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Estimation of Markov Regime-Switching Regression Models with Endogenous Switching

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Estimation of Markov Regime-Switching Regression Models with Endogenous Switching

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Abstract

Following Hamilton (1989), estimation of Markov regime-switching regressions typically relies on the assumption that the latent state variable controlling regime change is exogenous. We relax this assumption and develop a parsimonious model of endogenous Markov regime-switching. Inference via maximum likelihood estimation is possible with relatively minor modifications to existing recursive filters. The model nests the exogenous switching model, yielding straightforward tests for endogeneity. In Monte Carlo experiments, maximum likelihood estimates of the endogenous switching model parameters were quite accurate, even in the presence of certain model misspecifications. As an application, we extend the volatility feedback model of equity returns given in Turner, Startz and Nelson (1989) to allow for endogenous switching.

Keywords: Endogeneity, Regime-Switching JEL Classification: C13, C22, G12

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 Recent decades have seen extensive interest in time-varying parameter models of macroeconomic and financial time series. One notable set of models are regime-switching regressions, which date to at least Quandt (1958). Goldfeld and Quandt (1973) introduced a particularly useful version of these models, referred to in the following as a Markov-switching model, in which the latent state variable controlling regime shifts follows a Markov-chain, and is thus serially dependent. In an influential article, Hamilton (1989) extended Markov-switching models to the case of dependent data, specifically an autoregression.

The vast literature generated by Hamilton (1989) typically assumes that the regime shifts are exogenous with respect to all realizations of the regression disturbance. In this paper we work with Markov-switching regressions of the type considered by Hamilton (1989) and various extensions, but relax the exogenous switching assumption. We develop a model of endogenous Markov regime-switching that is based on a probit specification for the realization of the latent state. The model is quite parsimonious, and admits a test for endogenous switching as a simple parameter restriction. The model parameters can be estimated via maximum likelihood with relatively minor modifications to the recursive filter in Hamilton (1989).

Why are we motivated to investigate Markov-switching regressions with endogenous switching? Many of the model's applications are in macroeconomics or finance in situations where it is natural to assume the state is endogenous. As an example, it is often the case that the estimated state variable has a strong business cycle correlation. This can be seen in recent applications of the regime-switching model to identified monetary VARs, such as Sims and Zha (2002) and Owyang (2002). It is not hard to imagine that the shocks to the regression, such as the macroeconomic shocks to the VAR, would be correlated with the business cycle. As another example, some applications of the model contain parameters that represent the reaction

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of agents to realization of the state (see for example Turner, Startz and Nelson, 1989). However, it is likely that agents do not observe the state, but instead draw inference based on some information set, the contents of which are unknown to the econometrician. Use of the actual state to proxy for this inference leads to a regression with measurement error in the explanatory variables, and thus endogeneity.

In order to evaluate the performance of maximum likelihood estimates of the endogenous switching model parameters, as well as tests for endogenous switching, we conduct a battery of Monte Carlo experiments. These experiments suggest that: 1) When the true Markov-switching process is endogenous, maximum likelihood estimation assuming exogenous switching yields biased parameter estimates, 2) Maximum likelihood estimates of the endogenous switching model were close to their true values, as were quasi-maximum likelihood estimates obtained from data generated by a non-Gaussian endogenous switching model, and 3) The likelihood ratio test for endogenous switching was close to having correct size.

As an application, we extend the volatility feedback model of equity returns given in Turner, Startz and Nelson (1989) to allow for endogenous switching. As discussed above, this model provides a setting in which we might reasonably expect the Markov-switching state variable to be endogenous. We find strong statistical evidence for endogenous switching in the model and that allowing for endogeneity has substantial effects on parameter estimates.

It should be noted that the model of endogenous switching developed in this paper has much in common with an earlier literature using switching regressions. This earlier literature, such as Maddala and Nelson (1975), was often concerned with endogenous switching, as the primary applications were in limited dependent variable contexts such as self-selection and market disequilibrium settings. The model we have presented here can be interpreted as an

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extension of the Maddala and Nelson (1975) approach, which was a model of independent switching, to the Hamilton (1989) regime-switching model, in which the state process is serially dependent.

