

# Kvaser USBcan R v2 User's Guide



Copyright 2017 Kvaser AB, Mölndal, Sweden  
<http://www.kvaser.com>

Printed Wednesday 13<sup>th</sup> September, 2017

We believe that the information contained herein was accurate in all respects at the time of printing. Kvaser AB cannot, however, assume any responsibility for errors or omissions in this text. Also note that the information in this document is subject to change without notice and should not be construed as a commitment by Kvaser AB.

(This page is intentionally left blank.)

## Contents

|          |   |           |
|----------|---|-----------|
| <b>1</b> | <b>About this manual</b>                        | <b>4</b>  |
| <b>2</b> | <b>Introduction</b>                             | <b>5</b>  |
| 2.1      | Welcome to Kvaser USBcan R v2 . . . . .         | 5         |
| 2.2      | Major features . . . . .                        | 6         |
| 2.3      | Additional software and documentation . . . . . | 6         |
| <b>3</b> | <b>Kvaser USBcan R v2 hardware</b>              | <b>7</b>  |
| 3.1      | Hardware installation . . . . .                 | 7         |
| 3.2      | USB connector . . . . .                         | 7         |
| 3.3      | CAN channels . . . . .                          | 8         |
| 3.4      | Power supply . . . . .                          | 8         |
| 3.5      | LED Indicators . . . . .                        | 8         |
| 3.6      | Troubleshooting . . . . .                       | 9         |
| <b>4</b> | <b>Appendices</b>                               | <b>10</b> |
| 4.1      | Technical data . . . . .                        | 10        |
| 4.2      | CAN connectors . . . . .                        | 10        |
| 4.3      | CAN bus termination . . . . .                   | 11        |
| 4.4      | Updating the firmware . . . . .                 | 11        |
| <b>5</b> | <b>Disposal and Recycling Information</b>       | <b>13</b> |
| <b>6</b> | <b>Legal acknowledgements</b>                   | <b>14</b> |
| 6.1      | Usage warning . . . . .                         | 14        |
| 6.2      | EU Regulatory Compliance . . . . .              | 15        |
| 6.3      | Patents, Copyrights and Trademarks . . . . .    | 16        |
| <b>7</b> | <b>Document Revision History</b>                | <b>17</b> |

## 1 About this manual

This manual is intended for Kvaser USBcan R v2 users. This document contains a description of the hardware's properties and general instructions for connecting the device to a computer.

## 2 Introduction

This section will describe the functions and features of the Kvaser USBcan R v2.

### 2.1 Welcome to Kvaser USBcan R v2



Figure 1: Kvaser USBcan R v2

Kvaser USBcan R v2 is a reliable low cost product. In hostile environments where dust and water are the norm, the IP65 rated housing assures reliable protection. With a time stamp precision of 100 microseconds it handles transmission and reception of standard and extended CAN messages on the bus. It is compatible with applications that use Kvaser's CANlib.

This guide applies to Kvaser USBcan R v2 devices listed in Table 1.

| Device                  | Product Number   |
|-------------------------|------------------|
| Kvaser USBcan R v2 2xHS | 73-30130-00920-2 |

Table 1: Kvaser USBcan R v2 devices and their EAN numbers.

## 2.2 Major features

- USB CAN interface.
- IP65 rated lightweight aluminum housing.
- Quick and easy plug-and-play installation.
- Supports both 11-bit (CAN 2.0A) and 29-bit (CAN 2.0B active) identifiers.
- 100% compatible with applications written for other Kvaser CAN hardware with Kvaser CANlib.
- High-speed CAN connection (compliant with ISO 11898-2), up to 1 Mbit/s.
- Fully compatible with J1939, CANopen, NMEA 2000<sup>®</sup> and DeviceNet.
- Simultaneous operation of multiple devices.

## 2.3 Additional software and documentation

The Kvaser CANlib SDK includes everything you need in order to develop software for Kvaser CAN hardware. The SDK contains full documentation and many sample programs, written in C, C++, C#, Delphi, Python and Visual Basic. All Kvaser CAN interface hardware share a common software API. Programs written for one device type will run without modification on other device types.

The latest versions of documentation, software and drivers can be downloaded for free at [www.kvaser.com/download](http://www.kvaser.com/download).

## 3 Kvaser USBcan R v2 hardware

In this section you can read more about the CAN channels, power supply and LED indicators.

