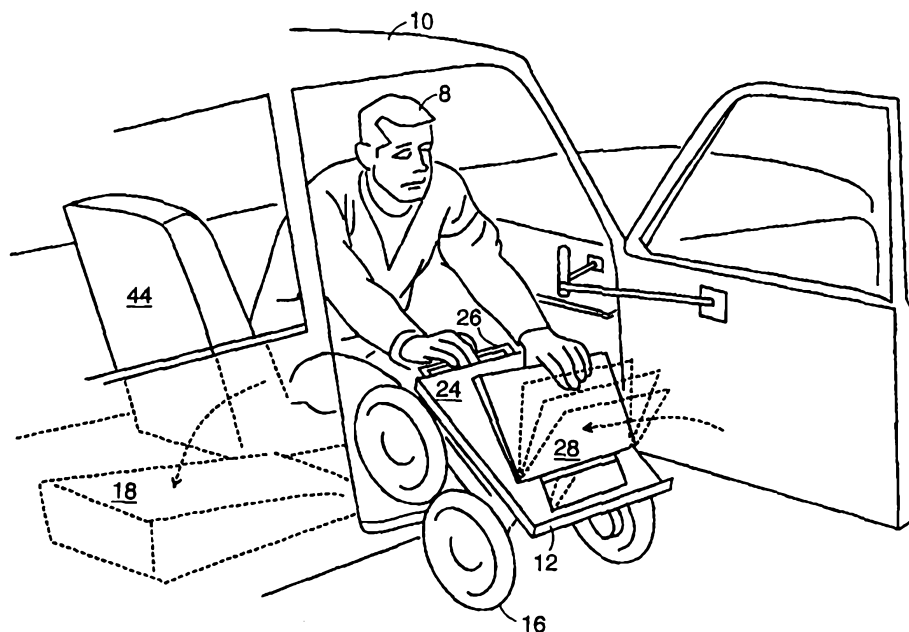




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(54) Title: AUTOMOBILE INGRESS/EGRESS SYSTEM



(57) Abstract

A system for enabling a person to enter an enclosed vehicle such as an automobile and to load a personal vehicle such as a wheelchair into the enclosed vehicle. A force sensing handle facilitates control of the personal vehicle by the subject who is no longer supported by the personal vehicle or by another person. In some embodiments of the invention, a transfer mechanism is provided from within the enclosed vehicle for transferring the subject to a seat of the enclosed vehicle.

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Automobile Ingress/Egress System

Technical Field

The present invention pertains to a system for allowing a person to board or
5 disembark from an automobile or other enclosed vehicle and to load a motorized
personal vehicle into or out of the enclosed vehicle.

Background of the Invention

It is often necessary or advantageous for a person to have a single personal
10 vehicle, such as a wheelchair, motorized or otherwise, available for locomotion both
prior to and after being transported in an automobile or other closed conveyance.
Methods currently employed for allowing a person to board an enclosed conveyance
along with a personal vehicle require either a long ramp with a gradual incline to allow
the person to roll up to the level of the passenger compartment of the conveyance, or,
15 otherwise, require the assistance of another person. Lifts employed for this purpose tend
to be both cumbersome and expensive.

Summary of the Invention

In accordance with one aspect of the invention, in one of its embodiments, there
20 is provided a system for enabling a person to enter and exit an enclosed vehicle, such as
a car, bus, or train, and to load a personal vehicle into the enclosed vehicle without the
assistance of another person. Where the personal vehicle has a support, a first actuator
for driving at least one wheel rotatable about an axis, and a second actuator for varying
the disposition of the axis with respect to the support, the system has a control loop for
25 energizing at least one of the first and second actuators on the basis of at least the
disposition of the axis with respect to the support, and also a control input for providing
commands to the control loop of the personal vehicle for governing the operation of the
personal vehicle and for causing the personal vehicle to enter and exit the enclosed
vehicle.

30 In accordance with another embodiment of the invention, the control loop may
have

a force sensing device for governing the operation of a motorized personal vehicle. The force sensing device has a handle coupled to the personal vehicle for grasping by a subject, at least one pressure sensor for producing an output related to forces applied to the handle, and a controller for varying at least one of the orientation, configuration, and
5 motion of the personal vehicle on the basis of forces applied to the handle. One or more of the pressure sensors may be a piezoelectric force sensor.

The system may have a transfer mechanism deployable from inside the enclosed vehicle for supporting the person during transfer between the personal vehicle and the seat and a control input for providing commands to the personal vehicle for governing
10 the operation of the personal vehicle and for causing the personal vehicle to board the enclosed vehicle. The transfer mechanism may be a stowable seat disposed within the enclosed vehicle. The personal vehicle may have a support for supporting the person and a ground contacting element, such as a wheel, that is movable with respect to a local axis, and the local axis may itself be movable with respect to a second axis having a
15 defined relation with respect to the support. An actuator arrangement may be provided for permitting controllable motion of the ground contacting element with respect to the local axis and of the local axis with respect to the support. A controller then receives the commands from the control input and controls the actuator arrangement in such a manner as to cause the personal vehicle to board the enclosed vehicle.

20 In accordance with yet another alternate embodiment of the invention, there is provided a stowable seat for an automobile, the seat having a normal position for seating a passenger. The stowable seat has a retraction mechanism for removing the stowable seat from the normal position to a retracted position, and a transfer mechanism for conveying a person from a personal vehicle to a seated position within the automobile.

25

Brief Description of the Drawings

The invention will be more readily understood by reference to the following description, taken with the accompanying drawings, in which:

FIG. 1 is a perspective view of a user seated on a personal vehicle prior to
30 boarding the passenger cabin of an automobile, in accordance with a preferred embodiment of the invention;

FIG. 2 shows the user beginning to transfer himself to the passenger cabin of the automobile of Fig. 1;

FIG. 3 shows a further step of the user transferring to an automobile in accordance with the embodiment of the invention shown in Fig. 1, with the personal vehicle shown in dashed lines;

FIG. 4 shows the user rotating the orientation of the personal vehicle of Fig. 1 from within the passenger cabin, in accordance with an embodiment of the present invention;

FIG. 5 is a perspective view of a personal vehicle having a force sensing handle in accordance with an embodiment of the present invention;

FIG. 6 is a top cross-sectional view of the force sensing handle of FIG. 5;

FIG. 7 shows the user retracting an automobile seat of the automobile of Fig. 1, in accordance with an embodiment of the present invention;

FIG. 8 is a side view in cross-section of a retractable automobile seat mechanism in accordance with an embodiment of the invention;

FIG. 9 shows the user causing the personal vehicle of Fig. 1 to employ a step mode of control in order to ascend to the passenger cabin for conveyance by the automobile, in accordance with an embodiment of the present invention;

FIG. 10 shows the personal vehicle of Fig. 1 stowed within the passenger cabin for conveyance by the automobile; and

FIG. 11 shows a top view of the passenger cabin of an automobile employing a transfer board to facilitate the transfer of a person from a personal vehicle to the passenger seat of an automobile in accordance with an alternate embodiment of the invention.

