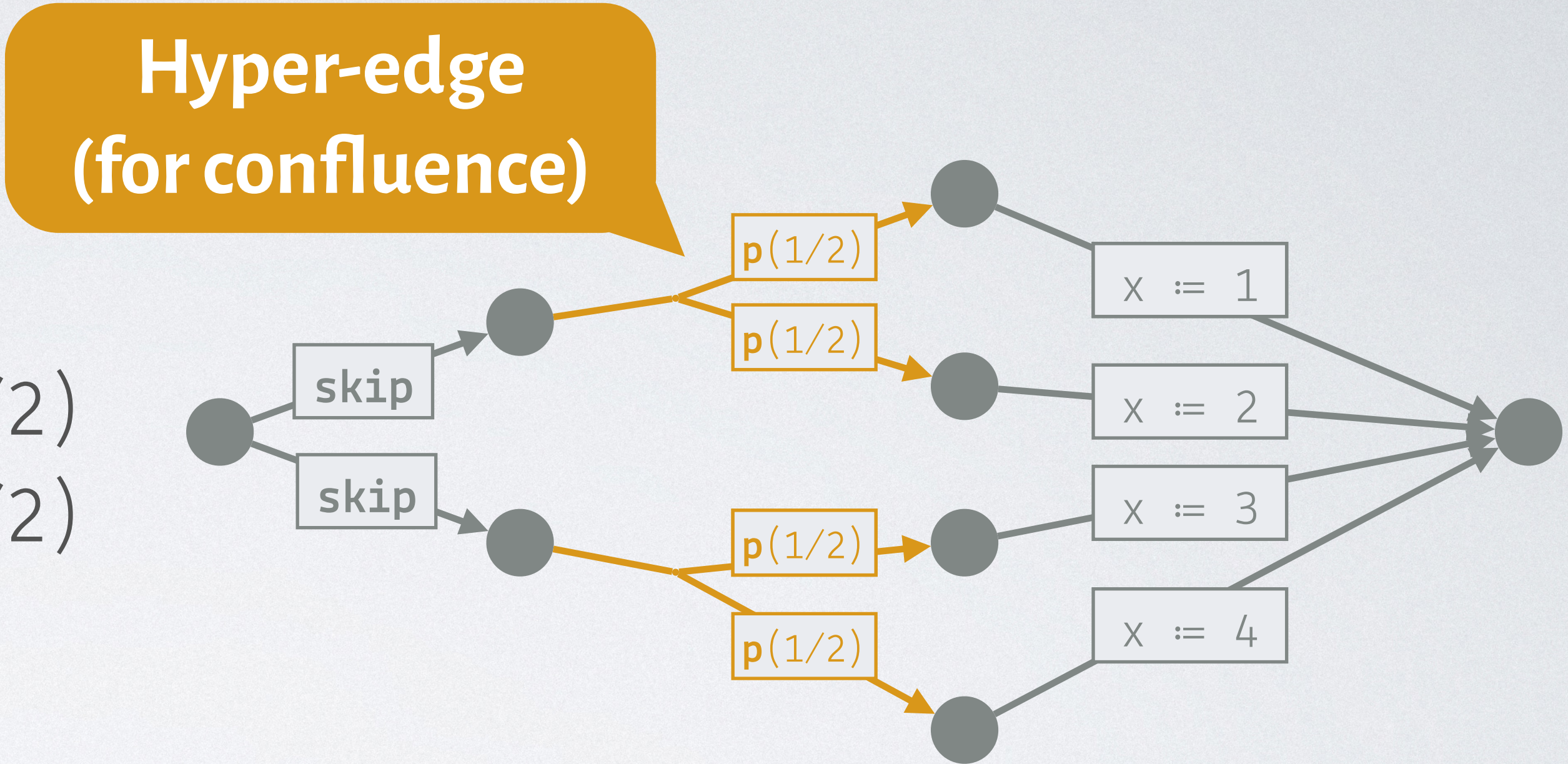
```
if  
| true →  $x \in_p (1 @ 1/2 \mid 2 @ 1/2)$   
| true →  $x \in_p (3 @ 1/2 \mid 4 @ 1/2)$   
fi
```