In the next section we lay out a two-regime Markov-switching regression model with endogenous switching and discuss maximum likelihood estimation. Section 3 generalizes this model to the *N*-regime case. Section 4 gives the results of Monte Carlo experiments evaluating the performance of parameter inference and tests for endogenous switching. In Section 5 we present an empirical example based on a model of volatility feedback in equity markets taken from Turner, Startz and Nelson (1989). Section 6 concludes.

2. A Two-Regime Endogenous Switching Model

2.1 Model Specification

Consider the following Gaussian regime-switching model for the sample path of a time series, $\{y_t\}_{t=1}^T$:

$$
y_t = x_t \beta_{S_t} + \sigma_{S_t} \varepsilon_t,
$$

\n
$$
\varepsilon_t \sim i.i.d.N(0,1),
$$
\n(2.1)

where y_t is scalar, x_t is a ($k \times 1$) vector of observed exogenous or predetermined explanatory variables, which may include lagged values of y_t , and $S_t = i$ is the state variable. Denote the number of regimes by *N*, so that $i = 1, 2, ..., N$. We begin with the case where $N = 2$. In addition to aiding intuition, the two-regime case is a popular specification in applied work.¹

The state variable is unobserved and is assumed to evolve according to a Markov chain with transition probabilities:

$$
P(S_t = i | S_{t-1} = j, z_t) = P_{ij}(z_t).
$$
\n(2.2)

In (2.2), the transition probabilities are influenced by a $(q \times 1)$ vector of observed exogenous or predetermined variables z_t , where z_t may include elements of x_t . The Markov chain is assumed to evolve independently of all observations of those elements of x_t not included in z_t . We assume the Markov process is stationary, with unconditional probabilities

$$
P(S_t = i | \overline{z}) = P(S = i | \overline{z}), \forall t.^2
$$

The transition probabilities (2.2) are constrained to be in $[0,1]$ using a probit specification for S_t :

$$
S_{t} = \begin{cases} 1 & \text{if } \eta_{t} < (a_{s_{t-1}} + z_{t} b_{s_{t-1}}) \\ 2 & \text{if } \eta_{t} \ge (a_{s_{t-1}} + z_{t} b_{s_{t-1}}) \end{cases},
$$
(2.3)

¹ As the regime ordering is arbitrary, we assume that the model in 2.1 is appropriately normalized to achieve identification. See Hamilton, Waggoner and Zha (2004) for detailed discussion of this issue.

² Several special cases of (2.2) are worth mentioning. The unrestricted model is the time-varying transition probability Markov-switching model of Goldfeld and Quandt (1973), Diebold, Lee and Weinbach (1994) and Filardo (1994). When the transition probabilities are not influenced by S_{t-1} , we have the time-varying transition probability independent switching model of Goldfeld and Quandt (1972). When the transition probabilities are not influenced by *^t z* , we have the fixed transition probability Markov-switching model of Goldfeld and Quandt (1973) and Hamilton (1989). When the transition probabilities are influenced by neither z_t or S_{t-1} , we have the fixed transition probability independent switching model of Quandt (1972).

$$
\eta_t \sim i.i.d.N(0,1).
$$

The transition probabilities are then:

$$
p_{1j}(z_t) = P(\eta_t < (a_j + z_i b_j)) = \Phi(a_j + z_i b_j),
$$

\n
$$
p_{2j}(z_t) = P(\eta_t \ge (a_j + z_i b_j)) = 1 - \Phi(a_j + z_i b_j),
$$
\n(2.4)

where Φ is the standard normal cumulative distribution function.