25

Detailed Description of Preferred Embodiments

FIGS. 1-4, with identical numerals designating identical or similar elements of an embodiment of the invention, represent temporally successive views, in which a person 8 is shown entering an automobile 10 from a personal vehicle 12 and then loading the personal vehicle into the automobile. Referring to FIG. 1, automobile 10 is shown as an example of an enclosed vehicle to which the current invention is applicable though application to other enclosed conveyances such as trucks, buses, or trains, is within the

scope of the invention. While the right side of automobile **10** is shown in the figures as the passenger side of the automobile, mirror-imaging of automobile **10** about its center-line of automobile **10** is also within the scope of the invention and of the appended claims. Subject **8** is depicted as seated on personal vehicle **12**, shown, by way of
5 example, as a wheelchair. The invention is applicable to any personal vehicle, motorized or otherwise, upon which subject **8** may be seated or otherwise disposed. In particular, the invention is applicable to a personal vehicle designed to maintain balance while surmounting obstacles, such as embodiments of the invention described in U.S. patent
no. 5,701,965 which is hereby incorporated herein by reference.

10 To enter automobile **10** without the assistance of another person, in accordance with a preferred embodiment of the invention, subject **8** may open door **14** of automobile **10** and position personal vehicle **12** adjacent to the passenger side of automobile **10**. The opening of door **14** may be manual or powered within the scope of the invention. Referring now to FIG. 2, subject **8**, once positioned on personal vehicle **12** adjacent to
15 automobile **10**, may lock wheels **16** of the personal vehicle and transfer himself to a transfer mechanism, which, in accordance with a preferred embodiment of the invention, may be a passenger seat **18**.

Referring to FIG. 11, in which passenger cabin **110** of automobile **10** is shown, a transfer board **112** may be provided in accordance with an alternate embodiment of the
20 invention. Transfer board **112** may be extended in direction **114** toward subject **8** positioned outside of automobile **10** either by manual reach or by remote command. Transfer board **112** may be retained and thereby supported both vertically and laterally by transfer mechanism **116**. Subject **8** may use transfer board **112** to transfer out of personal vehicle **10** to driver's seat **118**, with subject's weight being supported by
25 transfer board **112** to the extent required. Transfer board **112** is configured so as to be easily held by subject **8** during the course of the transfer to driver's seat **118**.

FIG. 3 shows subject **8** having transferred into passenger seat **18**. Personal vehicle **12** is shown in dashed lines for the sake of clarity. Once subject **8** has transferred into passenger seat **18**, personal vehicle **12** may then be loaded into the automobile.

30 Referring now to Fig. 4, in accordance with a preferred embodiment of the invention, personal vehicle **12** may be controlled by a person such as subject **8** who is no

longer seated on the vehicle. Subject **8** may command personal vehicle **12** to turn in the direction of arc **20** so as to allow alignment of wheels **16** for ascent into automobile **10**. In accordance with a preferred embodiment of the invention, personal vehicle **12** has actuator control of wheels **16** and of the position of the axes **22** of one or more wheels
5 with respect to a support **24** of the personal vehicle. In a mode of control referred to as the "auto ingress mode," either of two submodes may be entered: In "roll mode," the wheels may roll while axes **22** remain fixed with respect to support **24**. In "step mode," the position of one or more of axes **22** may be varied while some or all of the wheels may be braked. A "step/roll" switch may be provided to allow the user to toggle between
10 these modes. Additionally, in accordance with an alternate embodiment of the invention, the height of support **24** may be adjusted by means of commands provided by the user, either by explicit activation of a force sensor, or by manually acting on the frame of the personal vehicle.

One means of allowing a user, no longer supported on personal vehicle **12**, to
15 govern the position and configuration of the personal vehicle is discussed with reference to Fig. 5. A force sensitive device **26** may be provided for controlling the orientation or configuration of the personal vehicle, or both, by means of motions of the hand, wrist, or body. The use of remote control units is also known and is within the scope of the invention as claimed in any appended claims. Remote control may be via wire or
20 wireless connection to personal vehicle **12**.

An embodiment of force sensitive device **26** configured in a handle configuration is shown in cross section in FIG. 6. Force sensors **32**, which may be piezoelectric sensors, for example, produce electrical signals based on tensile, compressive, or torsional activation of handle **34** in any plane, as transmitted mechanically to the sensors.
25 The electrical signals are processed by controller **36** to govern the motion, orientation, or configuration of the personal vehicle.

Referring again to FIG. 5, stowage of personal vehicle **12** may be facilitated, in accordance with alternate embodiments of the invention, by providing for the folding forward of seat back **28** along arc **30**.

30 Referring now to FIG. 7, once personal vehicle **12** has been commanded to step up to the floor of the passenger cabin of automobile **10** using the auto ingress mode of

control discussed above, subject **8** may stow passenger seat **18** by tilting it along arc **38** toward the rear of the passenger cabin. One embodiment of a retractable passenger seat **40** is shown in FIG. 8, allowing space on floor **42** of the automobile for stowage of the personal vehicle as described above.

5 Referring now to FIG. 9, once passenger seat **18** has been retracted, subject **8**, from the position of driver's seat **44**, may activate personal vehicle **12** by means of force handle **26** to complete its ascent into automobile **10**. Support **24** may be lowered with respect to wheels **16**, and folding back **28** may be lowered to lower the center of gravity of the personal vehicle while it is stowed in the automobile.

10 FIG. 10 shows subject **8** seated in driver's seat **44** and personal vehicle **12** in a stowed position within automobile **10**. In order to unload personal vehicle **12** and to alight from the automobile, subject **8** may again employ the invention by reversing the process heretofore described.

The described embodiments of the invention are intended to be merely exemplary
15 and numerous variations and modifications will be apparent to those skilled in the art. All such variations and modifications are intended to be within the scope of the present invention as defined in the appended claims.

What is claimed is:

1. A system for enabling a person to enter and exit an enclosed vehicle and to load and unload a personal vehicle having a support and a first actuator for driving at least one wheel rotatable about an axis and a second actuator for varying of the disposition of
5 the axis with respect to the support, into the enclosed vehicle without the assistance of another person, the system comprising
 - a. a control loop for energizing at least one of the first and second actuators on the basis of at least the disposition of the axis with respect to the support; and
 - b. a control input for providing commands to the control loop of the personal
10 vehicle for governing the operation of the personal vehicle and for causing the personal vehicle to enter and exit the enclosed vehicle.
2. A system according to claim 1, wherein the control input includes a force sensing device for governing the operation of a motorized personal vehicle, the force sensing device comprising:
 - 15 a. a handle coupled to the personal vehicle for grasping by a subject;
 - b. at least one pressure sensor for producing an output related to forces applied to the handle; and
 - c. a controller for varying at least one of the orientation, configuration, and motion of the personal vehicle on the basis of forces applied to the handle.
- 20 3. A system according to claim 2, wherein the at least one pressure sensor includes a piezoelectric force sensor.
4. A system for enabling a person to enter and exit an enclosed vehicle and to load and unload a dynamically stabilized personal vehicle into the enclosed vehicle without the assistance of another person, the system comprising a control input for providing
25 commands to the dynamically stabilized personal vehicle for governing the operation of the personal vehicle and for causing the personal vehicle to enter and exit the enclosed vehicle.
5. A system according to claim 4, wherein the dynamically stabilized personal vehicle comprises:
 - 30 a. a support for supporting the person;

