

A spatiotemporal extension of density matrices and time-reversal symmetry of measurements

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based on joint work with James Fullwood (Hainan University)



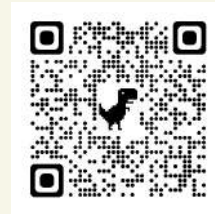
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Main idea

- positive semidefinite $\rho \geq 0$ and $\text{tr}[\rho] = 1$
- A density matrix ρ produces expectation values for observables A by the formula $\langle A \rangle_\rho = \text{tr}[\rho A]$ $A^\dagger = A$ (hermitian/self-adjoint)
 - A state over time (to be defined) is a matrix $E * \rho$ involving an initial density matrix ρ and a quantum channel $E: A \rightarrow B$ that gives the joint expectation values of measuring an observable A followed by B after evolution by E .
 - Motivating question: When does there exist a channel $\mathcal{F}: B \rightarrow A$ such that $\mathcal{F} * E(\rho)$ gives the joint expectation values of measuring B followed by A , i.e., when are the measurements time-reversal symmetric?

Static expectation values in quantum

Notation A, B denote matrix algebras

Example $A = M_2$ is 2×2 complex matrices (algebra of a qubit)

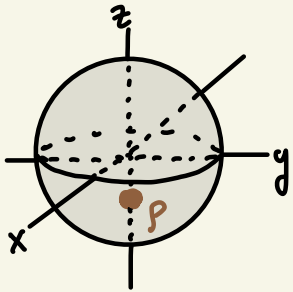
Defn Let $\rho \in A$ be a density matrix. Let $A \in A$ be an observable. The expectation value of A with respect to ρ is the real number $\langle A \rangle_\rho := \text{Tr}[\rho A]$.

Example

$\rho = \begin{pmatrix} 1/3 & 0 \\ 0 & 2/3 \end{pmatrix}$ describes a state in which a qubit has $1/3$ ($2/3$) chance of being spin up (down) along z . Hence,

$\langle \sigma_z \rangle_\rho = \text{Tr} \left[\begin{pmatrix} 1/3 & 0 \\ 0 & 2/3 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right] = -1/3$ is the expected value of the spin in the z direction. Meanwhile,

$\langle \sigma_x \rangle_\rho = \text{Tr} \left[\begin{pmatrix} 1/3 & 0 \\ 0 & 2/3 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right] = 0$ is the expected value of the spin in the x direction.



Dynamic expectation values in quantum

Defn Let $\rho \in \mathcal{A}$ be a density matrix and let $\mathcal{E}: \mathcal{A} \rightarrow \mathcal{B}$ be a quantum channel, i.e., a completely positive trace-preserving (CPTP) map.

Let $A \in \mathcal{A}$, $B \in \mathcal{B}$ be observables with spectral decompositions

$$A = \sum_i \lambda_i P_i \quad B = \sum_j \mu_j Q_j \quad (\lambda_i, \mu_j \in \mathbb{R} \ \& \ P_i \in \mathcal{A}, \ Q_j \in \mathcal{B} \text{ projectors}).$$

The two-time expectation value of A and B with respect to the pair (ρ, \mathcal{E}) is the real number $\langle A, B \rangle_{(\rho, \mathcal{E})} := \sum_{ij} \lambda_i \mu_j \text{Tr}[\mathcal{E}(P_i \rho P_i) Q_j]$.

Remark The state after measuring A and getting outcome λ_i

is $\frac{P_i \rho P_i}{\text{Tr}[\rho P_i]}$ due to the state-update rule.

Example Suppose $\rho = \sum_i p_i |i\rangle\langle i|$, w/ $\{|i\rangle\}$ orthonormal basis, $\{p_i\}$ probabilities,

$$P_i = Q_i = |i\rangle\langle i|, \quad \mathcal{E}(|i\rangle\langle j|) = \sum_k f_{ki} \delta_{ij} |k\rangle\langle k|, \quad A = \sum_i \lambda_i P_i, \quad B = \sum_j \mu_j Q_j.$$

Then, $\langle A, B \rangle_{(\rho, \mathcal{E})} = \sum_{ij} \lambda_i \mu_j f_{ji} p_i$ ($\{f_{ji} p_i\}$ is standard joint probability).

