

Application Technique

Original Instructions



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by ROCKWELL AUTOMATION

EtherNet/IP Socket Interface



Summary of Changes

This publication contains the following new or updated information. This list includes substantive updates only and is not intended to reflect all changes.

Topic	Page
Added Secure Socket Object section	13
Revised instructions for communicating with a socket object via an MSG instruction	15, 16
Added error codes	38, 39
Added Exposing TLS Errors section	40

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About This Publication

This publication describes the socket interface that you can use to program MSG instructions to communicate between a Logix 5000™ controller via an EtherNet/IP™ module and Ethernet devices that do not support the EtherNet/IP application protocol, such as barcode scanners, RFID readers, or other standard Ethernet devices.

Download Firmware, AOP, EDS, and Other Files

Download firmware, associated files (such as AOP, EDS, and DTM), and access product release notes from the Product Compatibility and Download Center at rok.auto/pcdc.

Socket Interface Architecture

The socket interface lets a Logix 5000® controller communicate with Ethernet devices that do not support the EtherNet/IP™ protocol. Such devices include barcode scanners, RFID readers, or other standard Ethernet devices.

Socket services are available with these modules:

- ControlLogix® 5580 and GuardLogix® 5580 controllers
- CompactLogix™ 5380 and Compact GuardLogix 5380 controllers
- CompactLogix 5370 and Compact GuardLogix 5370 controllers
- CompactLogix 5480 controllers
- 1756-EN2x, 1756-EN3TR, and 1756-EN4TR EtherNet/IP communication modules
- 1756-EWEB and 1768-EWEB EtherNet/IP web server modules

IMPORTANT MicroLogix™ 1400 controllers also support socket capability, but the information in this document does not apply to those products. For details on those products, see the MicroLogix 1400 Programmable Controllers Reference Manual, publication [1766-RM001D](#).

Before you use the socket interface, make sure that you are familiar with these concepts:

- Basic TCP/IP, UDP, and socket programming concepts
- How to write socket programs in a programming language, such as C or Visual Basic
- How to use diagnostic tools, such as a network sniffer
- The application protocols of the devices and applications with which the Logix 5000 controller communicates
- How to write ladder logic or Structured Text for a Logix 5000 controller

Socket Interface Architecture

The socket interface is implemented via the socket object in the EtherNet/IP module or directly in the controller via the front port. Logix 5000 controller programs communicate with the socket object via MSG instructions. MSG requests to the socket object are similar to socket API calls in most computer operating systems. The socket object services let you open connections, accept incoming connections, send data, and receive data.

To communicate with another device, you must understand the application protocol of the device. The EtherNet/IP module has no application protocol knowledge. The module makes only the socket services available to programs in Logix 5000 controllers.

Number and Type of Sockets

The following table shows the number of supported socket instances.

32 Socket Instances	20 Socket Instances
<ul style="list-style-type: none"> • ControlLogix 5580 controllers • GuardLogix 5580 controllers • CompactLogix 5480 controllers • CompactLogix 5380 controllers • Compact GuardLogix 5380 controllers • CompactLogix 5370 controllers • Compact GuardLogix 5370 controllers • 1756-EN2x EtherNet/IP communication modules • 1756-EN3TR EtherNet/IP communication module • 1756-EN4TR EtherNet/IP communication module 	<ul style="list-style-type: none"> • 1756-EWEB EtherNet/IP web server module • 1768-EWEB EtherNet/IP web server module

Each instance can be one of these types:

- UDP socket—Sends and receives UDP datagrams.
- TCP client socket—The Logix 5000 program initiates the connection.
- TCP server socket—Another device initiates the connection to the Logix 5000 program.
- TCP listen socket—Listens on a specified port number for incoming connections.

These options are available for UDP and TCP send and receive services.

Type	Communication	Send (Write)	Receive (Read)
UDP	Unicast	Yes	Yes
	Multicast	Yes	Yes
	Broadcast	Yes	Yes
TCP	Unicast	Yes	Yes
	Multicast	—	—
	Broadcast	—	—

You must have a listen socket for each TCP port number that accepts connections. Multiple TCP server sockets can share a listen socket if the connections are made to the same port number.

You can partition the available socket instances between UDP and TCP sockets in these ways:

- Use all instances for client TCP connections.
- Use one instance to listen for incoming TCP connections and then accept the remaining connections from other devices.
- Perform both TCP client and server operations.
- Perform both TCP and UDP operations.

The following table lists the available socket services.

Socket Service	Socket Instance	Page
Socket Create	Server or client	23
OpenConnection	Client	25
AcceptConnection	If you issue an AcceptConnection service, the instance is a listen type. If the AcceptConnection service returns an instance as a result of an incoming connection request, the socket instance is a server type.	26
ReadSocket	Server or client	27
WriteSocket	Server or client	29
DeleteSocket	Server or client	30
DeleteAllSockets	Server or client	31
ClearLog	Server or client	32
JoinMulticastAddress	Server or client	32
DropMulticastAddress	Server or client	33

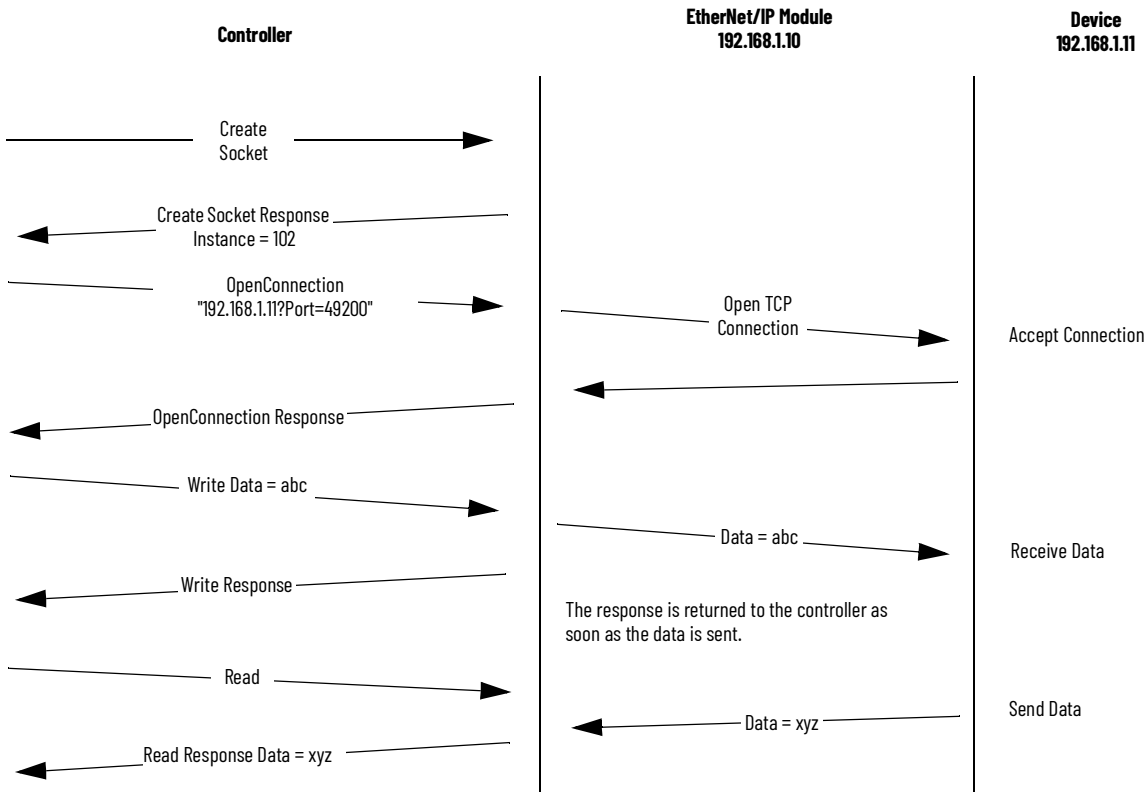
Once you open a connection on a client socket instance, you cannot use the same socket instance to accept incoming connections. Similarly, if you accept connections on a socket instance, you cannot then use the instance to open outgoing connections. This behavior is consistent with standard socket API behavior.

Typical Sequence of Transactions for a TCP Client

The following diagram shows a typical sequence of socket interface transactions with the Logix 5000 controller that acts as a TCP client. Each transaction between the Logix 5000 controller and the EtherNet/IP module is a message (MSG) instruction.

In the following example, the Logix 5000 controller sends data to a device, and then the device sends a response. This sequence of transactions is typical. Depending on the application protocol, the device can instead send data to the Logix 5000 controller once the connection is open.

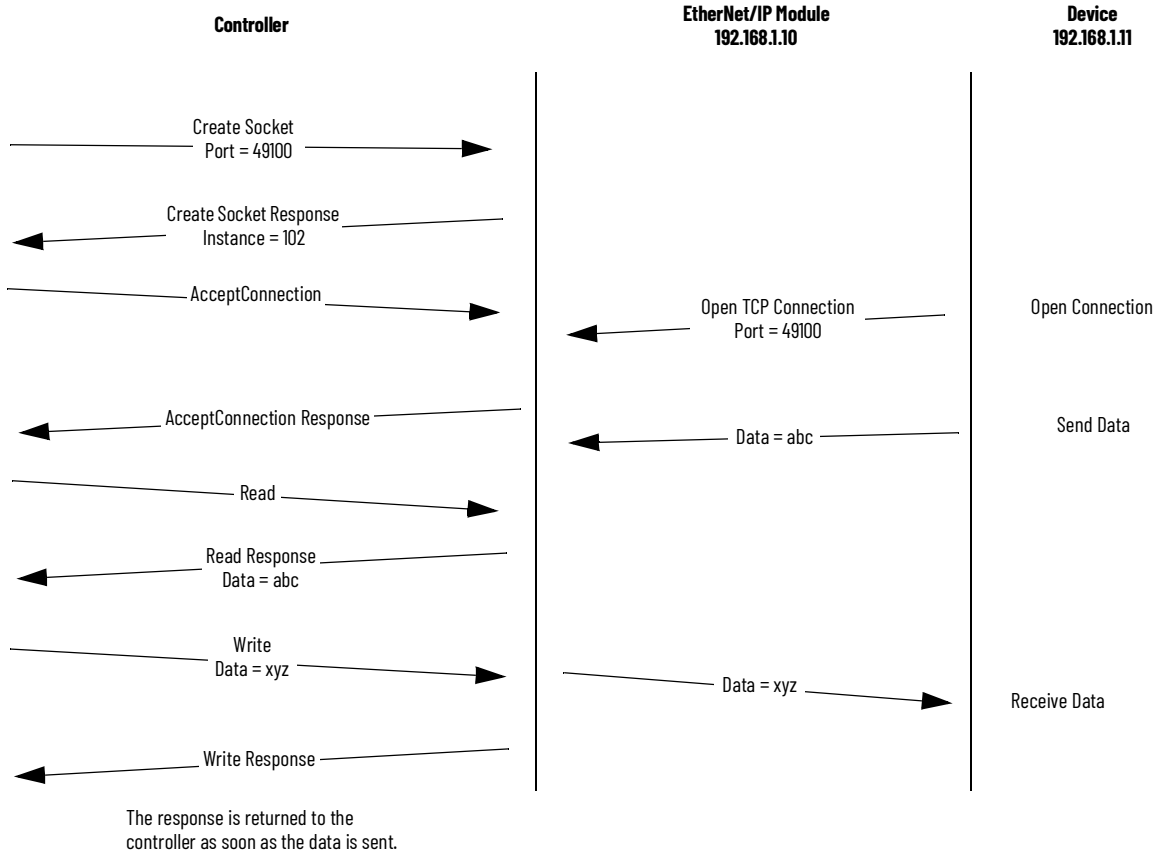
Also, each write transaction does not require an application response or acknowledgment. The application protocol determines the exact sequence of application transactions.