- b. a ground contacting element movable with respect to a local axis, the local axis being movable with respect to a second axis having a defined relation with respect to the support;
 - c. an actuator arrangement for permitting controllable motion of the ground contacting element with respect to the local axis and of the local axis with respect to the support; and
 - d. a controller for receiving the commands from the control input and for controlling the actuator arrangement in such a manner as to cause the personal vehicle to board the enclosed vehicle.
- 10 **6.** A system for enabling a person to enter and exit an enclosed vehicle having a seat and to load and unload a personal vehicle into the enclosed vehicle without the assistance of another person, the system comprising:
- a. a transfer mechanism for supporting the person during transfer between the personal vehicle and the seat; and
 - 15 b. a control input for providing commands to the personal vehicle for governing the operation of the personal vehicle and for causing the personal vehicle to enter and exit the enclosed vehicle.
- 7.** A system according to claim 6, wherein the transfer mechanism is deployable from inside the enclosed vehicle.
- 20 **8.** A system according to claim 6, wherein the transfer mechanism includes a retractable seat disposed within the enclosed vehicle.
- 9.** A stowable seat for an conveyance, the seat having a normal position for seating a passenger, the stowable seat comprising:
- a. a retraction mechanism for removing the stowable seat from the normal position to a retracted position; and
 - 25 b. a transfer mechanism for conveying a person from a personal vehicle to a seated position within the conveyance.

