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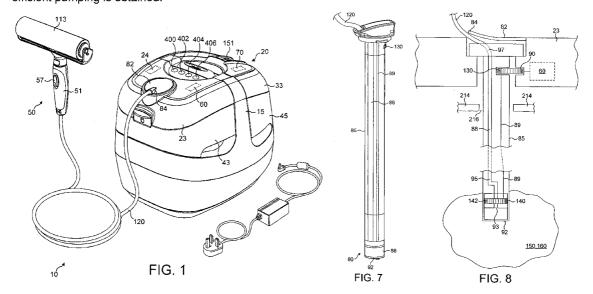
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(54) Abstract Title: Painting apparatus

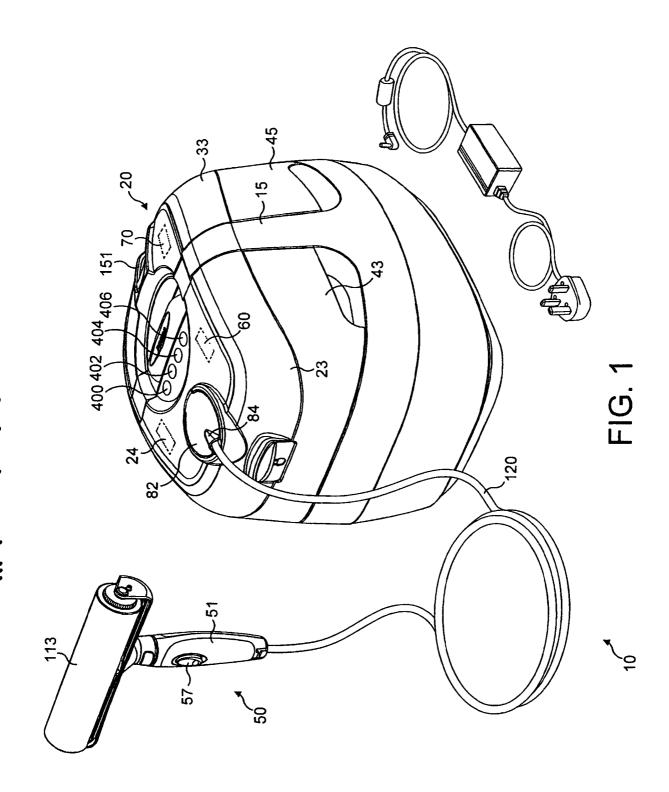
(57) A painting apparatus comprising a paint module 20, an applicator assembly 50, and a dip-tube assembly 80 containing a pump 86, the applicator assembly being fluidly connectable to liquid in the paint module via the dip-tube assembly, in which the pump is arranged within the dip-tube such that the pump is submerged in the liquid to substantially drive liquid away from the pump when supplying liquid to the applicator assembly. The paint module includes a module motor 60 and a module gear drive wheel 90 which engages with a drive gear wheel 130, the pump comprising two meshed gears 140, 142 which is connected via drive shaft 89 to gear 130. More efficient pumping is obtained.

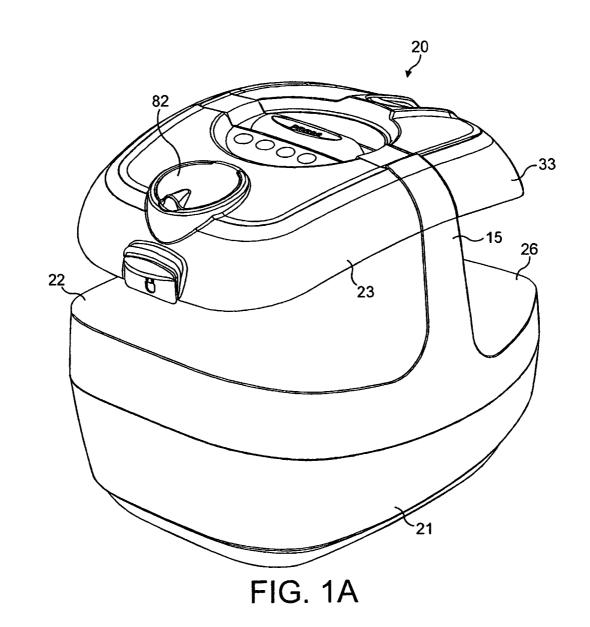


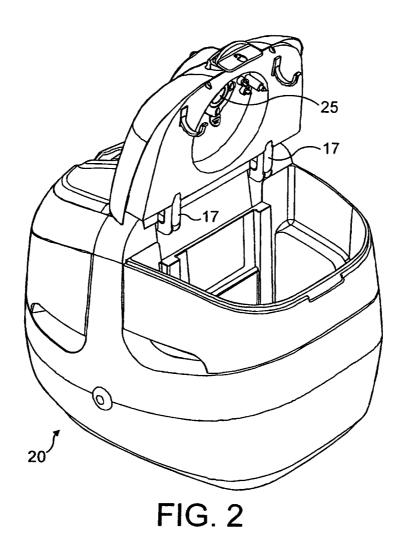
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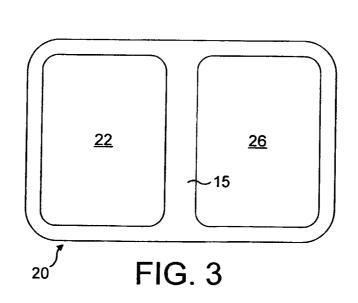
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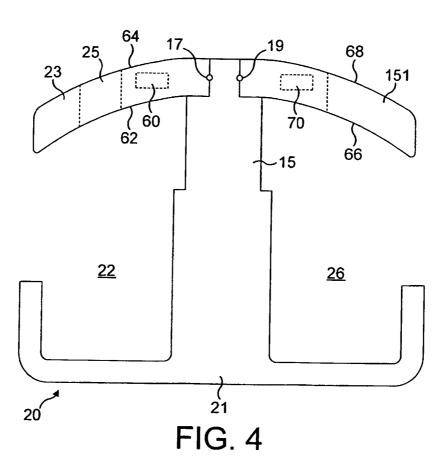




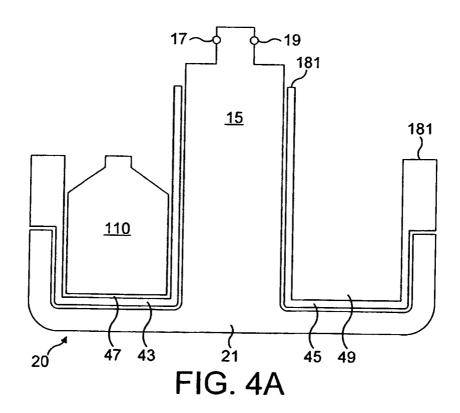












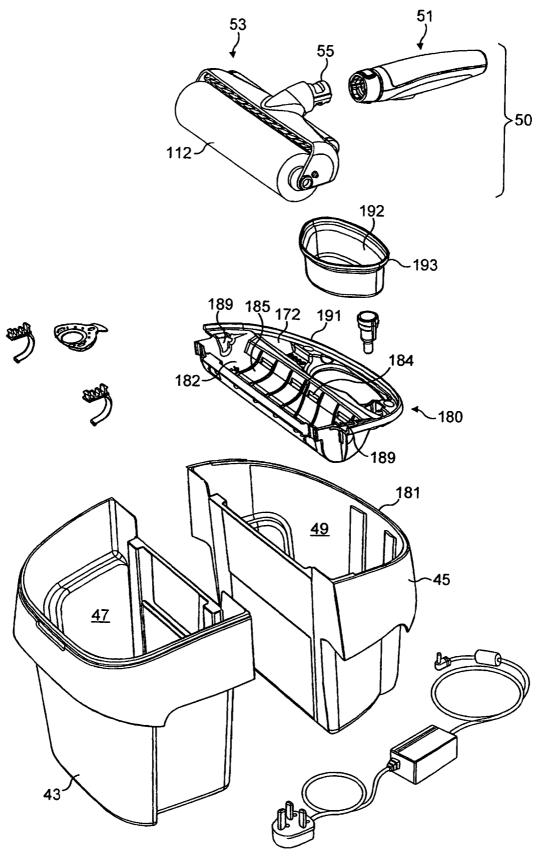
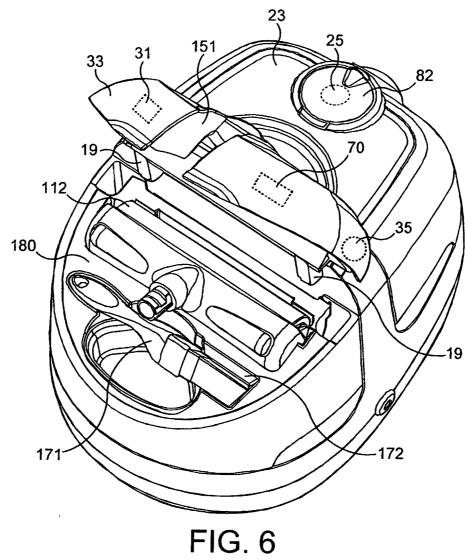
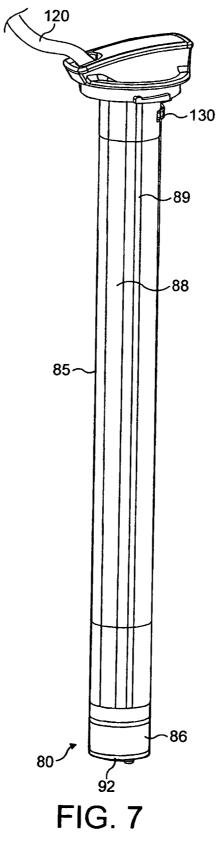
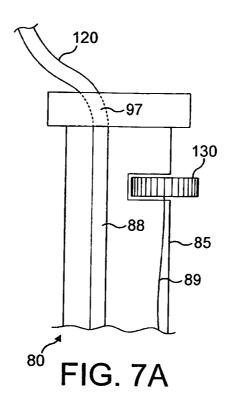