Typical Sequence of Transactions for a TCP Server

The following diagram shows a typical sequence of socket interface transactions with the Logix 5000 controller as a TCP server. Each transaction between the Logix 5000 controller and EtherNet/IP module is an MSG instruction.

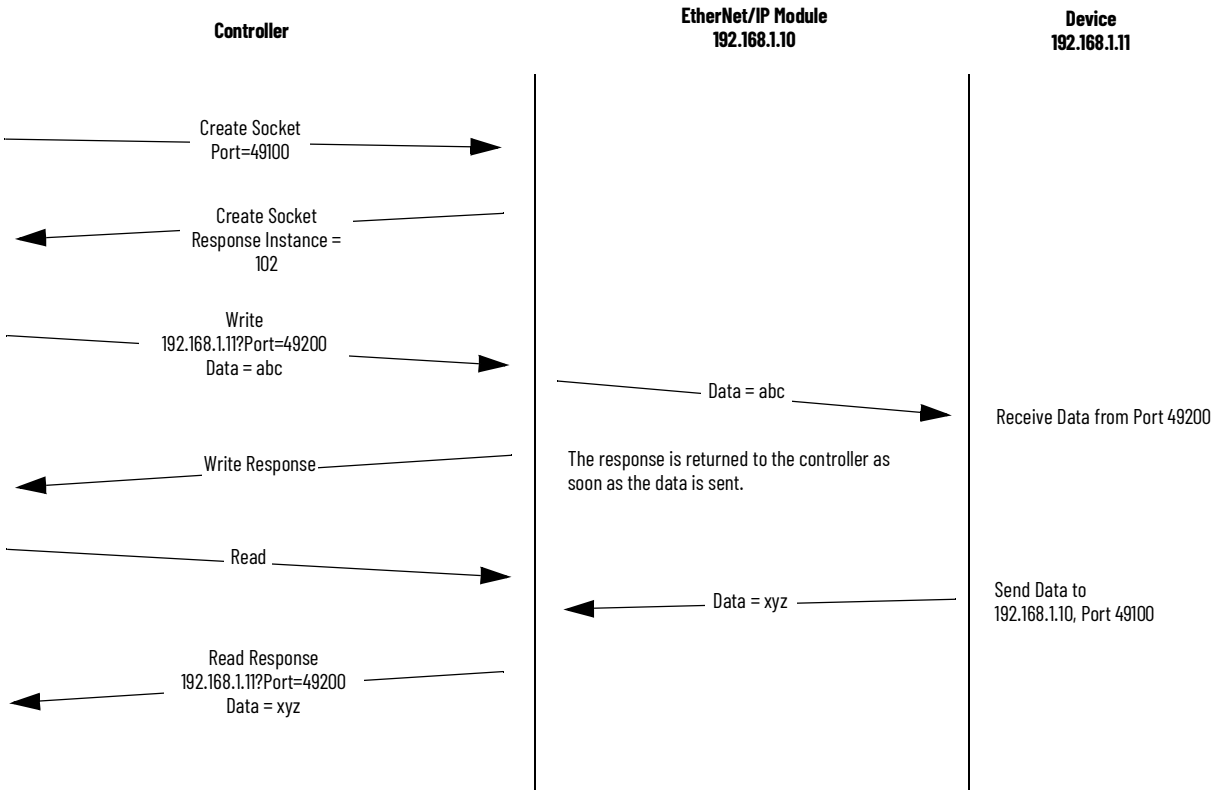
The following is a typical sequence of transactions. The exact sequence to send and receive data depends on the application protocol.



Typical Sequence of Transactions for UDP without OpenConnection

The following diagram shows a typical sequence of socket interface transactions for UDP communication without using the OpenConnection service to specify the destination address. In this case, the Logix 5000 controller specifies the destination for each datagram and receives the address from the sender along with each datagram it receives. Each transaction between the Logix 5000 controller and the EtherNet/IP module is an MSG instruction.

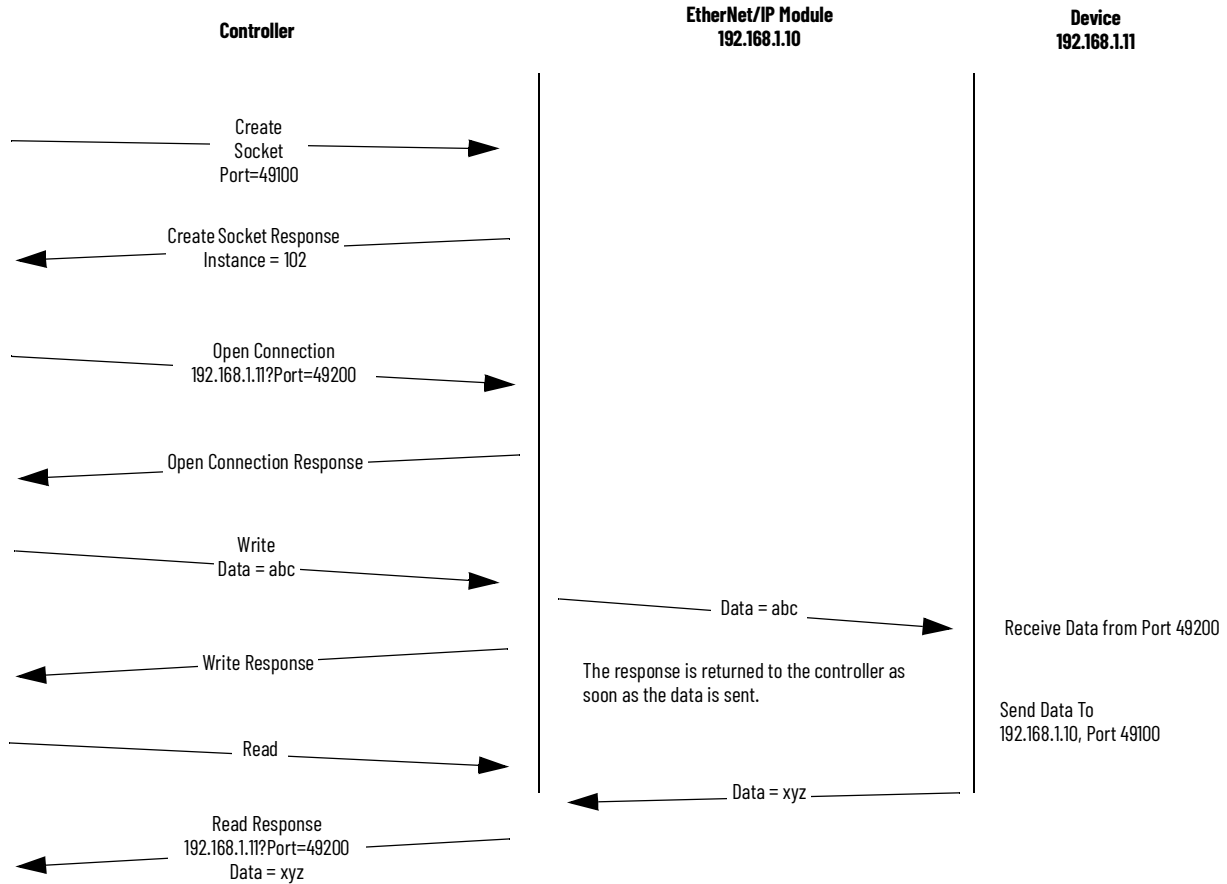
This example shows the Logix 5000 controller sending data to a device, and then the device sending a response. This sequence of transactions is atypical. Depending on the application protocol, the device could instead initiate sending data to the Logix 5000 controller. Also, each Write transaction does not require an application response or acknowledgment. The application protocol determines the exact sequence of application transactions.



Typical Sequence of Transactions for UDP with OpenConnection

The following diagram shows a typical sequence of socket interface transactions for UDP communication when using the OpenConnection service to specify the destination address. Each transaction between the Logix 5000 controller and the EtherNet/IP module is an MSG instruction.

The following is a typical sequence of transactions. The exact sequence of sending and receiving data depends on the application protocol.



Secure Socket Object

The following devices support Transport Layer Security (TLS) for a secure socket object.

IMPORTANT TLS for a secure socket object is not supported in ControlLogix redundancy or 1756-EN4TR redundant adapter mode.

Controllers and Communication Modules	First Available in Firmware Revision
CompactLogix 5380	35.011 and later
Compact GuardLogix 5380 SIL 2	35.011 and later
Compact GuardLogix 5380 SIL 3	35.011 and later
CompactLogix 5380 Process	35.011 and later
ControlLogix 5580	35.011 and later
GuardLogix 5580	35.011 and later
ControlLogix 5580 Process	35.011 and later
1756-EN4TR, 1756-EN4TRK, 1756-EN4TRXT	5.001 and later

The TLS support has these considerations:

- TCP/TLS version 1.2 only; UDP/DTLS not supported
- Client only; server not supported
- Server authentication supported; client authentication not supported
- Secure socket object and CIP Security™ cannot be used at the same time
- Connections with multiple servers are not supported
- No Certificate Revocation List support
- No Subject Alternative Name support
- On multi-port devices (ControlLogix 5380 in dual IP mode), the same security is applied to both ports

TLS support is enabled by putting server certificates on the SD card. Certificates are loaded at startup only. The server certificates are expected to be stored in the following files in PEM format:

- certs/ca.pem—A CA certificate signed by some trusted certificate authority
- certs/trustedcert.pem—A trusted peer certificate to be compared against the certificate sent during the TLS handshake

The following rules apply to the TLS protocol:

- If at least one certificate is present in the prescribed location and prescribed filename, TLS is applied to the socket object.
- If the SD card is not present, disabled, or neither of the certificates are present, then the socket object behaves as in previous releases and no security is applied.

Once the encryption is enabled, it cannot be disabled without restarting the device.