Our Approach: Control-Flow Hyper-Graphs

```

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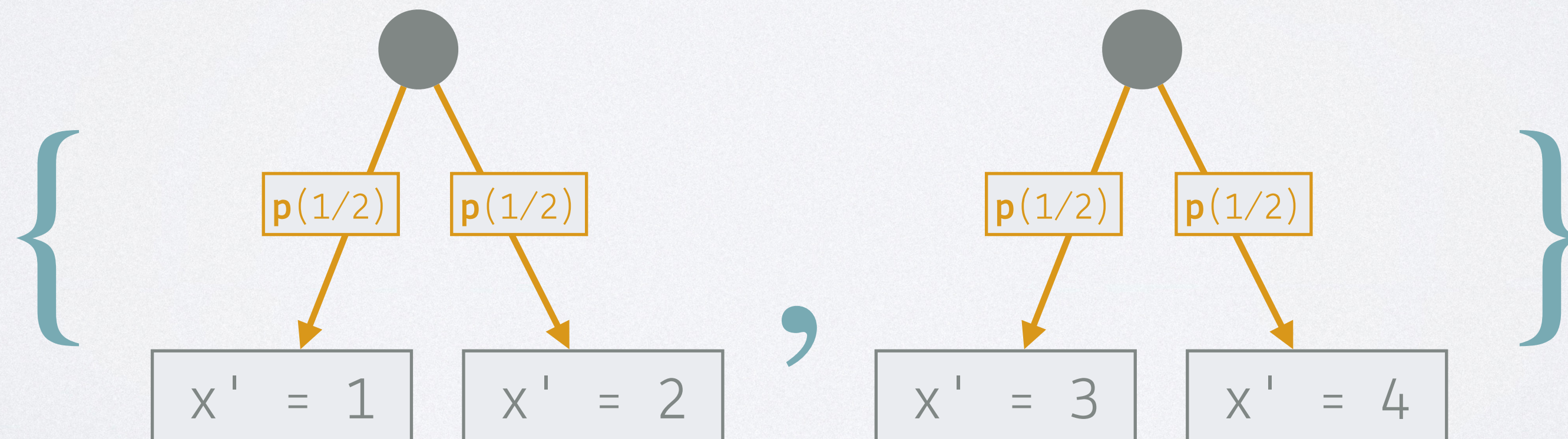
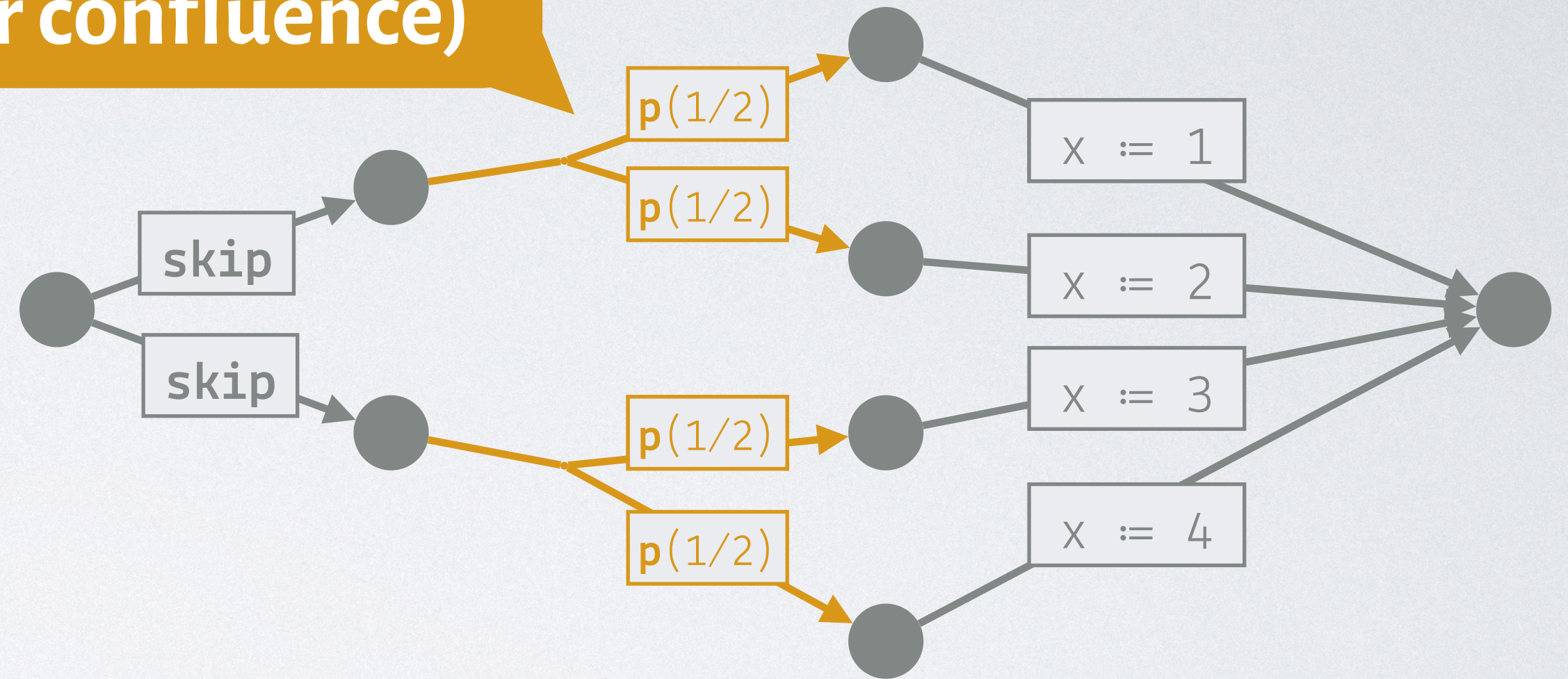


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**Hyper-edge
(for confluence)**

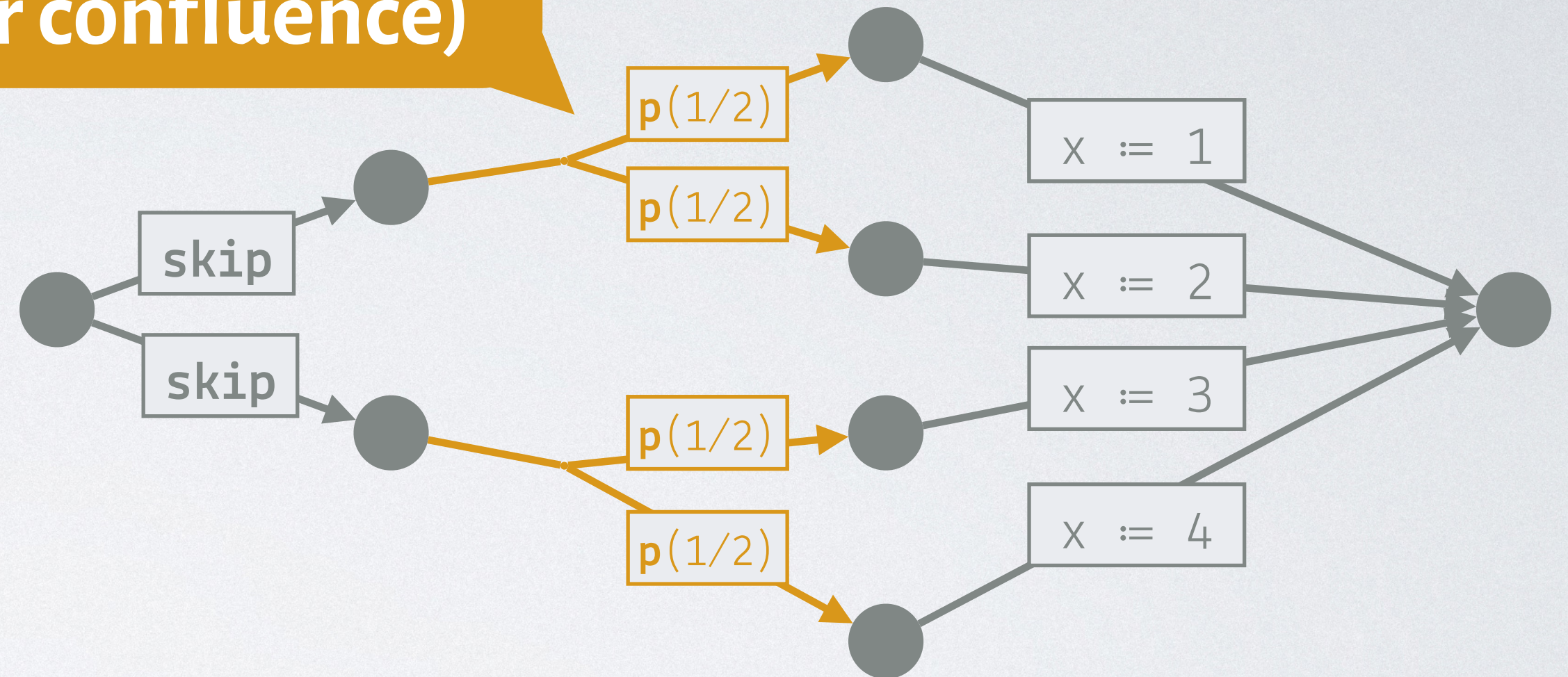


Our Approach: Control-Flow Hyper-Graphs

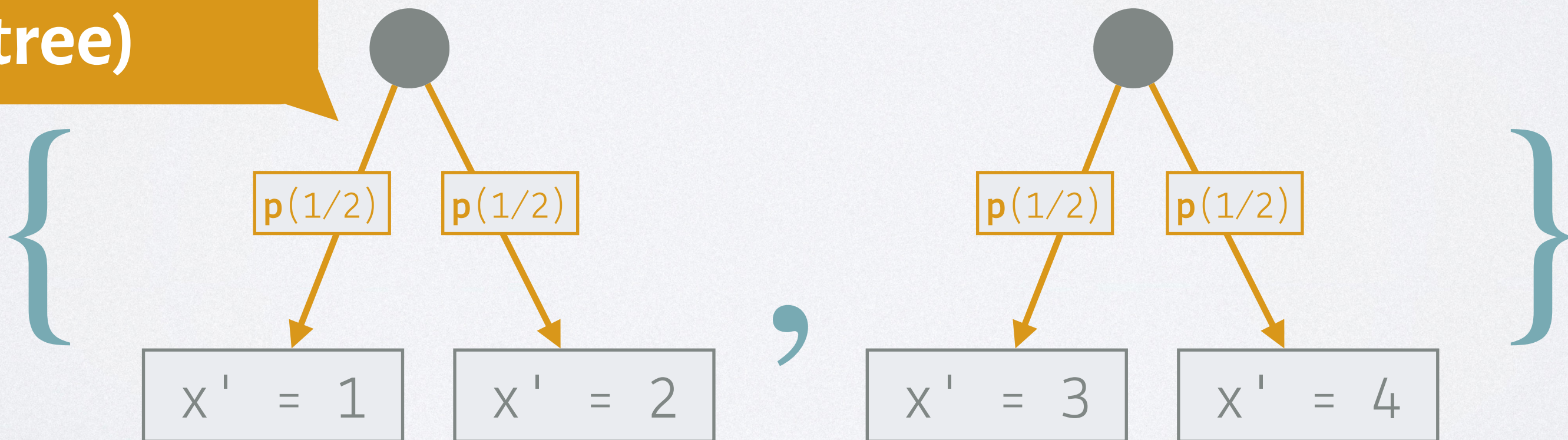
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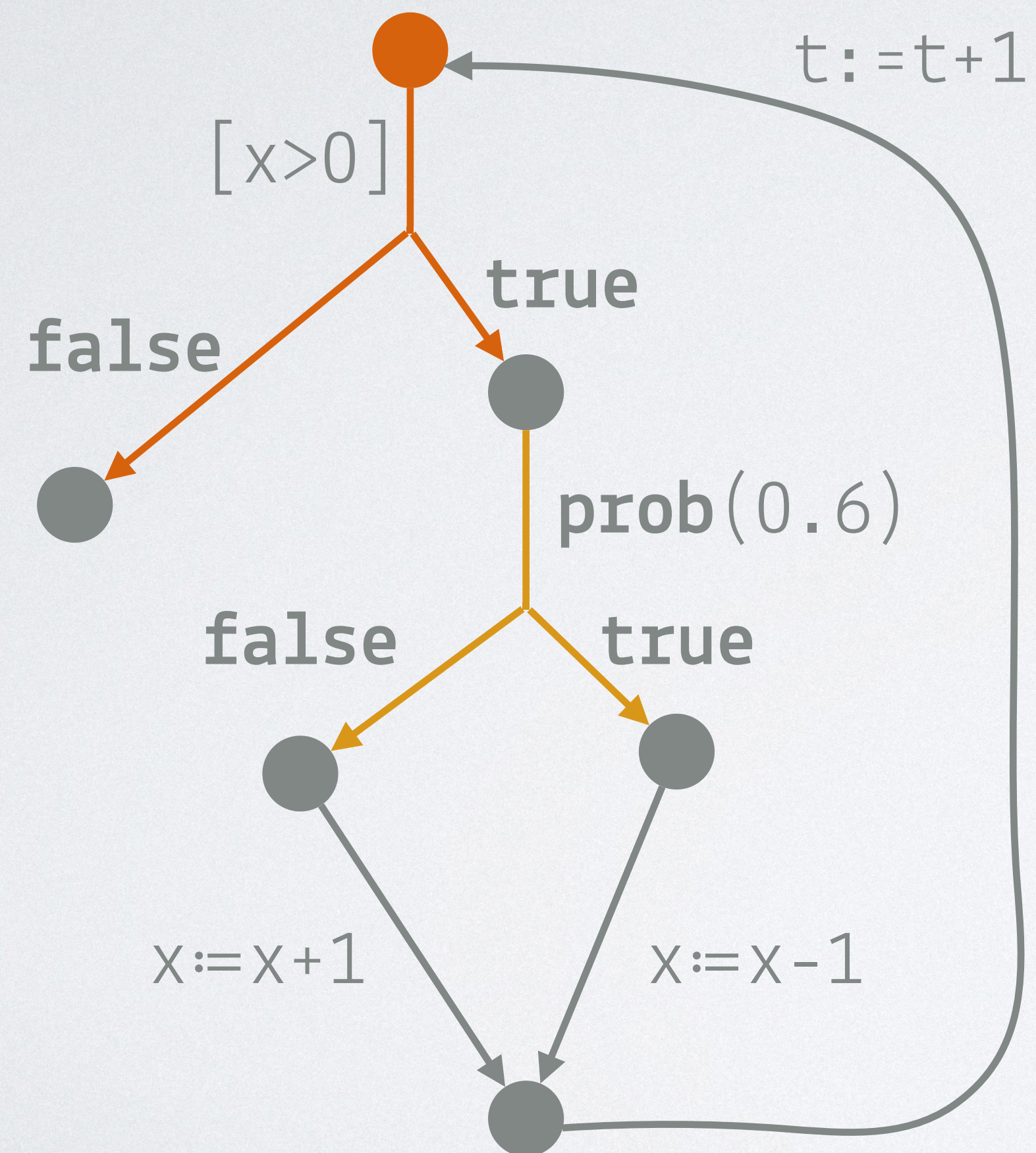
**Hyper-path
(like a tree)**



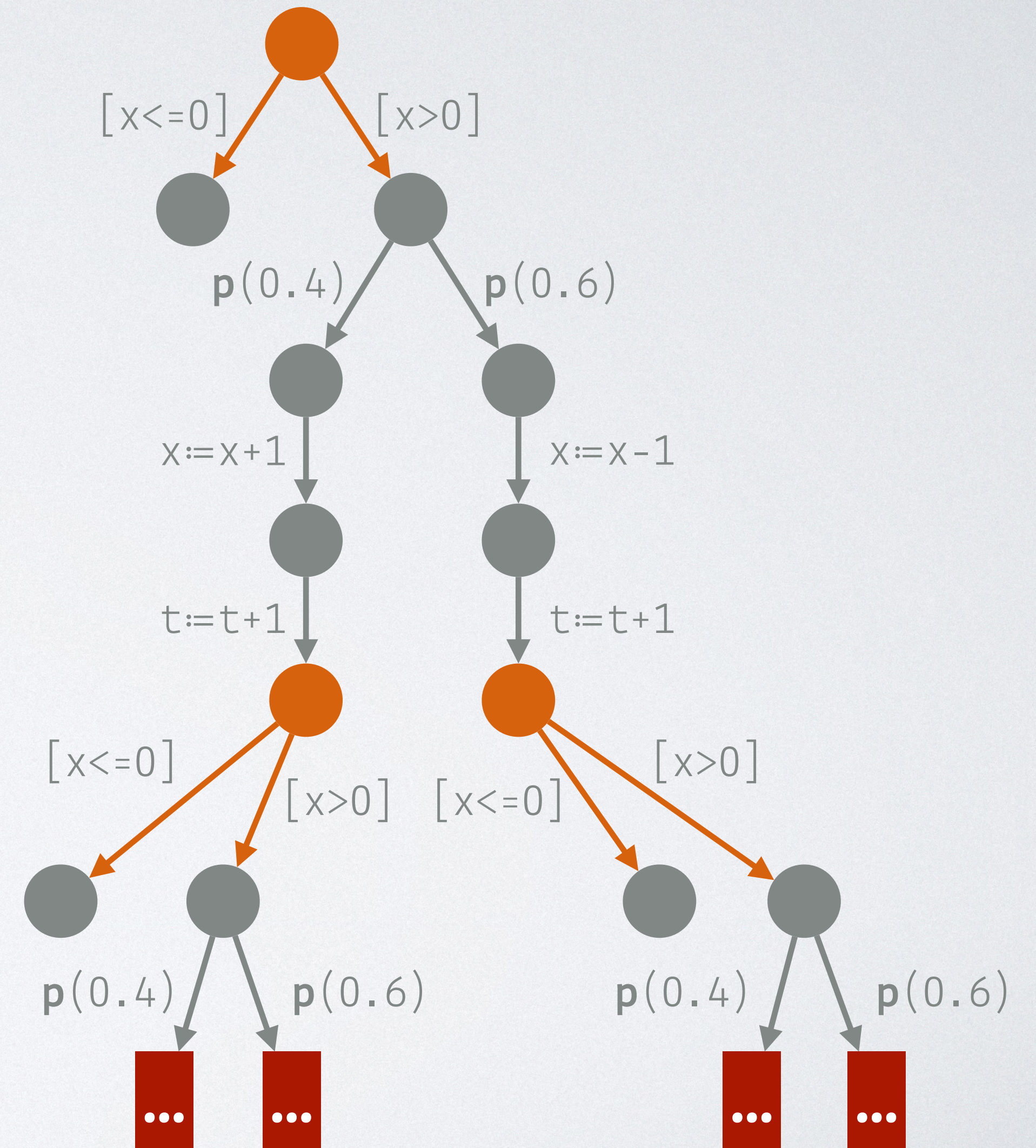
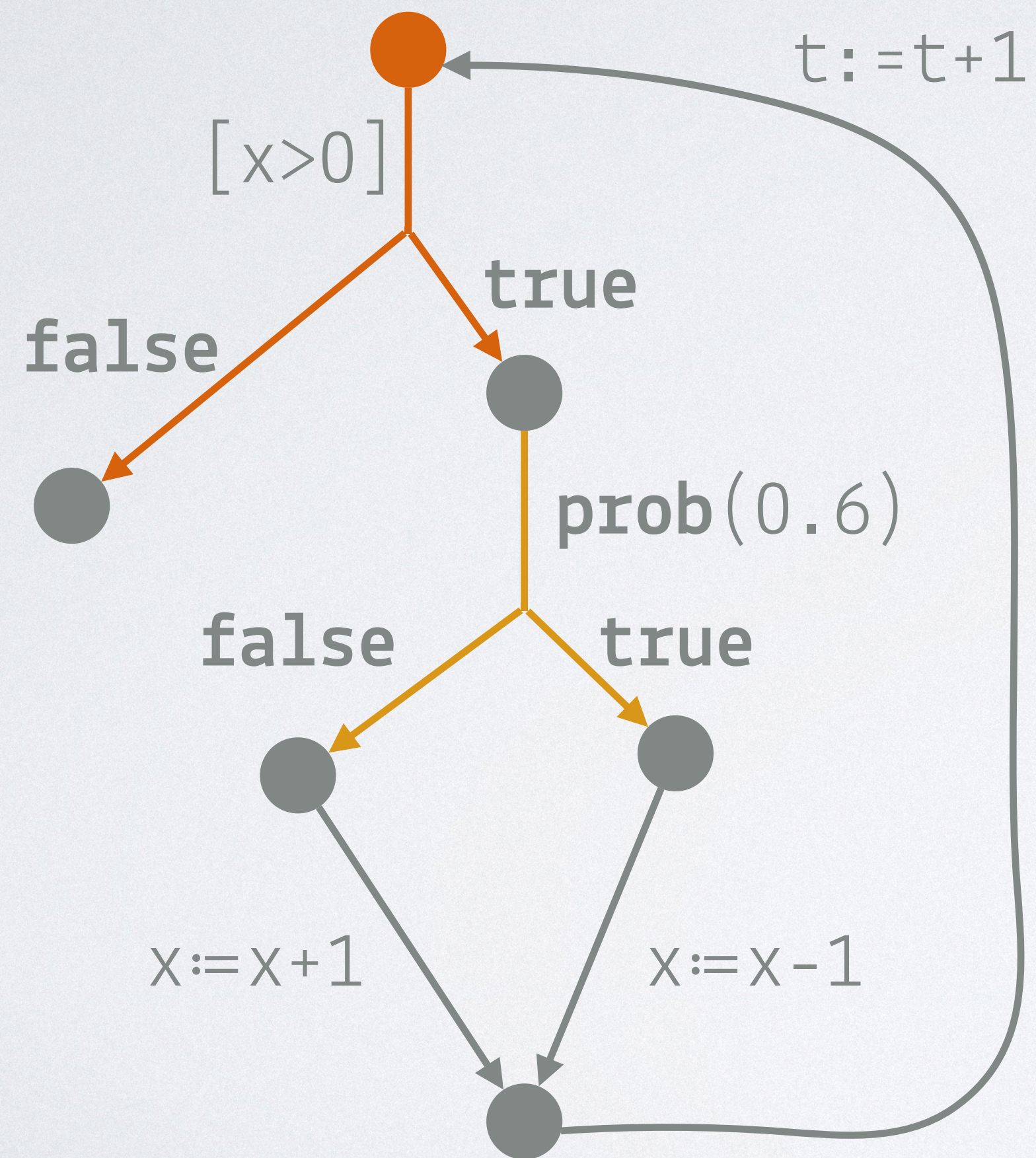


Hyper-Paths are Infinite Trees!

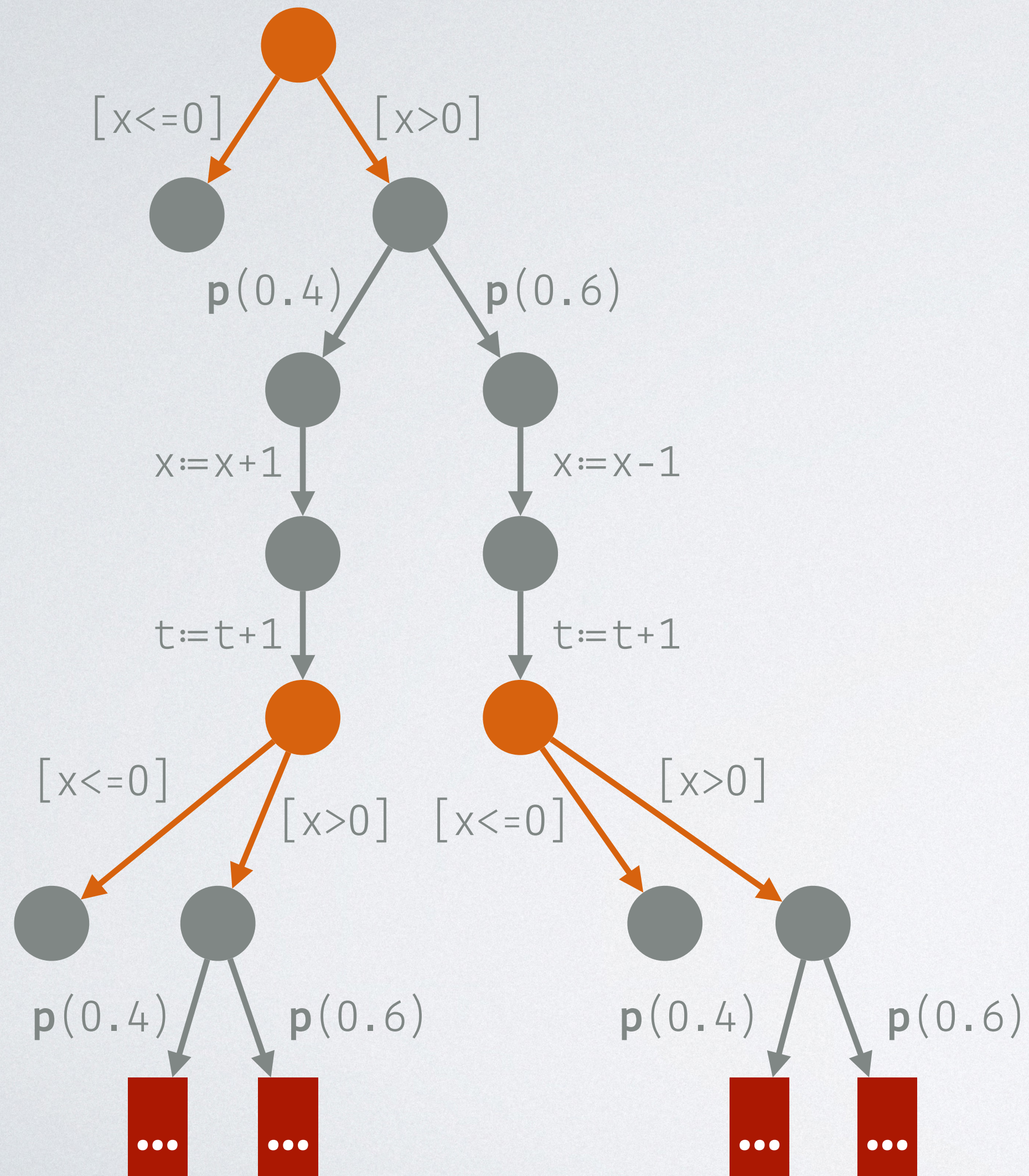
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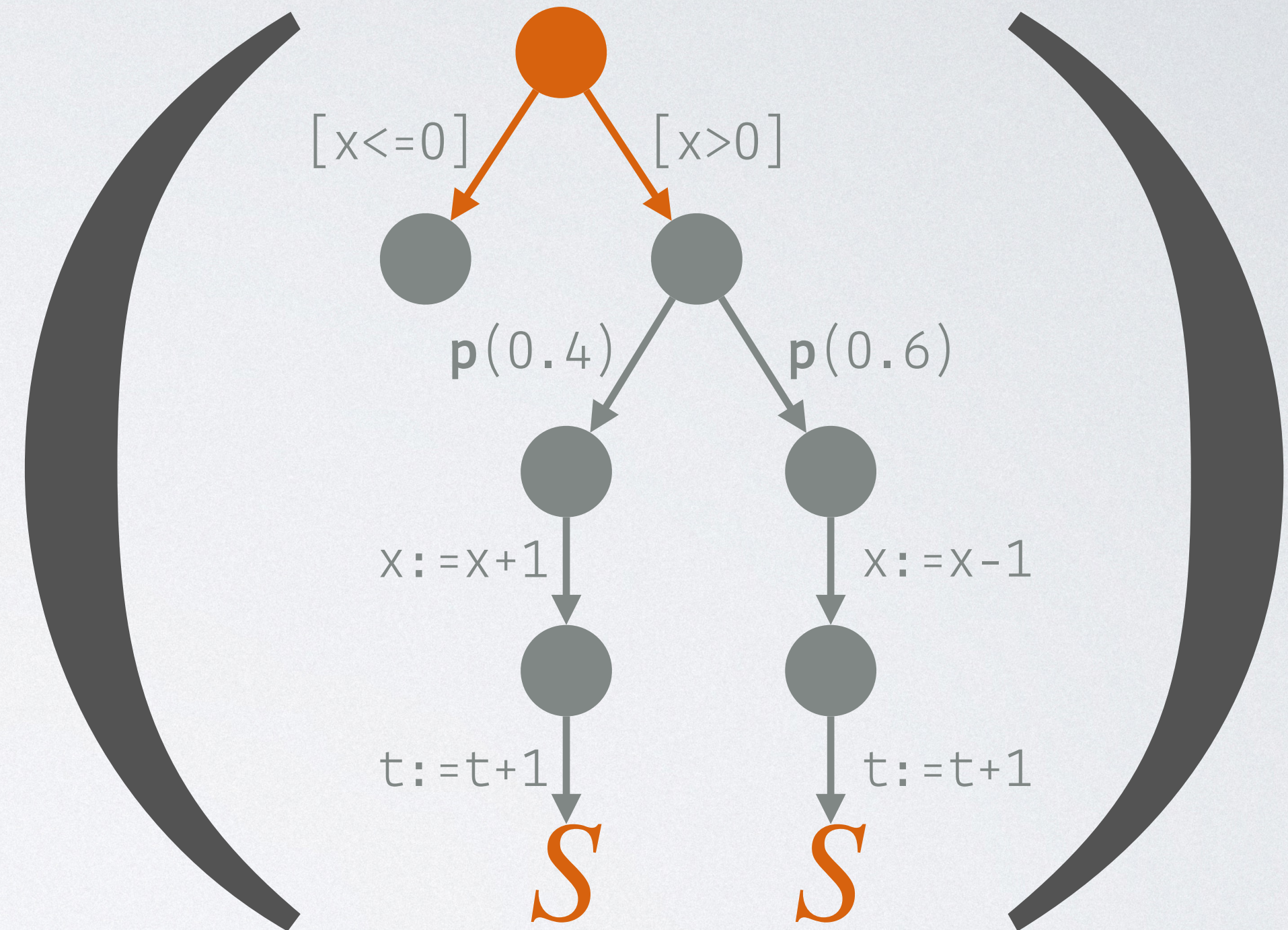
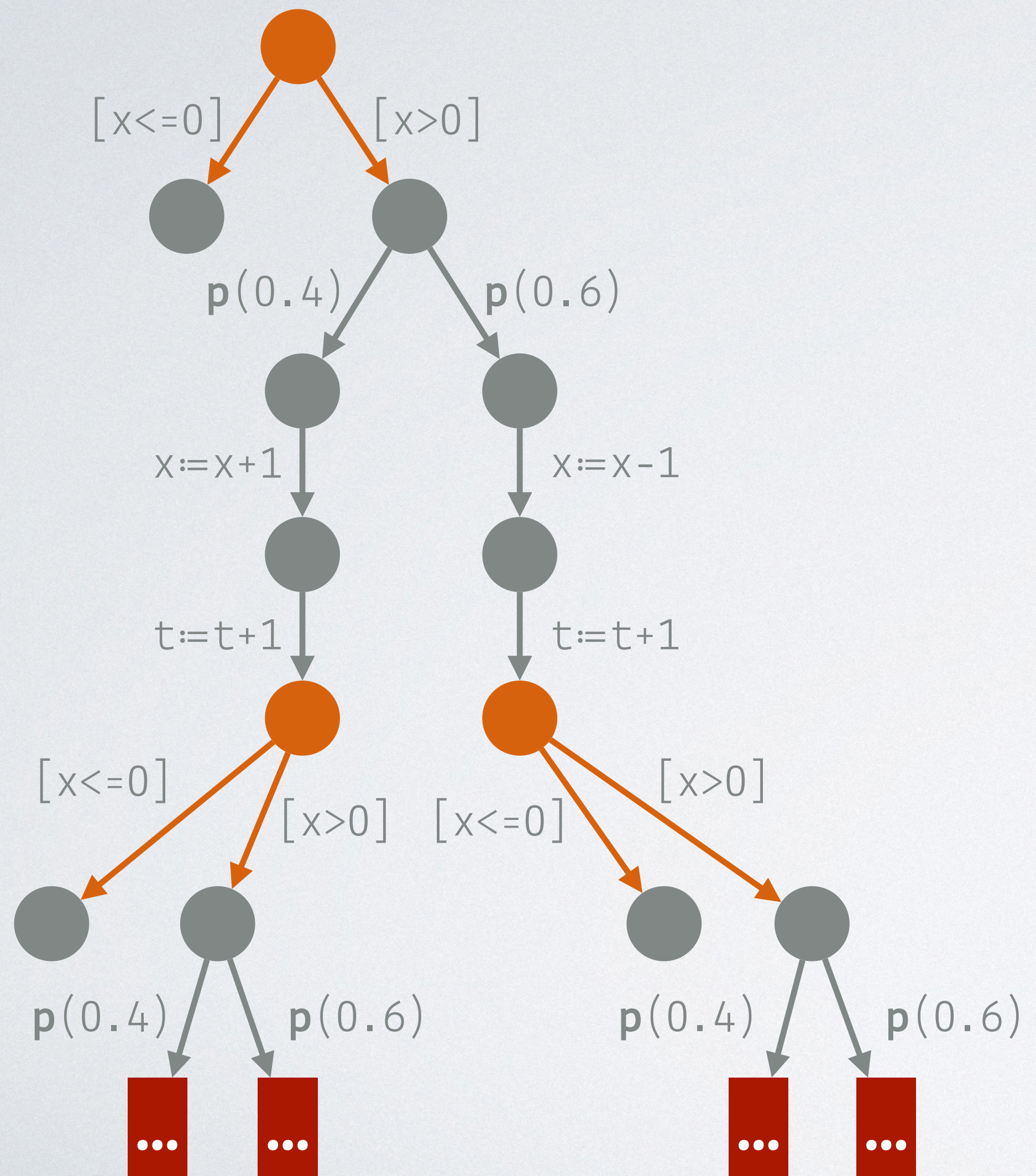