FIG. 5

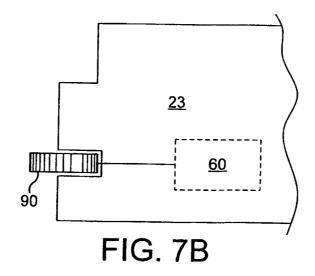












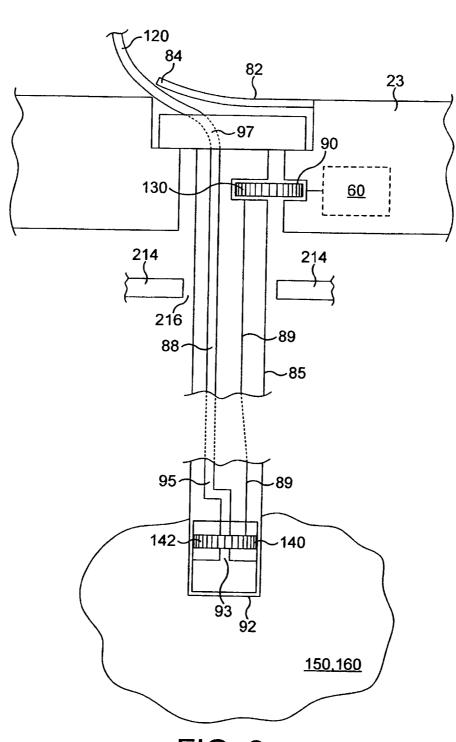
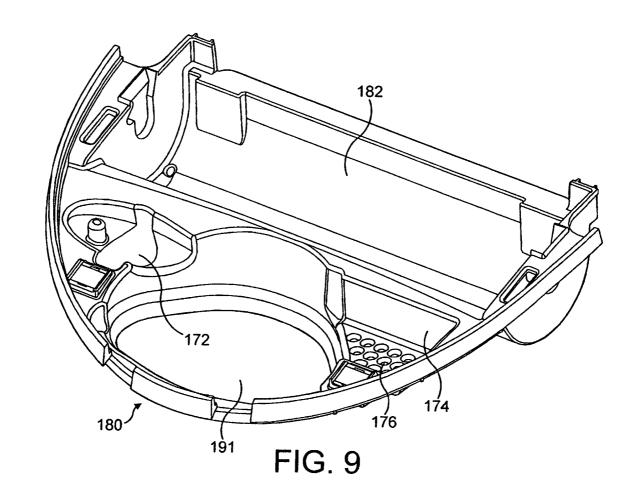
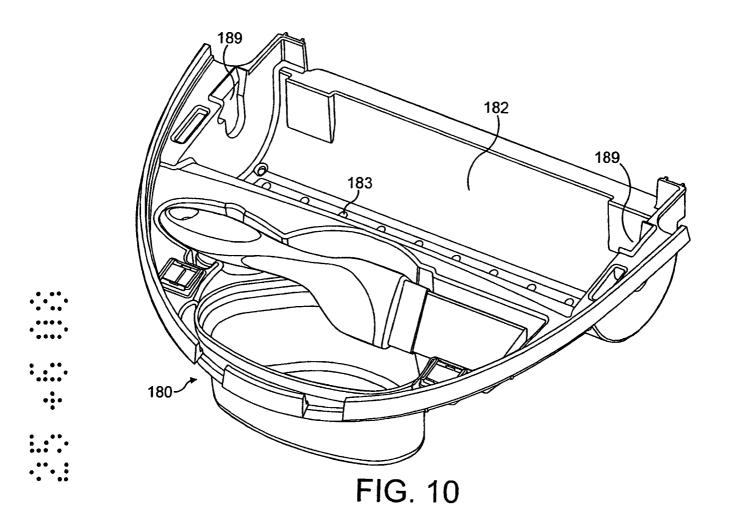
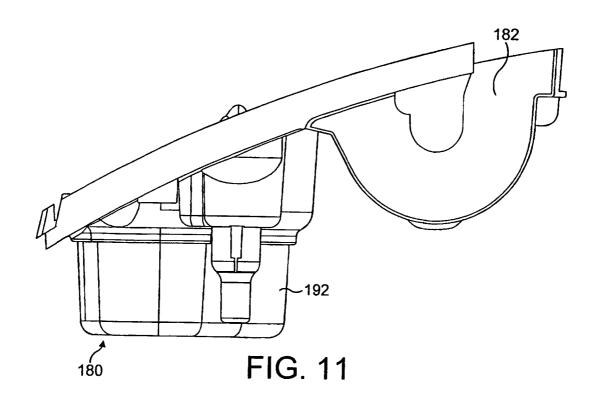
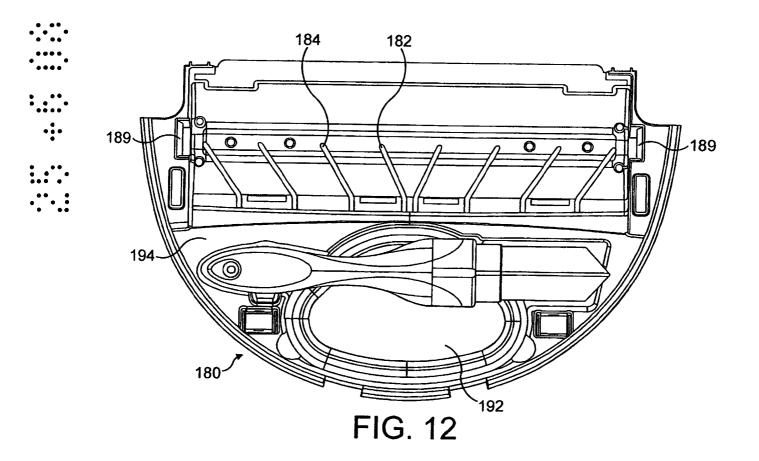


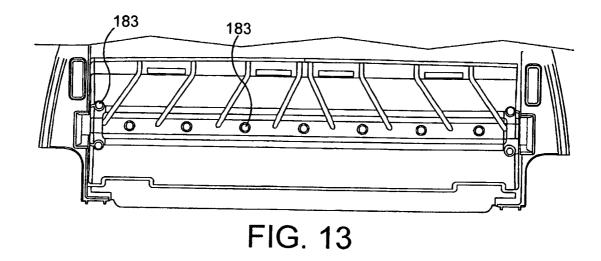
FIG. 8

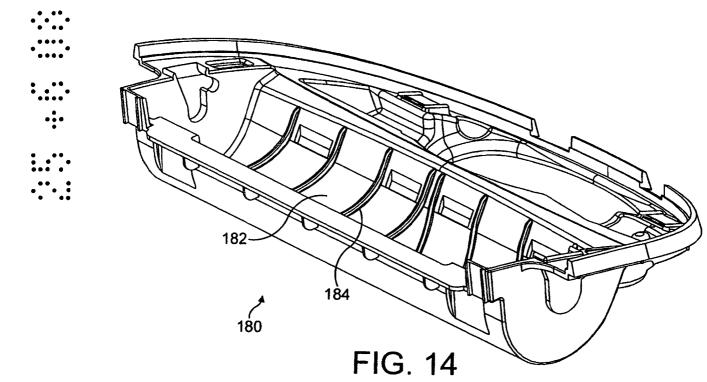












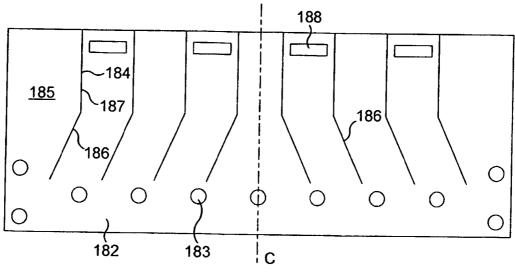


FIG. 15

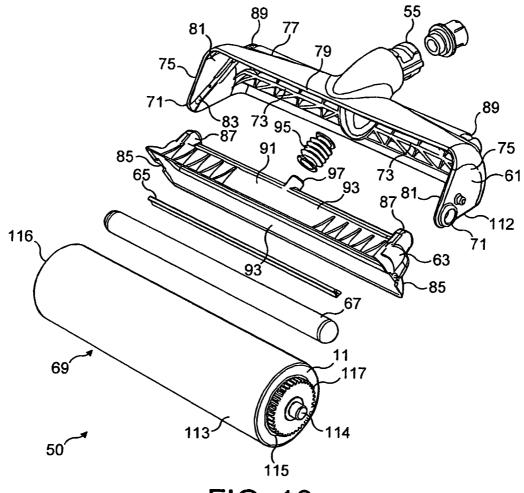
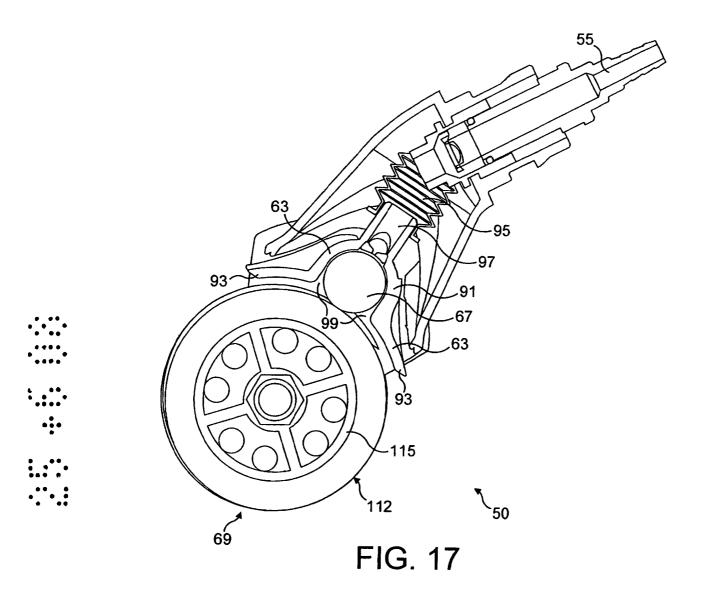


FIG. 16



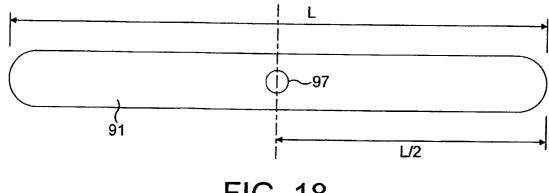
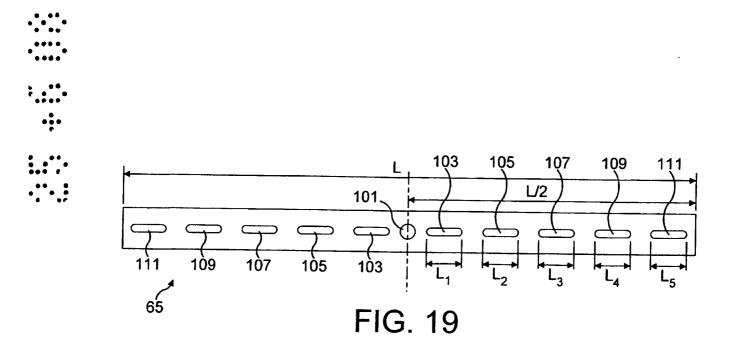
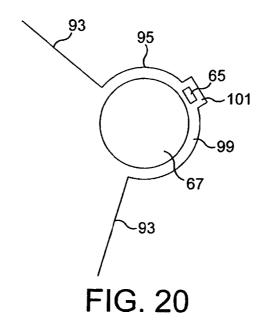
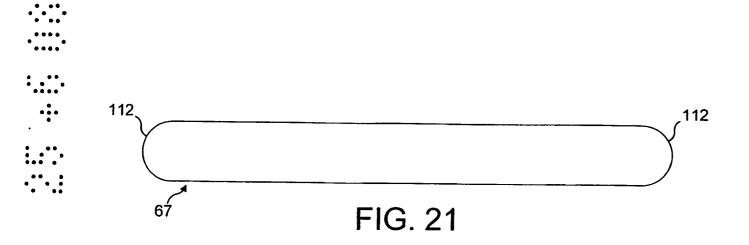
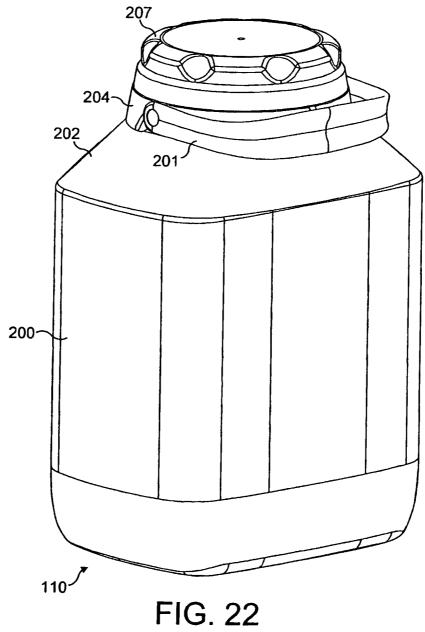