Supported cipher suites include the following:

- TLS_ECDHE_RSA_WITH_AES_128_CBC_SHA256 (0xc027)
- TLS_ECDHE_RSA_WITH_AES_128_GCM_SHA256 (0xc02f)
- TLS_ECDHE_RSA_WITH_AES_256_GCM_SHA384 (0xc030)
- TLS_ECDHE_RSA_WITH_AES_256_CBC_SHA384 (0xc028)
- TLS_ECDHE_ECDSA_WITH_AES_128_CBC_SHA256 (0xc023)
- TLS_ECDHE_ECDSA_WITH_AES_128_GCM_SHA256 (0xc02b)
- TLS_ECDHE_ECDSA_WITH_AES_256_GCM_SHA384 (0xc02c)
- TLS_ECDHE_ECDSA_WITH_AES_256_CBC_SHA384 (0xc024)

When encryption is enabled, the overall socket object performance is reduced. The impact depends on many factors, such as payload size, number of sockets involved, and the cipher suite used.

[Table 1](#) shows the maximum transfer rate when a socket object instance is running as a client connected to the HTTPS REST API server. Simultaneously, the module handles multiple class 3 connections and data exchange with the server. The HTTP values apply to non-TLS communications, while the HTTPS values apply with cipher suite TLS_ECDHE_RSA_WITH_AES_128_CBC_SHA256 applied.

Table 1 - Secure Socket Object Transfer Rates, Max

	1756-EN4TR	ControlLogix 5580 CompactLogix 5380
Payload: 60 kB		
Request: GET		
HTTPS	140 kB/sec	270 kB/sec
HTTP	280 kB/sec	660 kB/sec
Payload: 60 kB		
Request: PUT/POST		
HTTPS	180 kB/sec	380 kB/sec
HTTP	290 kB/sec	800 kB/sec
Payload: 1 kB		
Request: GET		
HTTPS	12 kB/sec	20 kB/sec
HTTP	14 kB/sec	30 kB/sec
Payload: 1 kB		
Request: PUT/POST		
HTTPS	19 kB/sec	30 kB/sec
HTTP	21 kB/sec	50 kB/sec

For information on how to develop your application to access the HTTP REST API and implement HTTPS via the socket interface with TLS, see documentation for these objects in the Common Application Libraries available in the Product Compatibility and Download Center at rok.auto/pcdc:

- raC_Impl_HTTPClient
- raC_Impl_HTTPCmdGET
- raC_Impl_HTTPCmdPOST
- raC_Impl_HTTPCmdPUT

Communicate with the Socket Object via an MSG Instruction

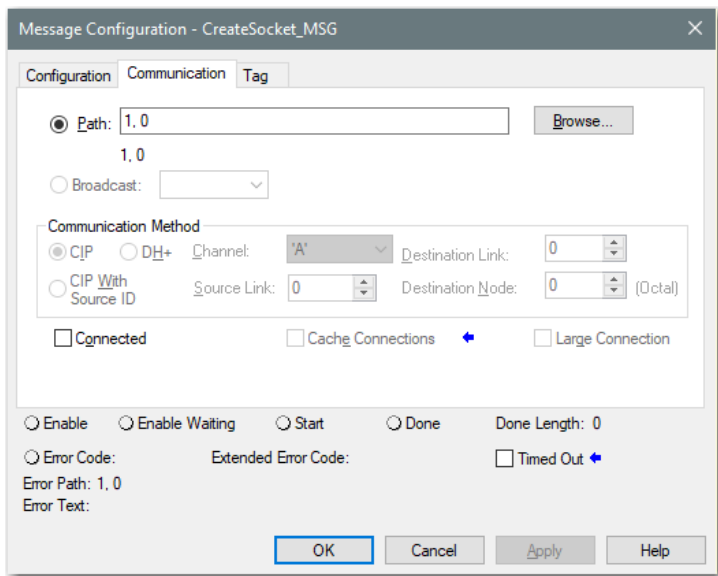
In the Logix Designer application, use a CIP™ Generic MSG instruction to request socket services.

On the Configuration tab for the MSG instruction, configure the parameters as described in [Table 2](#).

Table 2 - Configuration Tab

Field	Description
Message Type	Choose CIP Generic.
Service Type	Choose a socket service type. The software automatically completes the Service Code and Class fields. Choose Get Attributes Single or Set Attributes Single when getting or setting a socket object attribute. For more information, see Socket Attributes on page 35 .
Service Code	Enter the unique service code that corresponds to the socket service you chose in the Service Type field.
Class	Enter 342 (hexadecimal) for the socket object.
Instance	Enter one of these values: <ul style="list-style-type: none"> 0 for Socket Create, Delete All Sockets, or ClearLog services Instance number that is returned by Socket Create for other services Use a relay ladder instruction or Structured Text statement to move the returned instance number from a Socket Create service into the Instance member of an MSG instruction.
Attribute	Enter an attribute value only when getting or setting an attribute, but not when using other services.
Source Element	Choose the tag that contains the request parameters for the socket service. To define the request parameters, create a user-defined data type for the tag.
Source Length	Enter the length of the source element.
Destination Element	Choose the tag that contains the response data that the socket service returns. To define the response data, create a user-defined data type for the tag.

On the Communication tab for the MSG instruction, configure the parameters that are described in [Table 3](#).



IMPORTANT If you use the front Ethernet port on a controller, you must use **unconnected** MSG instructions. For unconnected MSG instructions, you must clear the Connected checkbox on the Communication tab.

Table 3 - Communication Tab

Field	Description
Path	Enter the communication path to the EtherNet/IP module. <ul style="list-style-type: none"> For all communication modules, the path is 1, x, where x is the slot number of the communication module. For ControlLogix 5580 controllers, if the front Ethernet port is used, the path is 1, x where x is the slot number of the ControlLogix controller. For all supported CompactLogix controllers, the path is 1, 0. When using the front Ethernet port on a controller with firmware revision 28.011 or later, you can also use a path of 'THIS'.
Large Connection	To send large messages via an EtherNet/IP module on the backplane when using a ControlLogix 5560, 5570, or 5580 controller, you can check the Large Connection checkbox. Large connections are only available with connected MSG instructions. For information about how to use the Connected or Cache Connections options, refer to the Logix 5000 Controllers Messages Programming Manual, publication 1756-PM012 . <p>IMPORTANT: To use controller memory efficiently, use large connections only for ReadSocket or WriteSocket services that require more than the standard connection size, as shown in Table 4.</p> To avoid errors, be sure that you use unconnected MSG instructions by clearing the Connected checkbox in these scenarios: <ul style="list-style-type: none"> You are using the front Ethernet port on a ControlLogix 5580, CompactLogix 5380, or CompactLogix 5480 controller. Large connections are enabled by default on these controllers. You are using a CompactLogix 5370 controller. Large connections are not supported on these controllers.

The maximum amount of data you can send or receive depends on how you configure the MSG instruction, as shown in [Table 4](#). The size of the data excludes the parameters in the ReadSocket and WriteSocket services.

Table 4 - Maximum Packet Sizes

Service	Unconnected Size	Standard Connection Size	Large Connection Size
ReadSocket	484 bytes	484 bytes	3984 bytes
WriteSocket	462 bytes	472 bytes	3972 bytes

If an MSG requests more than the maximum packet size (standard or large), the module can return a failure status and the MSG instruction can set the .ER bit:

- For TCP sockets, if the application data is larger than the maximum size, you can issue multiple ReadSocket or WriteSocket services to receive or send the entire application message.
- For UDP sockets, the size of application data cannot exceed the maximum sizes for the ReadSocket and WriteSocket services.

Service Timeouts

You must specify a timeout parameter in milliseconds for any service that does not always complete immediately, such as OpenConnection, AcceptConnection, ReadSocket, and WriteSocket services. The timeout tells the socket object the maximum amount of time to wait when attempting to complete the service. While waiting for the service to complete, the MSG instruction is enabled.

If the requested service does not complete before the timeout period expires, the socket object returns a response to the service request. See the service descriptions in [Chapter 2](#) for the content of the response.

IMPORTANT Make the value of the service timeout parameter is shorter than the MSG instruction timeout. Otherwise, application data could be lost.

MSG Instruction Timeouts

The default MSG instruction timeout is 30 seconds. The maximum MSG timeout is approximately 35 minutes. Specify the MSG instruction timeout by setting the appropriate member of the MSG tag:

- If the MSG is unconnected, set the UnconnectedTimeout member.
- If the MSG is connected, set the ConnectionRate and TimeoutMultiplier member.

The MSG timeout is determined by multiplying the ConnectionRate by the TimeoutMultiplier. A TimeoutMultiplier of 0 corresponds to multiplier of 4, 1 corresponds to multiplier of 8, and so on.

Socket Instance Timeouts

Each socket instance has an inactivity timeout with a default of 5 minutes. If a socket instance receives no service requests for the amount of time that is specified by the inactivity timeout, the socket instance is deleted. If you then try to use the socket instance, the MSG instruction receives the error class or instance not supported.

You can change the timeout by setting the inactivity timeout attribute via the Set Attribute service. See [Socket Instance Attributes on page 47](#).

If you put the controller in Program mode and then back into Run mode before existing socket instances time out, you can receive errors when the program tries to create socket instances. Eventually the socket instances time out and you can create more instances.

IMPORTANT Make sure that the inactivity timeout is longer than the longest interval between socket operations. If the inactivity timeout is too short, socket instances can time out and result in MSG instruction errors.

Disable the Socket Object with an MSG Instruction

The socket object is enabled by default. You can use a CIP Generic MSG instruction to disable the socket object.

After you disable the socket object:

- All object-specific services and all instance attributes are unavailable for writing and reading. The Object Enable attribute is read-only.
- The TCP/IP socket object is disabled, and a factory reset can enable it again.

IMPORTANT The MSG instruction must be sent to the EtherNet/IP module via backplane.

On the Configuration tab, configure the parameters as described in [Table 2](#).