### 3.1 Hardware installation

The Kvaser USBcan R v2 may be inserted in any free USB socket on the host computer. You do not need to switch the power off before inserting or removing the device.

For the Kvaser USBcan R v2 to communicate with the host computer, the correct version of the Kvaser driver and firmware must be installed. The firmware is downloaded and installed directly on the Kvaser USBcan R v2 and the driver is installed on the host computer. The latest version of the driver and firmware can be downloaded from [www.kvaser.com/download](http://www.kvaser.com/download).

The driver is installed by running the file `kvaser_drivers_setup.exe`.

For information on how to upgrade the firmware, see Section 4.4, Updating the firmware, on Page 11.

### 3.2 USB connector

The Kvaser USBcan R v2 has a standard USB type "A" connector.



Figure 2: A standard USB type "A" connector.

### 3.3 CAN channels

The Kvaser USBcan R v2 has two CAN Hi-Speed channels with 9-pin D-SUB CAN connectors (see Figure 3 on Page 8). See Section 4.2, CAN connectors, on Page 10 for pinout information.



Figure 3: CAN connectors on Kvaser USBcan R v2 2xHS

### 3.4 Power supply

The Kvaser USBcan R v2 is powered from the USB port.

### 3.5 LED Indicators

The Kvaser USBcan R v2 has three LEDs as shown in Figure 4. Their functions are shown in Table 2 on Page 9.

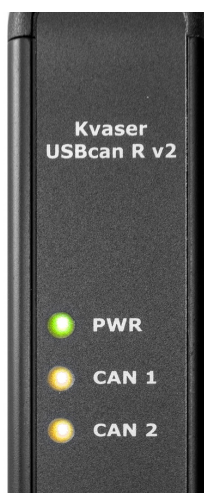


Figure 4: LEDs on the Kvaser USBcan R v2.



| LED            | Function          | Description  |
|----------------|-------------------|--|
| PWR (Green)    | Power             | Steady light when unit is powered and working.                                     |
|                | USB configuration | Blinking once every three seconds when something is wrong with the USB connection. |
|                | Firmware          | 2 Hz flash if something is wrong with the firmware configuration.                  |
| CAN 1 (Yellow) | CAN RxTx          | Status for CAN channel 1.  |
| CAN 2 (Yellow) | CAN RxTx          | Status for CAN channel 2.  |

Table 2: LEDs on the Kvaser USBcan R v2.

### 3.6 Troubleshooting

Use “Kvaser Hardware” in the Control Panel to verify that the computer can communicate with the Kvaser USBcan R v2. If the firmware version shown is all zeros, there are communication problems.

If the LEDs are not flashing or do not light up at all, check the power supply.

## 4 Appendices

In this section you will find technical information about the Kvaser USBcan R v2 and its connectors.

### 4.1 Technical data

In Table 3 below you will find the Kvaser USBcan R v2's technical specifications.

|                        |  |
|------------------------|--|
| CAN Channels           | 2 (No galvanic isolation between CAN channels.)                            |
| CAN Transceivers       | TJA1051T (Compliant with ISO 11898-2)                                      |
| CAN Controller         | Built into the processor   |
| CAN Bit Rate           | 50 kbit/s to 1 Mbit/s  |
| Time stamp resolution  | 100 $\mu$ s  |
| Max message rate       | 15000 msg/s per channel  |
| Error Frame Detection  | Yes  |
| Error Frame Generation | No   |
| Silent mode            | No   |
| PC interface           | USB Hi-Speed   |
| Power consumption      | Typical 132 mA   |
| Hardware configuration | Done by software (Plug & Play).  |
| Software requirements  | Windows 7 or later. (For other operating systems, contact Kvaser support.) |
| Dimensions             | 30 x 200 x 17 mm for body incl. strain relief                              |
| Weight                 | 176 g  |
| Operating temperature  | -40 °C to +70 °C   |
| Storage temperature    | -40 °C to +85 °C   |
| Relative humidity      | 0 % to 85 % (non-condensing.)  |
| IP Rating              | IP65   |

Table 3: Technical Specifications.

### 4.2 CAN connectors

Kvaser USBcan R v2 devices that use the 9-pin D-SUB connector (see Figure 5 on Page 11) have the pinning described in Table 4 on Page 11.