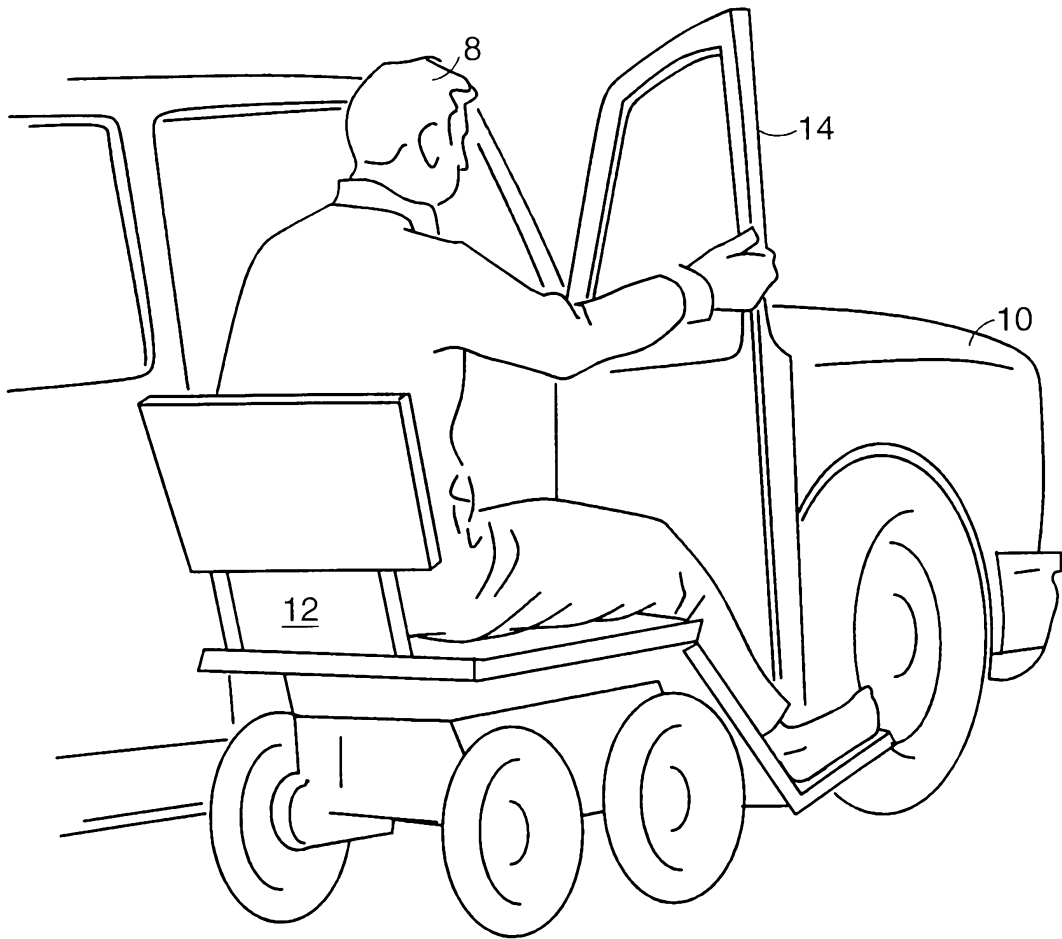


FIG. 1

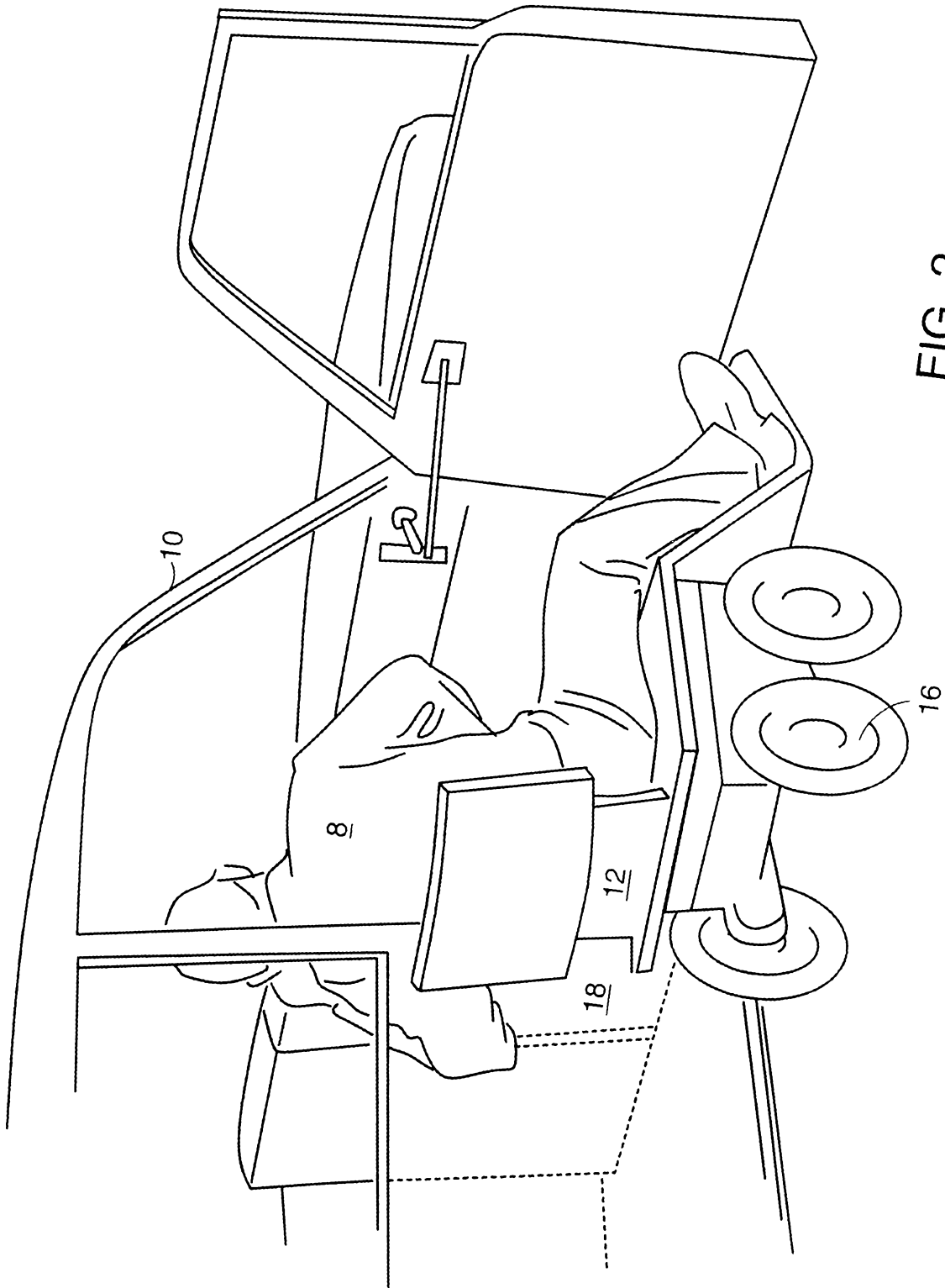