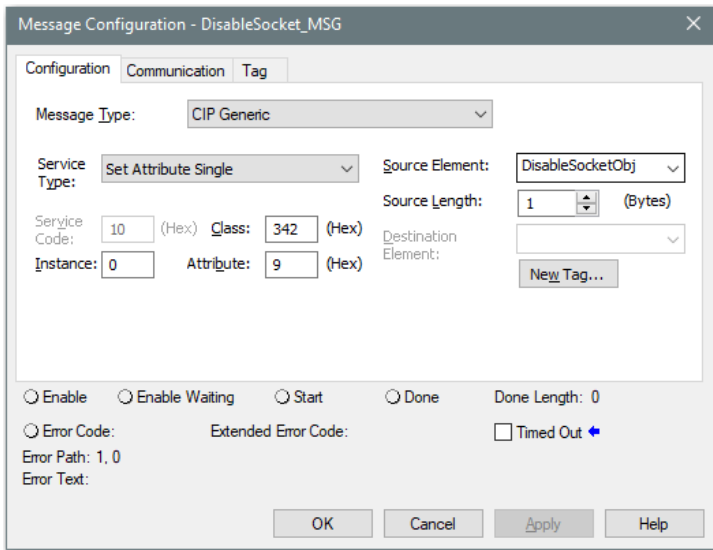
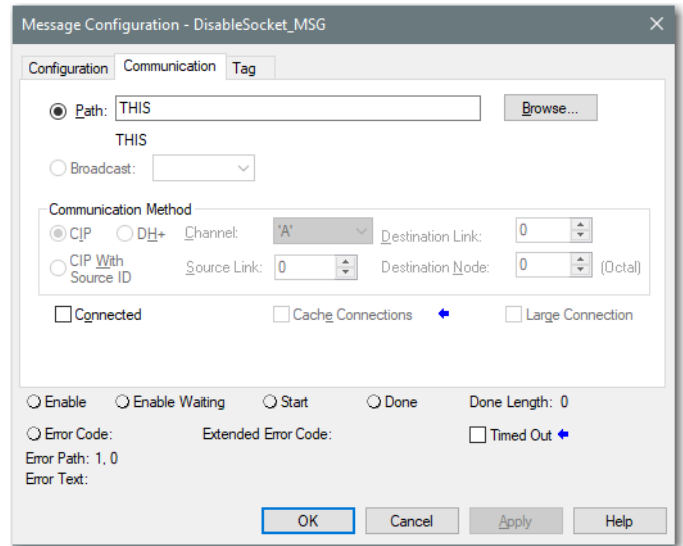
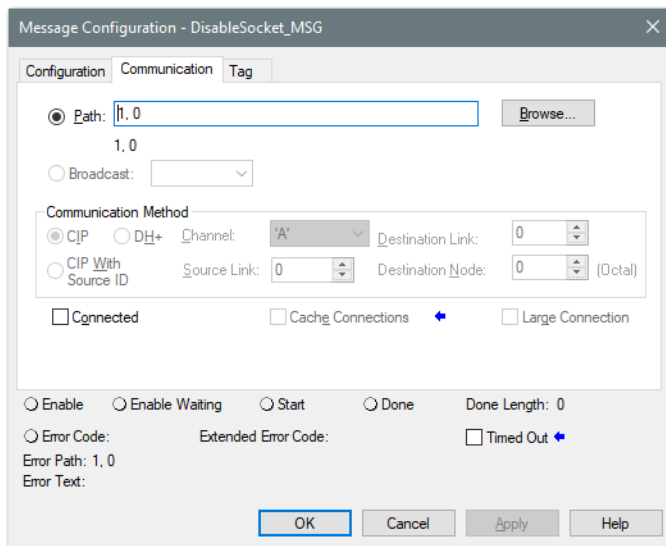


Table 5 - Configuration Tab

Field	Description
Message Type	Choose CIP Generic.
Service Type	Choose Set Attributes Single.
Service Code	10 (hex)
Class	342 (hex)
Instance	0
Attribute	9 (hex)
Source Element	Choose the SINT tag that contains the value of zero.
Source Length	1
Destination Element	Not required.

On the Communication tab, configure the parameters that are described in [Table 3](#).



IMPORTANT If you are using the front Ethernet port on a controller, you must use **unconnected** MSG instructions.

Table 6 - Communication Tab

Field	Description
Path	<p>Enter the communication path to the EtherNet/IP module. The module must be accessed via the backplane; you cannot access the module via the Ethernet port.</p> <ul style="list-style-type: none"> For all controllers and communication modules, the path is 1, x. Where x is the slot number of the communication module, or the slot number of a ControlLogix 5580 controller if the front Ethernet port is used. For all supported CompactLogix controllers, the slot is 0. For all CompactLogix 5370, CompactLogix 5380, Compact GuardLogix 5380, CompactLogix 5480, ControlLogix 5580, and GuardLogix 5580 controllers with version 28.11 or later, you can also use a path of 'THIS'.

Programming Considerations

Observe these programming considerations.

TCP Connection Loss

Your application program can encounter conditions that result in TCP connection loss. For example, a network cable can be unplugged, or a target device can be turned off.

Your application program detects the loss of TCP connections and handles those events appropriately. You can detect connection loss when one of the following occurs:

- The ReadSocket service returns with an error.
- The WriteSocket service returns an extended error code other than 16#0000_0046. See [Error Codes for Socket Services on page 51](#).

Depending on the application, try these actions:

- Try to re-establish the connection if there is a client connection.
- Wait for another incoming connection to be established if there is a server connection.

If you want to re-establish communication with the other device, complete these actions:

- Delete the socket instance for the lost connection.
- If the connection is a client connection, create a socket instance and issue an OpenConnection service to the target device.
- If the connection is a server connection, issue an AcceptConnection service to wait for another connection from the remote device.

IMPORTANT User code must manage messages so that only one message to a socket instance is active at a time. For example, the read and write socket instructions for a given socket should be interlocked so that only one executes at a time. This is on a per socket basis.

ControlLogix Redundancy

IMPORTANT Socket instances that are created in EtherNet/IP modules are **not** crossloaded in a redundancy system.

If your application uses sockets in an enhanced redundancy system, your application program must manage switchovers in these ways:

- After a switchover, socket instances in the EtherNet/IP module in the old primary chassis must be recreated in the EtherNet/IP module in the new primary chassis via controller logic.
- Sockets that are connected outside of the enhanced redundancy system must recognize that communication is lost with socket instances in the EtherNet/IP module in the old primary chassis after a switchover. A change in IP address of the EtherNet/IP module after a switchover causes loss of communication. See [TCP Connection Loss on page 19](#).
- Although socket instances in the EtherNet/IP module in the old primary chassis are automatically deleted once their inactivity timeout expires, it is possible that a second switchover can occur before the timeout expires. To be sure that these non-functioning socket instances are deleted before a second switchover, your application program can issue a message to delete all sockets if there is a switchover before creating functioning socket instances.

To learn more about redundancy systems, refer to the ControlLogix 5570 Redundancy User Manual, publication [1756-UM535](#).

EtherNet/IP Module Reset

If the EtherNet/IP module is reset, for example by cycling power or with removal and insertion under power (RIUP), all socket instances are lost.

If you create socket instances while MSG instructions are still using the old instance numbers, the new instance numbers can match the old instance numbers. In this situation, your old MSG instructions can succeed but could not be communicating with the correct remote device.

Handle this situation by monitoring the status of the EtherNet/IP module via a GSV instruction. If you lose communication with the EtherNet/IP module, the Logix 5000 program reinitializes its socket communication.

Change Controller Mode between Run and Program

If the Logix 5000 controller transitions from Run mode to Program mode while socket requests are active, the transition does not complete until all outstanding MSG requests complete or time out. If you have long timeout values, you can experience an unexpectedly long time for the Run-to-Program transition to complete.

Alleviate long transition times by appropriately setting the timeout parameter for the socket services. In the Logix 5000 program, you can also set the .TO bit for any outstanding socket-related MSG instruction. This causes the MSG instruction to time out and set the .ER bit.

If the controller transitions from Run mode to Program mode, then back to Run mode again, previous socket instances can still exist on the EtherNet/IP module. The previous socket instances time out eventually. Depending on the number of sockets you need, your program can encounter errors during Run-Program-Run transitions because all available socket instances are in use.

To alleviate this situation, follow this procedure:

1. Wait for all socket instances to time out before putting the controller in Run mode.
2. When the Logix 5000 program starts, use the DeleteAllSockets service to delete any previous instances.

The DeleteAllSockets service deletes all socket instances, not just those instances that the controller that calls the service creates.

Application Messages and TCP

A TCP connection is a byte stream between two application entities. The application protocol determines the message formats. Messages can be fixed size or variable size.

If an application sends variable size messages, a common strategy is to first send a fixed-size header that contains the size of the message followed by the message. The receiving device can first issue a ReadSocket service of the fixed size header to determine the remaining size, and then issue a subsequent ReadSocket service to receive the remaining data.

Application Messages and Inhibited Modules

Unlike I/O connected via an EtherNet/IP module, communication via messaging to socket instances can continue when a module is inhibited. If you want to stop socket communication when a module is inhibited, your application code must detect the status of the module and take the appropriate action.

Partial Reads

It is possible for a read service to return a BufLen that is less than the requested amount of data. For example, your program can request 100 bytes of data. Because TCP is a byte stream and not a datagram protocol, you can receive less than 100 bytes when the read service returns.

Depending on the application protocol, issue additional read requests to receive all data. If the application protocol dictates that all messages are 100 bytes, then you must issue additional read requests until you receive 100 bytes. If the application protocol uses variable size messages, your program needs additional logic to handle variable message sizes as defined by the application protocol.

When issuing multiple read requests, be careful to adjust the destination tag that receives the data so that data is not overwritten.

If the read request times out before any data is received, a BufLen of 0 is returned with success (0) status.

This fragment of Structured Text logic shows an example of handling a partial read request.

```
/* copy the message we just read */
COP (ReadResponse.Buf[0], ReadBuf[CurrentLen],
ReadResponse.BufLen);

CurrentLen := CurrentLen + ReadResponse.BufLen;

/* do we need to read more data get a complete message? */
if (CurrentLen < ApplicationMsgLen) then

/* issue another read */

ReadParams.BufLen := ApplicationMsgLen - CurrentLen;

MSG (ReadMSG0);

    end_if;
```

Partial Writes

Although uncommon, sometimes a write service is unable to send all specified bytes if the write service is called multiple times before the target application can receive the data.

If the write service is not able to send the requested data, your program issues subsequent writes to send the remaining data. Your program also adjusts the source tag, so that old data is not sent.

If the number of bytes written is less than requested, an extended error is returned, and the actual length of the data sent.

This fragment of Structured Text logic shows an example of handling a partial write service.

```
if (WriteMSG0.ER) then

/* write failed. if the extended error code was 16#0000_0046,
then it means less than the requested byte were sent. */

if (WriteMSG0.EXERR = 70) then

/* need to issue another write, with the data that was not
sent */

    SentLen := WriteResponse; /* here's what was sent */

    /* adjust the size */

    WriteParams.BufLen := WriteParams.BufLen - SentLen;

    /* copy remaining data to send to MSG buffer */

    COP (WriteBuf[SentLen], WriteParams.Buf[0],
WriteParams.BufLen);

/* BufLen = Timeout + Sockaddr + data length */

WriteMSG0.REQ_LEN := 4 + 12 + WriteParams.BufLen;

    MSG (WriteMSG0);

end_if;

    end_if;
```

Performance Considerations

The socket interface enables a Logix 5000 controller to communicate via an EtherNet/IP module with Ethernet devices that do not support the EtherNet/IP application protocol, such as barcode scanners, RFID readers, or other standard Ethernet devices. The socket interface, via messaging, is not well suited for real-time control as communication with this method is not scheduled or deterministic.