To model endogenous switching, assume that the joint density function of ε_t and η_t is bivariate normal:

$$
\begin{bmatrix} \varepsilon_t \\ \eta_t \end{bmatrix} \sim N(0, \Sigma), \quad \Sigma = \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix},
$$
\n(2.5)

where ε_t and η_{t-h} are uncorrelated $\forall h \neq 0$. Regime-switching models found in time-series applications nearly always make the assumption that ε _{*t*} is independent of S _{*t*-*h*}, \forall *h*, which corresponds to the restriction that $\rho = 0$ in the model presented here.³

³ In recent work, Chib and Dueker (2004) develop a non-Markov regime switching model in which observable variables are related to the sign of a Gaussian autoregressive latent state variable, the innovations to which are allowed to be correlated with the model residual through a bivariate normal specification as in (2.5). The authors develop Bayesian procedures to estimate this model.

2.2 Maximum Likelihood Estimation

Let
$$
\Omega_t = (x_t, x_{t-1},..., x_1, z_t, z_{t-1},..., z_1)
$$
 and $\xi_t = (y_t, y_{t-1},..., y_1)$ be vectors containing

observations observed through date *t*, and $\theta = (\beta_1, \sigma_1, a_1, b_1, \beta_2, \sigma_2, a_2, b_2, \rho)$ be the vector of model parameters. The conditional likelihood function for the observed data ζ_t is constructed as

$$
L(\theta) = \prod_{t=1}^{T} f(y_t | \Omega_t, \xi_{t-1}; \theta), \text{ where:}
$$

$$
f(y_t | \Omega_t, \xi_{t-1}; \theta)
$$

= $\sum_i \sum_j f(y_t | S_t = i, S_{t-1} = j, \Omega_t, \xi_{t-1}; \theta) \Pr(S_t = i, S_{t-1} = j | \Omega_t, \xi_{t-1}; \theta).$ (2.6)

The weighting probability in (2.6) is computed recursively by applying Bayes' Rule given the initial unconditional probabilities $P(S_0 = i | \bar{z}) = P(S = i | \bar{z})$:

$$
Pr(S_{t} = i, S_{t-1} = j | \Omega_{t}, \xi_{t-1}; \theta) = P_{ij}(z_{t}) Pr(S_{t-1} = j | \Omega_{t}, \xi_{t-1}; \theta),
$$
\n
$$
Pr(S_{t} = i | \Omega_{t+1}, \xi_{t}; \theta) = Pr(S_{t} = i | \Omega_{t}, \xi_{t}; \theta)
$$
\n
$$
= \frac{1}{f(y_{t} | \Omega_{t}, \xi_{t-1}; \theta)} \sum_{j} f(y_{t} | S_{t} = i, S_{t-1} = j, \Omega_{t}, \xi_{t-1}; \theta) Pr(S_{t} = i, S_{t-1} = j | \Omega_{t}, \xi_{t-1}; \theta).
$$
\n(2.7)

 To complete the recursion in (2.6)-(2.7), we require the regime-dependent conditional density function, $f(y_t | S_t = i, S_{t-1} = j, \Omega_t, \xi_{t-1}; \theta)$. For the exogenous switching case, when $\rho = 0$, this density function is Gaussian:

$$
f(y_t | S_t = i, S_{t-1} = j, \Omega_t, \xi_{t-1}; \theta) = \frac{1}{\sigma_i} \phi \left(\frac{y_t - x_t^* \beta_i}{\sigma_i} \right),
$$
\n(2.8)

where ϕ is the standard normal probability density function. However, for more general values of $\rho \in (-1,1)$, $f(y_t | S_t = i, S_{t-1} = j, \Omega_t, \xi_{t-1}; \theta)$ is:⁴