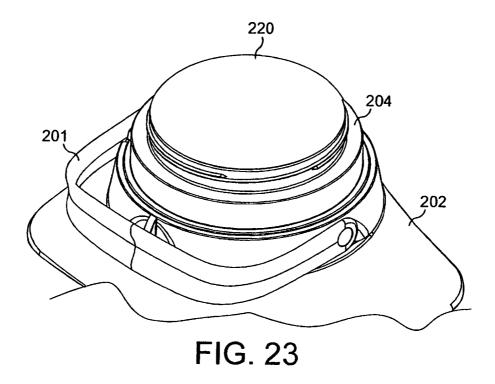
FIG. 18

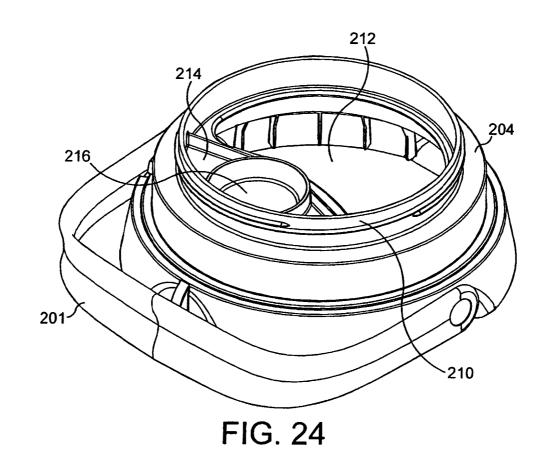


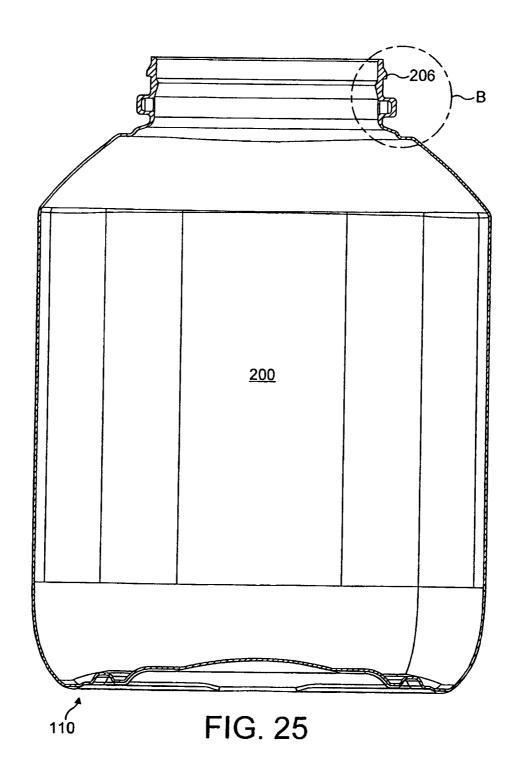












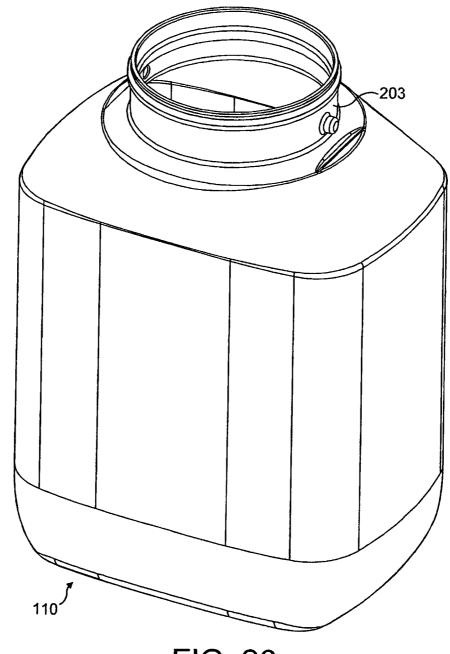
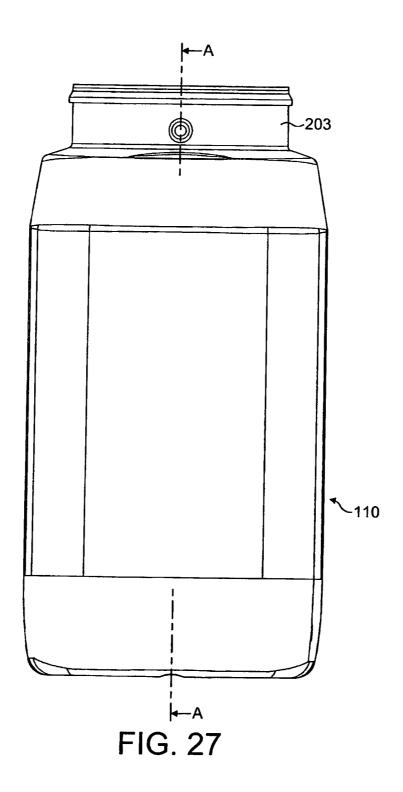
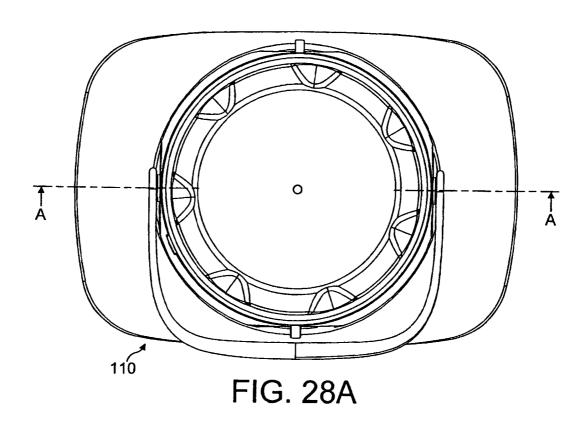
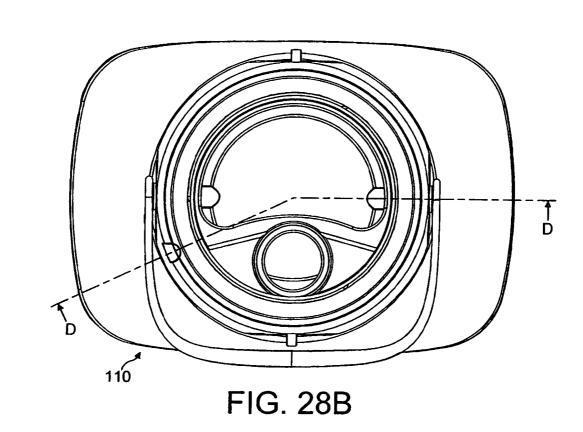


FIG. 26







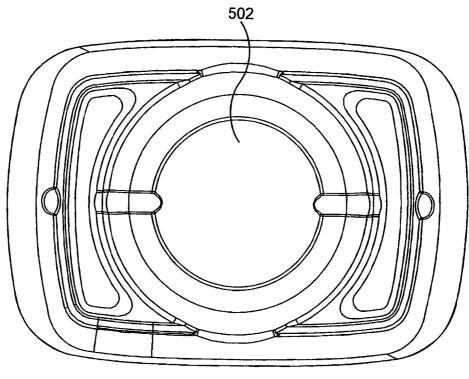
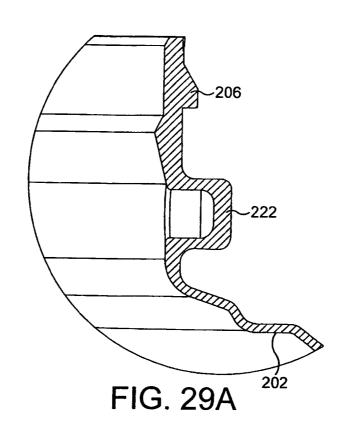
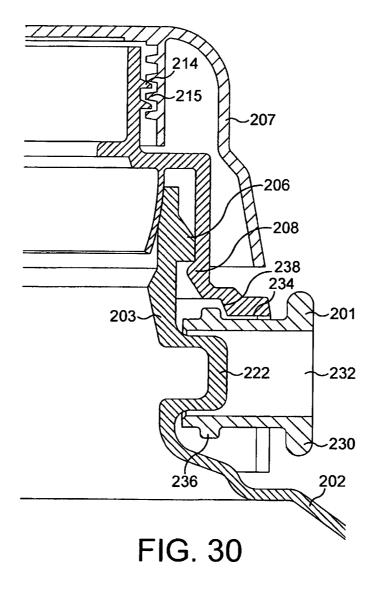
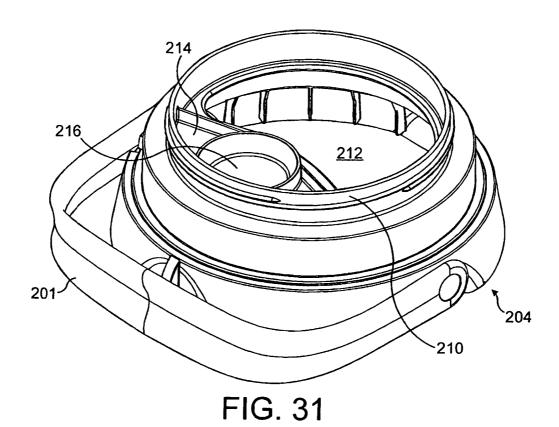


FIG. 29

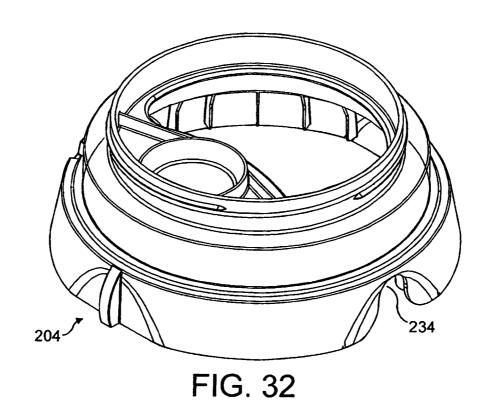












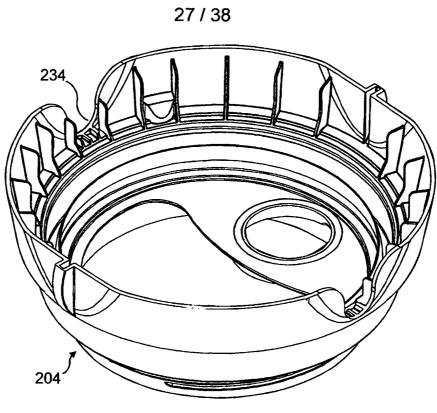
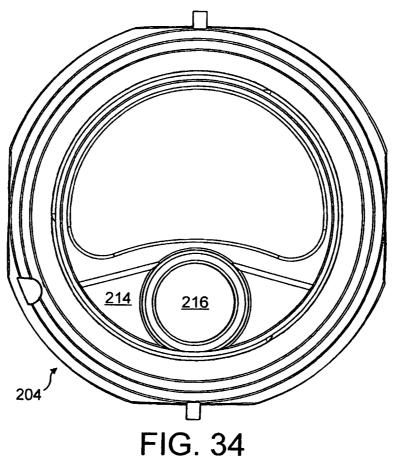
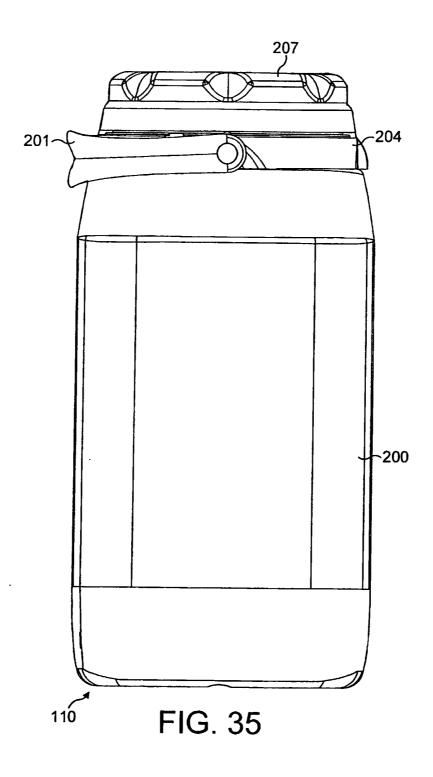
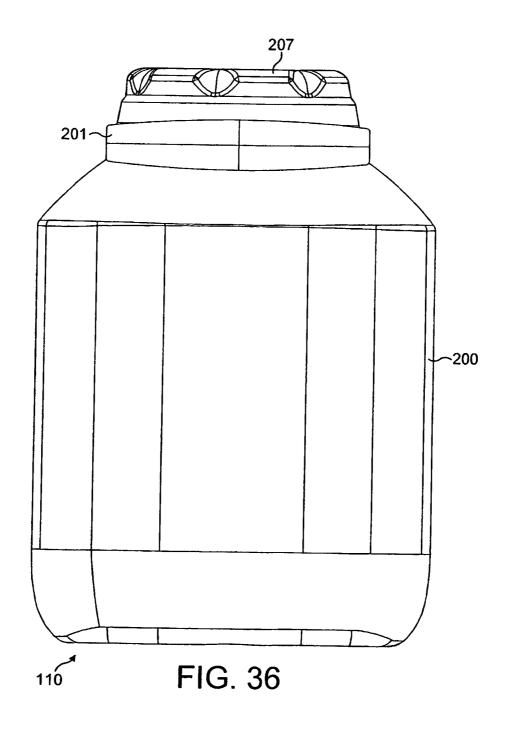