There are various factors that can affect the performance of the socket interface. For examples of some of the factors to consider, see the Knowledgebase Article [1756-EWEB Performance](#).

Socket Object Services

For a socket object, application data has no inherent byte order. The service receives data in the same byte order as it is sent. However, Logix 5000® controllers store data in CIP™ byte order (little-endian). For example, if you issue a write service with one DINT, that DINT is sent over a TCP connection or in a UDP datagram in CIP byte order. If you issue a read service and your destination tag for the response contains a DINT, the Logix 5000 controller assumes that the incoming data is in CIP byte order. Depending on the byte order of the application that you are communicating with, you may need to convert the byte order in your Logix 5000 program or in the application.

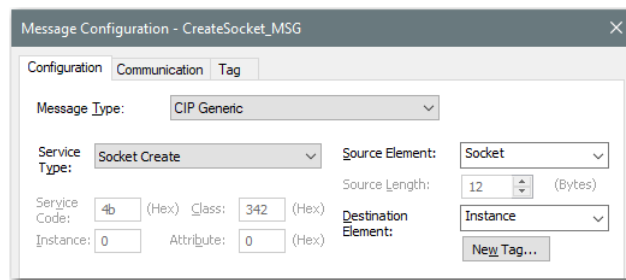
To check your MSG configuration in the Studio 5000 Logix Designer® application, choose a service type from the Service Type pull-down menu on the Configuration tab of the Message Configuration dialog box. The software completes the Service Code and Class fields.

With RSLogix 5000® software, version 15 and earlier, choose Custom from the Service Type pull-down menu and manually complete the Service Code and Class fields.

Socket Create

The Socket Create service creates an instance of the socket object. The service returns an instance number that you use in the subsequent socket operations. Call the Socket Create service with instance 0 (Socket object class).

Parameter	Value
Service Type	Socket Create
Service Code	4b
Class	342
Instance	0
Attribute	0



MSG Source Element

Choose a tag with a user-defined data type. Use the information in [Table 7](#) to define the data type.

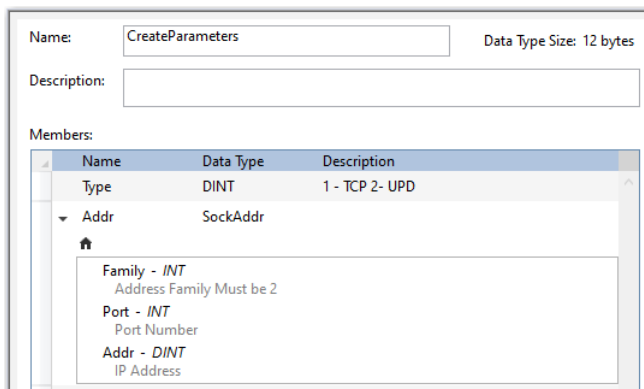


Table 7 - Data Type for Socket Create Source Element

Member Name	Data Type	Description
Type	DINT	Specify one of these values: <ul style="list-style-type: none"> • 1 for TCP • 2 for UDP
Addr	structure	A user-defined structure that specifies the address for the socket.
Family	INT	Specify the address family. Must be 2.
Port	INT	Specify the local port number on which an application listens and receives. If you want a port that is randomly assigned, use port 0.
Addr	DINT	Specify an IP address. Typically, set to 0 (any address) for a CompactLogix™ 5370, CompactLogix 5380, Compact GuardLogix® 5380, CompactLogix 5480, ControlLogix® 5580, GuardLogix 5580 controller in Linear/DLR mode. For CompactLogix 5380, Compact GuardLogix 5380, and CompactLogix 5480 controllers in Dual-IP mode, the IP address must be set in HEX format with 1 byte per octet. See Knowledgebase Article 5380 Ethernet Socket Errors and Path Information .

MSG Source Length

Specify the size of the user-defined structure for the source element. In this example, CreateParams is 12 bytes.

MSG Destination Element

The MSG instruction returns the instance number of the socket that it created to the destination element. Specify a DINT tag.

Considerations

Use the instance that the Socket Create service returns on subsequent service requests.

Use a MOV instruction to move the instance to another MSG tag (the .Instance field).

If you use a local port number that is already in use by the EtherNet/IP™ module, you receive extended error code 16#0000_0030. Avoid using commonly used ports.

When a CompactLogix 5380, Compact GuardLogix 5380, and CompactLogix 5480 controller operate in Dual-IP mode, the default IP address for use with a Socket_Create service type is 0.0.0.0.

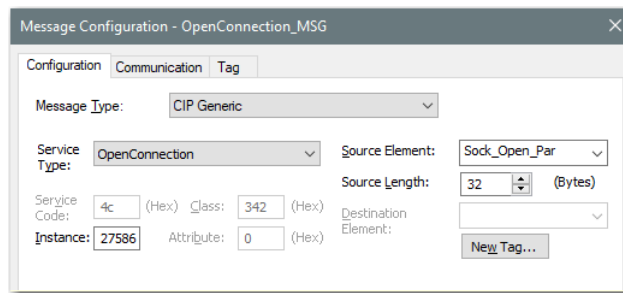
- If you use 0.0.0.0, IP communication that the Socket Object instance initiates follows the same routing rules as DNS request routing rules described in these publications:
 - CompactLogix 5380 and Compact GuardLogix 5380 Controllers User Manual, publication [5069-UM001](#).
 - CompactLogix 5480 Controllers User Manual, publication [5069-UM002](#).
- If you use the IP address of port A1 instead of 0.0.0.0, IP packets can only go to the port A1 subnet or via its default gateway.
- If you use the IP address of port A2 instead of 0.0.0.0, IP packets can go only to port A2 subnet or via its default gateway.
- If you use the IP address of port B1 instead of 0.0.0.0, IP packets can only go to the port B1 subnet or via its default gateway.
- If you use an IP address other than the port A1 or A2 IP addresses or 0.0.0.0, the Create_Socket_Service request is rejected.

OpenConnection

The OpenConnection service does one of the following:

- Opens a TCP connection with the specified destination address
- For UDP, associates a destination IP address and port number with the specified socket

Parameter	Value
Service Type	OpenConnection
Service Code	4c
Class	342
Instance	from Socket Create
Attribute	0



MSG Source Element

Choose a tag with a user-defined data type. Use the information in [Table 8](#) to define the data type.

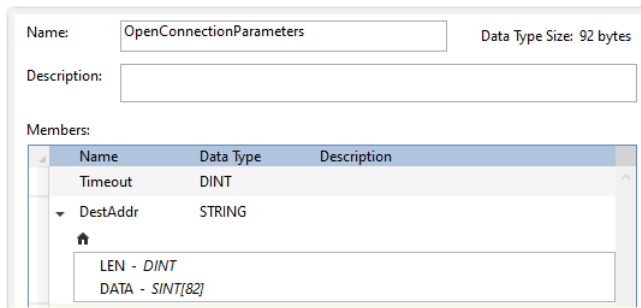


Table 8 - Data Type for OpenConnection Source Element

Member Name	Data Type	Description
Timeout	DINT	Specify the timeout in milliseconds.
DestAddr	STRING	Specify an array of characters (maximum of 64) to define the destination of the connection. You can specify either Hostname or IP address. <ul style="list-style-type: none"> • Hostname?port=xxxzaz • IPAddr?port=xxx For example, to specify an IP address, enter 10.88.81.10?port=2813
.LEN	DINT	The length of the destination address.
.DATA	SINT array	The array that contains the destination address.

The MSG instruction that issues the OpenConnection service has a source length of 8 (Timeout + AddrLen) plus the number of characters in the destination address.

MSG Source Length

Specify 8 bytes (Timeout + AddrLen) + number of characters in the destination address.

MSG Destination Element

Not used. The MSG instruction does not return any data.

Considerations

In some cases, the OpenConnection service can return before the timeout period without creating a TCP connection. For example, if the destination device is running, but is not listening for connections on the specified port number, the OpenConnection service returns with an error before the timeout period.

For UDP, the information you must specify depends on whether you use the OpenConnection service:

- If you use the OpenConnection service, you do not have to specify the IP address and port number each time you send data. If you do not specify an IP address and port number, you can receive data only from the previously specified IP address and port number until you call the OpenConnection service to specify another IP address and port number.
- If you do **not** use the OpenConnection service, you must specify the destination address each time you call the WriteSocket service to send data. When you call the ReadSocket service, you receive the data and the address of the sender. You can then use the address of the sender to send a response via the WriteSocket service.

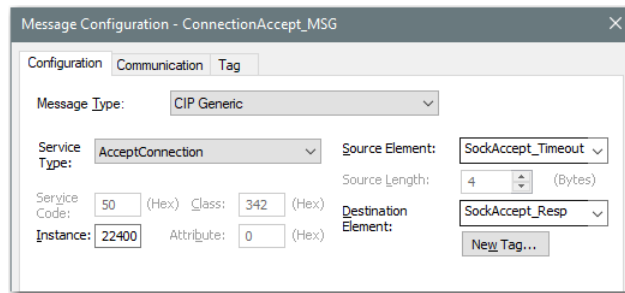
If you call the OpenConnection service on a UDP socket with an AddrLen of 0, this removes the association with the destination address.

AcceptConnection

The AcceptConnection service accepts a TCP connection request from a remote destination. Before calling the AcceptConnection service, call the Socket Create service and specify the local port number that accepts the connection. When the AcceptConnection service completes, it returns a socket instance that you use to send and receive data on the newly created connection.

The AcceptConnection service is not valid for UDP sockets.

Parameter	Value
Service Type	AcceptConnection
Service Code	50
Class	342
Instance	from Socket Create
Attribute	0



MSG Source Element

Choose a DINT tag to contain the timeout in milliseconds.

MSG Source Length

Specify 4 bytes (Timeout).

MSG Destination Element

Choose a tag with a user-defined data type. Use the information in [Table 9](#) to define the data type.

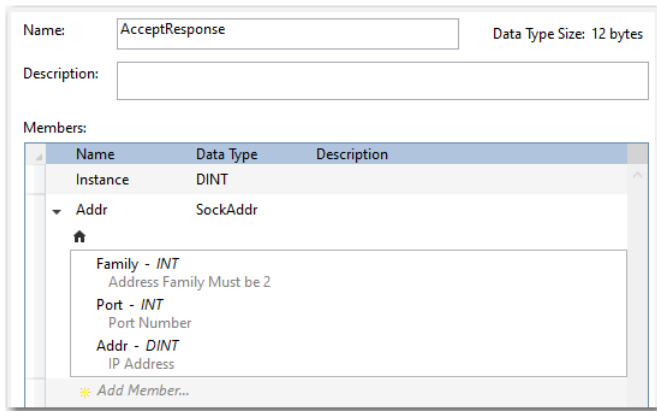


Table 9 - Data Type for AcceptConnection Destination Element

Member Name	Data Type	Description
Instance	DINT	Contains the instance for this service. Use this Instance on subsequent Read and Write services for this connection. IMPORTANT: Copy this Instance number to Read and Write Messages
Addr	structure	A user-defined structure that contains the address for the socket.
Family	INT	Contains the address family. Must be 2.
Port	INT	Contains a remote port number.
Addr	DINT	Contains a remote IP address.