FIG. 2

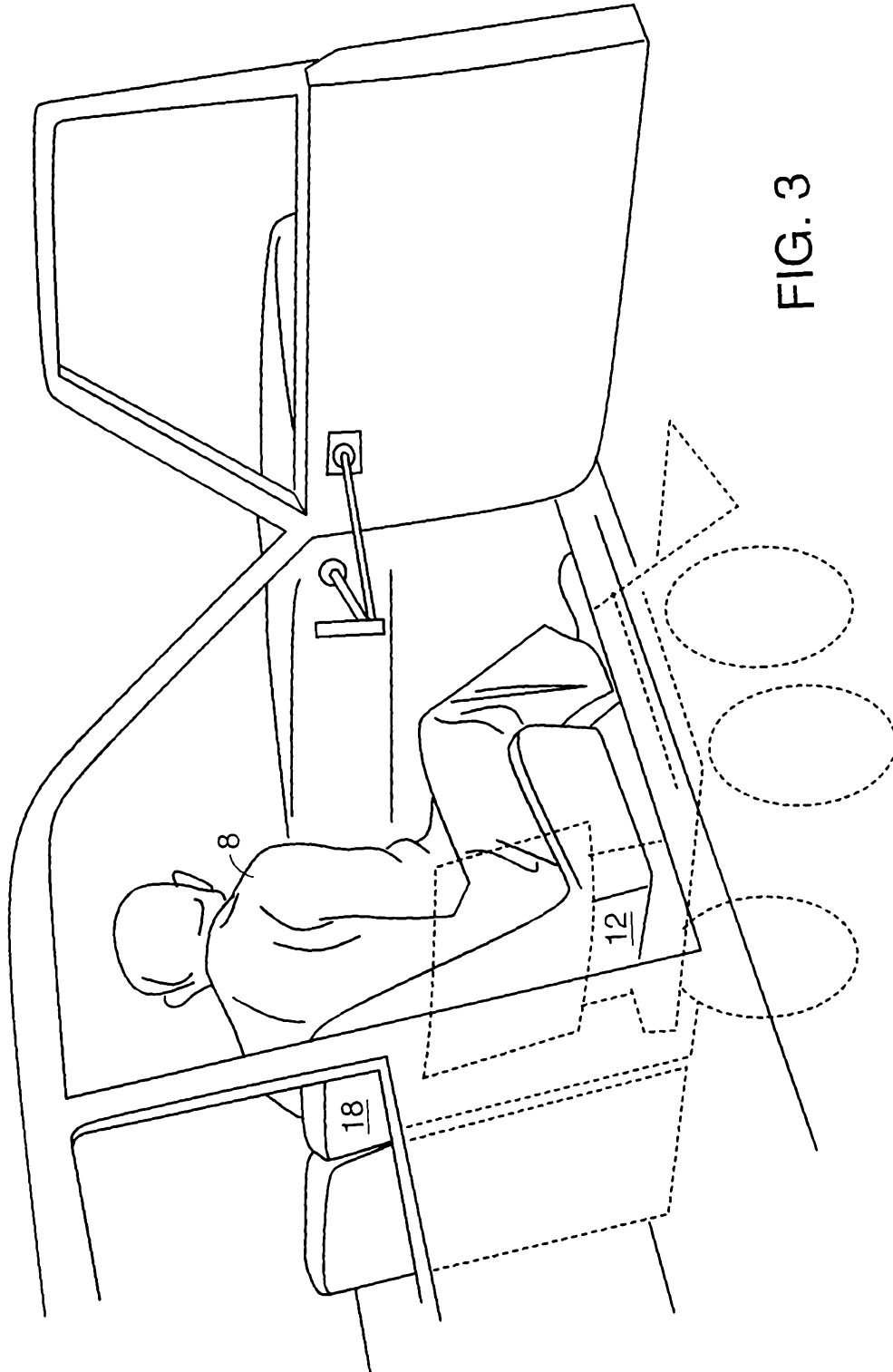
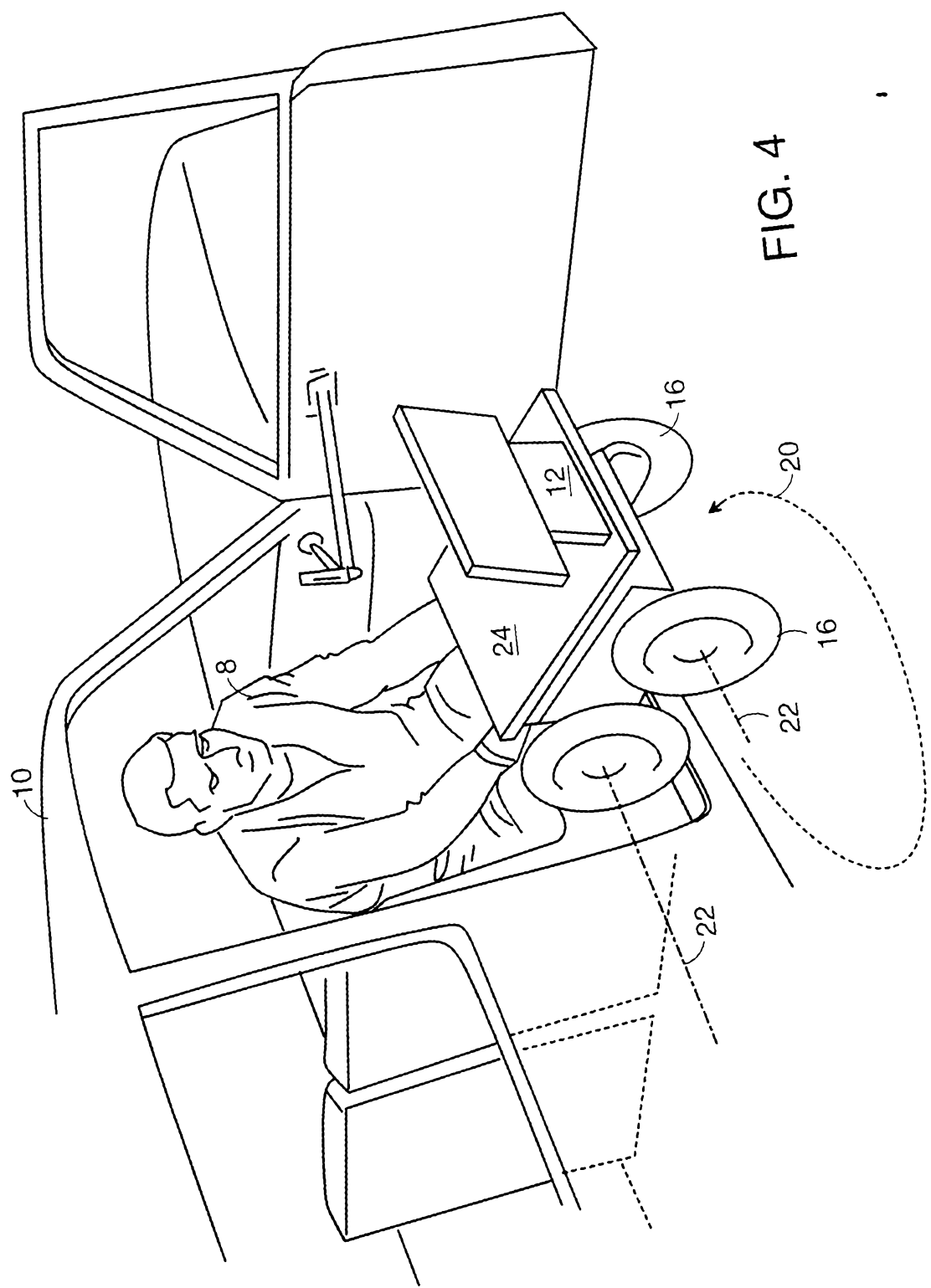