A no-go theorem for sequential measurements

Notation $\rho \in \mathcal{A}$ density matrix & $\mathcal{E}: \mathcal{A} \rightarrow \mathcal{B}$ channel $\Rightarrow (\rho, \mathcal{E})$ process

Defn A process (ρ, \mathcal{E}) is representable iff there exists a matrix $X \in \mathcal{A} \otimes \mathcal{B}$ s.t. $\langle A, B \rangle_{(\rho, \mathcal{E})} = \text{Tr}[X A \otimes B]$
for all observables $A \in \mathcal{A}$, $B \in \mathcal{B}$.

Theorem If \mathcal{A}, \mathcal{B} are matrix algebras of dimension ≥ 2 , then there exists a process (ρ, \mathcal{E}) that is not representable.

Example $\mathcal{E} = \text{id}_{\mathbb{M}_n}$ and ρ any density matrix NOT equal to $\frac{\mathbb{1}_n}{n}$.

In what follows, we will bypass this no-go theorem by focussing on a subset of observables that are nevertheless quite robust.

The observables

Defn An observable $A \in \mathcal{A}$ is light touch iff its spectrum is either $\{-\lambda, \lambda\}$ for some $\lambda > 0$ or $\{\lambda\}$ for some $\lambda \in \mathbb{R}$.

Example $\mathcal{A} = \mathbb{M}_2$ Pauli matrices $\mathbb{1}, \sigma_x, \sigma_y, \sigma_z$ are all light touch.

Also, if $\vec{n} \in S^2 \subseteq \mathbb{R}^3$, then $\vec{n} \cdot \vec{\sigma} = n_x \sigma_x + n_y \sigma_y + n_z \sigma_z$ is, too.

Theorem Let (ρ, \mathcal{E}) be a process. Then there exists a unique matrix $X \in \mathcal{A} \otimes \mathcal{B}$ such that $\langle A, B \rangle_{(\rho, \mathcal{E})} = \text{Tr}[X A \otimes B]$

for all light touch observables $A \in \mathcal{A}$ and all observables $B \in \mathcal{B}$.

Example when $\mathcal{A} = \mathbb{M}_2$, X is called a "pseudo-density matrix" and it can be expressed as

Ref: [Fitzsimons-Jones-Vedral]

$$X = \frac{1}{4} \sum_{\alpha, \beta} \langle \sigma_\alpha, \sigma_\beta \rangle \sigma_\alpha \otimes \sigma_\beta = \frac{1}{2} \left\{ \rho \otimes \mathbb{1}_2, \underbrace{(\text{id}_{\mathbb{M}_2} \otimes \mathcal{E})(\text{SWAP})}_{\mathcal{J}[\mathcal{E}]} \right\}$$

$\sigma_0 = \mathbb{1}, \sigma_1 = \sigma_x, \sigma_2 = \sigma_y, \sigma_3 = \sigma_z$ $\{a, b\} = ab + ba$ $\text{SWAP} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

The state over time for sequential measurements

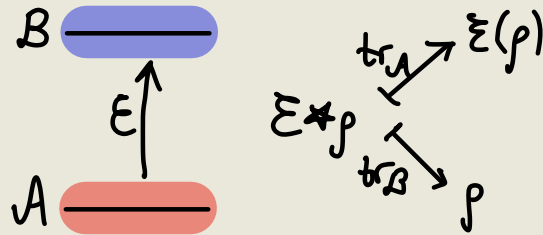
More generally, given a process (p, \mathcal{E}) , the matrix $X \in \mathcal{A} \otimes \mathcal{B}$ s.t. $\langle A, B \rangle_{(p, \mathcal{E})} = \text{Tr}[X A \otimes B]$ for all light touch $A \in \mathcal{A}$

and observables $B \in \mathcal{B}$ is given by the formula

$$X = \frac{1}{2} \left\{ p \otimes \mathbb{1}_B, (\text{id}_A \otimes \mathcal{E})(\text{SWAP}_A) \right\}, \text{ where } \text{SWAP}_A = \sum_{ij} |i\rangle\langle j| \otimes |j\rangle\langle i|.$$

This matrix is an example of a state over time.