Considerations

Create a separate socket instance with the Socket Create service for each port number that accepts connections. After you create socket instances, call the AcceptConnection service to wait for an incoming connection request. You can accept connections on the same port number. Each call to the AcceptConnection service returns another instance number to use to read and write data.

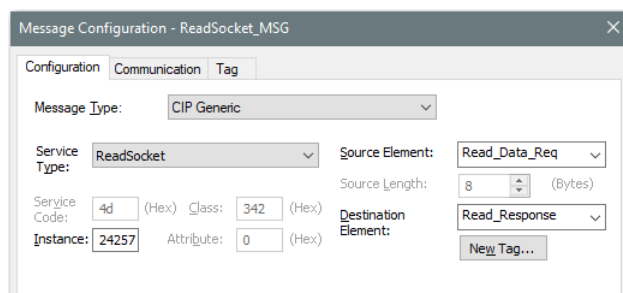
ReadSocket

The ReadSocket service reads data on a socket. You specify the number of bytes to receive. The service returns the number of bytes received.

For TCP, the ReadSocket service returns when any data is received, up to the requested number of bytes. If no data is received before the timeout period, the service returns a status of success by setting a message instruction Done Bit (.DN) and a BufLen of 0. The service can return fewer bytes than were requested. Your application can require multiple read requests to receive an entire application message.

For UDP, the ReadSocket service completes when a datagram is available.

Parameter	Value
Service Type	ReadSocket
Service Code	4d
Class	342
Instance	See Instance
Attribute	0



Instance

This service uses the instance that is returned from the CreateConnection service. However, when accepting a connection via the AcceptConnection service, use the instance that is returned from this AcceptConnection service as the ReadSocket instance.

MSG Source Element

Choose a tag with a user-defined data type. Use the information in [Table 10](#) to define the data type.

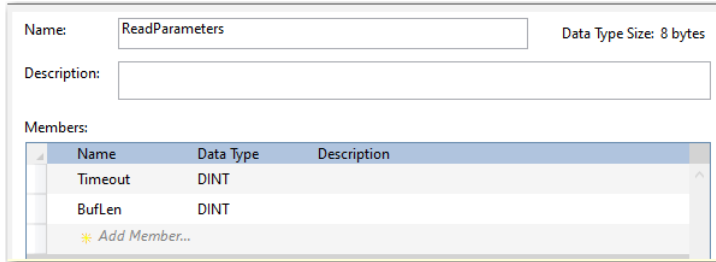


Table 10 - Data Type for ReadSocket Source Element

Member Name	Data Type	Description
Timeout	DINT	Specify the timeout in milliseconds.
BufLen	DINT	Specify the number of bytes of data to receive.

MSG Source Length

Specify 8 bytes (Timeout + BufLen).

MSG Destination Element

Choose a tag with a user-defined data type. Use the information in [Table 11](#) to define the data type.

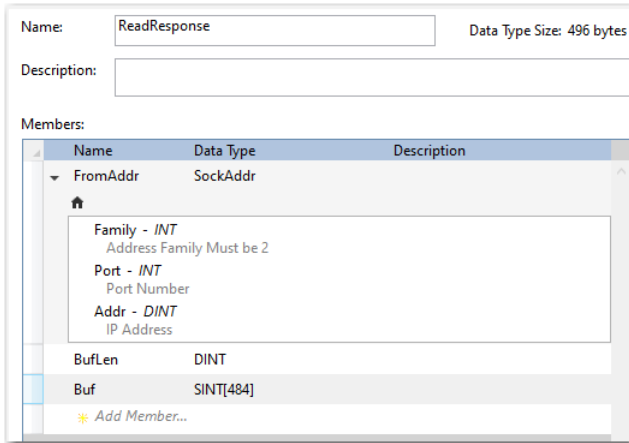


Table 11 - Data Type for ReadSocket Destination Element

Member Name	Data Type	Description
FromAddr	structure	A user-defined structure that can contain the address of the device that sends UDP data. This structure is populated from the end device. For TCP or UDP with OpenConnection, this structure is not used and contains all zeros. The TCP connection conveys all remote address information.
Family	INT	Contains the address family for UDP. Must be 2.
Port	INT	Contains the remote port number for UDP. The remote device uses this port for sending. 0 is an invalid port number for UDP.

Table 11 - Data Type for ReadSocket Destination Element

Member Name	Data Type	Description
Addr	DINT	Contains the remote IP address for UDP
BufLen	DINT	Contains the number of bytes of data received.
Buf	SINT array	Contains the data. This number must be large enough to contain the maximum amount of data expected. For a standard connection, the maximum is SINT[484]. For a large connection, the maximum is SINT [3984].

WriteSocket

The WriteSocket service sends data on a socket. You specify the number of bytes to send. The service attempts to send the requested number of bytes and returns the number of bytes sent.

Parameter	Value
Service Type	WriteSocket
Service Code	4e
Class	342
Instance	See Instance
Attribute	0



Instance

This service uses the instance that is returned from the CreateConnection service. However, when accepting a connection via the AcceptConnection service, use the instance that is returned from this AcceptConnection service as the WriteSocket instance.

MSG Source Element

Choose a tag with a user-defined data type. Use the information in [Table 12 on page 30](#) to define the data type.

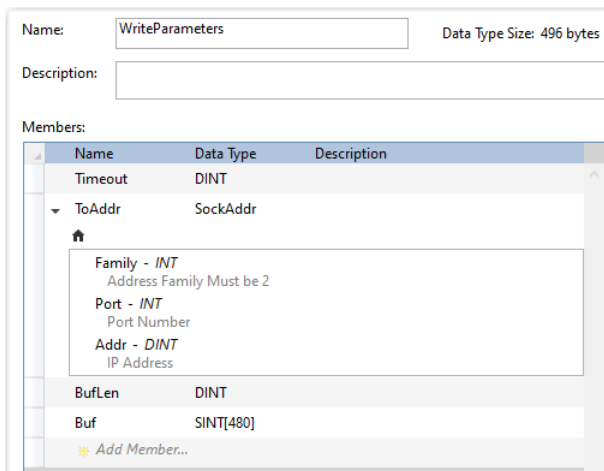


Table 12 - Data Type for WriteSocket Source Element

Member Name	Data Type	Description
Timeout	DINT	Specify the timeout in milliseconds.
ToAddr	structure	A user-defined structure that contains the address to which to write UDP data. For TCP or UDP with OpenConnection, this structure is not used and contains all zeros. The TCP connection conveys all required remote address information.
Family	INT	Specify the address family. Must be 2 for UDP.
Port	INT	Specify the remote port number for UDP. This is the port that the remote device uses for receiving. 0 is an invalid port number for UDP.
Addr	DINT	Specify the remote IP address for UDP. 0.0.0.0 is an invalid IP address for UDP.
BufLen	DINT	Specify the number of bytes of data to write.
Buf	SINT array	Contains the data. This number must be large enough to contain the maximum amount of data expected. For a standard connection, the maximum is SINT[472]. For a large connection, the maximum is SINT [3972].

MSG Source Length

Specify 16 bytes (Timeout + Addr + BufLen) + number of bytes to write.

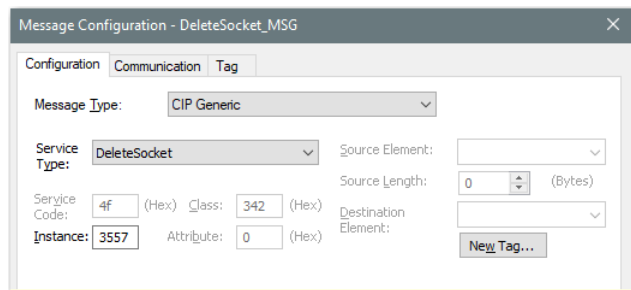
MSG Destination Element

The MSG instruction returns the number of bytes that were written. Choose a DINT tag.

DeleteSocket

The DeleteSocket service deletes a socket instance. For a TCP connection, the DeleteSocket service also closes the connection before it deletes the instance.

Parameter	Value
Service Type	DeleteSocket
Service Code	4f
Class	342
Instance	from Socket Create
Attribute	0



MSG Source Element

Not used.

MSG Source Length

Specify 0 bytes.

MSG Destination Element

Not used.

Considerations

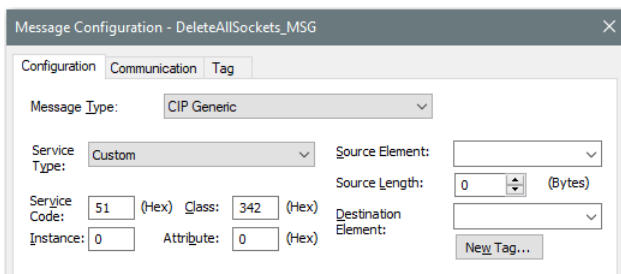
Delete a socket instance if it is no longer needed. If unused instances are not deleted and you continue to create additional instances, you can exceed the maximum number of instances.

DeleteAllSockets

The DeleteAllSockets service deletes all currently created socket instances. For TCP, the DeleteAllSockets service also closes all connections before it deletes the instances.

Choose Custom for the service type. DeleteAllSockets is not an available option from the Service Type pull-down menu.

Parameter	Value
Service Type	Custom
Service Code	51
Class	342
Instance	0
Attribute	0



MSG Source Element

Not used.

MSG Source Length

Specify 0 bytes.

MSG Destination Element

Not used.

Considerations

Call the DeleteAllSockets service with instance 0.

IMPORTANT Be careful with the DeleteAllSockets service when there are multiple controllers that use the socket interface of the EtherNet/IP module. The service deletes all socket instances that are created by all controllers, not just the controller that calls the service.

Use the DeleteAllSockets service as the first operation when the program first begins to operate.

ClearLog

The ClearLog service clears the debug log on the TCP/IP Socket Object webpage. This service does not change the logging options.

IMPORTANT The TCP/IP Socket Object webpage is not visible on ControlLogix 5580, GuardLogix 5580, CompactLogix 5380, Compact GuardLogix 5380, and CompactLogix 5480 controllers.

Choose Custom for the service type. ClearLog is not an available option from the Service Type pull-down menu.

Parameter	Value
Service Type	Custom
Service Code	52
Class	342
Instance	0
Attribute	0

MSG Source Element

Not used.

MSG Source Length

Specify 0 bytes.

MSG Destination Element

Not used.