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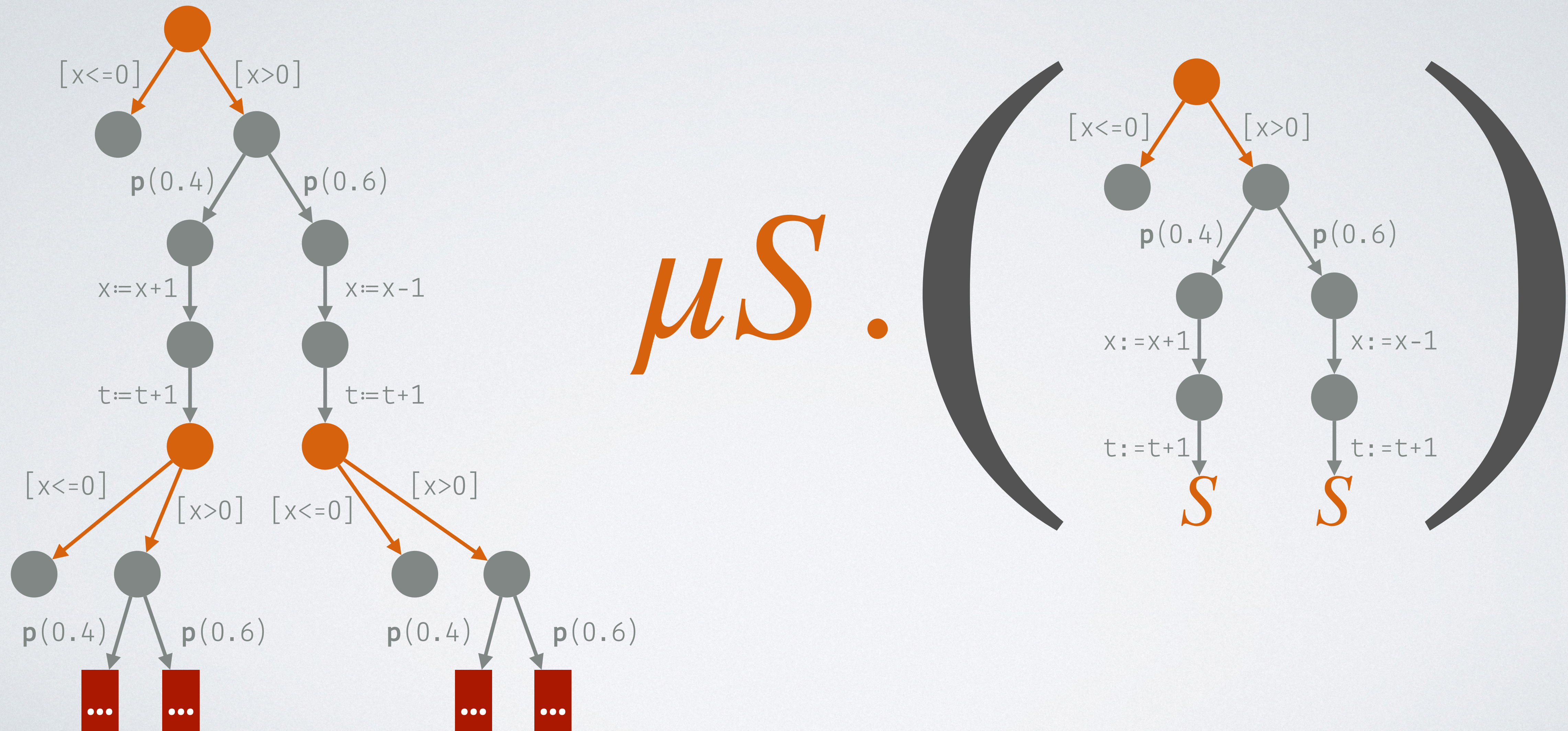
Recursive Program Schemes



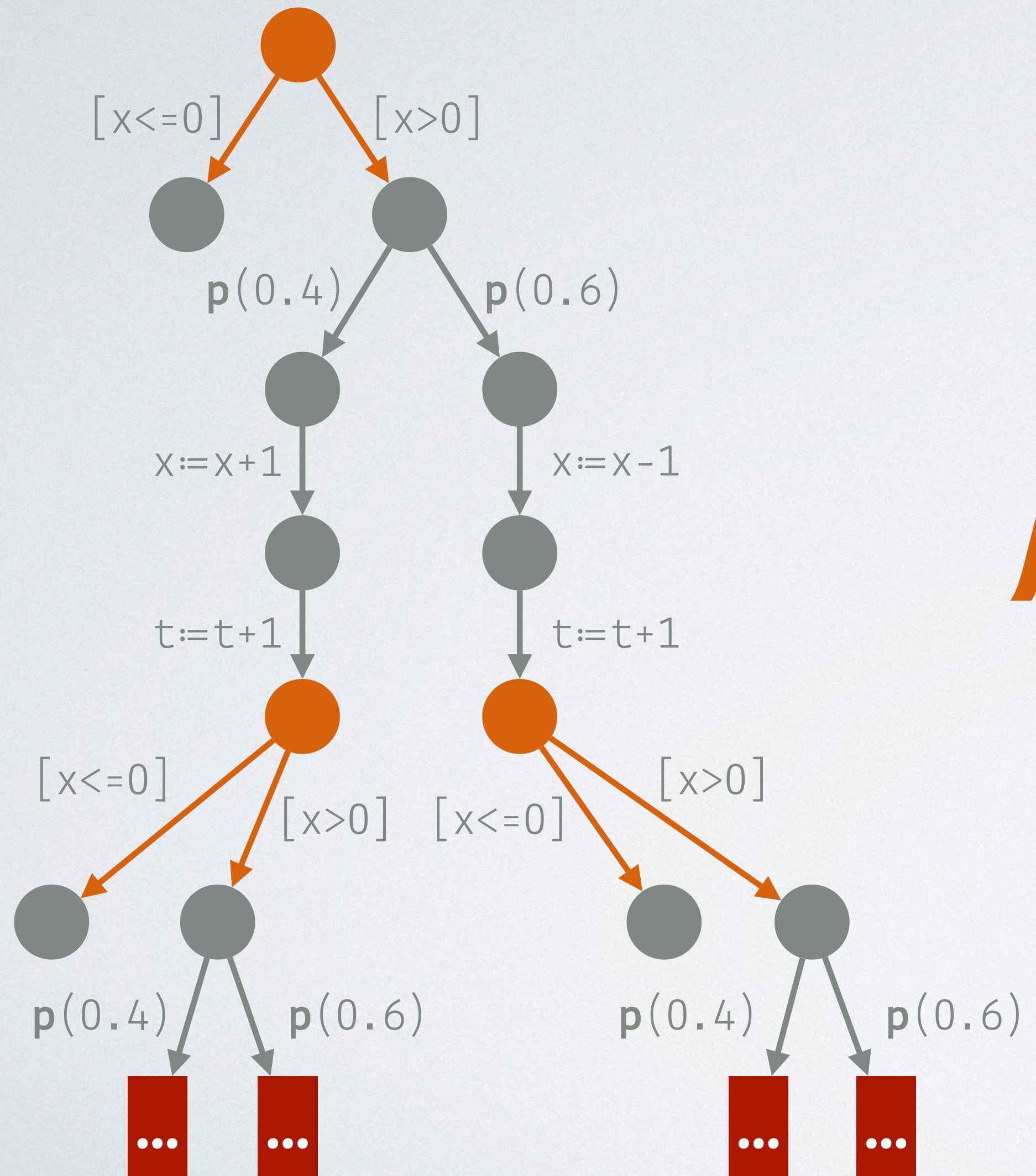
Recursive Program Schemes



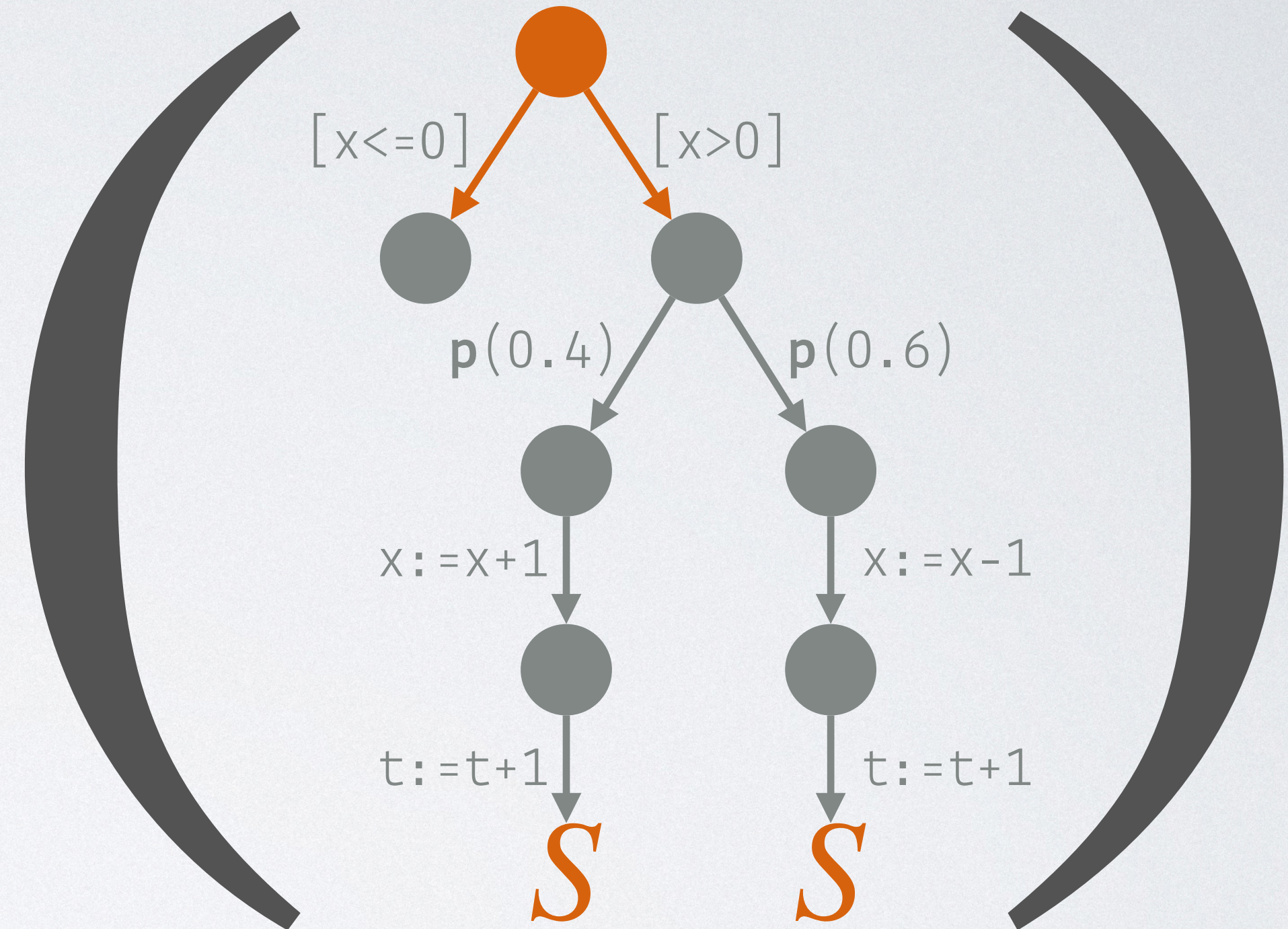
Recursive Program Schemes



Recursive Program Schemes



μS



$$\mu S. \left(\begin{array}{l} \text{cond}[x > 0](\text{prob}[0.6](\text{seq}[x := x - 1](\text{seq}[t := t + 1](S))); \\ \text{seq}[x := x + 1](\text{seq}[t := t + 1](S))); \\ \underline{1} \end{array} \right)$$



A Control-Flow-Hyper-Graph's Perspective

- © **Markov Algebras** are compatible with **control-flow hyper-graphs** via **recursive program schemes**



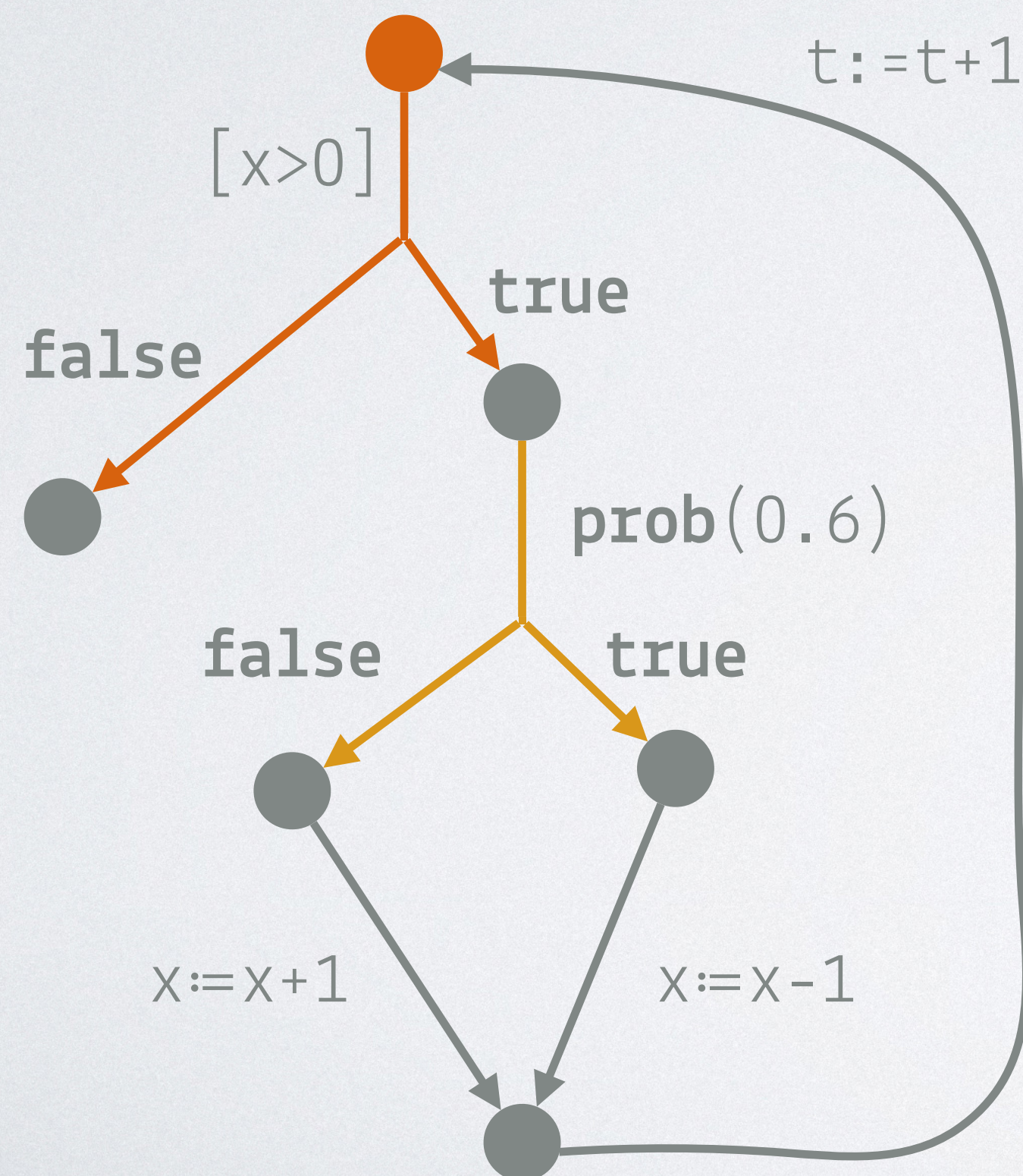
A Control-Flow-Hyper-Graph's Perspective

- **Markov Algebras** are compatible with **control-flow hyper-graphs** via **recursive program schemes**