Defn A state over time function \star is a function (for each A, B)



$$\text{States}(A) \times \text{Channels}(A, B) \xrightarrow{\star} A \otimes B$$

sending (p, \mathcal{E}) to $\mathcal{E} * p$ s.t. the two marginals of $\mathcal{E} * p$ are p and $\mathcal{E}(p)$.

$\mathcal{E} * p$ is called a state over time.

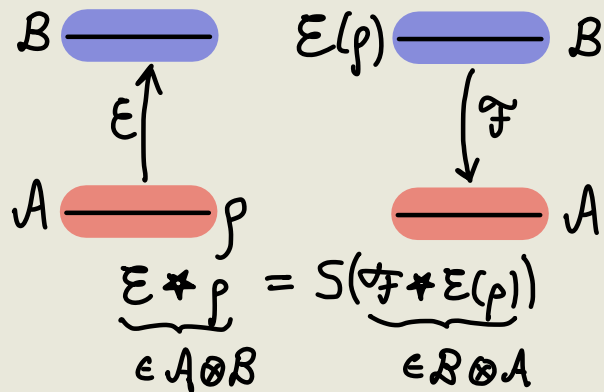
Note: Despite terminology, we do not demand $\mathcal{E} * p$ to be a state!

Operational and Bayesian inverses

Defn A Bayesian inverse of (ρ, \mathcal{E}) is a channel $\mathcal{F}: B \rightarrow A$ s.t.

$$\mathcal{E} * \rho = S(\mathcal{F} * \mathcal{E}(\rho)),$$

where $S(B \otimes A) = A \otimes B$ is the swap isomorphism,



Defn An operational inverse of (ρ, \mathcal{E}) is a channel $\mathcal{F}: B \rightarrow A$ s.t. $\langle A, B \rangle_{(\rho, \mathcal{E})} = \langle B, A \rangle_{(\mathcal{E}(\rho), \mathcal{F})}$ for all light touch observables $A \in \mathcal{A}, B \in \mathcal{B}$.

Theorem Given (ρ, \mathcal{E}) , a Bayesian inverse exists if and only if an operational inverse exists. Moreover, the two coincide.

Consequence Solve for \mathcal{F} via Sylvester equation $\{\mathbb{1}_B \otimes \rho, \mathcal{F}[\mathcal{E}^*]\} = \{\mathcal{E}(\rho) \otimes \mathbb{1}_A, \mathcal{F}[\mathcal{F}]\}$

Examples with unitary dynamics and classical dynamics

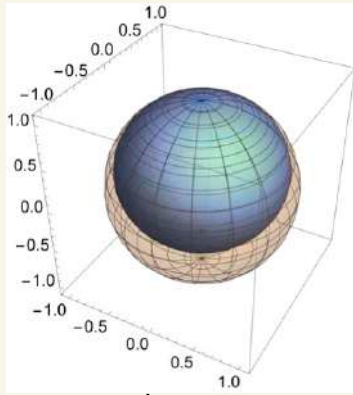
Theorem If (ρ, \mathcal{E}) is a process with $\mathcal{E} = \text{Ad}_U$, where U is a unitary operator, then the Bayesian inverse is $\mathcal{F} = \text{Ad}_{U^\dagger}$ regardless of the initial state ρ .

Remark When A, B are finite dim'l commutative algebras, this definition reproduces Bayes' rule $P(y|x)P(x) = P(x|y)P(y)$.
Alternatively, we can state this in the following way.

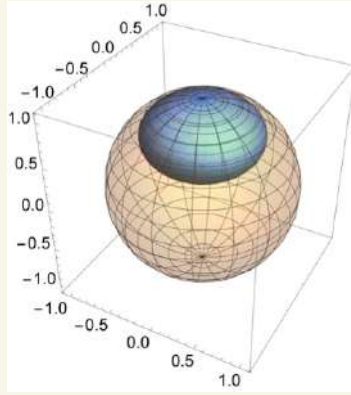
Theorem If $\rho = \sum_i p_i |i\rangle\langle i|$, w/ $\{|i\rangle\}$ orthonormal basis, $\{p_i\}$ probabilities, $\mathcal{E}(|i\rangle\langle j|) = \sum_k f_{ki} \delta_{ij} |k\rangle\langle k|$, where $\{f_{ki}\}$ define conditional probabilities, then the Bayesian inverse \mathcal{F} satisfies $\mathcal{F}(|k\rangle\langle l|) = \sum_i g_{ik} \delta_{kl} |i\rangle\langle i|$, where $\{g_{ik}\}$ are the conditional probabilities satisfying the (classical) Bayes' rule $f_{ki} p_i = g_{ik} q_k \forall i, k$, where $q_k = \sum_j f_{kj} p_j$.