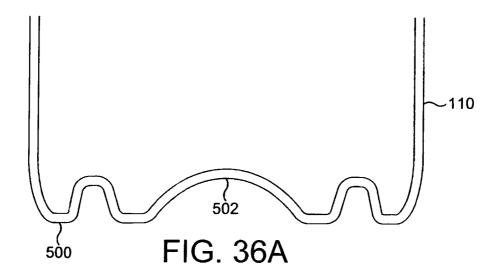
FIG. 33



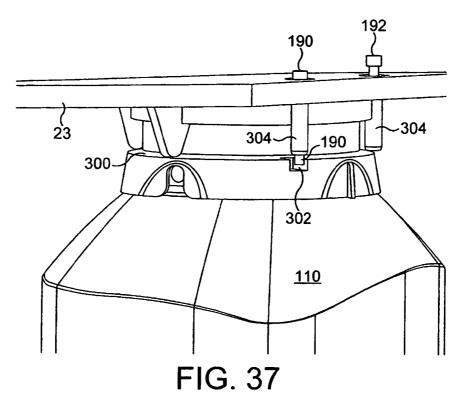


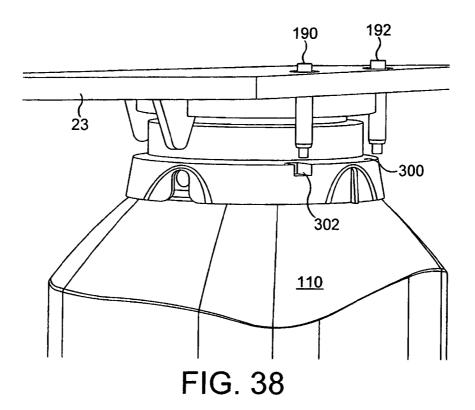














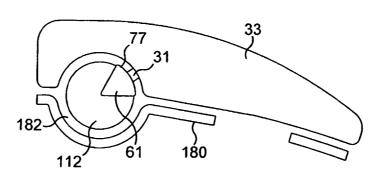
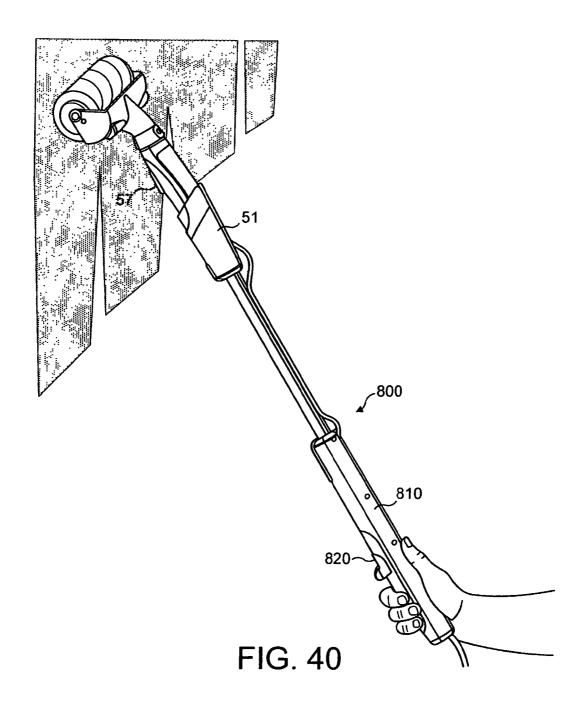
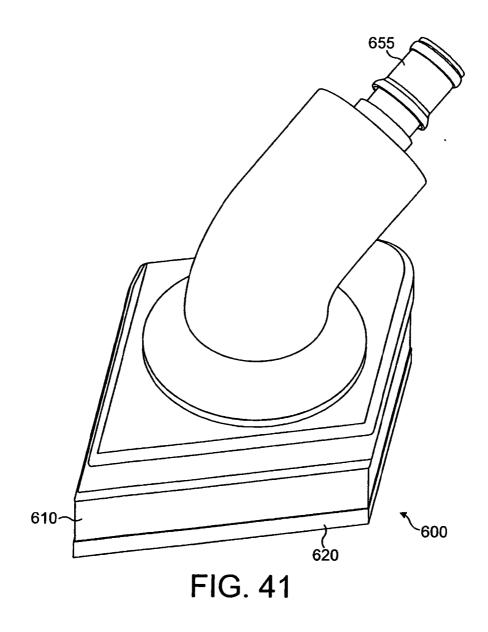


FIG. 39





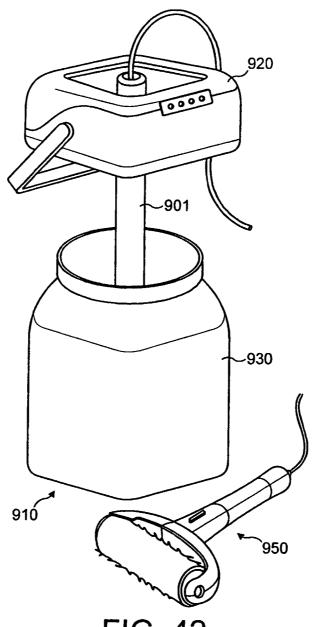
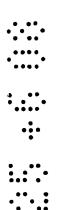
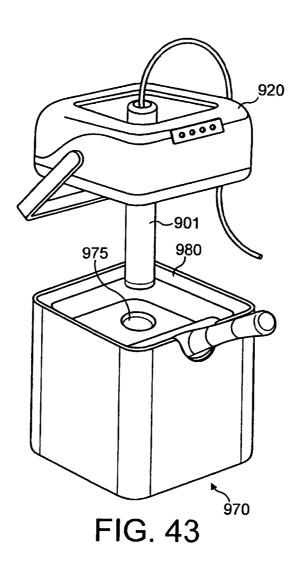
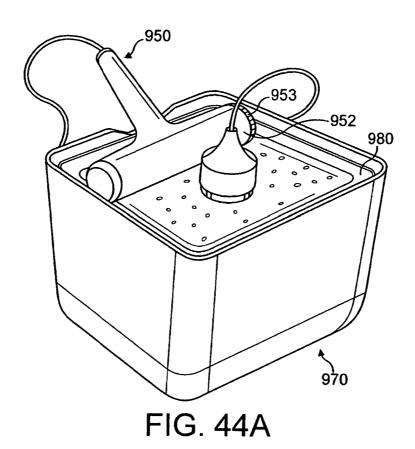


FIG. 42

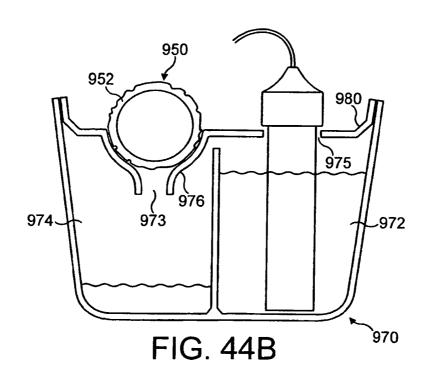


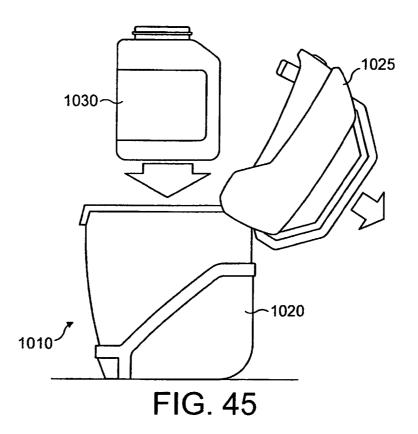




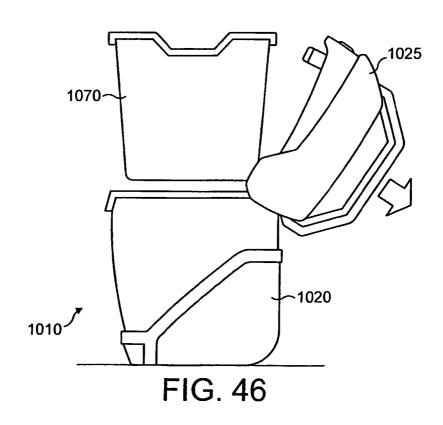


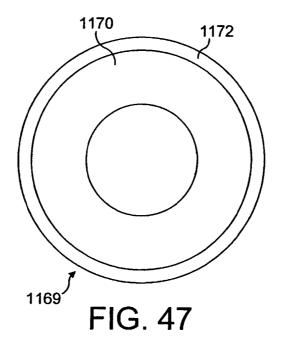














A Painting Apparatus

The present invention relates to a painting apparatus.

It is known for users to decant paint from a paint container into a roller tray, load a roller sleeve or primary roller with paint using the roller tray, and then apply paint to a surface such as a wall or ceiling with the roller sleeve.

Users find this known process both time consuming, in that it is necessary to continually load the roller sleeve with paint from the roller tray and decant paint from the paint container to the roller tray. The risk of spilling paint is also high due to the need to decant paint into the roller tray, and then load the roller sleeve before applying the paint to the surface.

Painting apparatus exists whereby paint is automatically fed using a pump from the paint container to the roller sleeve without the need to decant the paint into a roller tray, and load the roller sleeve.

A problem with such apparatus relates to the efficiency of the pumping process in apparatus where the pump is required to draw up paint from the paint container.

According to the present invention there is provided a painting apparatus comprising a paint module, an applicator assembly, and a dip-tube assembly containing a pump, the applicator assembly being fluidly connectable to liquid in the paint module via the dip-tube assembly, in which the pump is arranged within the dip-tube such that the pump is submerged in the liquid to substantially drive liquid away from the pump when supplying liquid to the applicator assembly.

Advantageously, the pump drives paint away from the pump which is a more efficient way of pumping liquid, for example, paint in a paint container, to the applicator.

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According to another aspect of the present invention there is provided a painting apparatus comprising a paint module, an applicator assembly, and a dip-tube assembly containing a pump, the applicator assembly being fluidly connectable to liquid in the paint module via the dip-tube assembly, in which the paint module includes a module motor and a module gear drive wheel, and the dip-tube assembly includes a dip-tube assembly gear drive wheel, the dip-tube assembly and module gear wheels engaging such that the motor can drive the pump.

Advantageously, providing the motor on the module rather than on the dip-tube assembly itself allows the dip-tube assembly to be potentially disposed of.

The invention will now be described by way of example only, with reference to the accompany drawings, in which:

Figure 1 is a perspective view of a painting apparatus according to the present invention,

Figure 1A is a perspective view of part of the painting apparatus of Figure 1,

Figure 2 is a perspective view of part of the painting apparatus of Figure 1,

Figure 3 is a plan view of part of the painting apparatus of Figure 1,

Figures 4 and 4A are side views of part of the painting apparatus of Figure 1,

Figure 5 is an exploded perspective view of the painting apparatus of Figure 1,

Figure 6 is a perspective view of part of the painting apparatus of Figure 1,

Figure 7 is a perspective view showing part of the painting apparatus of Figure 1,

Figures 7A, 7B, and 8 are front view showing part of the painting apparatus of Figure 1,

Figures 9 to 11 are perspective views showing part of the painting apparatus of Figure 1,

Figures 12 and 13 are plan views showing part of the painting apparatus of Figure 1,

Figure 14 is a perspective view showing part of the painting apparatus of Figure 1,

Figure 15 is a plan view showing part of the painting apparatus of Figure 1,

Figure 16 is an exploded view of part of the painting apparatus of Figure 1,

Figure 17 is a side section view showing part of the painting apparatus of Figure 1,

Figure 18 is a plan view showing part of the painting apparatus of Figure 1,

Figure 19 is a plan view showing part of the painting apparatus of Figure 1,

Figure 20 is a side view showing part of the painting apparatus of Figure 1,

Figure 21 is a plan view showing part of the painting apparatus of Figure 1,

Figure 22 is a plan view showing a paint container for use in the painting apparatus of Figure 1,

Figures 23 to 27 are perspective views showing part of the paint container of Figure 22,

Figure 28A is a plan view of the paint container of Figure 22 with the closure secured,

Figure 28B is a plan view of the paint container of Figure 22 with the closure removed,

Figure 29 is a below plan view of the paint container of Figure 22,

Figure 29A is a sectional side view of part of the paint container of Figure 22,

Figure 30 is a sectional side view of part of the paint container of Figure 22,

Figures 31 to 34 are perspective views showing part of the paint container of Figure 22,

Figure 35 is a side view of the paint container of Figure 22,

Figure 36 is a front view of the paint container of Figure 22,

Figure 36A is a section front view showing part of the paint container of Figure 22,

Figures 37 and 38 are perspective views showing part of the painting apparatus of Figure 1,

Figure 39 is a side view showing part of the painting apparatus of Figure 1,

Figure 40 is a perspective view of a an alternative painting apparatus,

Figure 41 is a perspective view a a paint pad according to another aspect of the present invention,

Figure 42 is a perspective view of an alternative painting apparatus,

Figure 43 and 44A are persective views of a cleaning module according to another aspecf of the present invention,

Figure 44B is a side sectional view of the cleaning module of Figure 44A,

Figures 45 and 46 are side views of an alternative painting apparatus, and

Figure 47 is an end view of part of an alternative roller assembly.

