

(12) UK Patent Application (19) GB (11) 2 376 079 (13) A

(43) Date of Printing by UK Office 04.12.2002

(21) Application No 0214982.1

(22) Date of Filing 30.10.2001

(30) Priority Data

(31) 09703766 (32) 01.11.2000 (33) US
(31) 10057650 (32) 29.10.2001

(86) International Application Data
PCT/US2001/048737 En 30.10.2001

(87) International Publication Data
WO2002/037052 En 10.05.2002

(51) INT CL⁷
G01B 7/13

(52) UK CL (Edition T)
G1N NACNE N3S7

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(58) Field of Search by ISA
U.S. : 33/544.3, 3.542, 543, 544, 544.2, 542.1, 783,
555.1, 555.2, 558.01, 558.04, 558.2

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(54) Abstract Title

Use of magneto-resistive sensors for borehole logging

(57) A downhole caliper instrument (10) utilizing a linear or arcuate magneto-resistive sensor (24) to determine the position of one or more caliper arms (11 or 111) which extend from a carrier tool (22) to touch the surface of a borehole wall (20). A processor and firmware are included to calculate and plot the borehole radius. A plurality of magneto-resistive sensors (24, 102) are provided to calculate the sine, cosine and tangent for accurate motion of each independent arm (11, 111). The magneto-resistive sensors (24, 102) sense the position of a precise magnetic ruler (94) linked to the caliper arm (11, 111). The position of the caliper arm (11, 111) determines the radius of the borehole. Calculation of Radius/Diameter is preferably performed in the computer on the surface. The downhole controller's firmware controls the multiplexer switching, A/D conversion and other functions.