Example with amplitude-damping channel I

Take $\mathcal{E} = \text{Ad}_{E_0} + \text{Ad}_{E_1}$ ($\text{Ad}_V(A) = VAV^\dagger$) w/ $E_0 = \begin{pmatrix} 1 & 0 \\ 0 & \sqrt{1-\gamma} \end{pmatrix}$, $E_1 = \begin{pmatrix} 0 & \sqrt{\gamma} \\ 0 & 0 \end{pmatrix}$



$\gamma = 0.2$



$\gamma = 0.6$

the Bloch ball is shown in blue for two values of $\gamma \in [0, 1]$.

Now take input state $\rho = \frac{1}{2} \begin{pmatrix} 1+z & 0 \\ 0 & 1-z \end{pmatrix} \Rightarrow \mathcal{E}(\rho) = \frac{1}{2} \begin{pmatrix} 1+z' & 0 \\ 0 & 1-z' \end{pmatrix}$,

where $z' = z + \gamma(1-z)$.

Fact With these parameters $z \in (-1, 1)$, $\gamma \in (0, 1)$, a Bayesian inverse exists if and only if $z \geq \frac{\gamma}{\gamma-2}$

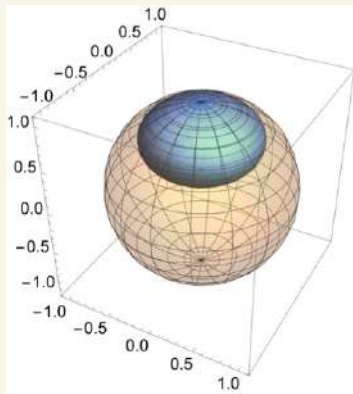
A qubit density matrix is of the form $\frac{1}{2} \begin{pmatrix} 1+z & x-iy \\ x+iy & 1-z \end{pmatrix}$ with $\|(x, y, z)\|^2 \leq 1$ and \therefore

identifies with a point in Bloch ball. The image of

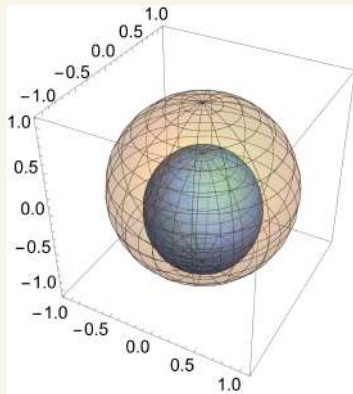
for two values of $\gamma \in [0, 1]$.

Example with amplitude-damping channel II

Fact (continued) The Bayesian inverse is given explicitly by



original \mathcal{E} w/ $\gamma = 0.6$



Bayesian inverse \mathcal{F} w/ $\gamma = 0.6, z = 0.2$

$$\mathcal{F} = \text{Ad}_{F_0} + \text{Ad}_{F_1} + \text{Ad}_{F_2} \quad \text{where}$$

$$F_0 = \begin{pmatrix} \sqrt{\frac{1+z}{1+z'}} & 0 \\ 0 & \sqrt{\frac{(1-\gamma)(1+z')}{1+z}} \end{pmatrix},$$

$$F_1 = \begin{pmatrix} 0 & 0 \\ \sqrt{\frac{\gamma(1-z)}{1+z'}} & 0 \end{pmatrix}, \quad F_2 = \begin{pmatrix} 0 & 0 \\ 0 & \sqrt{\frac{\gamma(z+z')}{1+z}} \end{pmatrix}.$$

This is a bit-flipped amplitude-damping channel with dephasing.

| | σ_0 | σ_1 | σ_2 | σ_3 |
|------------|------------|-------------------|-------------------|-----------------|
| σ_0 | 1 | 0 | 0 | z' |
| σ_1 | 0 | $\sqrt{1-\gamma}$ | 0 | 0 |
| σ_2 | 0 | 0 | $\sqrt{1-\gamma}$ | 0 |
| σ_3 | z | 0 | 0 | $1-\gamma(1-z)$ |

← Two-time expect. values $\langle \sigma_\alpha, \sigma_\beta \rangle$ w/ Pauli σ_α in top row measured first and then (after \mathcal{E}) Pauli σ_β in left column measured second.