JoinMulticastAddress

Joining a multicast group lets a socket receive multicast data. When a join is executed, it sends an IGMP membership packet and enables the hardware filters to receive the multicast data. A specific address can be joined only once. Subsequent joins receive an error message until the multicast address is dropped. Multicast joins are system wide. Two sockets cannot join the same multicast address simultaneously. When the socket that the join was executed on is deleted, the multicast address is dropped. Each socket can join one or more multicast groups.

Choose Custom for the service type. JoinMulticastAddress is not an available option from the Service Type pull-down menu.

Parameter	Value
Service Type	Custom
Service Code	53
Class	342
Instance	from Socket Create
Attribute	0

MSG Source Element

Choose a tag with a user-defined data type. Use the information in [Table 13](#) to define the data type.

Populate the Join_Source_Data.Addr field with a multicast IP address in hexadecimal format. The value must be a hexadecimal representation of the IP address. For example, for address 239.1.2.100, enter 16#EF010264.

Name	Data Type	Description
Family	INT	2 for IP4 family
Port	INT	Port Number
Address	DINT	Multicast IP Address
* Add Member...		

Table 13 - Data Type for JoinMulticastAddress Source Element

Member Name	Data Type	Description
SocketsAddr	structure	A user-defined structure that specifies the multicast address to join.
Family	INT	Specify the address family. Must be 2.
Port	INT	Not used. The port is determined when the socket is created.
Addr	DINT	Specify the multicast IP address to receive from.

MSG Source Length

Specify 8 bytes.

MSG Destination Element

Not used.

DropMulticastAddress

Dropping a multicast address disables a socket from receiving multicast data. When a drop is executed, it sends an IGMP leave group packet and disables the hardware filters from receiving the multicast data.

Choose Custom for the service type. DropMulticastAddress is not an available option from the Service Type pull-down menu.

Parameter	Value
Service Type	Custom
Service Code	54
Class	342
Instance	from Socket Create
Attribute	0

MSG Source Element

Choose a tag with a user-defined data type. Use the information in [Table 14 on page 34](#) to define the data type.

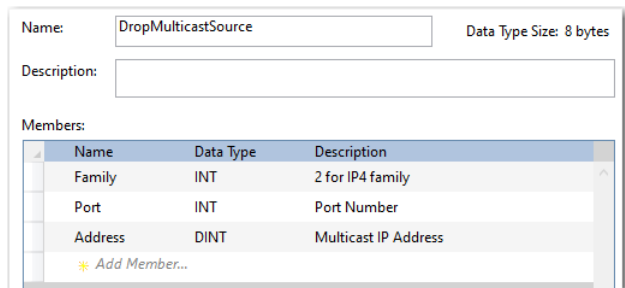


Table 14 - Data Type for DropMulticast Address Source Element

Member Name	Data Type	Description
SocketsAddr	structure	A user-defined structure that specifies the multicast address to drop.
Family	INT	Specify the address family. Must be 2.
Port	INT	Not used. The port is determined when the socket is created.
Addr	DINT	Specify the multicast IP address to drop.

MSG Source Length

Specify 8 bytes.

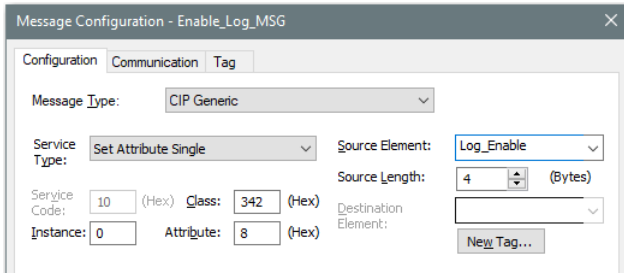
MSG Destination Element

Not used.

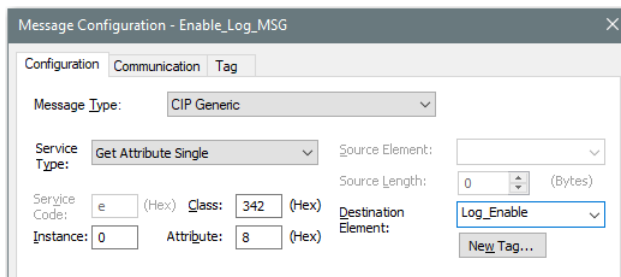
Socket Attributes

You access socket attributes by configuring a CIP™ Generic MSG instruction to get or set the specific attribute:

- To change an attribute value for a socket, choose Set Attribute Single from the Service Type pull-down menu.



- To get a socket value, choose Get Attribute Single from the Service Type pull-down menu.



Some socket attributes apply to all sockets, and some apply to specific socket instances:

- For information about all sockets, type 0 in the Instance field. See [Socket Class Attributes](#).
- For information about a specific socket instance, type the specific socket instance number in the Instance field. A Socket Create or AcceptConnection service returns the instance number. See [Socket Instance Attributes on page 36](#).

Socket Class Attributes

Class attributes apply to the socket object, not to specific socket instances. When you get or set a Class attribute, set the instance to 0.

Table 15 - Socket Class Attributes

Class Attribute	Name	Data Type	Access	Description
1	Revision	INT	Get	Object revision.
2	Max Instance	INT	Get	Largest socket instance number currently created.
3	Number of Instances	INT	Get	Number of socket instances currently created.
8	Log Enable ⁽¹⁾	DINT	Get Set	Enable (1) or disable (0) logging to the Socket Object Log webpage. Each socket service has a corresponding bit: <ul style="list-style-type: none"> If enabled, requests for that service request are logged. If disabled, then requests for that service are not logged. Bit 0: Socket Create requests Bit 1: OpenConnection requests Bit 2: AcceptConnection requests Bit 3: Read requests Bit 4: Write requests Bit 5: DeleteSocket and DeleteAllSockets requests Bit 6: Get / Set Attribute requests Bit 7: Log all service errors
9	Object Enable	SINT	Get Set	Enable (1) or disable (0) the Socket Object. Default is enabled.

(1) The Socket Object webpage is not visible on ControlLogix® 5580, GuardLogix® 5580, CompactLogix™ 5380, Compact GuardLogix 5380, and CompactLogix 5480 controllers.

If you use the Get Attributes All service to get class attributes, the response contains all class attributes in [Table 15](#) in the order shown with a total size of 10 bytes.

If you use the Set Attributes All service to set class attributes, the request contains only the Log Enable class attribute.

Socket Instance Attributes

The socket object provides a number of instance attributes that apply to specific socket instances. To get or set an instance attribute, specify a valid instance number.

Table 16 - Socket Instance Attributes

Instance Attribute	Name	Data Type	Access	Description
1 (16#01)	LocalAddr	Struct SockAddr	Get	Local address for the socket.
2 (16#02)	RemoteAddr	Struct SockAddr	Get	Remote address for the socket.
3 (16#03)	SendBufSize	DINT	Get Set	Size of the socket send buffer (bytes).
4 (16#04)	RecvBufSize	DINT	Get Set	Size of the socket receive buffer (bytes).
5 (16#05)	TCPKeepAlive	DINT	Get Set	Enable (1) or disable (0) TCP Keep Alive for the socket. Enabled by default.
6 (16#06)	TCPNoDelay	DINT	Get Set	Enable (1) or disable (0) the TCP No Delay behavior. Enabled by default.
7 (16#07)	InactivityTimeout	DINT	Get Set	Time for the inactivity timeout (default of 5 minutes). If a socket instance receives no service requests for the amount of time that is specified by the inactivity timeout, the socket instance is deleted. If you then try to use the socket instance, the MSG instruction receives the error Class or instance not supported.
8 (16#08)	MulticastTTL	DINT	Get Set	Set the TTL value for UDP multicast, transmitted packets.
9 (16#09)	UDPBroadcast	DINT	Get Set	Enable (1) or disable (0) the ability to transmit broadcast packets on UDP. Disabled by default.
10 (16#0A)	LingerOnOff	DINT	Get Set	Specifies whether the socket performs an orderly close (1) or an immediate close (0). Defaults to no linger (immediate close). For TCP sockets, setting linger to 0 results in a TCP RST packet to close the connection. If you set linger to nonzero, then it results in the standard TCP connection close sequence (3-way FIN, FIN-ACK, ACK handshake followed by TIME_WAIT).

If you use the Get Attributes All service to get instance attributes, the response contains all attributes in [Table 16](#) in the order that is shown with a total size of 36 bytes.

If you use the Set Attributes All service, the request must include attributes 3, 4, 5, 6 and 7 in that order with a total size of 20 bytes.

Troubleshoot Socket Applications

To help you troubleshoot socket applications, this chapter describes the following resources:

- Diagnostic webpages
- Debugging tips
- Error codes
- Knowledgebase articles

Diagnostic Webpages

To help debug and troubleshoot applications, the socket interface provides a set of webpages:

IMPORTANT The Socket Object webpage is not visible on ControlLogix® 5580, GuardLogix® 5580, CompactLogix™ 5380, Compact GuardLogix 5380, and CompactLogix 5480 controllers.

- For communication modules and controllers, go to Diagnostics > Advanced Diagnostics > Miscellaneous > System Data > Socket Object.
- For web server modules, go to Diagnostics > Advanced Diagnostics.

Webpage	Description
Socket Object Diagnostics	Displays information about each instance: <ul style="list-style-type: none"> • Instance number • Socket type—client, server, or listen • Local and remote ports and IP addresses • Send and receive buffer sizes • Socket up time and inactivity time • Socket state and last error state
Socket Object Attributes	Displays attribute settings for each instance
Socket Object Logs	Displays a log of service requests with a maximum of 100 log entries: <ul style="list-style-type: none"> • Service requests made to the socket object • Parameters that are passed for each service request • Whether the service request was a success or failure You can enable or disable logging for some services by using the Log Enable class attribute. See Socket Class Attributes on page 35 .

Debugging Tips

This table describes tips for debugging problems by category.

Category	Consideration
EtherNet/IP™ module	Make sure the EtherNet/IP module has a valid IP address. Also, if you communicate with devices on different subnets, configure the EtherNet/IP module with a valid subnet mask and gateway address.
Socket Create service	Make sure that the Destination tag is a DINT tag. After creating the socket with the Socket Create service, make sure that you use the instance number that the service returns in the subsequent socket services you call.
MSG instruction	Make sure that the Source Element is of a type that matches the request parameters for the requested service. Also make sure that the Source Length is the correct length for the service parameters. There is a limit to the number of active MSG instructions in a Logix 5000® controller. If an MSG instruction is enabled and exceeds the maximum number of active MSG instructions, the MSG instruction receives an error (.ER bit set).
OpenConnection service	Make sure that the Source Length includes the size of the Timeout parameter + Address Length parameter + the Length of the address itself.
Service Timeout parameter	Make sure that the Timeout parameter is sufficient for the service. Also make sure that the Timeout parameter is less than the MSG instruction timeout. If the timeout is set to 0, the service returns immediately.
TCP protocol	A TCP connection is a byte stream with no inherent message boundaries. The application defines how to interpret message boundaries. For example, the application can use a fixed length for all messages. For a variable-length message, the application can use a fixed-length header that contains the length of the remainder of the message. Both ends of the TCP connection must agree on the application protocol that is used. "our program should handle the loss of TCP connections in case they get dropped due to network issues or other reasons.
Ethernet sniffer	An Ethernet sniffer is useful to monitor the messages between the EtherNet/IP module and other devices. You can capture network traffic and create filters to isolate messages between particular devices and particular messages between those devices.