With reference to Figures 1 to 21, there is shown a painting apparatus 10 comprising a paint module 20 and a paint applicator assembly in the form of a roller assembly 50.

The paint module 20 is a plastic housing comprising a main body 21 having a liquid supply section 22, and a cleaning section 26. The supply 22 and cleaning 26 sections are separated by an upstanding centre wall 15 of the main body 21.

The paint module 20 includes a supply section closure 23 which is attached to the upstanding wall 15 by a hinge 17, and a cleaning section closure 33 which is also attached to the upstanding wall 15 by a hinge 19 (both hinges being shown simplified in Figure 4 but more detailed in Figures 2 and 6).

The supply section closure 23 includes a motor 60 (shown as a broken line in Figures 1 and 4) which is located between a lower wall 62 and an upper wall 64 of the closure 23.

The cleaning section closure 33 includes a motor 70 (shown as a broken line in Figures 1 and 4) which is located between a lower wall 66 and an upper wall 68 of the closure 33, the motor being drivingly connectable via a gear drive 35 (shown as a broken line in Figure 6) to part of the roller assembly 50 when the closure 33 is closed.

The cleaning section closure 33 also includes a spring loaded projection 31 which acts against the roller assembly 50 when the closure 33 is closed (see below).

The cleaning section closure also includes an aperture 151 (Figures 1 and 6).

The paint module 20 further includes a rigid plastic supply container 43 which is releasably housed in the liquid supply section 22, and a rigid plastic receiving container 45 which is releasably housed in the cleaning section 26 (Figures 4A and 5).

The rigid plastic supply container 43 defines a supply chamber 47, and the rigid plastic receiving container defines a receiving chamber 49. The supply chamber 47 is able to house a paint container 110 (containing paint 150), or a cleaning fluid such as water 160 (see below).

It can be seen from Figures 3 to 5 that the supply container 43 and the receiving container 45 can be removed from the main body 21 of the paint module 20. This enables the supply container 43 to be filled with the cleaning fluid before a cleaning cycle is commenced, and the receiving container to be emptied of a combination of cleaning fluid and paint after the cleaning cycle has been completed (see below).

The supply section closure 23 includes a through aperture 25 which allows a dip-tube assembly 80 to be inserted therethrough and into either paint in the paint container 110 housed below in the receiving chamber 48, or cleaning fluid in the receiving chamber 49 below, depending on whether the paint or cleaning cycle is required.

The supply section closure 23 also includes a removable cover 82 hingeably moveable between an open position which allows insertion of the dip-tube assembly 80, and a closed position when the dip tube assembly 80 has been inserted (as shown in Figure 1). The removable cover 82 includes a raised portion 84 to allow a connecting tube 120 (see below) to pass under the cover 82 and be connected to the roller assembly 50 when the cover 82 is in the closed position.

The supply section closure 23 also includes a drive gear 90 which connects the motor 60 to a drive gear 130 of the dip-tube assembly 80 (Figure 8) when the dip-tube 80 is inserted into the aperture 25 allowing the gears 90,130 to engage with each other (Figures 7, 7A, 7B and 8).

With reference to Figures 7, 7A, 7B and 8, the dip-tube assembly 80 comprises a sealed cylindrical housing 85 having a gear pump 86 located at its lower free end. The

cylindrical housing 85 includes a lower casing 92 to retain the gear pump 86. The lower casing 92 includes a plurality of holes (not shown) which are sized so as to prevent particles of greater than 2mm passing into the gear pump.

The gear pump 86 comprises two meshed gears 140,142. Gear 140 is connected via drive shaft 89 to gear 130 such that rotation of gear 90 which is connected to the motor 60 causes the two meshed gears 140,142 to rotate.

Rotation of the gears 140,142 causes either paint 150 or cleaning fluid 160 (depending on whether the cleaning cycle or paint cycle is activated) to be sucked up through the holes in the casing 92, and into the tube 88 via a hole 93 and channel arrangement 95. Tube 88 is fluidly connected via a connector 97 (shown as a broken continuation lines in Figures 7A and 8) to tube 120, and therefore paint is driven from the paint container to the roller assembly 50.

The tube 120 has an internal diameter of 6mm.

Such a dip-tube arrangement differs from that known in the prior art where the pump is positioned at the top of the dip-tube and the paint is sucked up from the paint container rather than being driven from the paint container when the gears are submerged in the paint as in the present invention. This enables more efficient priming of the roller assembly with paint due to the fact that the gear pump 86 does not have to suck up a quantity of air in the tube 88, but simply has to drive paint through the tube 88. Gear pumps operate more efficiently when driving a higher viscosity liquid such as paint or water as opposed to air.

The pump of the present invention has a pressure capacity, by which is meant the maximum pressure that the pump can apply to liquid leaving its outlet. This pressure is dissipated along the length of the tubing to achieve viscous flow. For specification purposes it is assumed that any applicator head (e.g. roller) in the whole device has been removed from the end of the tube, so that the pressure of the liquid leaving the tube is

close to atmospheric pressure. In this situation the measured pressure at the pump outlet is also the pressure difference between the start and end of the tube. The pressure capacity is in the range 0.5 to 7.5 barg which allows flow rates through the tubing in the range 30 to 4000 ml/min to be achieved by suitable choice of tubing length and internal bore diameter in the ranges 2 to 8m and 4 to 8 mm respectively.

In the embodiment above, the tube is 4m long with a 6mm internal bore diameter, and supplies paint at 200ml/min. At the upper end of the quality Rotothinner viscosity specification (8 Poise) this requires a pump outlet pressure of about 4.1 barg.

The paint module 20 includes an electronic control unit 24 (only shown in Figure 1) which sets the appropriate flow rate for the paint or cleaning fluid depending on whether the paint or cleaning cycle has been selected, and the direction of paint flow during the paint cycle (see below).

The paint module 20 includes a storage tray 180 which sits upon a rim 181 of the receiving container 45 (Figure 5).

The storage tray 180 includes a well 182 which is shaped and dimensioned such that it can receive part of the roller assembly 50 (see below).

The well 182 includes seven drainage holes 183 (all of which are only shown in Figure 13) spaced equally on its inner surface 185 along its lowest point. The holes have a diameter of approximately 5mm. Two further identical drainage holes 183 are positioned on the inner surface 185 at each end of the well, and circumferentially spaced either side of the lowest point of the well.

The well 182 includes a series of ribs 184 which project radially inwardly from the inner surface 185. The ribs 184 include an inclined portion 186 and a vertical portion 187 as shown in Figures 14 and 15. The ribs 184 are arranged either side of a centre line C such that the inclined portions 186 on either side oppose each other.

The well 182 also includes rectangular drainage slots 188 positioned on the inner surface 185 between alternate pairs of projecting ribs 184 on each side of the centre line C (Figure 15). The drainage slots 188 are positioned between the vertical portions 187 of the ribs 184. Each slot is approximately 5mm in height by 25mm in length. The slots 188 are angularly spaced from the seven drainage holes positioned at the lowest point by approximately 90 degrees.

The well 182 includes two locating slots 189 to receive the roller assembly 50.

The storage tray 180 includes a hole 191 which can receive a paint pot 192. The paint pot 192 has a rim 193 which enables the pot 192 to rest upon an upper surface 194 of the storage tray 180 (Figures 11 and 12).

The storage tray 180 includes a paint brush receiving section 172 (Figure 9), for housing a paint brush 173 (Figures 6, 10, and 12).

The paint brush receiving section 172 has a brush end 174 which includes a plurality of holes 176 to allow any paint on the brush to drain through the holes an into the receiving container 45.

The storage tray 180 can also be adapted such it can receive additional paint applicators such as a paint pad or a mini-roller (not shown).

The paint pot 192 can be used to store paint to enable other applicators to be loaded, for example, the paint brush.

The roller assembly 50 includes a handle 51 which is releasably attachable to a roller head 53 via a coupling 55 (Figure 5). The handle 51 can optionally include a sensor (not shown) which detects the presence of the roller head such that the paint flow rate is adjusted accordingly.

The handle 51 includes a switch 57 which is wirelessly connected to the control unit 24 to start and stop paint flow as required.

The roller cage or head 53 comprises a primary housing 61, a secondary roller housing 63, a distribution plate 65, a secondary roller 67 and a primary roller 69 (Figure 16).

The primary housing 61 includes two end portions 75 connected by a back portion 77.

Each end portion includes a lug 71 which locates inside slots 189 of the well 182 to enable the roller assembly 50 to locate on the storage tray 180. Each end portion 75 includes an inner surface 81 upon which is positioned a slot 83. Each lug 71 includes an internal through hole 112.

The back portion 77 includes two holes 89.

The primary housing 61 includes two springs in the form of metal tabs 73 (shown schematically in Figure 16) mounted on an inside surface 79 of the back portion 77.

The secondary roller housing 63 is defined by a hemicylindrical channel 91 which is congruent with two flared portions 93. The channel 91 defines a chamber 99 (Figure 17).

The channel 91 includes a through hole 97 at a mid point along its length L.

The hemicylindrical channel 91 is dimensioned so that it can receive the secondary roller 67 (see below).

The secondary roller housing 63 has two projections 87 which extend from the hemicylindrical channel 91 away from the flared portions 93.

The secondary roller housing 63 includes two pins 85.

The projections 87 locate inside holes 89 on the primary housing 61, and pins 83 locate inside the slots 83 on the primary housing 61 to enable the secondary roller housing 63 to locate on the primary housing 61.

When the secondary roller housing 63 is housed inside the primary housing 61, the secondary roller housing is biased towards the roller 69 as a result of the two springs 73 mounted on the primary housing 61 and acting on the housing 63, and a flexible coupling 95 which physically connects the primary housing 61 and the secondary roller housing 63, and fluidly connects the chamber 99 to the coupling 55. The secondary roller housing is biased away from the primary housing such that the flared portions 93 are in contact with a roller sleeve 113 (see below).

The distribution plate 65 is a rectangular strip which locates inside a recess 101 in the chamber 99 between the channel 91 and the secondary roller 67 (Figure 20).

The distribution plate 65 includes a central hole 102, and a series of rectangular slotted holes 103,105,107,109,111 having equal lengths L₁, L₂, L₃, L₄, and L₅. The purpose of the distribution plate 65 is to provide an even distribution of paint onto the secondary roller and hence onto the roller sleeve to prevent banding of paint when it is applied to a surface. The distribution plate would ideally be a single long tapered slot, however, such a long slot is unstable in moulding, and therefore a series of slots having increasing widths (hole 103 being the narrowest, hole 111 being the widest) enables both a stable moulding to be produced and minimise banding.

The secondary roller 67 is cylindrical with hemispherical ends 112 (Figure 21) and is dimensioned such that it is a close fit inside the chamber 99. The fit between the secondary roller and channel 91 is governed by the thickness of the paint film.

The secondary roller is designed to only rotate when both the flow of paint behind the secondary roller is sufficient to lift the secondary roller off the distribution plate, and when the roller sleeve is rotating. The secondary roller will rotate at a speed that depends

on the balance of the friction from the roller sleeve as a driving force and the viscous drag from the film of paint that it is sitting on in the channel 91, i.e. only partially dependent on the roller sleeve speed, and not fully dependent as is the case for secondary rollers that are coupled via drive pulleys to the roller sleeve. The viscous drag depends on the thickness of the paint film. The friction of the roller will depend on roller speed and spring biasing force. In this way the system can balance itself irrespective of paint flow rate and roller speed.