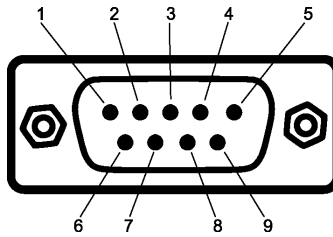


Figure 5: The D-SUB 9 connector pin numbers

| D-SUB pin number | Function      |
|------------------|---------------|
| 1                | Not connected |
| 2                | CAN_L         |
| 3                | GND           |
| 4                | Not connected |
| 5                | Shield        |
| 6                | Not connected |
| 7                | CAN_H         |
| 8                | Not connected |
| 9                | Not connected |

Table 4: Configuration of the 9-pin D-SUB

### 4.3 CAN bus termination

Every CAN bus must be terminated with a 120 Ohm resistor at each end of the bus. The Kvaser USBcan R v2 does not contain any CAN bus termination, because their inclusion could cause severe disturbance in a system which is already correctly terminated.

For laboratory or testing use, the exact value of the termination resistors is not always critical. Sometimes a single terminator is sufficient. For production, proper termination is essential. If you see error frames on the bus, you should check the termination.



**To save yourself a lot of trouble, always terminate the CAN bus properly.**

### 4.4 Updating the firmware

For the Kvaser USBcan R v2 to communicate with the host computer, compatible versions of the Kvaser CANlib (including driver) and firmware must be installed.

The latest versions of firmware and drivers can be downloaded for free at [www.kvaser.com/download](http://www.kvaser.com/download).

Connect the Kvaser USBcan R v2 to your PC with the USB cable. Start the update.exe application. A window opens where you should see the device listed if correctly connected to your PC. Select the device to update and click the Next button. Read the Release Notes carefully.

Click on the Start Upgrade button to start programming. Programming takes approximately 30 s. The progress is displayed on the screen.

If you see any error messages, try to disconnect and reconnect the device, and then perform the operation again.

To verify that the firmware has been updated, open "Kvaser Hardware" in Control Panel. Select "Kvaser USBcan R v2" in the tree view to the left, and click on the channel. The firmware revision information appears in the right half of the window.

## 5 Disposal and Recycling Information



When this product reaches its end of life, please dispose of it according to your local environmental laws and guidelines.

For information about Kvaser's recycling programs, visit:  
<http://www.kvaser.com/en/kvaser/recycling-policy.html>

## 6 Legal acknowledgements

### 6.1 Usage warning



#### **WARNING FOR ALL USERS**

WARNING! - YOUR USE OF THIS DEVICE MUST BE DONE WITH CAUTION AND A FULL UNDERSTANDING OF THE RISKS!

THIS WARNING IS PRESENTED TO INFORM YOU THAT THE OPERATION OF THIS DEVICE MAY BE DANGEROUS. YOUR ACTIONS CAN INFLUENCE THE BEHAVIOR OF A CAN-BASED DISTRIBUTED EMBEDDED SYSTEM, AND DEPENDING ON THE APPLICATION, THE CONSEQUENCES OF YOUR IMPROPER ACTIONS COULD CAUSE SERIOUS OPERATIONAL MALFUNCTION, LOSS OF INFORMATION, DAMAGE TO EQUIPMENT, AND PHYSICAL INJURY TO YOURSELF AND OTHERS. A POTENTIALLY HAZARDOUS OPERATING CONDITION IS PRESENT WHEN THE FOLLOWING TWO CONDITIONS ARE CONCURRENTLY TRUE: THE PRODUCT IS PHYSICALLY INTERCONNECTED TO A REAL DISTRIBUTED EMBEDDED SYSTEM; AND THE FUNCTIONS AND OPERATIONS OF THE REAL DISTRIBUTED EMBEDDED SYSTEM ARE CONTROLLABLE OR INFLUENCED BY THE USE OF THE CAN NETWORK. A POTENTIALLY HAZARDOUS OPERATING CONDITION MAY RESULT FROM THE ACTIVITY OR NON-ACTIVITY OF SOME DISTRIBUTED EMBEDDED SYSTEM FUNCTIONS AND OPERATIONS, WHICH MAY RESULT IN SERIOUS PHYSICAL HARM OR DEATH OR CAUSE DAMAGE TO EQUIPMENT, DEVICES, OR THE SURROUNDING ENVIRONMENT.