Error Codes for Socket Services

If a socket object encounters an error with a service request, the following occurs:

- Socket object returns an error code.
- MSG instruction sets the .ER bit.
- MSG instruction sets error codes in the Error (.ERR) and Extended Error (.EXTERR) fields.

This table describes common error codes. For more a comprehensive list of error codes, see the Knowledgebase article [Logic Sockets Services Error Codes](#).

Table 17 - Common Error Codes

Error Code	Extended Error Code	Description
16#0001	16#0000_0117	An invalid path was programmatically entered in the MSG.Path string via COP or another string manipulation command. For more information, see the Knowledgebase article, Sockets Error code 16#0001 Extended Code 16#0000_0117 .
16#0001	16#0000_0318 or 16#0000_0103	When configuring a CIP Generic MSG instruction for Open Socket communication, all CompactLogix 5370 controllers must use unconnected MSG instructions. If you configure an MSG instruction for a CompactLogix 5370 controller, make sure that the Connected checkbox is cleared on the Communication tab of the Message Configuration dialog box (page 16).
16#0001	16#0000_0900 through 16#0000_0915	See the I/O fault code descriptions in Logix 5000 Controller and I/O Fault Codes, publication 1756-RD001 .
16#0002		Simultaneous execution of Read, Write, or Delete messages.
16#0004		An attempt to access the socket object via the Ethernet port is blocked because of resiliency concerns. For more information, see the Knowledgebase article, Logix Sockets message error 16#0004 .
16#0005	16#0000_0000 or 16#0000_0001	1. Ethernet module does not have firmware that supports Logix Sockets. 2. The socket instance does not exist. This error can occur in these scenarios: <ul style="list-style-type: none"> - The socket instance number that the Socket Create service returned does not match the instance number in the socket read or write message. - The socket instance closed due to inactivity. - The DeleteSocket service deleted the socket.
16#0006		Failed attempt to write more than 460 bytes with a CompactLogix 5370 controller. SocketWrite messages are limited to 460 bytes with CompactLogix 5370 controllers. This value is specified in the MessageSourceBuffLen tag.

Table 17 - Common Error Codes (Continued)

Error Code	Extended Error Code	Description
16#0008		A 1756-ENxT or 1756-ENxTR module that is used for socket messages is in a remote chassis that is connected to the controller over the ControlNet® network or is using an older EtherNet/IP module that supports only 478-byte messages. For more information, see the Knowledgebase Article Open Sockets: Message Read/Write error 16#0008 if "Large Connection" option is enabled.
16#0009		Invalid socket descriptor. To resolve this error, do the following: <ul style="list-style-type: none"> • Make sure that a valid socket instance exists. • Make sure that the message source data format and source values are correct. • For Create messages, make sure that Type and Family is set correctly. • For UDP Read/Write messages, make sure that Source tag member Family is set to 2.
16#000b or 16#000c		The Open (Connect) message instruction and Accept message were executed on the same socket. For more information, see the Knowledgebase Article Open Sockets Error codes 16#000b, 16#000c.
16#000d		Invalid data in Source UDT.
16#0011		Failed attempt to read more than 484 bytes with a CompactLogix 5370 controller. SocketRead messages are limited to 484 bytes with CompactLogix 5370 controllers. This value is specified in the MessageSourceBuffLen tag.
16#0013 or 16#0015		The 'Write' message instruction Source length must be exactly equal to the buffer length+16. For more information, see the Knowledgebase Article Open Sockets Error code 16#0013 and 16#0015.
16#0020		The 'Write' message instruction Source length is less than 17 bytes. Length must be exactly equal to the buffer length+16. For Connect messages, make sure that the Destination String address includes '?port=xxx' similar to 192.168.1.34?port=9100. For more information, see the Knowledgebase Article 1756-EN2T, 1756-EWEB sockets error 16#0020.
16#00ff	16#0000_0016 or 16#0000_0033	Open Sockets (TCP Client) is unable to connect to a third-party device (Slave). The device reports WIN=0 and the 1756-EN2T module immediately closes the connection. For more information, see the Knowledgebase Article Open Sockets: Open connection fails with error 16#0000_0046, 16#0000_0016 or 16#0000_0033.
16#00ff	16#0000_0030	The address is already in use. This error can occur when multiple Socket Create requests are issued to the same port address.
16#00ff	16#0000_0036	A connection was forced closed by a peer. This error can occur when a remote device closes a connection with a Logix module without notifying the module. To resolve this error, delete the socket and then reconnect to the remote device.
16#00ff	16#0000_0039	In Server mode, instance number from Accept Message was not copied to Read/Write messages.
16#00ff	16#0000_003d	A connection refused by a peer. Possibly peer is out of connections if Logix module closes them without Linger Attribute set. For more information, see the Knowledgebase Article Logix Open Sockets Linger Control.
16#00ff	16#0000_0041	A socket operation could not find a route to the remote host. This error typically occurs in these scenarios: <ul style="list-style-type: none"> • A remote IP address that is specified in the MSG instruction is not on the same subnet as the Logix module. and • The IP address of the gateway or router is not specified in the Logix module properties. UDP multicasts messages to an unpingable IP address require you to specify a gateway address in the Logix module properties even if a gateway address does not exist or is not required. For more information, see the Knowledgebase Article 1756-EWEB socket errors 16#0041 and 16#0043.
16#00ff	16#0000_0043	The remote device or gateway is not responding. This error can occur if a UDP multicast message is sent to a gateway address that is not specified in the Logix module properties. For more information, see the Knowledgebase Article 1756-EWEB socket errors 16#0041 and 16#0043.
16#00ff	16#0000_0046	The socket operation timed out. Known reasons include the following: <ul style="list-style-type: none"> • Connect Service message: <ul style="list-style-type: none"> - Server IP exists, but port does not. - Server IP and port exist, but does not accept connections on this port. - Service timeout value in UDT set to 0 or low value. The peer device reports WIN=0 and the 1756-EN2T module immediately closes the connection. For more information, see the Knowledgebase Article Open Sockets: Open connection fails with error 16#0000_0046, 16#0000_0016 or 16#0000_0033. <ul style="list-style-type: none"> • Read/Write Service message: <ul style="list-style-type: none"> - Read and write executed simultaneously. For more information, see the Knowledgebase Article Open Sockets message Error 16#00FF extended 16#0000_0046. <ul style="list-style-type: none"> • UDP Read message only: <ul style="list-style-type: none"> - UDP Receive buffer is empty with no new incoming data.
16#00ff	16#0009_0315	Invalid path string manually or programmatically entered to the MSG.Path string.
16#00d0	16#0000_0001	CA certificate file has a loading error.
16#00d0	16#0000_0002	Trusted peer certificate file has a loading error.
16#00d0	16#0000_0003	Both certificate files have a loading error.
16#00d0	16#0000_0004	No resources for the TLS session.
16#00d0	16#0000_0005	Unknown error during TLS handshake.

Exposing TLS Errors

During the TLS handshake process, errors can occur that are not covered by the CIP specification but are defined in various RFCs. These errors are exposed through extended status codes 16#0000_0900...16#0000_0915, as defined in Logix 5000 Controller and I/O Fault Codes, publication [1756-RD001](#).

Knowledgebase Articles

For additional help, see these Knowledgebase articles:

Knowledgebase Article	Description
Sample Application for Ethernet module Sockets Feature	Sample applications for the 1756-EWEB module and CompactLogix 5380 controllers.
Logic Sockets Services Error Codes	Descriptions of possible socket error codes.
EWEB socket services hints	Helpful hints for EWEB socket services.
Summary of Logix Socket Information	Summary of major sockets topics and functionality descriptions.
RSLogix 5000®: AOI example for using sockets to read time from NTP or SNTP server	Add-On Instruction example for using sockets to read time from NTP or SNTP server
Example Add On Instructions for Sockets	Using sockets in AOIs (Add-on Instructions).
Email with Basic Login Authentication Using Sockets and AOI	Using Sockets for Email with Basic Login Authentication

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Additional Resources

These documents contain additional information concerning related products from Rockwell Automation. You can view or download publications at rok.auto/literature.

Resource	Description
EtherNet/IP Network Devices User Manual, ENET-UM006	Describes how to configure and use EtherNet/IP devices to communicate on the EtherNet/IP network.
Ethernet Reference Manual, ENET-RM002	Describes basic Ethernet concepts, infrastructure components, and infrastructure features.
System Security Design Guidelines Reference Manual, SECURE-RM001	Provides guidance on how to conduct security assessments, implement Rockwell Automation products in a secure system, harden the control system, manage user access, and dispose of equipment.
UL Standards Listing for Industrial Control Products, publication CMPNTS-SR002	Assists original equipment manufacturers (OEMs) with construction of panels, to help ensure that they conform to the requirements of Underwriters Laboratories.
American Standards, Configurations, and Ratings: Introduction to Motor Circuit Design, publication IC-AT001	Provides an overview of American motor circuit design based on methods that are outlined in the NEC.
Industrial Components Preventive Maintenance, Enclosures, and Contact Ratings Specifications, publication IC-TD002	Provides a quick reference tool for Allen-Bradley industrial automation controls and assemblies.
Safety Guidelines for the Application, Installation, and Maintenance of Solid-state Control, publication SGI-1.1	Designed to harmonize with NEMA Standards Publication No. ICS 1.1-1987 and provides general guidelines for the application, installation, and maintenance of solid-state control in the form of individual devices or packaged assemblies incorporating solid-state components.
Industrial Automation Wiring and Grounding Guidelines, publication 1770-4.1	Provides general guidelines for installing a Rockwell Automation industrial system.
Product Certifications website, rok.auto/certifications .	Provides declarations of conformity, certificates, and other certification details.

Rockwell Automation Support

Use these resources to access support information.

Technical Support Center	Find help with how-to videos, FAQs, chat, user forums, Knowledgebase, and product notification updates.	rok.auto/support
Local Technical Support Phone Numbers	Locate the telephone number for your country.	rok.auto/phonesupport
Technical Documentation Center	Quickly access and download technical specifications, installation instructions, and user manuals.	rok.auto/techdocs
Literature Library	Find installation instructions, manuals, brochures, and technical data publications.	rok.auto/literature
Product Compatibility and Download Center (PCDC)	Download firmware, associated files (such as AOP, EDS, and DTM), and access product release notes.	rok.auto/pcdc

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