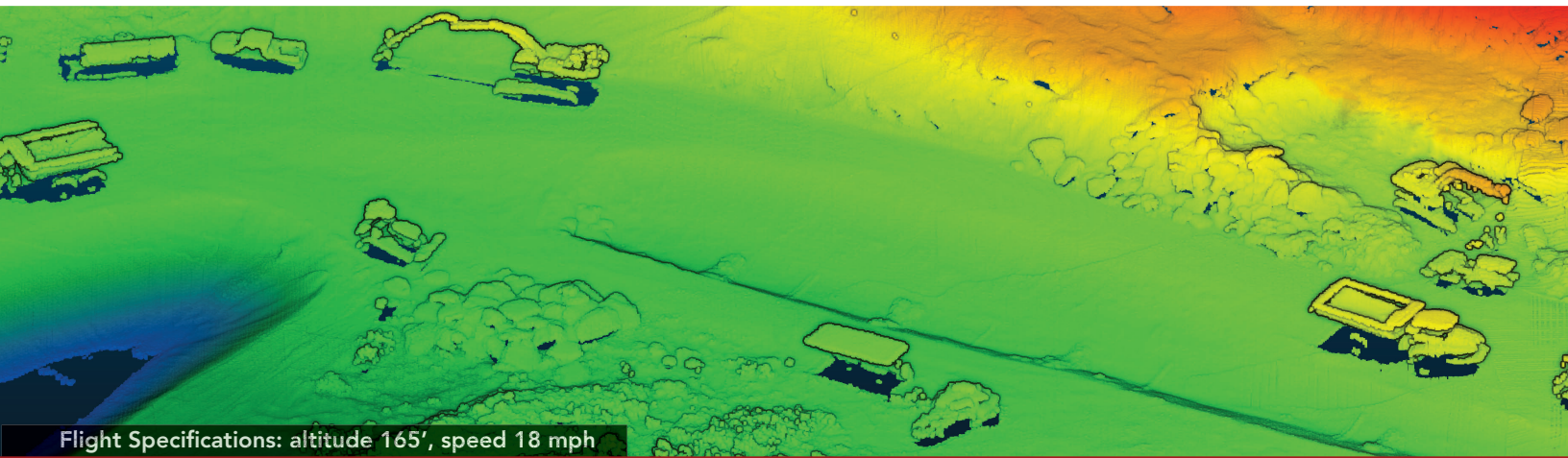


APPLICATION CONSTRUCTION

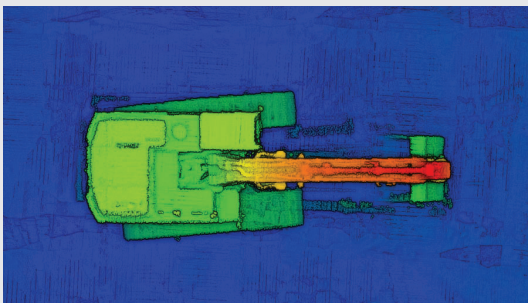


Flight Specifications: altitude 165', speed 18 mph

High Resolution Images

Simple Operation

High Point Density



High-Resolution Point Clouds

Flight Specifications: altitude 100', speed 13 mph

The RedTail LiDAR system - licensed from the U.S. Army Research Laboratory - is designed to provide high-resolution imaging from multicopters, hybrid, and fixed-wing UAVs.

Designed specifically for small unmanned aerial vehicles, the RedTail LiDAR System is a superior point cloud generation tool that can help you manage all stages of the construction process by creating high resolution, highly accurate 3D point clouds of your construction project area. From roadways to rail corridors, to ports and airports, there are many uses for LiDAR data during construction including: 1) conceptual design, 2) asset management, 3) confirm as-bid conditions prior to construction, 4) monitor construction impacts, 5) document as-built plans, 6) generate surface profiles, 7) monitor post construction subsurface settlement, 8) establish emergency access to construction projects, and 9) survey projects located in hazardous areas without endangering the crew or the public.

The power of LiDAR imaging for construction is the creation of point clouds that can be rotated, zoomed, and used for accurate distance and volume measurements. Accurate, high-resolution data can be acquired in a minimal amount of time, with less manpower and no interference with operations or construction activities. The data collected can be imported directly into construction and architectural software solutions, allowing for detailed simulations of the construction build.

The RedTail LiDAR System is the optimal solution for construction project planning, mapping, and monitoring. With a pulse repetition rate of up to 400,000 pulses per second, even ground-point distribution, superior ranging capability, and optimized scan angles, the RedTail LiDAR System simplifies even the most challenging construction projects.

Learn more at redtaillidar.com

Phone **304.306.2396** Email sales@redtaillidar.com

About RedTail LiDAR Systems

RedTail LiDAR Systems is meeting the market demand for high-quality, high-resolution point clouds captured from manned and unmanned vehicles. The microelectromechanical (MEMs) mirror-based technology was developed at the Army Research Laboratory (ARL) with the goal of generating accurate, high resolution point clouds. At RedTail, our mission is to provide the optimal tool to rapidly and efficiently create superior point clouds for a broad range of commercial, academic and government customers.



RedTail LiDAR Systems – Scanning the way it was meant to be.™

HIGH RESOLUTION

RedTail's small beam divergence angle yields high-resolution point clouds.

EASE OF USE

The RedTail system has been designed by a team of professionals that understands how important it is to provide a system that is easy to use and simple to integrate onto UAV platforms.

RANGE

The RedTail system was designed with range being a critical performance attribute. Our system operates effectively against 20% reflective targets at a height of 70 meters, and 100 meters against 80% reflective targets, thereby ensuring mapping flights can be performed in a wide variety of operating environments (e.g., tall trees, buildings).

SCAN PATTERN

The RedTail Lisystem transmits all laser pulses to the ground to optimize point cloud density. LiDAR points are evenly spaced to provide superior mapping capability.

LINE SCAN FREQUENCY AND PULSE REPETITION RATE (PRR)

The RedTail system has a line scan frequency of 100 scans per second and a PRR of up to 400,000 pulses per second. This rapid side to side scan pattern, coupled with the high PRR, allows operators to fly faster and cover more area.

SCAN ANGLE AND SCAN TYPE

The RedTail system was designed with an optimum scan angle of 40 degrees, which enhances accuracy and data quality. In addition to side-to-side scanning, the RedTail system can operate in raster scanning mode which allows detailed images to be captured while stationary.