WITH THIS DEVICE, YOU MAY POTENTIALLY:

- CAUSE A CHANGE IN THE OPERATION OF THE SYSTEM, MODULE, DEVICE, CIRCUIT, OR OUTPUT.
- TURN ON OR ACTIVATE A MODULE, DEVICE, CIRCUIT, OUTPUT, OR FUNCTION.
- TURN OFF OR DEACTIVATE A MODULE, DEVICE, CIRCUIT, OUTPUT, OR FUNCTION.
- INHIBIT, TURN OFF, OR DEACTIVATE NORMAL OPERATION.
- MODIFY THE BEHAVIOR OF A DISTRIBUTED PRODUCT.
- ACTIVATE AN UNINTENDED OPERATION.
- PLACE THE SYSTEM, MODULE, DEVICE, CIRCUIT, OR OUTPUT INTO AN UNINTENDED MODE.

ONLY THOSE PERSONS WHO:

(A) ARE PROPERLY TRAINED AND QUALIFIED WITH RESPECT TO THE USE OF THE DEVICE,

(B) UNDERSTAND THE WARNINGS ABOVE, AND

(C) UNDERSTAND HOW THIS DEVICE INTERACTS WITH AND IMPACTS THE FUNCTION AND SAFETY OF OTHER PRODUCTS IN A DISTRIBUTED SYSTEM AND THE APPLICATION FOR WHICH THIS DEVICE WILL BE APPLIED, MAY USE THE DEVICE.

PLEASE NOTE THAT YOU CAN INTEGRATE THIS PRODUCT AS A SUBSYSTEM INTO HIGHER-LEVEL SYSTEMS. IN CASE YOU DO SO, KVASER AB HEREBY DECLARES THAT KVASER AB'S WARRANTY SHALL BE LIMITED TO THE CORRECTION OF DEFECTS, AND KVASER AB HEREBY EXPRESSLY DISCLAIMS ANY LIABILITY OVER AND ABOVE THE REFUNDING OF THE PRICE PAID FOR THIS DEVICE, SINCE KVASER AB DOES NOT HAVE ANY INFLUENCE ON THE IMPLEMENTATIONS OF THE HIGHER-LEVEL SYSTEM, WHICH MAY BE DEFECTIVE.

## 6.2 EU Regulatory Compliance



### EU Declaration of Conformity (DoC)

**We**

Company Name: Kvaser AB  
 Postal address: Aminogatan 25  
 Postcode: 431 53  
 City: Mölndal  
 Telephone number: +46 31 886344  
 E-mail address: sales@kvaser.com

**declare that the DoC is issued under our sole responsibility and belongs to the following product:**

Product: Kvaser USBcan R v2

**Object of the declaration** (identification of apparatus allowing traceability):

Product: Kvaser USBcan R v2

Type: 73-30130-00920-2

**The object of the declaration described above is in conformity with the relevant Union harmonisation legislation:**

Chemical substances (REACH) Regulation (EC) No 1907/2006

Electromagnetic Compatibility (EMC) Directive 2014/30/EU

RoHS recast Directive 2011/65/EU

Waste Electrical & Electronic Equipment (WEEE) Directive 2012/19/EU

**The following harmonised standards and technical specifications have been applied:**

**Title, Date of standard/specification:**

EN 55022 (2010) EN 55024 (2010)

EN 61000-6-3 (2007 + A1:2011) EN 50581 (2012)

EN 50419 (2005)

**Signed for and on behalf of:**

Mölndal

2017-08-25

Place of issue

Date of issue

Claes Haglund, Supply Chain and Quality director

**NOTE:** This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his/her own expense.

### 6.3 Patents, Copyrights and Trademarks

All trademarks are the property of their respective owner. Windows is a registered trademark of Microsoft Corporation in the United States and other countries.

Adobe, the Adobe logo, and Reader are either registered trademarks or trademarks of Adobe Systems Incorporated in the United States and/or other countries.

DeviceNet is a trademark of Open DeviceNet Vendor Association, Inc.

NMEA 2000 is the registered trademark of the National Marine Electronics Association, Inc.

For information about Kvaser related CAN patents, see [www.kvaser.com/patent](http://www.kvaser.com/patent).



## 7 Document Revision History

Version history for document UG\_98185\_usbcan\_r\_v2:

| Revision | Date       | Changes                              |
|----------|------------|--------------------------------------|
| 1.0      | 2017-01-18 | Initial version                      |
| 2.0      | 2017-08-25 | Updated EU Declaration of Conformity |