It has been found that using ball or hemispherical ends reduces dripping when compared to secondary rollers having straight ends because the hemispherical ends draw paint back into the chamber 99. The hemispherical ends also give a smooth transition to the roller which helps prevent dripping.

The secondary roller 67 is made of ABS which is dimensionally stable so that it does not warp and jam in the channel 91, and sufficiently wear and chemically resistant for use with paint.

The primary roller 69 includes a roller sleeve 113 having a first end cap 115 and a second end cap 116. Each end cap 115,116 has a lug 114 extending outwardly therefrom. The first end cap 115 includes an integrated gear 117.

The roller sleeve 113 is made of a flock material and has an internal diameter of 38mm, and an external diameter of 60mm, giving a pile length of 11mm. The roller has a longitudinal length of 218.3mm. The longitudinal free ends of the roller sleeve are also bevelled or tapered inwardly to minimise dripping compared to a roller sleeve where both the ends are parallel to each other, and perpendicular to the longitudinal axis of the roller sleeve.

The roller 69 is secured onto the primary housing 61 by engagement of the lugs 114 with the internal through hole 112 on the lugs 71.

The roller assembly is assembled as shown in Figure 16 by inserting the distribution plate 65 in the recess 101 of the channel 91, then locating the secondary roller housing inside the primary housing, positioning the secondary roller inside the chamber 99, and finally locating the roller 69 in the primary housing such that the secondary roller is retained floating in the chamber 99 by the roller sleeve.

It can be seen from Figures 16 and 17 that the secondary roller 67 is not secured to any part of the roller assembly and is therefore essentially floating inside chamber 99. The secondary roller is acting as a hydrodynamic bearing inside the chamber 99. This has the advantage that when the paint is not flowing into the chamber 99, the secondary roller sits in the chamber and provides a pressure drop to prevent paint dripping.

It can also be seen that paint flows around the secondary roller and not from inside it as is the case with known secondary rollers.

Furthermore, the hemicylindrical channel 91 fully envelopes the secondary roller 67 to prevent paint dripping from the ends of the secondary roller 67.

The flared portions 93 of the channel 91 partially surround and are biased against the roller sleeve such that they collect excess paint and feed it back onto the roller sleeve or into the chamber 99. Consequently there is less tendency for paint to drip from the roller sleeve.

The secondary roller housing 63 in which the secondary roller 67 locates is biased towards the roller sleeve. Secondary rollers which are on a fixed axes do not allow for variation in roller sleeve diameter and tolerance. Allowing both the secondary roller and the channel 91 to float significantly minimises dripping.

With reference to Figures 22 to 39, there is shown the paint container 110.

The paint container 110 includes a main body 200, a collar 204, a handle 201, and a closure 207 (Figure 22).

The main body 200 has an inwardly tapering neck portion 202 and an upstanding rim portion 203. The upstanding rim portion 203 has a rim 210 which defines a container aperture 212.

The rim 210 has an internal web 214 projecting radially inwardly. The web 214 includes an aperture 216 which is dimensioned such that it is a close fit around the cylindrical housing 85 of the dip-tube assembly 80 so as to remove excess paint from the cylindrical housing 85 when it is removed from the paint container 110 (Figure 24).

The aperture 216 is also positioned relative to the paint container 110 such that when the paint container 110 is housed within the paint module 20, it is vertically aligned with the aperture 25 on closure 23 such that the cylindrical housing can be inserted through both apertures with subjecting the housing to stress due to misalignment (Figure 8).

It can be seen from Figure 24 that the aperture 216 is offsett from the centre of the container aperture 212, therefore enabling access to paint in the container with a paint brush.

The collar 204 snap-fits onto the neck main body 202 by engagement of a main body projection 206 with a collar projection 208 such that the collar 204 is vertically and rotationally retained on the main body.

The collar 204 also includes a screw thread 214 onto which closure 207 is screwed via a corresponding closure screw thread 215 so as to close and seal the paint container 110.

The container aperture 212 can also be temporarily sealed using a tear-off foil seal 220.

The handle 201 includes inwardly projection lugs 230 with internal through holes 232 which locate on lugs 222 positioned on the upstanding rim portion 203 to secure the handle 201 to the main body. It can be seen from Figure 30 that the handle 201 is also

vertically retained on the main body of the paint container by the collar 204 by virtue of engagement between the lugs 230 and a lower surface 234 of the collar.

The handle is also horizontally retained on the main body by virtue of engagement between an increased diameter radial portion 236 on the lugs 230 and an inside surface 238 on the collar 204.

Thus it will be appreciated that the closure can be screwed onto the collar to form a subassembly, followed by snap-fitting of the subassembly onto the main body of the paint container. This is advantageous on production lines where snap-fit assembly is installed. The closure can then be screwed off and on again via the screw threads which is a more user friendly process compared to conventional closures which snap-fit directly onto the container main body.

With reference to Figure 36A, the paint container 110 has a base 500 which includes a convex recess 502. The effect of the recess is to raise the paint level inside the container so that less paint is left in the container when it falls below the level of the gear pump in the dip-tube assembly. The additional effect of the recess 502 is to enable the closure of an identical container to locate inside the recess to improve stacking stability.

With reference to Figures 37 to 39, the collar 204 has a second container feature in the form of an upper surface 300, and a first container feature in the form of a recess 302.

The supply section closure 23 includes a first detection switch 190 and a second detection switch 192 projecting from its lower surface 62. Both switches 190,192 are housed within separate hollow housings 304 and movable between open and closed positions. Both switches are biased towards the container (downwardly when viewing Figure 37) via a spring (not shown). The first and second detection switches 190,192 interact with the first and second container features as described below.

It is also possible to include taggants in the paint itself which can communicate with a sensor in the paint module to confirm the presence of the correct paint and hence correct paint container.

The paint module 20 also has four switches, a paint switch 400, a pause switch 402, a drain switch 404, and a cleaning switch 406 to activate the required mode (Figure 1).

The painting apparatus 10 operates as follows:

The user (not shown) selects the paint container 110 (Figure 22). The paint container 22 is supplied with paint 150.

Known paints cannot be used with the painting apparatus of the present invention because we have found problems arise in the operation of the apparatus. In particular, before painting can begin, the tubing connecting the paint container to the roller assembly must be primed with paint. This requires paint to be transferred from the container using a pump. The tubing is typically from 2 to 8 metres long with an internal diameter of from 0.4 to 0.8cm internal diameter.

Attempts to use known paints with the apparatus of the invention reveal that such known paints either cannot be pumped at all or can only be pumped at a very low flow rate. At best this is inconvenient making the painting process very slow, while at worse, the paint cannot be transferred to the roller for application to the substrate. This is thought to arise from the pressure loss associated with the flow of the paint through the tubing. Whilst a larger pump could overcome the pressure drop, it would make the apparatus more expensive and cumbersome in use. Suitable, conveniently sized pumps have pressure capacities (the maximum pressure that the pump can apply to paint leaving its outlet) of from 0.5 to 7.5 barg.

Diluting known paints with carrier liquid, such as water in the case of emulsion paints, enables the paints to flow at acceptable rates of from 30 to 4000ml/minute. However,

although this overcomes the priming problem, the diluted paints cause the roller to skid during the application process, the paint to sag and poor appearance of the dried paint film as well as poor opacity, the latter requiring more coats of paint to obliterate the substrate.

Surprisingly, we now provide paint formulations that can be pumped at flow rates of from 30 to 4000ml/minute using pumps of pressure capacities of from 0.5 to 7.5 barg without the problems of the known paints.

According to another aspect of the present invention there is provided

a liquid architectural paint composition comprising

- i) a first thickener having Newtonian flow
- ii) a second thickener having shear thinning flow

wherein the high shear viscosity of the paint is from 0.12 to 0.18 Pa.s and the medium shear viscosity is from 0.5 to 0.8 Pa.s.

By medium shear viscosity is meant the viscosity when measured at 160s⁻¹ and high shear viscosity when measured at 10000s⁻¹. The significance of measuring the viscosity at these two shear rates is that the former reflects the shear rate that the paint is exposed to in the tubing and the latter approximates to the shear rate in the pump assembly.

The medium shear viscosity is measured using a Rotothinner viscometer and the high shear viscosity using a Cone and Plate viscometer as described below.

Architectural coatings are for application to surfaces found in or as part of buildings such as interior and exterior walls, ceilings, window frames, doors and door frames and radiators.

By aqueous is meant that at least 50% of the continuous phase is water, preferably from 75 to 100%, more preferably from 85 to 100%, even more preferably from 95 to 100% and most preferably it is 100%. Any balance is preferably water compatible organic solvent or mixture of solvents.

Above a medium shear viscosity of 0.8 Pa.s, the paint cannot be pumped to the roller, whereas below 0.5 Pa.s the paint drips from the roller and the paint tends to sag unless great care and/or very many thin coats are applied. Preferably, medium shear viscosity is from 0.55 to 0.70 Pa.s and most preferably from 0.6 Pa.s to 0.7 Pa.s.

At a high shear viscosity above 0.20 Pa.s, the paint is very difficult to spread, feeling 'sticky' to the user. Below 0.12 Pa.s the roller skids during application. Preferably, the high shear viscosity is from 0.13 to 0.19 Pa.s, more preferably from 0.14 to 0.18 Pa.s and most preferably from 0.15 Pa.s to 0.17 Pa.s.

The first thickener type exhibiting Newtonian flow can be selected by making a composition according to the thickener composition test described below and comparing the viscosities at the two shear rates. The ratio of the medium shear viscosity:high shear viscosity must be less than 1.8, preferably from 0.8 to 1.8, more preferably from 0.6 to 1.6.

Suitable examples of the first thickener type fall into two thickener families, namely associative thickeners and low molecular weight (less than 100000 daltons) water soluble polymers. Suitable examples of the first family include the hydrophobically modified ethoxylated urethane (HEUR) type such as Acrysol RM1020, Acrysol RM2020 and Acrysol RM5000 available from Rohm and Haas. Other HEUR types include Borchi Gel 0434, Borchi Gel 0435 and Borchi Gel 0011 available from Borchers. Also included in this first family are hydrophobically modified polyacetal polyethers such as Aquaflow NHS 300 and Aquaflow NHS 310 available from Aqualon/Hercules. Suitable examples of the second family include cellulosic ethers such as hydroxyethylcellulose, sodium

carboxymethyl cellulose, methyl cellulose, ethylhydroxylethyl cellulose, hydroxypropyl cellulose; synthetic water-soluble polymers such as polyethylene oxide, poly vinyl alcohol and polyacrylamide.

The associative thickeners are preferred, more preferably hydrophobically modified polyacetal polyether and most preferred is Aquaflow NHS 300.

Similarly, the second thickener, having shear thinning flow, can be selected by making a composition according to the thickener composition test described below and comparing the viscosities at the two shear rates. The ratio of the medium shear viscosity:high shear viscosity must be greater than 1.8, preferably from 1.8 to 40, more preferably from 5 to 40.

Suitable examples of the second thickener type can be found in a number of thickener families. These include high molecular weight (greater than 100000 daltons) water soluble polymers, smectic clays, metal chelates, polymer microgels and associative thickeners.

Suitable examples of the high molecular weight water soluble polymers include carboxymethyl cellulose such as Blanose-available from Aqualon/Hercules, Finnfix-available from CP Kelco and Celflow; and hydroxyethyl cellulose such as Natrosol 250 MR and Natrosol 250 HHR-available from Aqualon/Hercules. Other cellulosics include methyl cellulose, ethylhydroxyethyl cellulose and, hydroxypropyl cellulose. Other suitable such water soluble polymers include the synthetic polymers including polyethylene oxide, polyvinyl alcohol and polyacrylamide; and the natural and synthetic gums such as guar, alginates carrageenan, xanthan and hydroxypropyl guar available from Rhodia.

Suitable examples of the smectic clays include montmorillonite available as Bentone EW from Elementis, bentonite, attapulgite and Iaponite

Suitable examples of the metal chelates include titanium carboxylate salts such as Tilcom, Vertec AT23, Vertec AT34 and Vertec AT 35 available from Johnson Matthey.