```
while  $x > 0$  do
  if prob(0.6) then  $x := x + 1$ 
  else  $x := x - 1$  fi;
   $t := t + 1$ 
od
```


A Control-Flow-Hyper-Graph's Perspective

- **Markov Algebras** are compatible with **control-flow hyper-graphs** via **recursive program schemes**

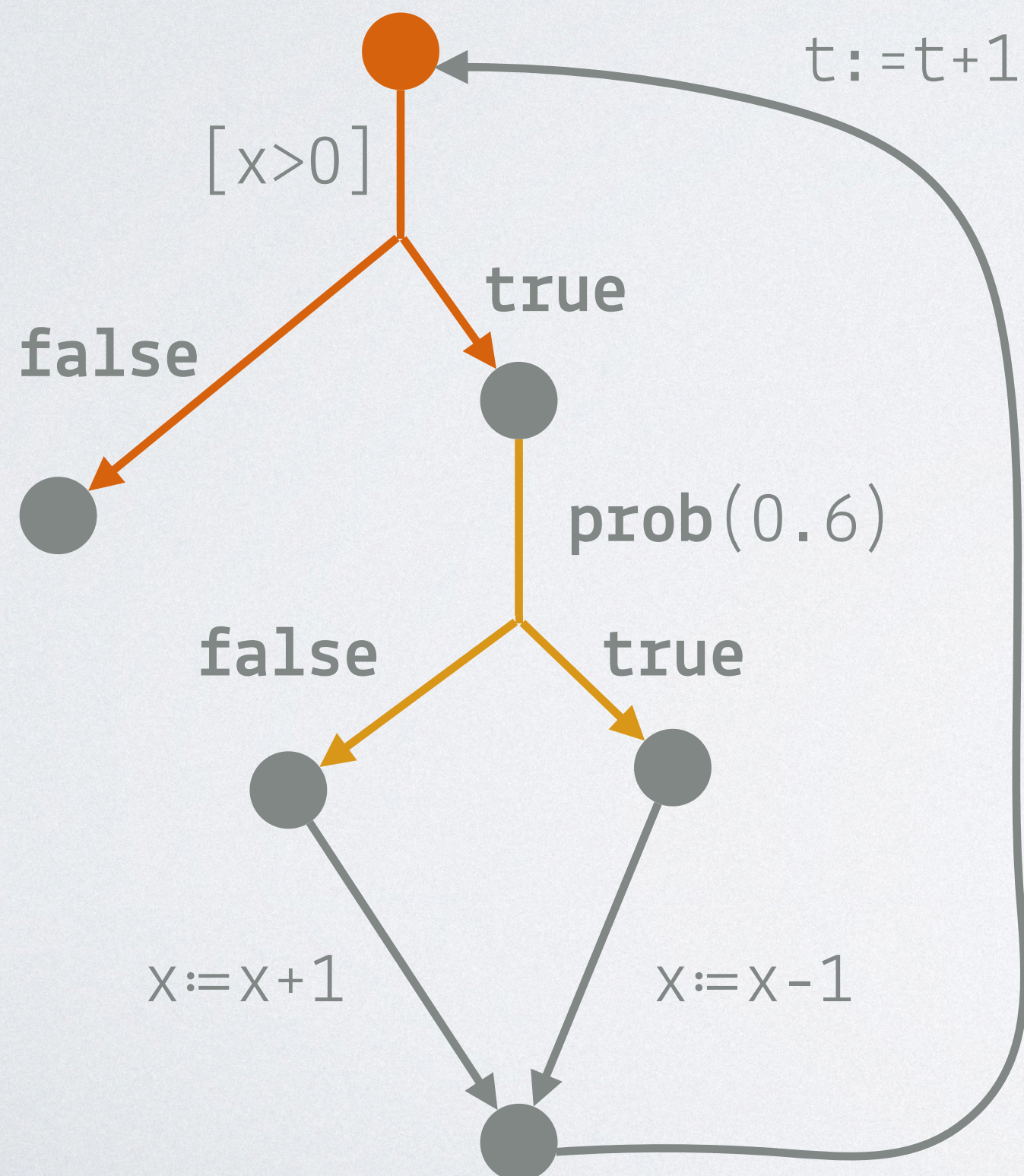


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Challenge III: How to carry out quantitative analyses efficiently?