$$
f(y_{t} | S_{t} = 1, S_{t-1} = j, \Omega_{t}, \xi_{t-1}; \theta) = \frac{\phi\left(\frac{y_{t} - x_{t} \beta_{1}}{\sigma_{1}}\right) \phi\left(\frac{(a_{j} + z_{t} b_{j}) - \rho\left(\frac{y_{t} - x_{t} \beta_{1}}{\sigma_{1}}\right)}{\sqrt{1 - \rho^{2}}}\right)}{\sigma_{1} p_{1j}(z_{t})}, \qquad (2.9)
$$
\n
$$
f(y_{t} | S_{t} = 2, S_{t-1} = j, \Omega_{t}, \xi_{t-1}; \theta) = -\frac{\phi\left(\frac{y_{t} - x_{t} \beta_{2}}{\sigma_{2}}\right) \phi\left(\frac{-(a_{j} + z_{t} b_{j}) + \rho\left(\frac{y_{t} - x_{t} \beta_{2}}{\sigma_{2}}\right)}{\sqrt{1 - \rho^{2}}}\right)}{\sqrt{1 - \rho^{2}}}
$$

$$
f(y_t | S_t = 2, S_{t-1} = j, \Omega_t, \xi_{t-1}; \theta) = \frac{\sigma_2 p_{2j}(z_t)}{\sigma_2 p_{2j}(z_t)}
$$

The appendix provides a derivation of (2.9).

When S_t is endogenous, maximum likelihood estimation assuming S_t is exogenous, and thus based on the distribution in (2.8), is inconsistent in general. To see this, note that:

$$
E(\varepsilon_{i} | S_{i} = 1, S_{i-1} = j; \theta) = E(\varepsilon_{i} | \eta_{i} < (a_{j} + z_{i}b_{j})) = -\rho \frac{\phi(a_{j} + z_{i}b_{j})}{\Phi(a_{j} + z_{i}b_{j})},
$$
\n
$$
E(\varepsilon_{i} | S_{i} = 2, S_{i-1} = j; \theta) = E(\varepsilon_{i} | \eta_{i} \geq (a_{j} + z_{i}b_{j})) = \rho \frac{\phi(a_{j} + z_{i}b_{j})}{1 - \Phi(a_{j} + z_{i}b_{j})}.
$$
\n(2.10)

⁴ The density (2.9) belongs to the "skew-normal" family of density functions, which are commonly credited to Azzalini (1985). See Arnold and Beaver (2002) for a survey of this literature.

Thus, when $\rho \neq 0$, the regime-dependent conditional mean of ε _t is non-zero, implying that maximum likelihood estimates based on (2.8) suffer from the ordinary problem of omitted variables. Another, less obvious, source of inconsistency arises because

 $f(y_t | S_t = i, S_{t-1} = j, \Omega_t, \xi_{t-1}$; θ) is non-Gaussian when $\rho \neq 0$, as is clear from (2.9). In this case maximum likelihood estimation based on (2.8) is Quasi-maximum likelihood estimation, which, as pointed out in Campbell (2002), is inconsistent for regime-switching models in general.

2.3 Testing for Endogeneity

In the model of endogenous switching presented above, the null hypothesis that S_t is exogenous is equivalent to the scalar restriction $\rho = 0$. Thus, a test for exogeneity can be carried out by any suitable test of the restriction $\rho = 0$, such as a Wald or likelihood ratio test.

3. An N-Regime Endogenous Switching Model

 In this section we generalize the two-regime Gaussian endogenous-switching model presented in Section 2 to *N* regimes. We begin by modifying the probit specification of the transition probabilities given in (2.3). Suppose the realization of S_t is now determined by the outcome of $\eta_i \sim i.i.d.N(0,1)$ as follows:

$$
S_{t} = \begin{cases} 1 & \text{if } & -\infty & \leq \eta_{t} < (a_{1,j} + z_{t}b_{1,j}) \\ 2 & \text{if } & (a_{1,j} + z_{t}b_{1,j}) & \leq \eta_{t} < (a_{2,j} + z_{t}b_{2,j}) \\ \vdots & & \\ N-1 & \text{if } (a_{N-2,j} + z_{t}b_{N-2,j}) \leq \eta_{t} < (a_{N-1,j} + z_{t}b_{N-1,j}) \\ N & \text{if } (a_{N-1,j} + z_{t}b_{N-1,j}) \leq \eta_{t} < \infty \end{cases}
$$
(3.1)