Suitable examples of the polymer microgels are the alkali swellable emulsions (ASE) such as Acrysol ASE 60 and Acrysol TT935 available from Rohm and Haas.

Suitable examples of the associative thickeners include the HEUR type such as Acrysol SCT-275, Acrysol RM8, Acrysol RM 825, Acrysol RM 895 available from Rohm and Haas; Tafigel PUR 40, Tafigel PUR 41, Tafigel PUR 50, Tafigel PUR 60 Tafigel PUR 61 available from Munzig; Borchi Gel 0620, Borchi Gel 0621, Borchi Gel 0622, Borchi Gel 0625, Borchi Gel 0626, Borchi Gel PW 25, Borchi Gel LW44, Borchi Gel 0024, Borchi Gel WN50S, Borchi Gel L75N, Borchi Gel L76 available from Borchers; the hydrophobically modified ethoxylated urethane alkali swellable emulsions (HEURASE) such as UCAR DR-73 available from Rohm and Haas; the hydrophobically modified alkali swellable emulsions (HASE) such as Acrysol TT615 available from Rohm and Haas, Aquaflow ALS 400 available from Aqualon.Hercules, Tafigel AP20 available from Munzig; and the hydrophobically modified polyacetal polyether Aquaflow NLS 200, Aquaflow NLS 205, and Aquaflow NLS 210 available from Aqualon.Hercules.

The associative thickener types are preferred, more preferably the HEUR type and most preferably it is Acrysol TT615.

Preferably the paint comprises from 0.05 to 1.0, more preferably from 0.1 to 0.5, yet more preferably from 0.15 to 0.30 and most preferably from 0.15 to 0.20 wt% of the first type of thickener and from 0.1% to 1.0, more preferably from 0.15 to 0.8, yet more preferably from 0.2 to 0.6 and most preferably from 0.2 to 0.5 wt% of the second type. All based on the non vol thickener calculated on the total formulation

It is essential that both types of thickener are present otherwise skidding and/or sagging and dripping will occur.

Thickener composition test

A thickener composition was made using the ingredients listed below.

	g
Water (1)	1219.69
Dispex N40	15.25
Disponil A1580	38.12
Benzyl alcohol	79.28
Water (2)	554.40
Acrylic copolymer emulsion	1682.90
Axilat DS_910	27.7.20
Water (3)	550.04
Ropaque Ultra E	326.20
Thickener	Variable
Ammonia 910	Variable

The acrylic copolymer emulsion is methyl methacrylate/2 ethyl hexyl acrylate copolymer having a glass transition temperatiure of 5°C. Revacryl 1A available from Synthomer is a suitable alternative.

Axilat 910 is a copolymer emulsion dispersion of composition styrene:butyl acrylate:acrylic acid ratio of 47:47:6 by weight. Available from Hexion.

The ingredients are added in the order shown and adjusted to pH 8 using ammonia. Since thickeners vary greatly in the magnitude of the viscosity they generate, the amount of thickener used in this test is adjusted until the medium shear viscosity measured on the Rotothinner viscometer is at least 0.05 Pa.s and the high shear viscosity reading on the cone and plate viscometer is at least 0.02Pa.s.

Viscosity Measurements

High Shear Viscosity

This is measured using a Cone and Plate viscometer operating at 10000s⁻¹

The viscometer used is a model CPI (available from Sheen Instruments, Kingston, UK) fitted with a cone suitable for operation from 0 to 0.5 or 0 to 10 Pa.s. The measurement is carried out in accordance with ISO standard test method BS EN ISO 2884-1:2006, BS 3900-A7-1:2006 Paints and varnishes "Determination of viscosity using rotary viscomenters. Cone and plate viscomneter operated at high shear rate. The test is carried out at 25°C +/- 0.2°C.

Medium Shear Viscosity

This is measured using a Rotothinner model 455N 0-1.5 Pa.s Digital Rotothinner from Sheen Instruments. The test is carried out using a 250 ml can at 25°C.

The invention will now be illustrated by reference to the paint example below.

Description	Supplier	Function	Weight %
Water (Mains)			16.00
Dispex N40	Ciba	pigment dispersant	0.20
Disponil A1580	Cognis	wetting agent	0.50
Benzyl Alcohol	<u> </u>	Coalescing solvent	1.04
Dispelair CF823	Blackburn Chemicals	Defoamer	0.10
Microdol H600	Omya	Dolomite	11.60
Polwhite B	Imerys	Kaolin	4.10
Tioxide TR92	Huntsman-Tioxide	TiO2	15.00
Water (Mains)			5.00
Natrosol Plus Grade 330 PA	Hercules/Aqualon	Low Shear thickener	0.30
Rocima V189	Thor	Biocide	0.07
Water (Mains)			2.50
Acrylic Copolymer Emulsion		Binder	24.28
AXILAT DS 910	Hexion	Binder	4.00
Water (Mains)			7.94
Ropaque (Tm) Ultra E	Rohm & Haas	opacifier	4.71
Dispelair CF823		Defoamer	0.16
Ammonia 910		stabiliser	0.05
Acrysol SCT-275	Rohm & Haas	Shear thinning thickener	1.55
Aquaflow NHS 300	Hercules/Aqualon	Newtonian thickener	0.90

Medium shear viscosity 0.65 Pa.s High shear viscosity 0.15 Pa.s The user unscrews the closure 207 from the collar 204, and peals off the foil seal 220 so as to expose aperture 216 on the collar 204.

The user opens the supply closure 23 of the paint module 20, and inserts the paint container 110 such that it locates inside the plastic supply container 43.

The user then closes the closure 23 of the paint module 20.

With the paint container 110 in the correct position, switch 190 locates inside recess 302, such that the switch 190 is in the closed position, and switch 192 abuts the uppermost surface 300 of the collar 204 such that it is in the open position (Figure 37). With the switches 190,192 in this configuration, and only in this configuration, the painting apparatus can operate to supply a flow of paint to the roller assembly.

If the paint container is incorrectly inserted, or a paint container which does not have the corresponding features on the collar is present such that the switch 190 is not in the closed position, and/or switch 192 is not in the open position then paint flow is prevented (Figure 38).

Thus, essentially, a double detection system operates which requires both switches to be in the correct position before paint can flow.

If the paint container is correctly inserted such that paint can flow, but the cleaning mode is selected instead of the painting mode, then a warning sounds which prevents the cleaning mode from operating.

If the paint container is incorrectly inserted such that paint will not flow, then a warning is given so that the user is prevented from inserting the dip-tube, which by virtue of the paint container being incorrectly inserted, will not be in aligned with the aperture through which it is supposed to pass through.

If the user selects the painting mode without the paint container being present then a warning is given

The switch logic can also be adapted to detect the absence of the paint container such that only the cleaning cycle can be activated.

The dip-tube assembly 80 is then inserted through aperture 25 of the closure 23, and through aperture 216 of the collar 204 such that the gear pump 86 is submerged in the paint.

Tube 120 (which is attached to handle 51) is then connected to the roller assembly via coupling 55. When the handle 51 is connected to coupling 55, a paint path is defined between paint in the paint container, and the roller sleeve 113.

When the user wishes to start painting, the paint switch 400 is activated, and the user depresses switch 57 on handle 51. Providing the roller sleeve is in engagement with the surface, for example a wall, to be painted, paint will flow to the roller sleeve. As the user rotates the roller sleeve against the wall, paint flows over the secondary roller 54 and onto the roller sleeve. Paint will not flow unless the control unit 24 detects either a change in pressure on the roller sleeve (via a sensor (not shown)), or optionally, rotational movement of the roller sleeve (via a rotational sensor on the roller assembly). Therefore the user simply has to remove the roller sleeve from the surface being painted to prevent paint flow, irrespective of whether the switch 57 is released. This prevents too much paint arriving at the roller sleeve when the user is not painting.

Suitable pressure sensors include piezoelectric as well as more exotic materials that change conductivity when stressed.

Movement sensors include accelerometers or simpler arrangements of a switch with a heavy free end. Displacement sensors include strain sensors as well as optical sensors.

To detect rotational movement it is possible to mount a magnet on the primary roller, and a sensor on the primary housing 61. The sensor could be a hall effect or simple reed switch.

In an alternative embodiment, pressure or rotational movement sensors need not be used, with the user simply relying on the switch 57 to control paint flow to the roller sleeve.

When the switch 57 is activated, paint will continue to be fed to the roller sleeve. As soon as the switch 57 is released, the control unit instructs the motor 60 to reverse the flow direction, and suck paint back through the tube 120 so as to remove any excess paint from the chamber 99, and thereby minimise dripping of paint from the roller assembly. The flow is reversed for a period of time sufficient to remove excess paint from the chamber, typically, under one to two seconds.

It is also possible to reverse the paint flow when either a pressure change, or lack of rotational movement of the primary roller is detected.

It will be appreciated that even if the primary roller has stopped rotating, it is possible to supply paint by activation of the switch 57. In such an embodiment, the supply of paint to the primary roller is not prevented by lack of rotational movement of the primary roller.

It will also be appreciated that the paint flow can be prevented if a pressure change on the primary roller is detected, and that the paint flow can be reversed when the primary roller is removed from the surface to be painted, but still potentially rotating. This allows the consumer to stop painting, and rely on the pressure change to prevent paint flow, but still reverses the paint flow irrespective of whether or not the primary roller is rotating, i.e. the paint flow reversal is not dictated only by the rotation of the primary roller.

The paint flow rate is between 150 and 250ml/min.

If the user wishes to use an alternative applicator, then the roller assembly 50 can be disconnected from the handle 51, and a different applicator, for example, a paint pad or mini roller can be connected.

When the user has finished painting, the roller sleeve is cleaned as follows:

Firstly, the cleaning section closure 33 is opened so as to expose the storage tray 180 (Figure 6).

The roller assembly 50 is positioned such that the roller sleeve 112 locates inside the well 182 (Figures 5, 6, and 39). When the cleaning section closure 33 is closed, the roller sleeve 112 is enveloped by the closure 33 (by virtue of it having a internal profile the same as that of the roller sleeve), and the well 182. The sprung loaded projection 31 abuts against the back 77 of the primary housing 61 to further push the secondary roller 67 against the roller sleeve 112 to increase the friction between the roller sleeve and the secondary roller such that more paint is removed (Figure 39, with the secondary roller removed for clarity).

When the cleaning section closure 33 is closed, the gear 35 positioned on the closure engages with the gear 117 on the roller sleeve 112 such that motor 70 can rotate the primary roller during the cleaning cycle.

The user then presses the drain switch which returns unused paint from the tube 120 to the paint container.

The dip-tube assembly 80 is removed from the paint module, and then the paint container 110 is removed from the supply container 43. The supply container 43 is then filled with water, and the dip-tube assembly is then inserted into the container 43 such that it can then pump water to the roller assembly.

Activation of the cleaning cycle causes water to flow at a rate of 1000 ml/min from the supply container 43 to the roller sleeve following the same path as when the paint flows to the roller sleeve. The flow rate of 1000ml/min is chosen as the rate at which the diameter of tube (6mm) results in a Reynolds number that is inside the turbulent flow region, which has the effect of enhancing the cleaning process in the tube.

The cleaning cycle also commences rotation of the roller sleeve 112. As the roller sleeve rotates, the secondary roller acts against the roller sleeve to causing a mixture of paint and water to be driven off. It has been found that an initial delay, typically 30 seconds, in rotating the roller sleeve after the water flows, or rotating the roller_sleeve_slowly, increases the removal rate of paint from the roller sleeve.

Typically the cleaning cycle takes 10 minutes.

A more detailed cleaning cycle is given in the chronological sequence below.