```
while prob(2/3) do  
  x := x + 1  
od
```



Iterative Program Analysis

```
while prob(2/3) do  
  x := x + 1  
od
```

$$\mu S . ((x := x+1) \otimes S)_{[2/3]} \oplus \mathbf{skip}$$



Iterative Program Analysis

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od
```

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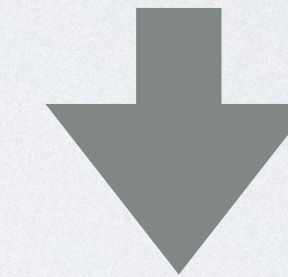
- Markov algebra for computing $\mathbb{E}[\Delta x]$
- Sequencing: $r \otimes t \triangleq r + t$
- Branching: $r_p \oplus t \triangleq p * r + (1 - p) * t$

Iterative Program Analysis

```

while prob(2/3) do
  x := x + 1
od

```

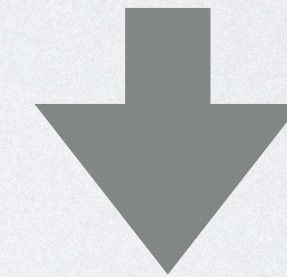
$$\mu S . ((x := x+1) \otimes S)_{[2/3]} \oplus \text{skip}$$


- Markov algebra for computing $\mathbb{E}[\Delta x]$
- Sequencing: $r \otimes t \triangleq r + t$
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$$\begin{aligned} \kappa^{(0)} &= 0 \\ \kappa^{(1)} &= 2/3 * (1 + \kappa^{(0)}) + 1/3 * 0 = 2/3 \\ \kappa^{(2)} &= 2/3 * (1 + \kappa^{(1)}) + 1/3 * 0 = 10/9 \\ &\dots \\ \kappa^{(\infty)} &= 2 \end{aligned}$$

Iterative Program Analysis

```
while prob(2/3) do
  x := x + 1
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```

$$\mu S . ((x := x+1) \otimes S)_{[2/3]} \oplus \text{skip}$$


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$$\kappa^{(1)} = 2/3 * (1 + \kappa^{(0)}) + 1/3 * 0 = 2/3$$

$$\kappa^{(2)} = 2/3 * (1 + \kappa^{(1)}) + 1/3 * 0 = 10/9$$

...

$$\kappa^{(\infty)} = 2$$

Need ∞ iterations to converge!

Non-iterative Program Analysis

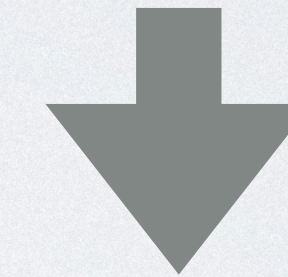
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Non-iterative Program Analysis

```
while prob(2/3) do  
  x := x + 1  
od
```

$$\mu S . ((x := x+1) \otimes S)_{[2/3]} \oplus \text{skip}$$


Equivalent to solve:

$$s = 2/3 * (1 + s) + 1/3 * 0,$$

Analytical solution:

$$s = 2$$

No need for iteration!

- Markov algebra for computing $\mathbb{E}[\Delta x]$
- Sequencing: $r \otimes t \triangleq r + t$
- Branching: $r_p \oplus t \triangleq p * r + (1 - p) * t$



Non-iterative Intra-procedural Analysis



Non-iterative Intra-procedural Analysis

- Observation: Loops are (right-) **linear recursions**, thus we can always extract a system of **linear equations**
 - For each $\mu S . E$, we extract an equation $S = E$



Non-iterative Intra-procedural Analysis

- Observation: Loops are (right-) **linear recursions**, thus we can always extract a system of **linear equations**
 - For each $\mu S . E$, we extract an equation $S = E$
- Techniques to solve linear equation systems extracted from probabilistic programs:
 - **Linear Programming:** Compute probabilities, expectations, or matrices
 - **Loop-Invariant Generation:** Derive probabilistic or expectation invariants



Beyond Loops

```
proc X begin
  if prob(1/3) then
    skip
  else
    call X;
    call X
  fi
end
```



Beyond Loops

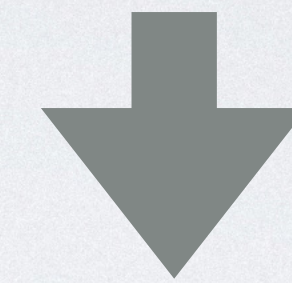
$$X = \mathbf{skip}_{1/3} \oplus (X \otimes X)$$

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Computing $\mathbb{P}[\text{terminate}]$

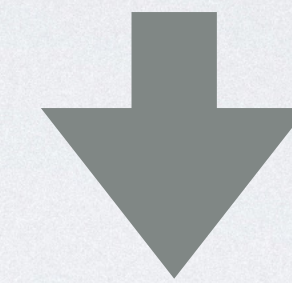
$$p = 1/3 * 1 + 2/3 * (p * p)$$

Beyond Loops

```
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$$X = \text{skip}_{1/3} \oplus (X \otimes X)$$

Non-linear!



Computing $\mathbb{P}[\text{terminate}]$

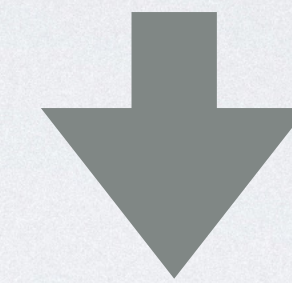
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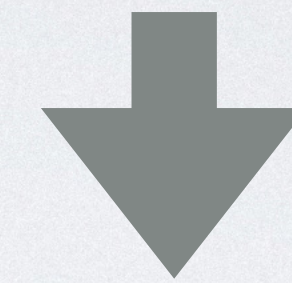
Newton's method

Beyond Loops

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Computing $\mathbb{P}[\text{terminate}]$