The transition probabilities, $p_{ij}(z_t)$, are then given as follows:

$$
p_{ij}(z_t) = \Phi(c_{i,j,t}) - \Phi(c_{i-1,j,t}),
$$
\n(3.2)

where $c_{0,j,t} = -\infty$, $c_{N,j,t} = \infty$, and $c_{i,j,t} = (a_{i,j} + z_i b_{i,j})$ for $0 < i < N$.

Again, to model endogenous switching, assume that the joint density of ε_t and η_t is bivariate normal as in (2.5):

$$
\begin{bmatrix} \varepsilon_i \\ \eta_i \end{bmatrix} \sim N(0, \Sigma), \quad \Sigma = \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix}, \tag{2.5}
$$

where ε_t and η_{t-h} are uncorrelated $\forall h \neq 0$. Let the vector of model parameters be $\theta = (\theta_1, \theta_2, ..., \theta_N, \rho)$, where $\theta_i = (\beta_i, \sigma_i, a_i, b_i)$. Given $f(y_i | S_i = i, S_{i-1} = j, \Omega_i, \xi_{i-1}; \theta)$, the likelihood function, $L(\theta)$, can again be constructed using the recursion in (2.6)-(2.7). It is

shown in the appendix that:

$$
f(y_t | S_t = i, S_{t-1} = j, \Omega_t, \xi_{t-1}; \theta)
$$

\n
$$
\phi\left(\frac{y_t - x_t \beta_i}{\sigma_i}\right) \left(\phi\left(\frac{c_{i,j,t} - \rho\left(\frac{y_t - x_t \beta_i}{\sigma_i}\right)}{\sqrt{1 - \rho^2}}\right) - \phi\left(\frac{c_{i-1,j,t} - \rho\left(\frac{y_t - x_t \beta_i}{\sigma_i}\right)}{\sqrt{1 - \rho^2}}\right)\right)
$$

\n
$$
= \frac{\sigma_i p_{ij}(z_t)}{\sigma_i}
$$
\n(3.3)

Finally, as with the two regime endogenous switching model, a test of the null hypothesis that *S^t* is exogenous is equivalent to a test of the restriction $\rho = 0$.

4. Monte Carlo Analysis

In this section we provide Monte Carlo evidence regarding maximum likelihood estimation of the endogenous switching model and associated tests for endogeneity. Given its prominence in the applied literature, we focus on the two-regime model with fixed, Markovswitching transition probabilities, so that $b_1 = b_2 = 0$. We begin by evaluating the performance of maximum likelihood estimation when the true model is the endogenous switching model presented in Section 2 with varying levels of ρ . We then investigate the sensitivity of maximum likelihood estimation based on the joint normality assumption in (2.5) to departures from this Gaussian assumption in the data generating process. Such a departure renders the estimator based on (2.5) a Quasi-maximum likelihood (QML) estimator, which is inconsistent for Markov-switching models in general. Our Monte Carlo experiments then provide some limited evidence of how badly the QML estimator performs in practice.

For each Monte Carlo experiment, 1000 simulated series are generated from the model given in (2.1)-(2.3). We consider two sample sizes for the simulated series, $T = 200$ and $T = 500$.

For each simulation, we generate the vector of exogenous explanatory variables as $x_t = \begin{bmatrix} 1 & x_t^* \end{bmatrix}$, where $x_t^* \sim i.i.d.N(0,2)$, and fix the vector of regime switching parameters to $\beta_1 = (\beta_{0,1}, \beta_{1,1})^T$ $=(1.0,1.0)$, $\beta_2 = (\beta_{0,2}, \beta_{1,2}) = (-1.0, -1.0)$, $\sigma_1 = 0.33$, $\sigma_2 = 0.67$. We consider three different sets of transition probabilities corresponding to moderate persistence ($p_{11} = 0.7$, $p_{22} = 0.7$), high persistence ($p_{11} = 0.9$, $p_{22} = 0.9$), and differential persistence ($p_{11} = 0.7$, $p_{22} = 0.9$). We also consider three different values for ρ , corresponding to high correlation $\rho = 0.9$, moderate correlation $\rho = 0.5$, and zero correlation $\rho = 0$.