FIG. 3



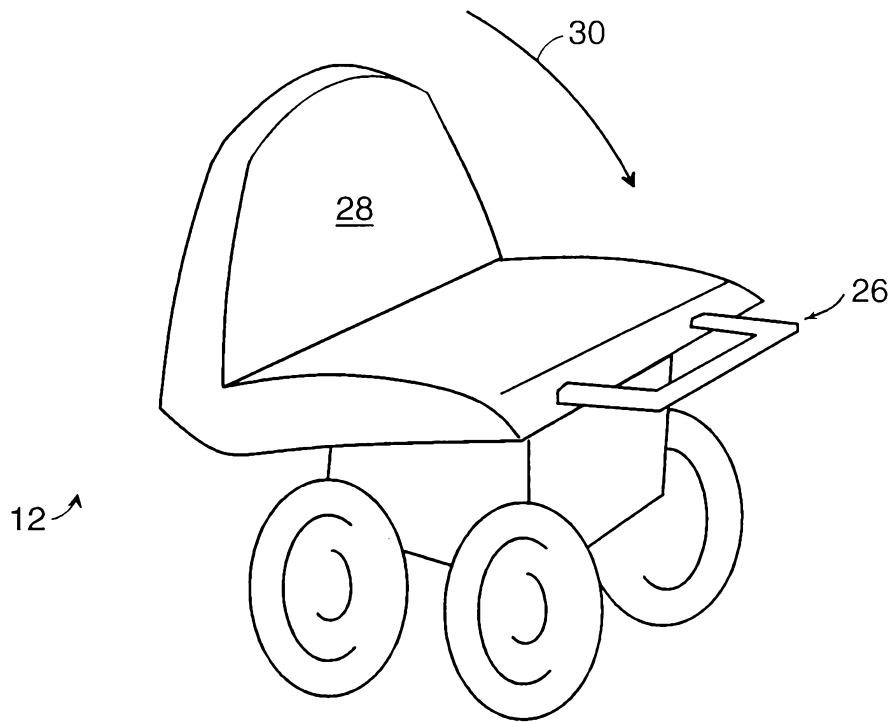


FIG. 5

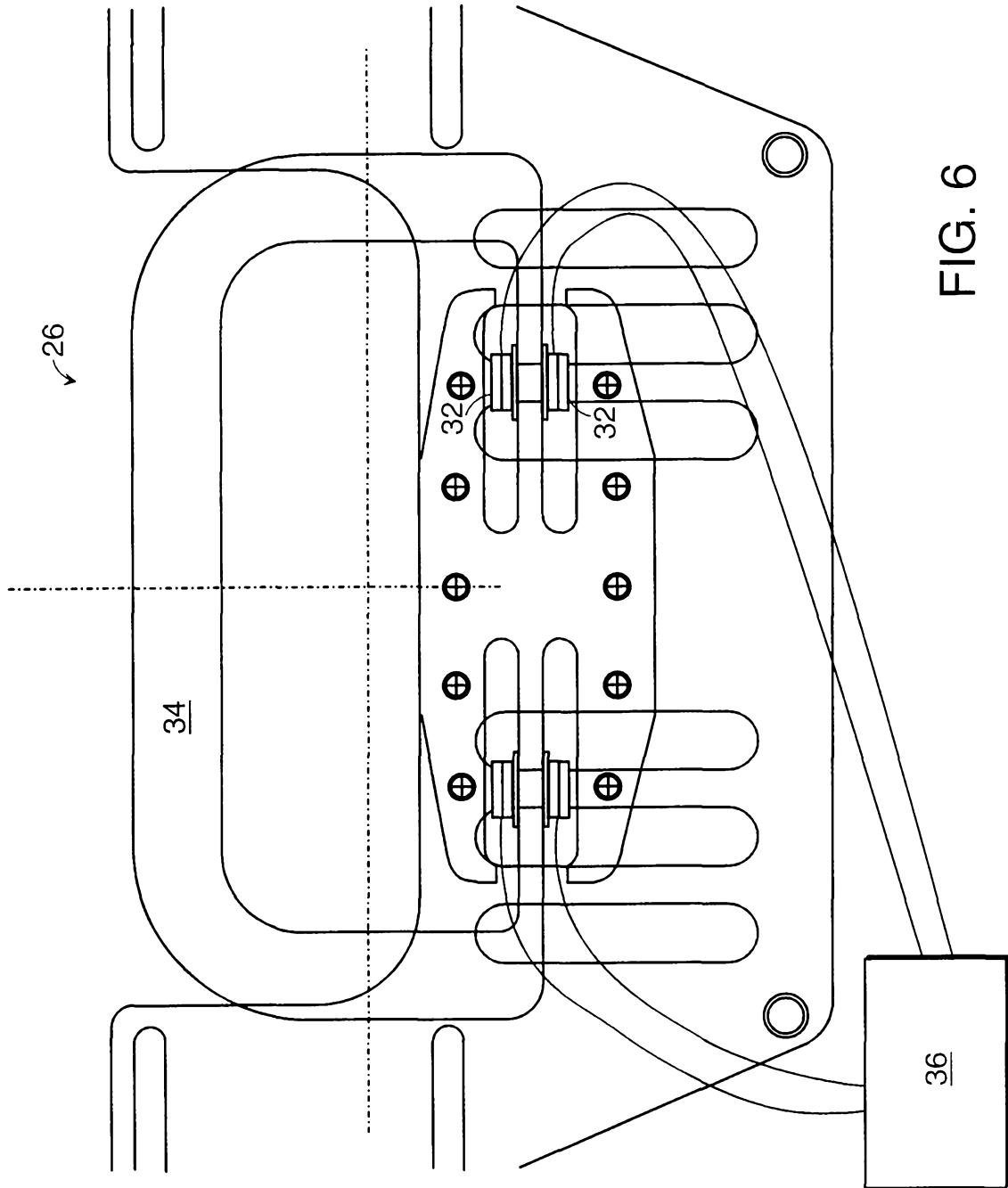


FIG. 6

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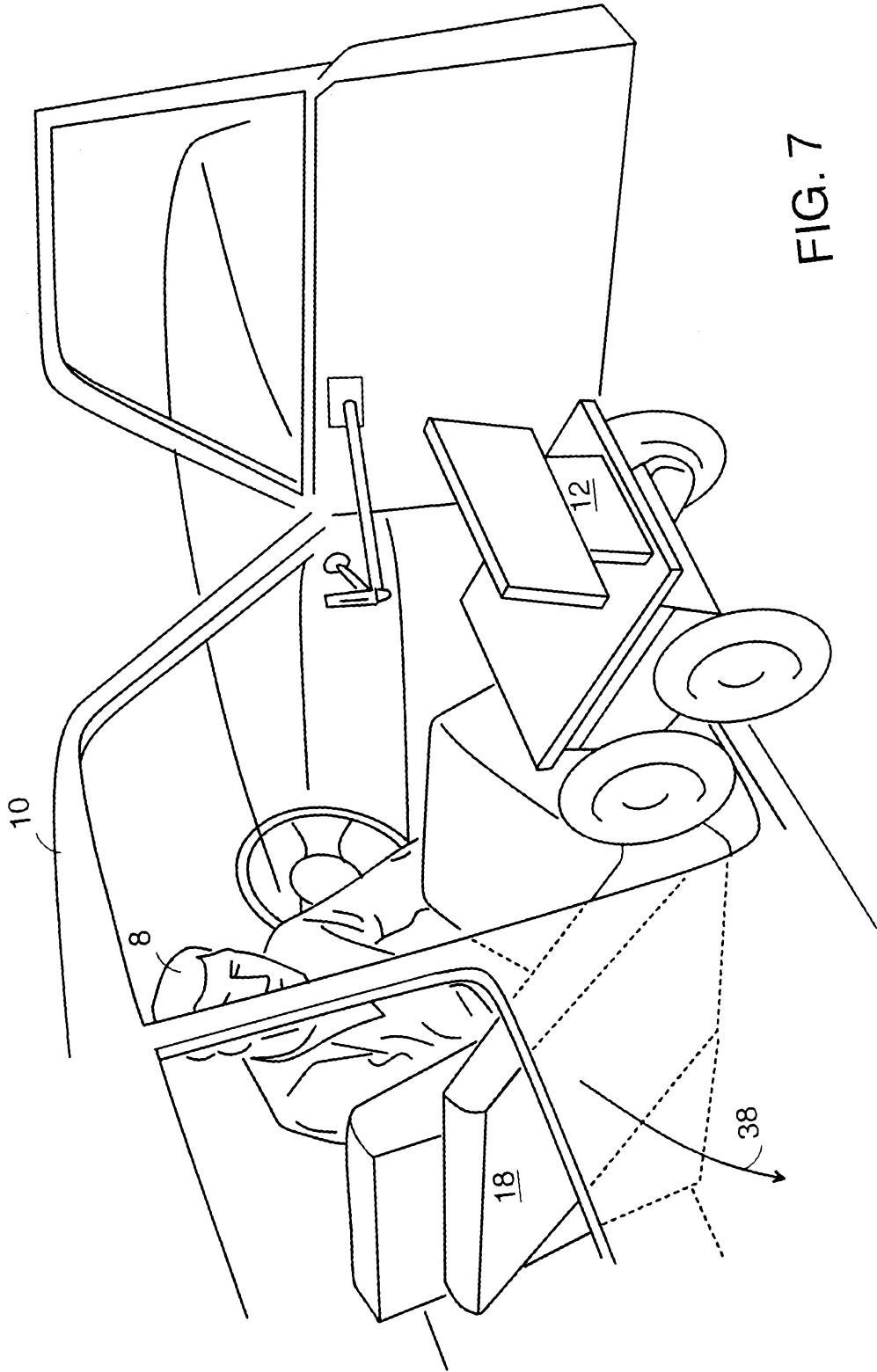