$$p = 1/3 * 1 + 2/3 * (p * p)$$

Newton's method

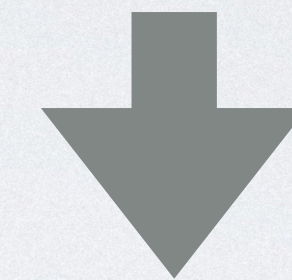
$$f(x) = 1/3 * 1 + 2/3 * (x * x)$$

Beyond Loops

```
proc X begin
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Non-linear!



Computing $\mathbb{P}[\text{terminate}]$

$$p = 1/3 * 1 + 2/3 * (p * p)$$

Newton's method

$$f(x) = 1/3 * 1 + 2/3 * (x * x)$$

$$\Delta^{(i)} = (f(p^{(i)}) - p^{(i)}) + f'(p^{(i)}) * \Delta^{(i)}$$

$$p^{(i+1)} \leftarrow p^{(i)} + \Delta^{(i)}$$

Beyond Loops

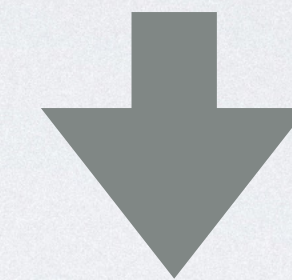
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```

$$X = \text{skip}_{1/3} \oplus (X \otimes X)$$

Non-linear!



Computing $\mathbb{P}[\text{terminate}]$

$$p = 1/3 * 1 + 2/3 * (p * p)$$

Newton's method

$$f(x) = 1/3 * 1 + 2/3 * (x * x)$$

Linear!

$$\Delta^{(i)} = (f(p^{(i)}) - p^{(i)}) + f'(p^{(i)}) * \Delta^{(i)}$$

$$p^{(i+1)} \leftarrow p^{(i)} + \Delta^{(i)}$$



Newton's Method



Newton's Method

- Solve the equation $f(x) = 0$ where $f'(x)$ is well-defined



Newton's Method

$$p = 1/3 * 1 + 2/3 * (p * p)$$

$$f(x) = 1/3 * 1 + 2/3 * (x * x) - x$$

$$= 2/3 * x^2 - x + 1/3$$

$$f'(x) = 4/3 * x - 1$$

- Solve the equation $f(x) = 0$ where $f'(x)$ is well-defined



Newton's Method

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$$f(x) = 1/3 * 1 + 2/3 * (x * x) - x$$

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- Start from an initial approximation $\nu^{(0)}$

$$\nu^{(0)} \leftarrow 0$$



Newton's Method

- Solve the equation $f(x) = 0$ where $f'(x)$ is well-defined

- Start from an initial approximation $\nu^{(0)}$

- At step i , solve a linear equation

$$f(\nu^{(i)}) + f'(\nu^{(i)}) * (y - \nu^{(i)}) = 0, \text{ i.e., set } \nu^{(i+1)} = \nu^{(i)} - f(\nu^{(i)})/f'(\nu^{(i)})$$

$$p = 1/3 * 1 + 2/3 * (p * p)$$

$$f(x) = 1/3 * 1 + 2/3 * (x * x) - x$$

$$= 2/3 * x^2 - x + 1/3$$

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Newton's Method

- Solve the equation $f(x) = 0$ where $f'(x)$ is well-defined

- Start from an initial approximation $\nu^{(0)}$

- At step i , solve a linear equation $f(\nu^{(i)}) + f'(\nu^{(i)}) * (y - \nu^{(i)}) = 0$, i.e., set $\nu^{(i+1)} = \nu^{(i)} - f(\nu^{(i)})/f'(\nu^{(i)})$

$$p = 1/3 * 1 + 2/3 * (p * p)$$

$$\begin{aligned} f(x) &= 1/3 * 1 + 2/3 * (x * x) - x \\ &= 2/3 * x^2 - x + 1/3 \end{aligned}$$

$$f'(x) = 4/3 * x - 1$$

$$\nu^{(0)} \leftarrow 0$$

$$\nu^{(1)} = 0 - f(0)/f'(0) = 1/3$$

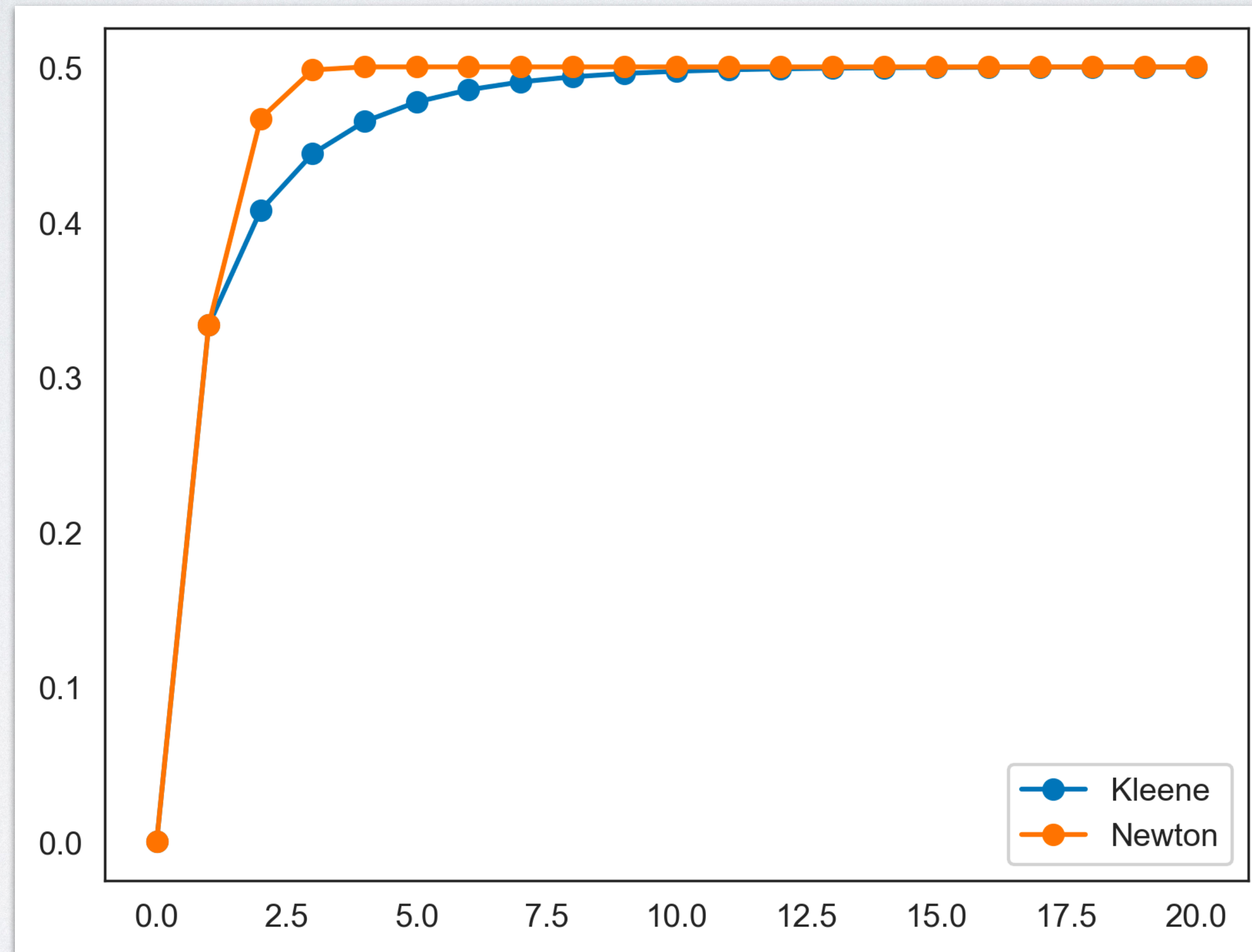
$$\nu^{(2)} = 1/3 - f(1/3)/f'(1/3) = 7/15$$

$$\nu^{(3)} = 7/15 - f(7/15)/f'(7/15) = 127/255$$

...

$$\nu^{(\infty)} = 1/2$$

Newton's Method Converges Faster



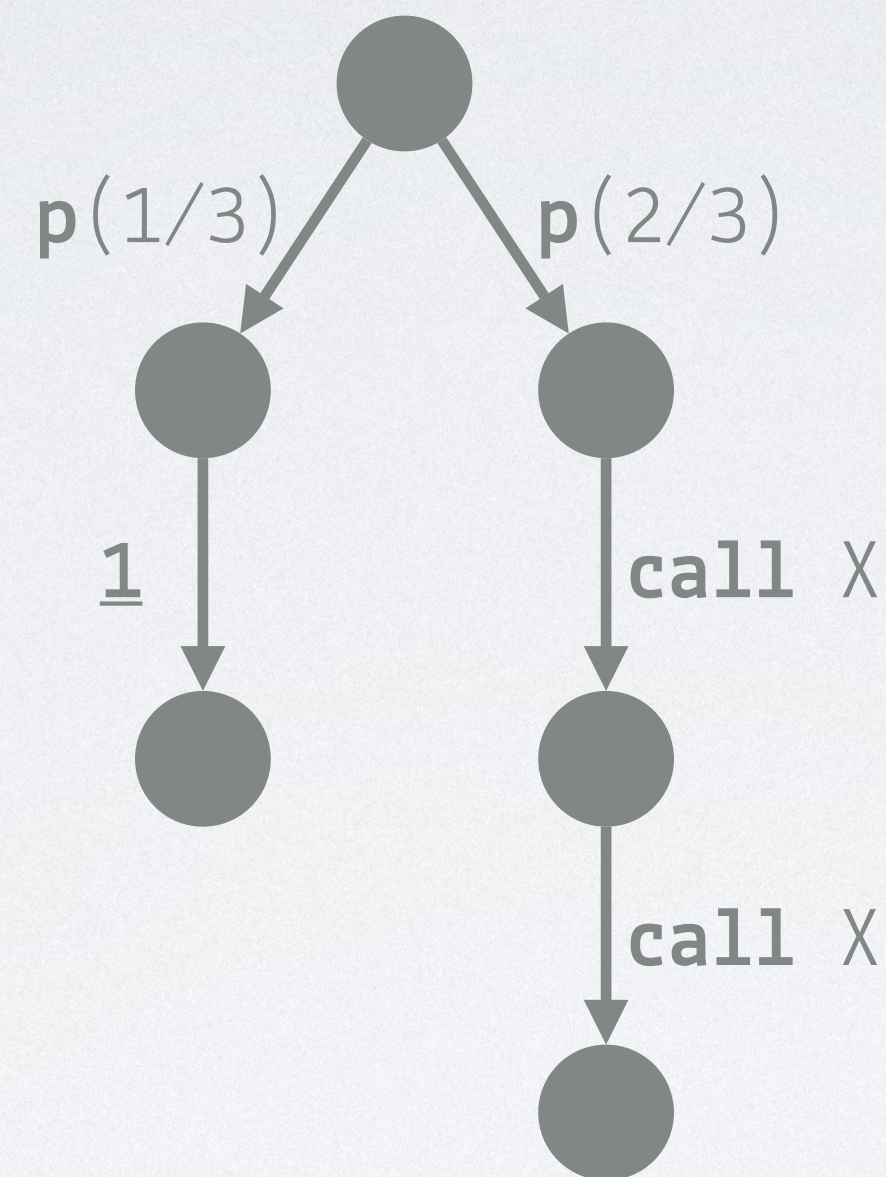


Newtonian Program Analysis (NPA)

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proc X begin
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```

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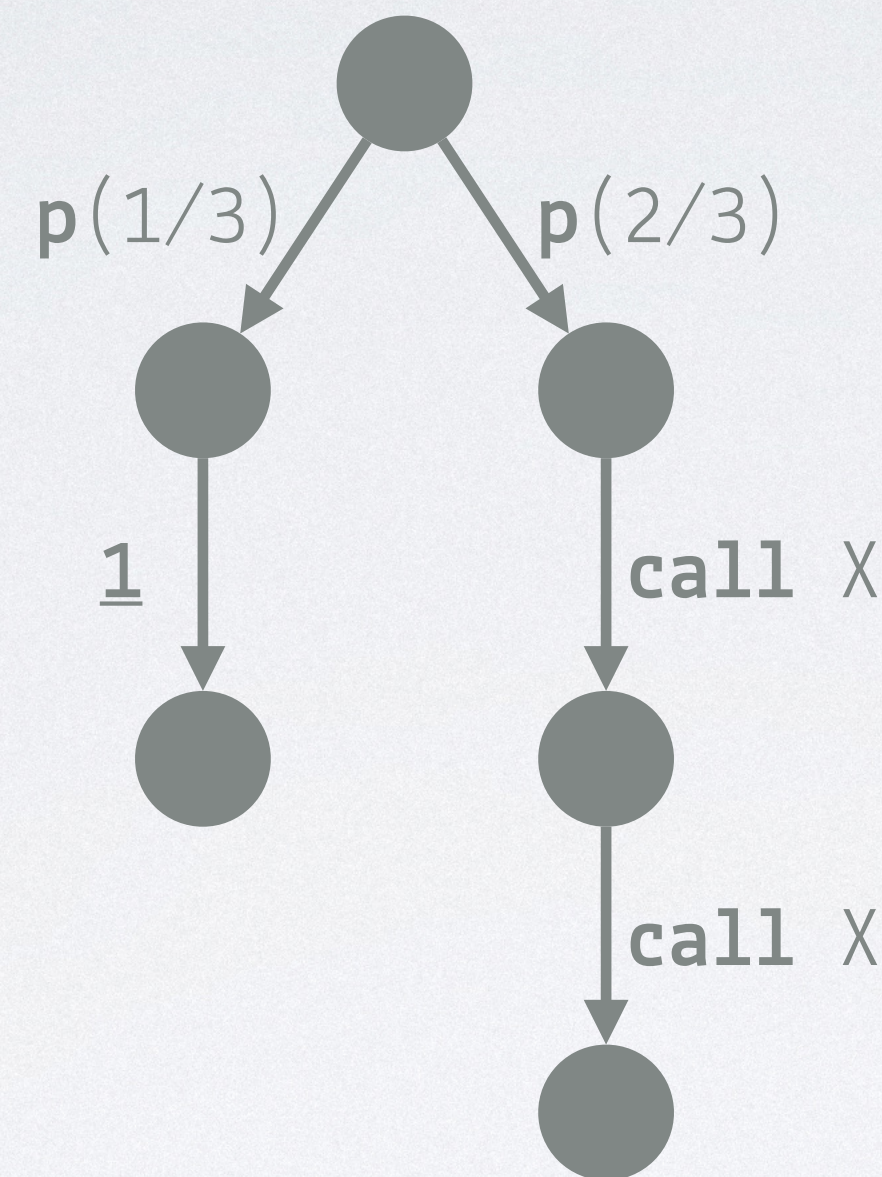


Newtonian Program Analysis (NPA)

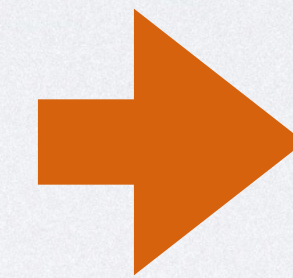
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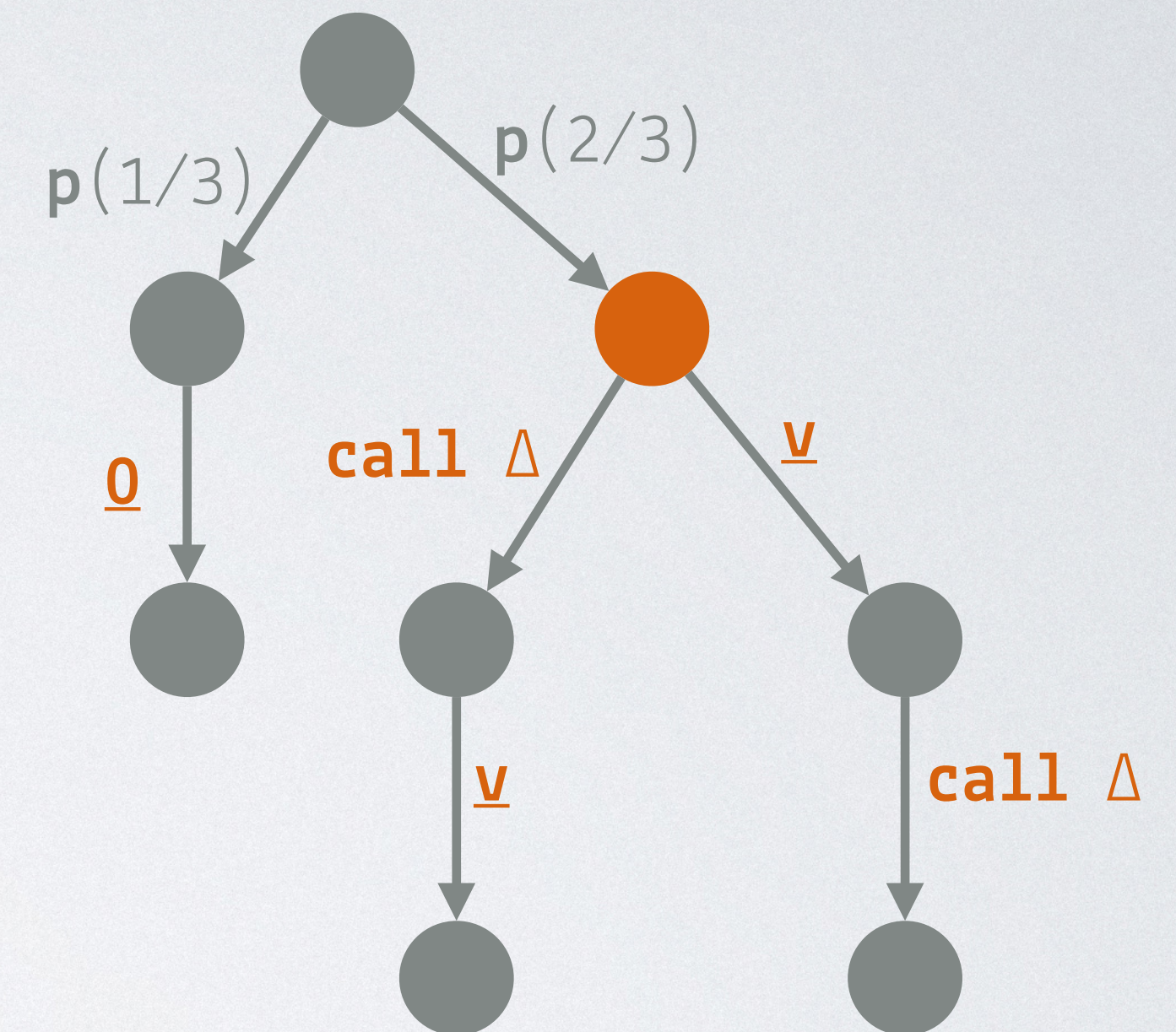
```