- 1. 5s (Pump on; Roller forward (anti-clockwise when viewing Figure 17)
- 2. 40s (Pump on; Roller stop)
- 3. Cycle 1:
 - a. 15s (Pump on; Roller forward)
 - b. 71.5s (Pump on 3.5s / Pump off 2s; Roller forward), repeated 13 times to total 71.5s
- 4. Cycle 2:
 - a. 15s (Pump on; Roller backward)
 - b. 71.5s (Pump on 3.5s / Pump off 2s; Roller forward), repeated 13 times to total 71.5s
- 5. Cycle 3:
 - a. 15s (Pump on; Roller backward)
 - b. 71.5s (Pump on 3.5s / Pump off 2s; Roller forward), repeated 13 times to total 71.5s
- 6. Cycle 4:

- a. 15s (Pump on; Roller backward)
- b. 71.5s (Pump on 3.5s / Pump off 2s; Roller forward), repeated 13 times to total 71.5s

7. Cycle 5:

- a. 15s (Pump on; Roller backward)
- b. 71.5s (Pump on 3.5s / Pump off 2s; Roller forward), repeated 13 times to total 71.5s

8. Cycle 6:

- a. 15s (Pump on; Roller backward)
- b. 71.5s (Pump on 3.5s / Pump off 2s; Roller forward), repeated 13 times to total 71.5s

9. 15s (Pump on; Roller backward)

During the intial pumping process it has been found that the release of the high viscosity paint under pressure can be quite dramatic and can cause a mess internally to the cleaning section. This effect can be enhanced by the rotation of the roller. Initially then the primary roller is held static. The effect of the rotational speed of rotation of the primary roller during the remainder of the cleaning cycle is not thought critical. The rotational speed should be high enough to ensure that the secondary roller sweeps the surface of the primary roller sufficient times to improve cleaning. However, a high speed with sufficient torque to turn the primary roller will result in a more expensive motor and higher power consumption. A rotational frequency of around 0.2 to 1Hz is a suitable range.

It has also been found that pulsing the water flow increases the rate of paint removal for a given amount of water by temporarily reversing the water flow as the system depressurises during the pauses in the cleaning cycle. This agitation has the effect of reducing the amount of water required to clean.

It has also been found that the direction of the roller rotation is important, specifically, that the direction should be anti-clockwise (when viewing Figure 17), as this prevents dirty water from damming up against the upper surface of the secondary roller.

The direction of primary roller rotation reverses at times during the cleaning cycle: The secondary roller is slightly loose in its channel to allow rotation. As the roller rotates the secondary roller is biased against one side of its channel by this motion. This causes the water to flow predominantly out of one side of the secondary roller. As a result the other side of the secondary roller does not clean as well. This roller motion also causes the secondary roller channel to rock in its mounting biasing one side against the primary roller surface and lifting the other. As a result one side of the secondary roller channel is washed clean by the primary roller while the other side can still retain paint residue. Reversing the direction of rotation periodically during the cleaning cycle counters these effects.

The rectangular drainage slots 188 act as weirs. The holes 183 in the well 182 allow the mixture of paint and water to drain into the receiving chamber 49. The number and size of the holes are controlled to cause the water level to increase in the well 182 such that the roller sleeve is sitting in water as it rotates. This has been found to improve the cleaning performance. The slots 188 prevent overflow of water should holes 183 become blocked.

It has also been found that it is possible to remove paint from the primary roller without enveloping the roller inside the well/lid combination, i.e. the roller is rotated in an open recess, suggesting that the primary mechanism for cleaning is the flow of clean water across the roller and the mangling action of the secondary roller.

When the roller is clean, the receiving chamber 49 can be emptied of the paint and water mixture.

When the user wishes to commence painting again, the paint container is reinserted into the paint module, and the process recommences as described above. The cleaning section also includes a sensor (not shown) to detect the presence of the roller assembly inside the well. Unless the roller assembly is detected, the cleaning cycle cannot be commenced

The paint module has to pump water at a high flow rate and paint at a lower flow rate at a higher torque. These two requirements are difficult to achieve with a single motor and gearbox, and therefore the motor includes a gear change which allows it to operate at its most efficient speed in the painting and cleaning modes. This also removes the requirement for costly and unreliable speed control of the motor.

In an alternative embodiment, the paint module can include a detector which detects the speed or change in current draw of the motor depending on whether paint or water or none of paint or water is being pumped. Suitable modes (cleaning or painting) can then be selected based on the fluid detected. The detector could also allow the detection of running out of paint or water witht the appropriate warnings given.

With reference to Figure 40 there is shown a roller assembly 50 and handle 51 identical to the embodiment above, with the addition of an extension handle 800 which fluidly connects the dip-tube to the roller assembly. The extension handle 800 includes a handle 810 having a paint flow switch 820. Switch 820 operates in the same way as switch 57 to stop and start paint flow via a wireless connection (not shown). The additional handle 810 is required due to the fact that handle 51 and the switch 57 is now remote from the user. The extension handle connects onto handle 51 in a known way, for example, a snap-fit connection, and the roller assembly fits onto the extension handle in the same way.

With reference to Figure 41 there is shown an alternative applicator in the form of a paint pad 600.

The paint pad 600 has pad body 610 and an applicator surface 620 which is kite shaped. The applicator surface 620 has a closed cell foam structure with apertures (not shown)

which fluidly connect the surface 620 to conduit 655. The conduit 655 can be connected to the handle 51 in the same way as the roller assembly can be connected to the dip-tube.

It will be appreciated that the surface 620 does not need to absorb a significant amount of paint compared to manually loaded paint pads, and hence the body 610 does not require a conventional open foam structure. The closed cell foam structure enables easier cleaning since less paint is stored.

With reference to Figure 42 there is shown an alternative painting apparatus 910 comprising a closure 920 having an integrated dip-tube assembly 901 as described above.

The closure 920 fits onto a standard paint container 930 (via a screw fit, clip-fit, or snap-fit for example) such that the dip-tube is submerged in the paint contained inside the paint container. Since the dip-tube assembly and closure are integrated, the motor in the closure is directly connected to the gear pump at the lower free end of the dip-tube, with no requirement for meshing of gears as described in the embodiment above where the dip-tube is removable from the paint module lid. The closure is connected to the roller assembly 950 as in the above embodiment.

With reference to Figures 43, 44A and 44B there is shown an alternative cleaning module 970 onto which the closure 920 fits. The cleaning module 970 comprises two distinct chambers, a supply chamber 972 which houses cleaning fluid, and a waste chamber 974. A removable cover 980 sits inside, and rests upon the module 970. The cover 980 includes a well 976 which is positioned above the waste chamber 974. The well 976 can receive a roller assembly 950, and has an aperture 973 to allow a paint and cleaning fluid mix to drain into the waste chamber below.

The cover 980 also includes an aperture 975 positioned above the supply chamber, which enables insertion of the dip-tube into the cleaning fluid such that cleaning fluid can be supplied to the roller assembly.

The roller assembly also has a primary roller 952 with an integrated gear wheel 953 which engages with a motor and drive (not shown) no the closure 920 when positioned on the module 970 to rotate the primary roller during the cleaning cycle.

The closure 920 can also be adapted to envelop the primary roller in combination with the well 976.

The cleaning fluid is supplied to the exterior surface of the primary roller. The primary roller can optionally include a secondary roller as described above to provide the mangling effect, or the mangling effect can be created by interaction with a secondary roller type feature that is integral with the closure 920.

With reference to Figures 45 and 46 there is shown an alternative painting apparatus 1010 comprising a paint module which can receive either a paint container 1030, or a cleaning module 1070. The cleaning module is identical to that of Figures 43, 44A, and 44B.

The paint module 1020 includes a hingeable closure 1025 which includes the dip-tube assembly and associated motor. The dip-tube assembly supplies paint or cleaning fluid to a roller assembly (not shown) in the same way as described above.

An alternative primary roller 1169 includes a closed cell structure 1170 with an outer removable thin layer 1172, such as a microfibre layer which has a low tendency to absorb paint (Figure 47). The closed cell structure can be used due to the fact that the primary roller does not need to absorb large quantities of paint because paint is fed continously to the exterior surface. The microfibre layer is chosen to give the required paint finish. The advantage of the removable layer is that it can either be disposed of, or cleaned relatively easily when compared to washing the complete primary roller.

The above embodiments describe a roller assembly with an integrated secondary roller. It would be possible to provide a stand alone cleaning module having a secondary roller or mangle which is not part of the roller assembly, but is arranged on the cleaning module

such that when the roller assembly is received in the cleaning module, the secondary roller or mangle acts against the primary roller to squeeze paint from the primary roller during cleaning.

For the avoidance of doubt, the present invention relates to the components described above, i.e. dip-tube, pump, paint container, roller assembly, cleaning module and paint module, both individually, and in combination.

Claims

- A painting apparatus comprising a paint module, an applicator assembly, and a diptube assembly containing a pump, the applicator assembly being fluidly connectable to liquid in the paint module via the dip-tube assembly, in which the pump is arranged within the dip-tube such that the pump is submerged in the liquid to substantially drive liquid away from the pump when supplying liquid to the applicator assembly.
- A painting apparatus according to claim 1 in which, in use, the pump is positioned at
 a lower free end of the dip-tube assembly.
- 3. A painting apparatus comprising a paint module, an applicator assembly, and a diptube assembly containing a pump, the applicator assembly being fluidly connectable to liquid in the paint module via the dip-tube assembly, in which the paint module includes a module motor and a module gear drive wheel, and the dip-tube assembly includes a dip-tube assembly gear drive wheel, the dip-tube assembly and module gear wheels engaging such that the motor can drive the pump.
- 4. A painting apparatus according to claim 3 in which the paint module has a container receiving section which is closeable by a releasably attachable lid, the applicator assembly being fluidly connectable to liquid in the container receiving section via the dip-tube assembly, in which the lid includes an aperture to allow the dip-tube assembly to pass therethrough and submerge the pump in the liquid, the lid including the module motor and gear drive wheel such that the module and dip-tube assembly gear wheel engage when the lid is in the closed position.
- 5. A painting apparatus according to claim 3 or 4 in which the dip-tube assembly comprises a cylindrical plastic housing, the gear drive wheel of the dip-tube assembly projecting radially beyond the plastic housing.

6.	Α	painting	apparatus	according	to	any	preceding	claim	in	which	the	dip-tube	
	ass	sembly is	releasably	attachable t	o th	e pai	nt module.						
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Application No: GB0806245.7 **Examiner:** Robert Mirams

Claims searched: 1, 2 and, in part 6 Date of search: 11 June 2008

Patents Act 1977: Search Report under Section 17

Documents considered to be relevant:

Category	Relevant to claims	Identity of document and passage or figure of particular relevance
X	1 and 2	AU8814382 A (KENNY) e.g. figure 5 and page 5 lines 6 to 17

Categories:

X	Document indicating lack of novelty or inventive	Α	Document indicating technological background and/or state
	step		of the art
Y	Document indicating lack of inventive step if combined with one or more other documents of	Р	Document published on or after the declared priority date but before the filing date of this invention.
	same category		
&	Member of the same patent family	E	Patent document published on or after, but with priority date
			earlier than, the filing date of this application

Field of Search:

Search of GB, EP, WO & US patent documents classified in the following areas of the UKC^X:

B2L

Worldwide search of patent documents classified in the following areas of the IPC

B05C

The following online and other databases have been used in the preparation of this search report

WPI,EPODOC

International Classification:

Subclass	Subgroup	Valid From	
B05C	0017/03	01/01/2006	
B05C	0017/00	01/01/2006	



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Application No:

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Robert Mirams

Claims searched:

3 to 5 and, in part 6

Date of search:

12 September 2008

Patents Act 1977 **Further Search Report under Section 17**

Documents considered to be relevant:

Category	Relevant to claims	Identity of document and passage or figure of particular relevance
X	3	US4842432 A (SNETTING) e.g. figures 1, 4 and 5 and column 2 line 16 to column 4 line 58
X	3	US4639156 A (STERN) e.g. figures 1 and 3 to 6 and column 7 line 59 to column 9 line 35

Categories:

X	Document indicating lack of novelty or inventive step Document indicating lack of inventive step if	A	Document indicating technological background and/or state of the art.
	combined with one or more other documents of same category.	•	Document published on or after the declared priority date but before the filing date of this invention.
&	Member of the same patent family	E	Patent document published on or after, but with priority date earlier than, the filing date of this application.

Field of Search:

Search of GB, EP, WO & US patent documents classified in the following areas of the UKCX:

Worldwide search of patent documents classified in the following areas of the IPC

B₀₅C

The following online and other databases have been used in the preparation of this search report

WPI,EPODOC

International Classification:

Subclass	Subgroup	Valid From
B05C	0017/03	01/01/2006
B05C	0017/00	01/01/2006