FIG. 7

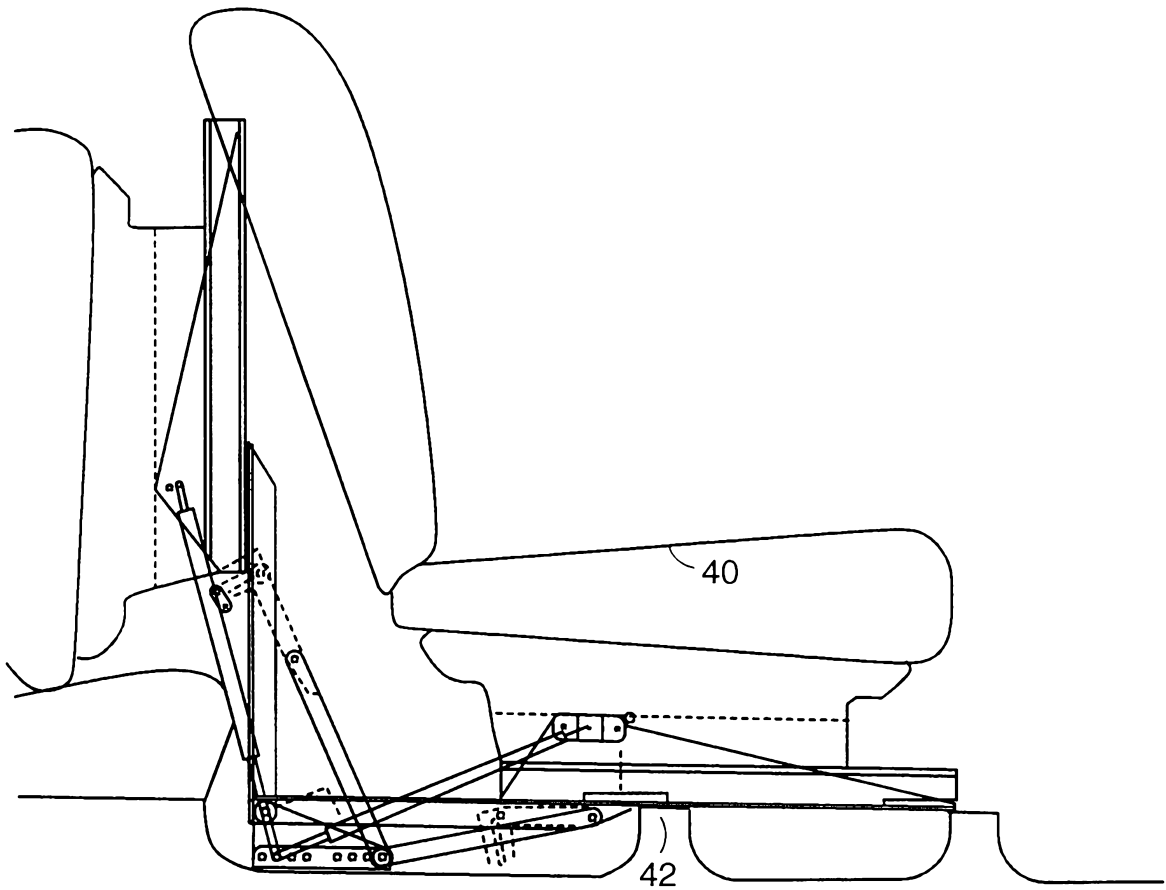


FIG. 8

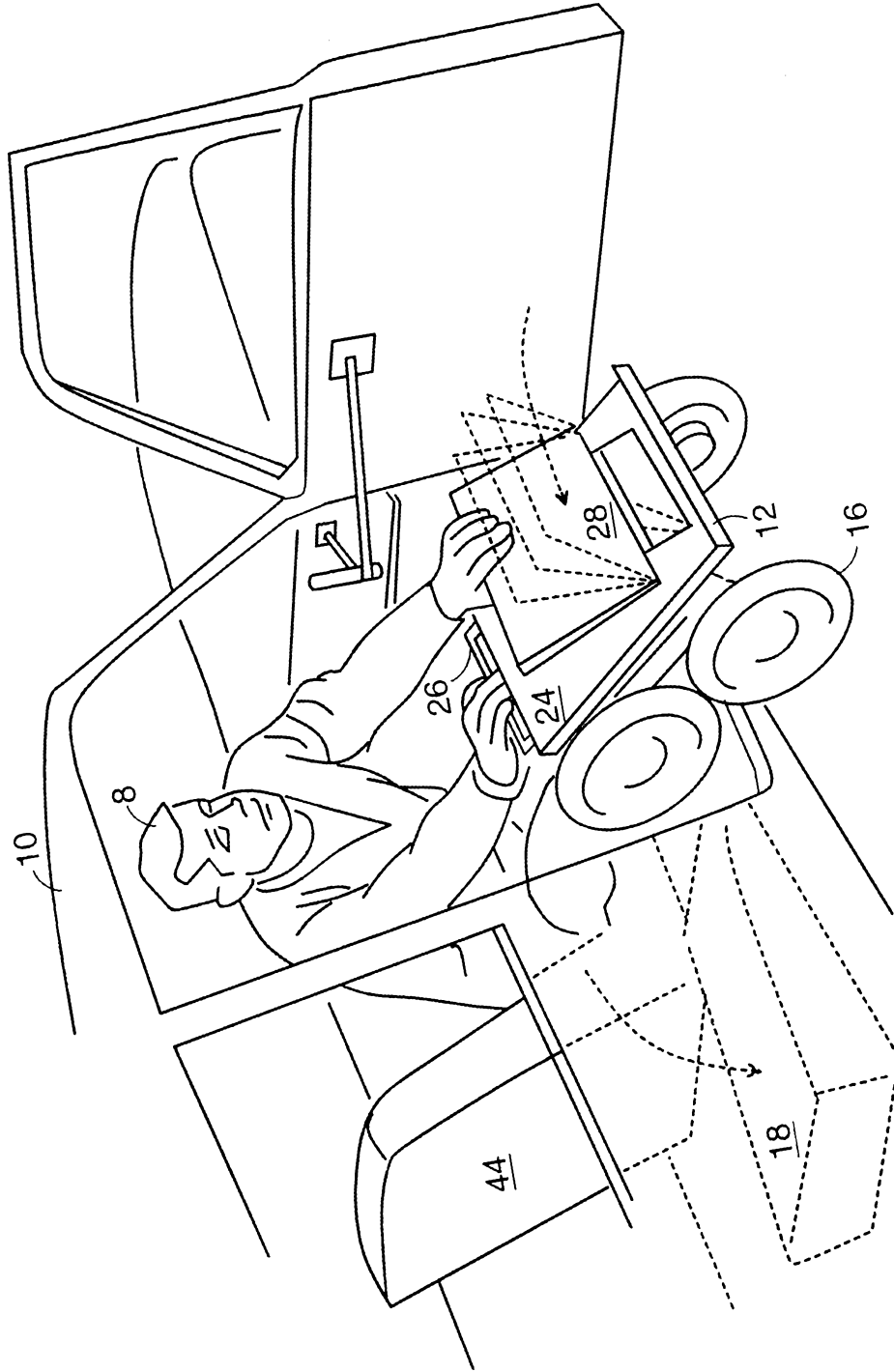