Differentiate



When $X = \underline{v}$

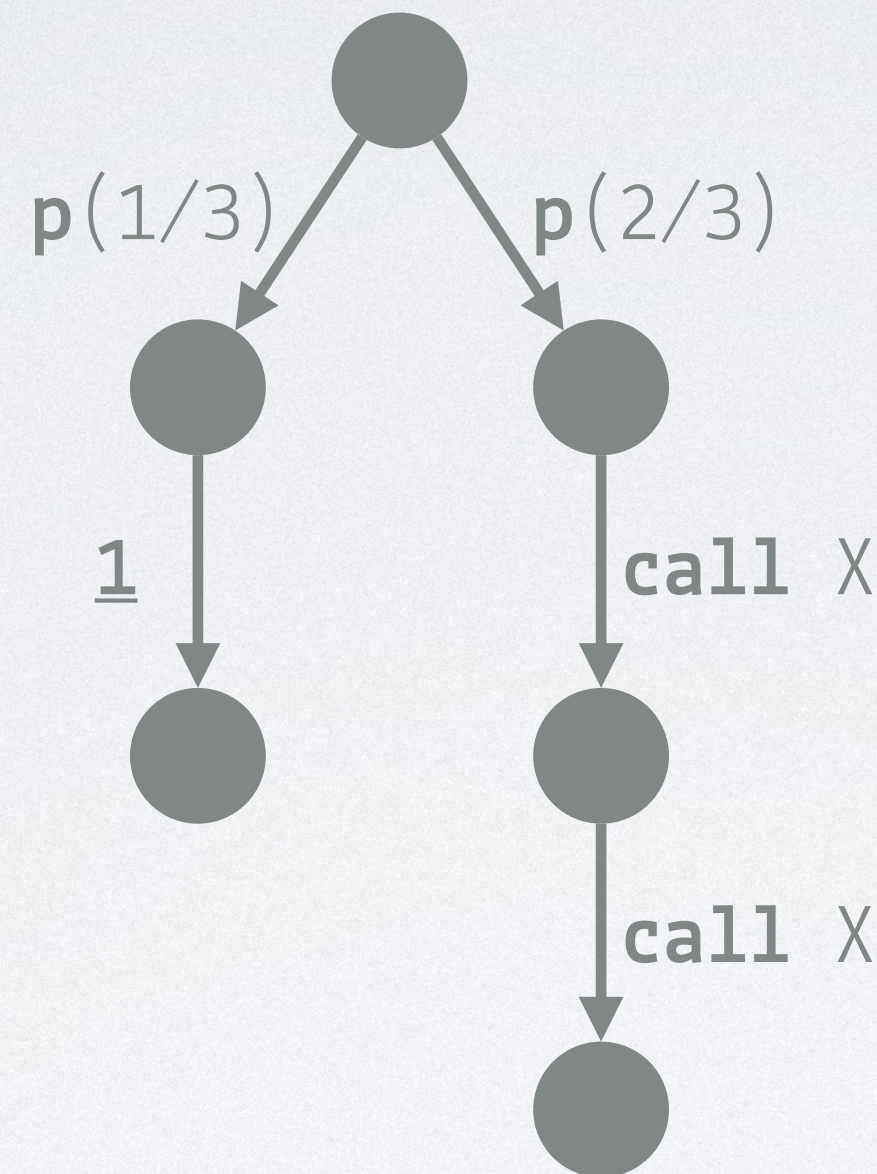


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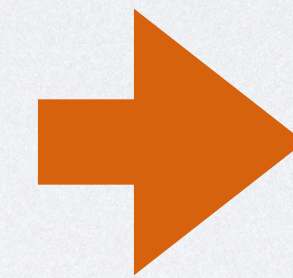
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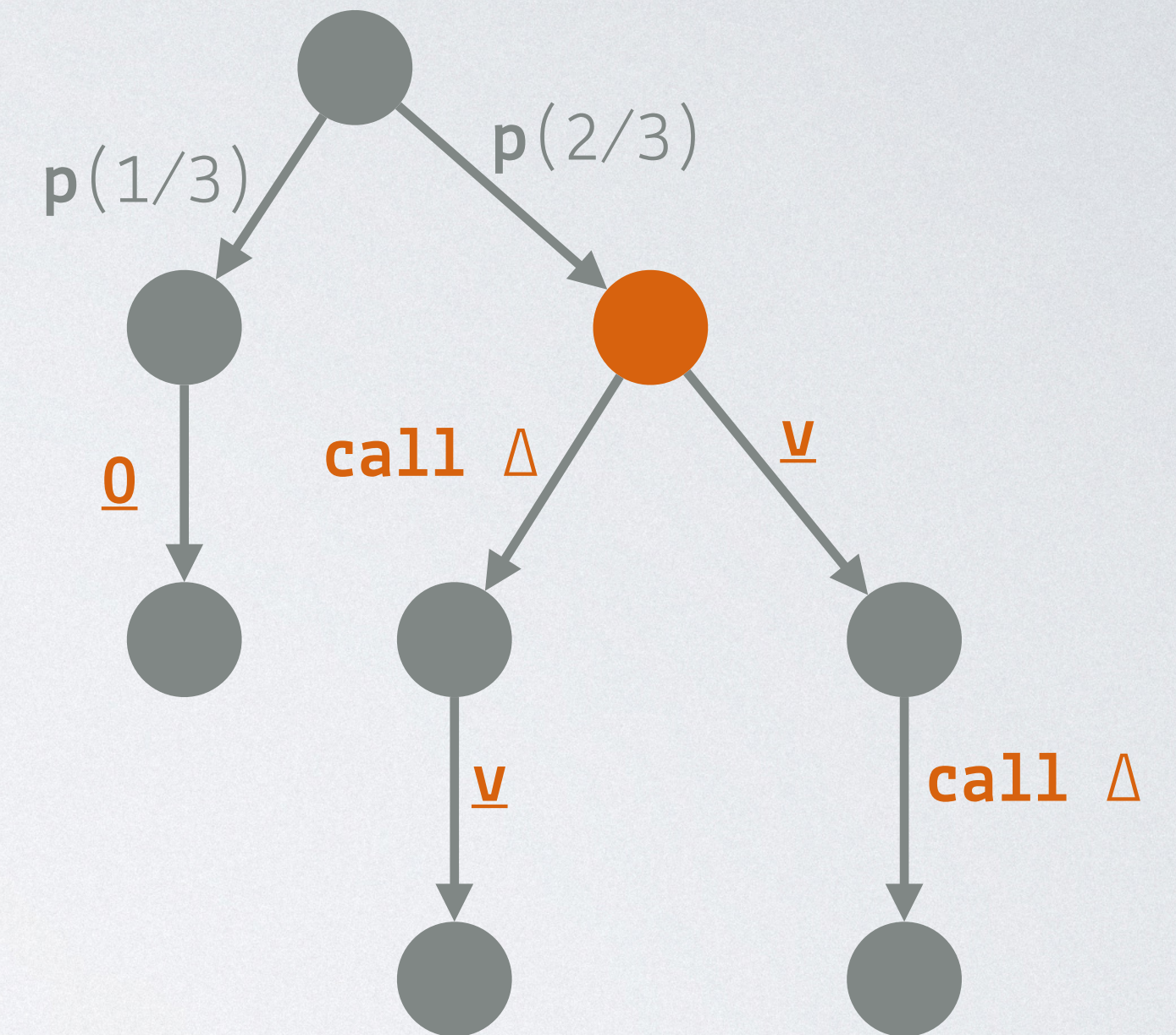
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Differentiate



When $X = \underline{v}$



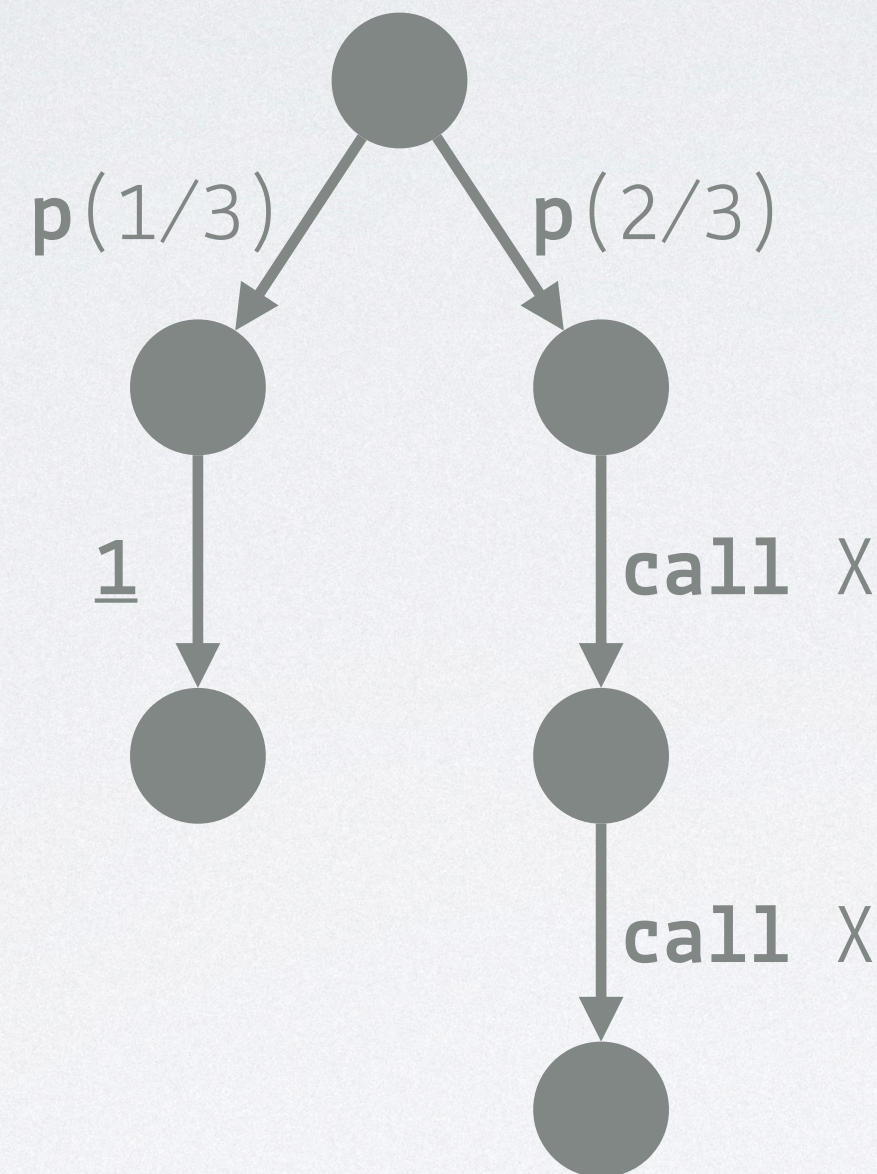
Every root-to-leaf path contains **at most one call!**

Newtonian Program Analysis (NPA)

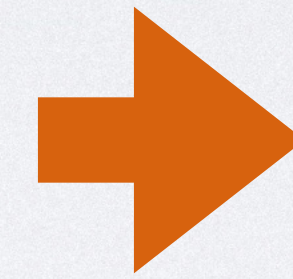
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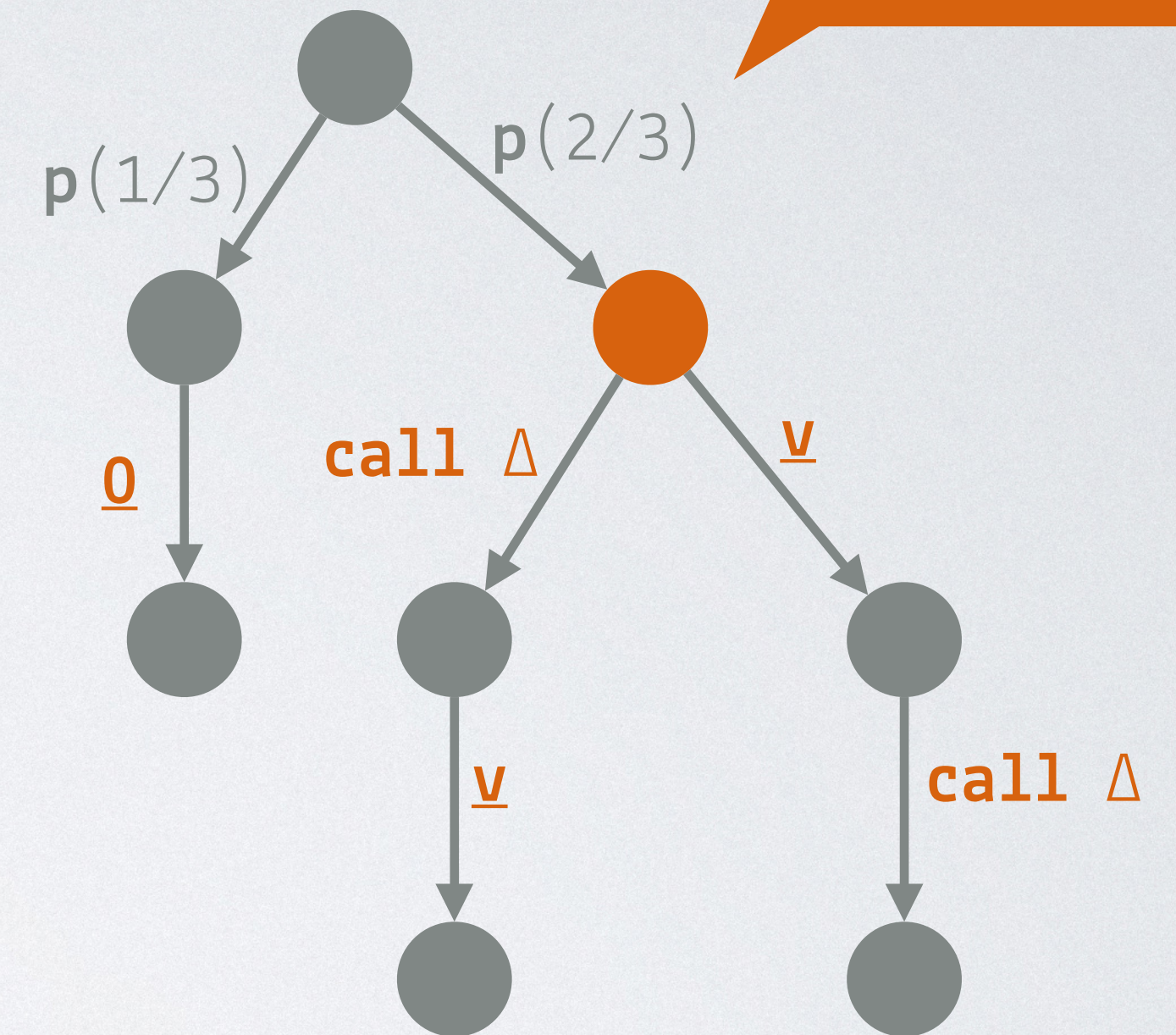
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Differentiate



When $X = \underline{v}$



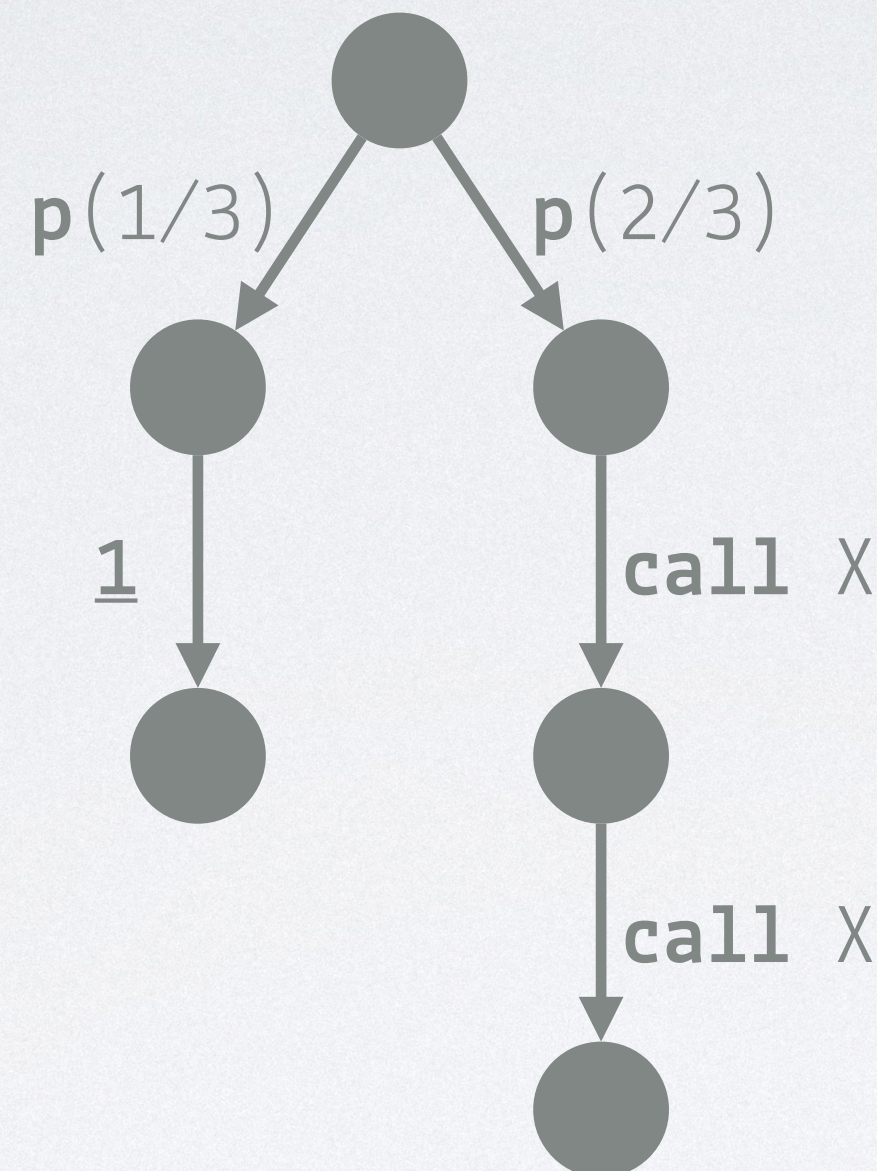
Linear!