Same but time-reversed $\langle \sigma_\beta, \sigma_\alpha \rangle$ using Bayesian inv. \mathcal{F}

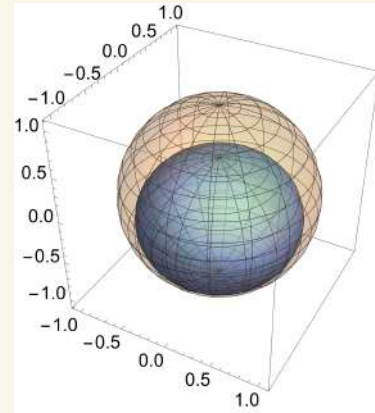
| | σ_0 | σ_1 | σ_2 | σ_3 |
|------------|------------|-------------------|-------------------|-----------------|
| σ_0 | 1 | 0 | 0 | z |
| σ_1 | 0 | $\sqrt{1-\gamma}$ | 0 | 0 |
| σ_2 | 0 | 0 | $\sqrt{1-\gamma}$ | 0 |
| σ_3 | z' | 0 | 0 | $1-\gamma(1-z)$ |

Example with amplitude-damping channel III

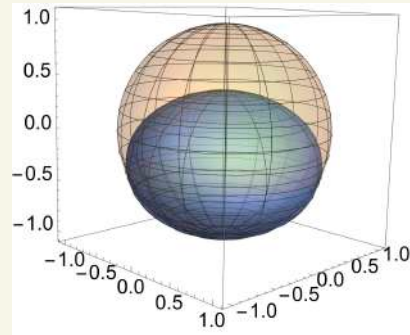
Remark The Bayesian inverse \mathcal{F} is NOT equal to the Petz recovery map $\mathcal{R} = \text{Ad}_{R_0} + \text{Ad}_{R_1}$,

$$\text{w/ } R_0 = \begin{pmatrix} \sqrt{\frac{1+z}{1+z'}} & 0 \\ 0 & 1 \end{pmatrix} \quad R_1 = \begin{pmatrix} 0 & 0 \\ \sqrt{\frac{\gamma(1-z)}{1+z'}} & 0 \end{pmatrix}$$

The Petz recovery map is depicted here \rightarrow



Remark If $z < \frac{\gamma}{\gamma-2}$, no operational inverse exists! Although \mathcal{F} is uniquely defined, it is not completely positive (an example when $z = -0.5$, $\gamma = 0.15$ is shown on right).



Summary & Key points

- Just like expectation values of observables at a fixed time are encoded in a density matrix, two-time expectation values of sequential measurements of light-touch observables are encoded in a state over time.
- Light touch observables are just as robust as projections in that their expectation values determine density matrices and states over time.
- Our theory of quantum Bayesian inverses has operational consequences for time-reversal symmetric multi-time expectation values.
- Immense plethora of open questions and low-hanging fruit!
Eg. What state over time is characterized by two-time expectation values of Gell-mann matrices? Great problems for grad students!

Thank you!

All joint work
with James Fullwood



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"On quantum states
over time"

Bypasses a no-go theorem
of Horsman et al, proving
existence of a state over
time that satisfies many conditions



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"Operator representation of
spatiotemporal quantum
correlations"

Provides an operational
meaning to states over time
and extends pseudo-densities

"From time-reversal symmetry
to quantum Bayes' rules"

A modern reference on states
over time and how they give
rise to a quantum extension
of Bayes' rule

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"Time-symmetric correlations
for open quantum systems"

What this talk was
mostly based on
(prediction using quantum
Bayes' rule)



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