FIG. 9

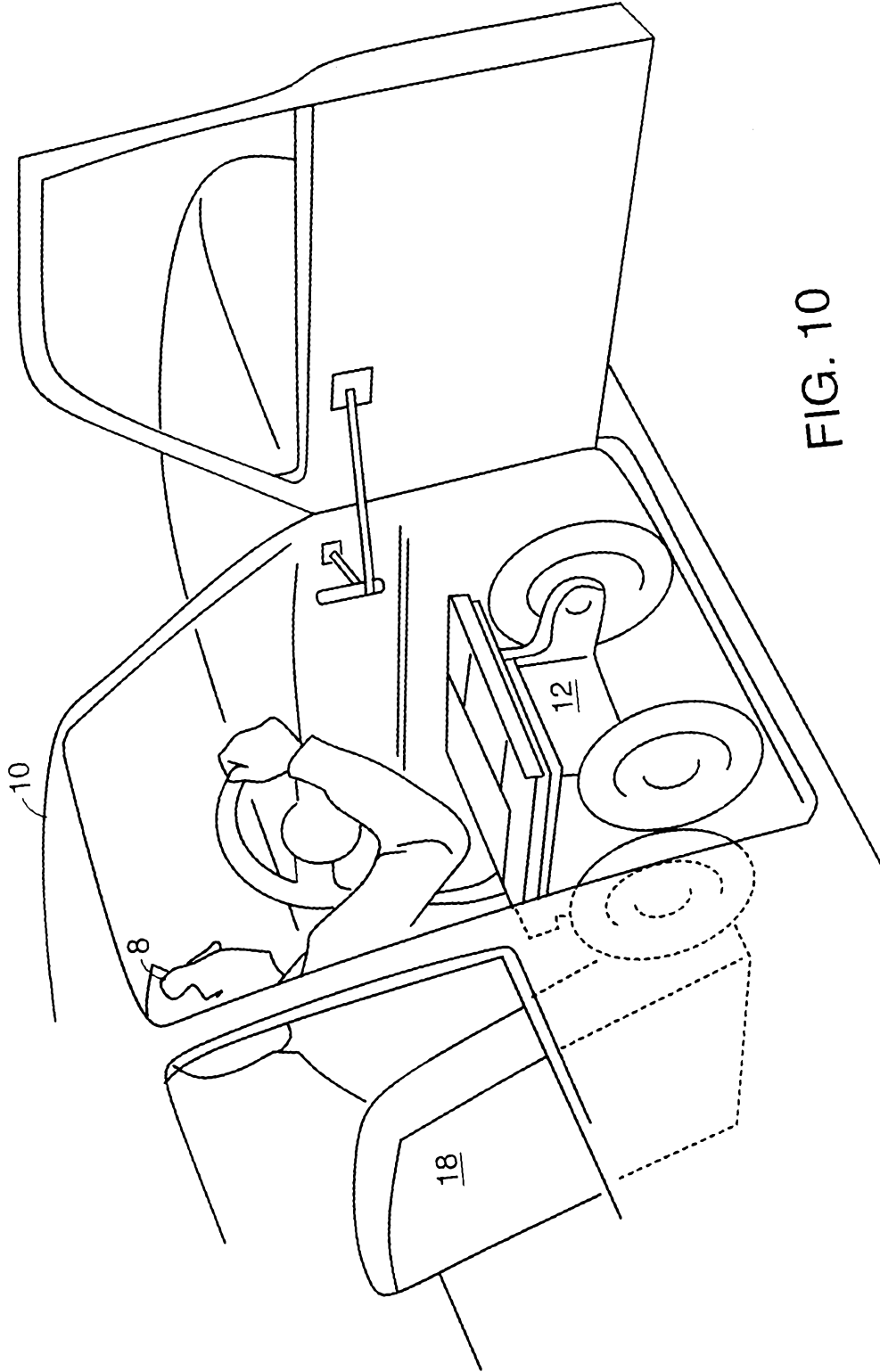


FIG. 10

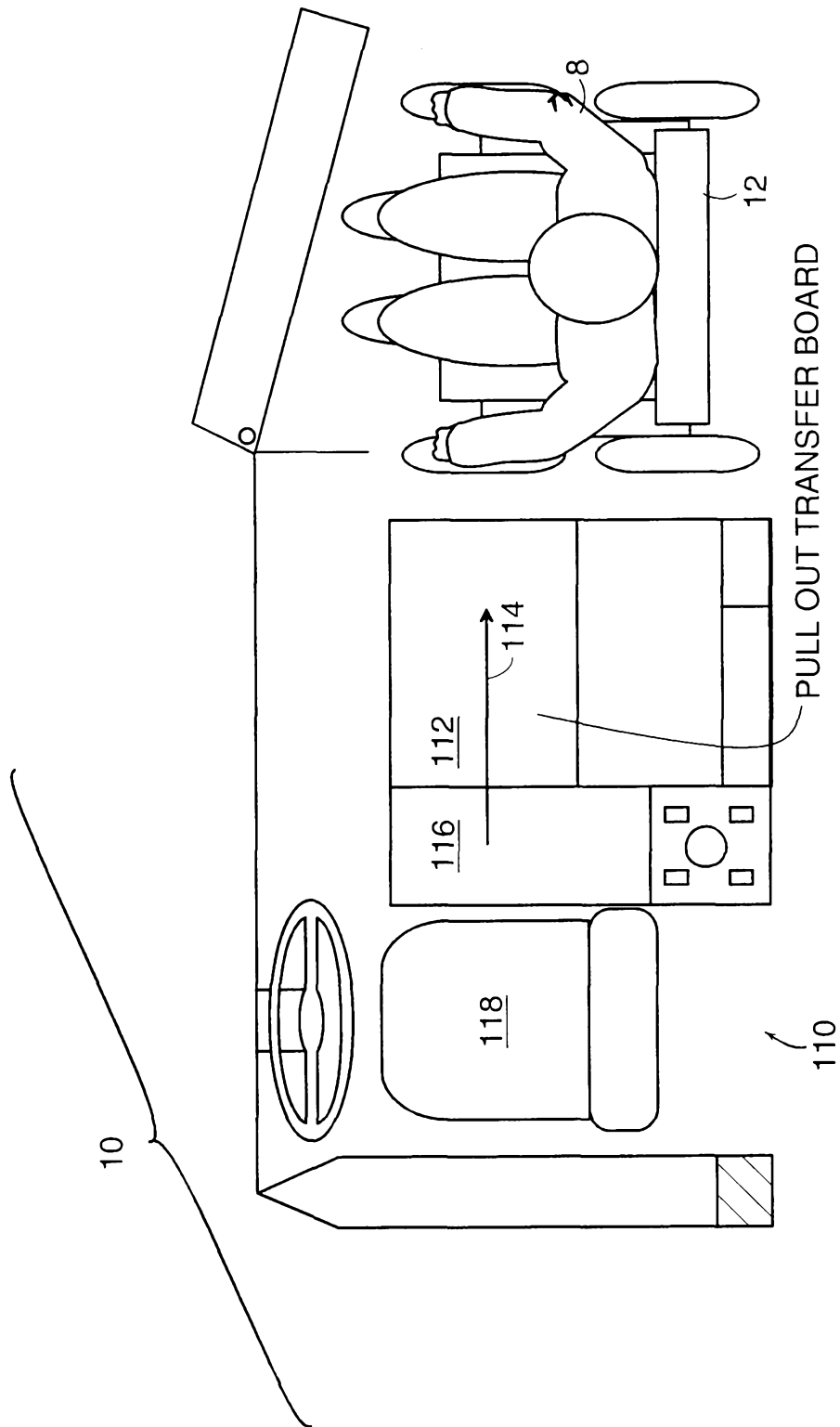


FIG. 11