Every root-to-leaf path contains **at most one call!**

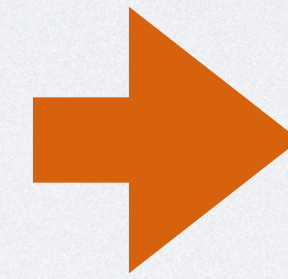
Newtonian Program Analysis (NPA)

```

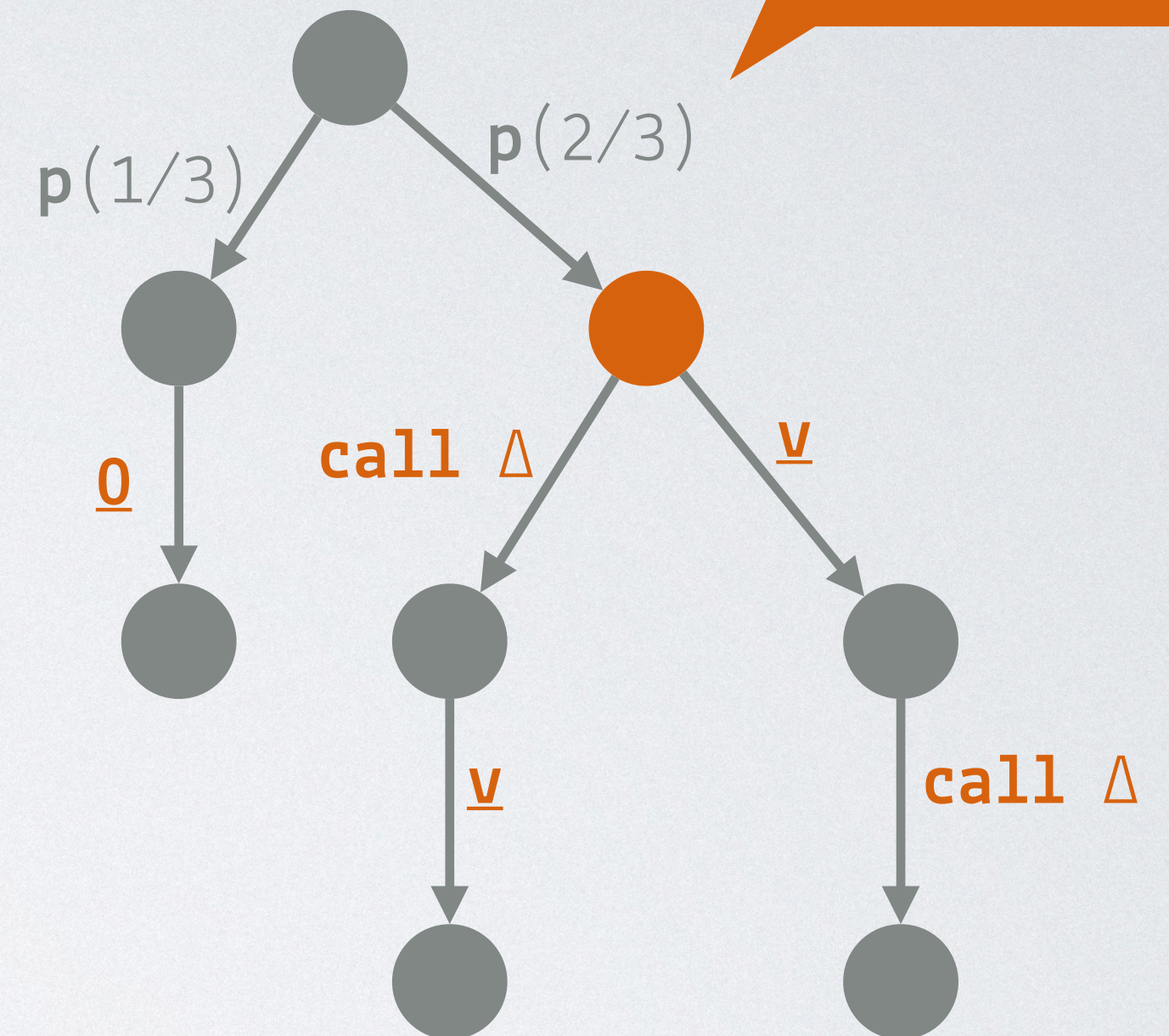
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Linear!

Every root-to-leaf path contains **at most one call!**

$$\frac{d(f * g)}{dx} = \frac{df}{dx} * g + f * \frac{dg}{dx}$$



Newtonian Program Analysis (NPA)



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$$\mathcal{D}(f \oplus g)|_{\nu}(Y) \triangleq \mathcal{D}f|_{\nu}(Y) \oplus \mathcal{D}g|_{\nu}(Y)$$

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Procedure call to X

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Branching $\mathcal{D}(X)|_{\nu}(Y) \triangleq Y$

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Sequencing $\mathcal{D}(f \oplus g) |_{\nu}(Y) \triangleq \mathcal{D}f |_{\nu}(Y) \oplus \mathcal{D}g |_{\nu}(Y)$

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Interpreting calls to X in g by ν

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Interpreting calls to X in g by ν

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Interpreting calls to X in g by ν



Our Approach: NPA for pre-Markov Algebras

- Key idea: Apply Newton's method to **pre-Markov algebras**
- We develop a differentiation routine for **recursive program schemes**



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Support multiple confluences,
loops, and recursion

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$$\langle M, \oplus, \otimes, \phi \oplus, \sqcap, \underline{0}, \underline{1} \rangle$$

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\oplus defines a partial order and gives an additive structure

$$\langle M, \oplus, \otimes, \phi \oplus, \sqcap, \underline{0}, \underline{1} \rangle$$



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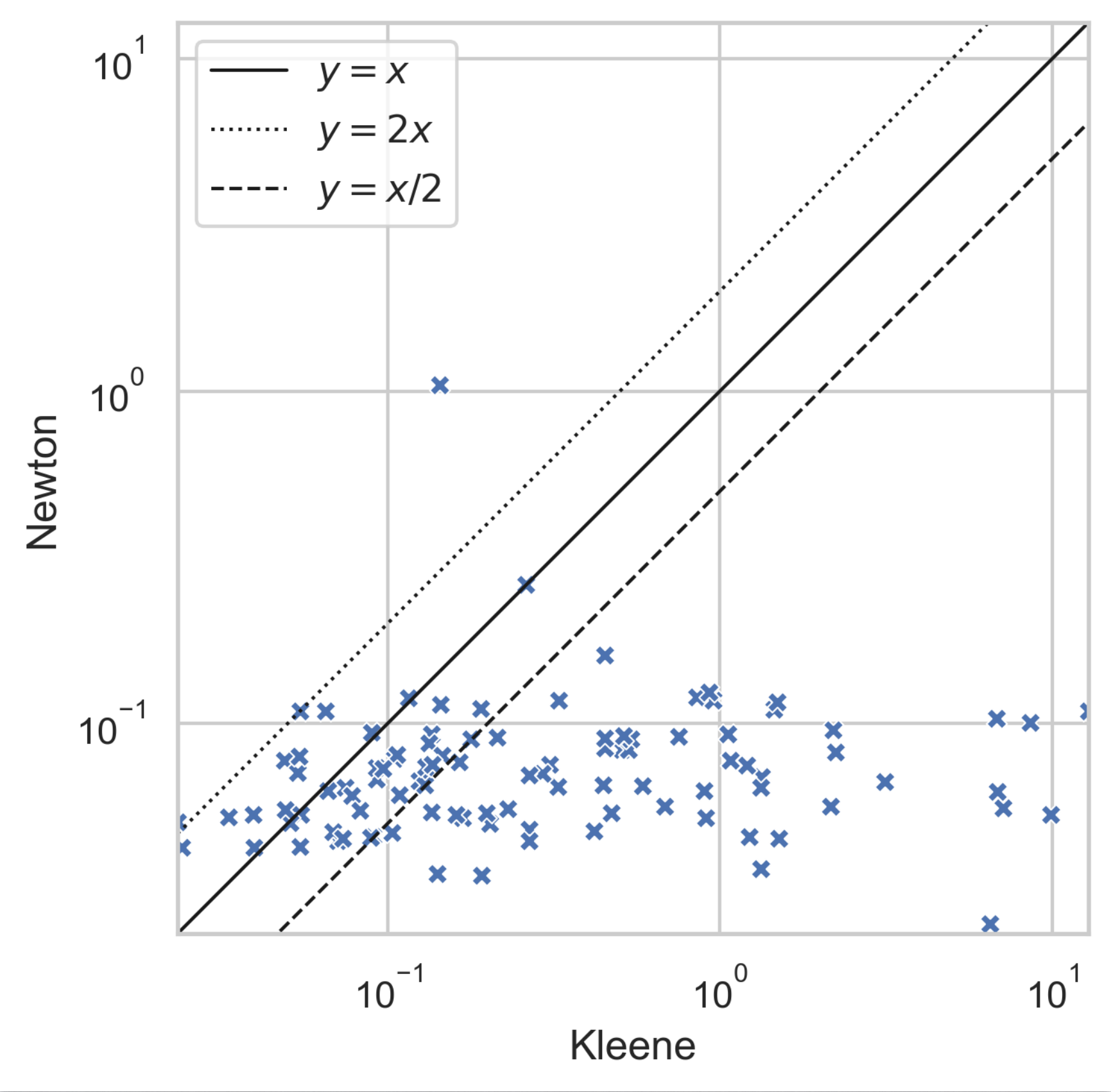
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Equation
System

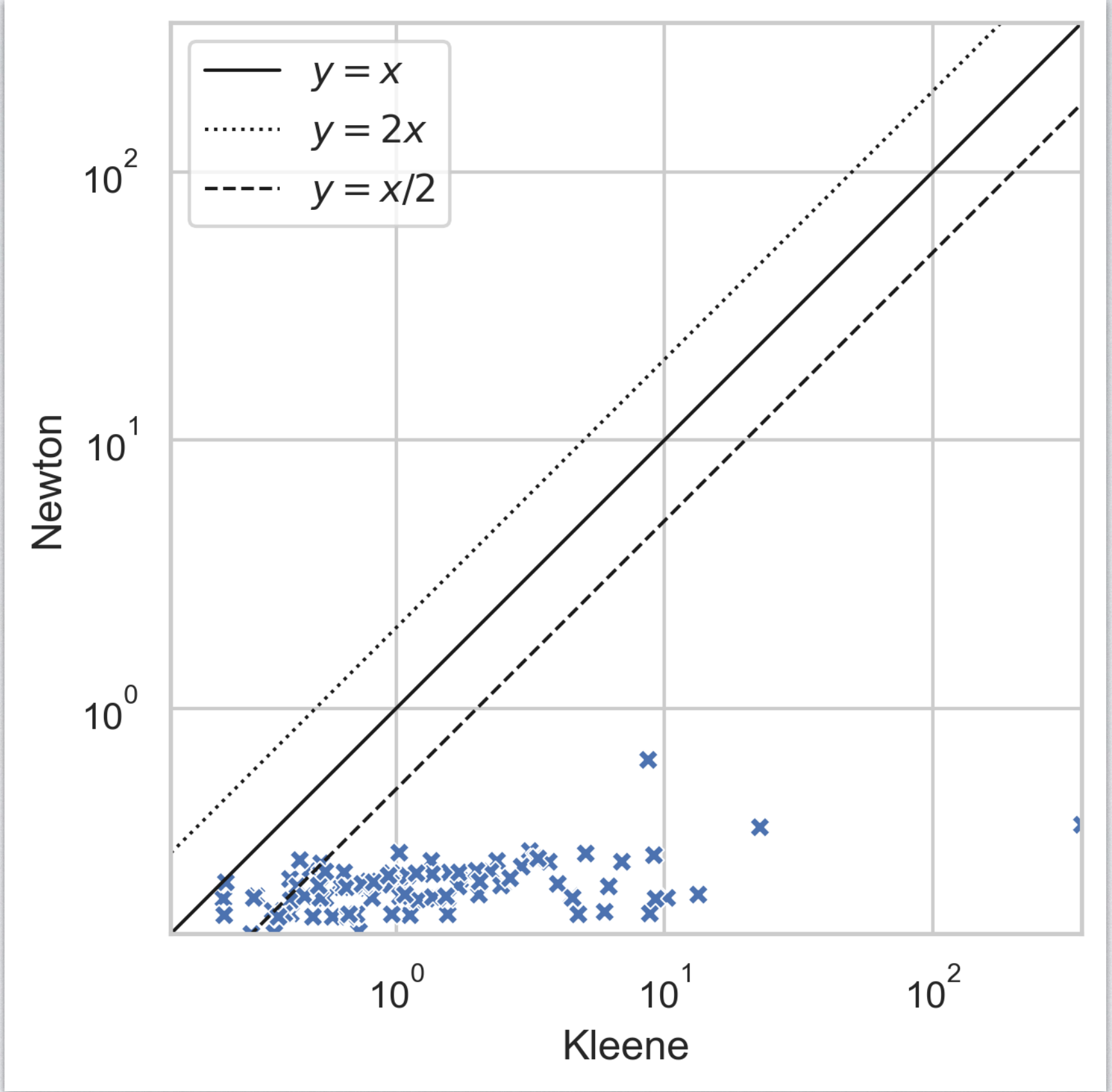
$$\langle M, \oplus, \otimes, \phi \oplus, \sqcap, \underline{0}, \underline{1} \rangle$$



Preliminary Evaluation



Reaching Probability



Expected Reward