We consider two different joint density functions for ε_t and η_t , labeled DGP1 and DGP2. DGP1 is the bivariate normal distribution in (2.5). DGP2 relaxes this joint normality assumption. Instead, ε_t is generated as a standard normal random variable, while η_t is generated as a weighted sum of ε _t and a *t*-distributed random variable with four degrees of freedom. The weighting is calibrated so that (ε_t, η_t) has covariance matrix:

$$
\Sigma = \begin{bmatrix} 1 & \rho \gamma_4 \\ \rho \gamma_4 & \gamma_4^2 \end{bmatrix},
$$

where $\gamma_4^2 = 2$ is the variance of a *t*-distributed random variable with four degrees of freedom.

For each simulated time series, two maximum likelihood estimates and associated standard errors are computed.⁵ The first, which we label the "exogenous" estimator, assumes that $\rho = 0$, and is thus based on the recursion in (2.6)-(2.7), using (2.8) to measure

⁵ All computations were performed in GAUSS 6.0 using the OPTMUM numerical optimization package. Standard errors were based on second derivatives of the log-likelihood function.

 $f(y_t | S_t = i, S_{t-1} = j, \Omega_t, \xi_{t-1}; \theta)$. The second, which we label the "endogenous" estimator, allows for $\rho \neq 0$, and is thus based on the recursion in (2.6)-(2.7), using (2.9) to measure $f(y_t | S_t = i, S_{t-1} = j, \Omega_t, \xi_{t-1}; \theta)$. Finally, we also record the outcome of 5% nominal size Wald and likelihood ratio tests of the null hypothesis $\rho = 0$. For those cases where $\rho = 0$ in the data generating process, these tests document the empirical size of the 5% nominal size tests. For those cases where $\rho \neq 0$, we use size-adjusted critical values, taken from the Monte Carlo simulations generated with $\rho = 0$, to measure the power of the tests.

Tables 1-5 show the results of the Monte Carlo experiments investigating maximum likelihood estimation of the endogenous switching model. Each table shows the mean of the 1000 maximum likelihood point estimates of β_1 , β_2 , σ_1 , σ_2 , the mean of the standard errors for these parameter estimates, and the rejection rate of the tests of $\rho = 0.^6$ Table 1 gives results when the data generating process has exogenous switching, that is $\rho = 0$. In this case, both the exogenous and endogenous estimator are exact maximum likelihood estimators, but the endogenous estimator is inefficient, as it does not restrict $\rho = 0$. As is clear from the table, for both sample sizes and all values of the transition probabilities, the exogenous and endogenous estimators produce estimates of the model parameters that are very close to their true values. As would be expected, the endogenous estimator is less efficient than the exogenous estimator, with the average standard error of the estimates consistently higher for the endogenous estimator.

Tables 2 and 3 give results when the true data generating process includes endogenous switching of the form in DGP1. The tables demonstrate the estimation bias that occurs when the endogenous state variable is treated as exogenous in estimation. When the exogenous estimator

is used, the mean estimates of $\beta_{0,1}$ and $\beta_{0,2}$ are far from their true values, with the bias larger for higher values of ρ . The mean estimates of σ_1 and σ_2 are also biased downward. Note that the mean estimates are nearly identical in the $T = 200$ and $T = 500$ cases, suggesting the bias is not a small sample phenomenon. Also note that the estimates of $\beta_{1,1}$ and $\beta_{1,2}$ are close to their true values. The accuracy of these parameter estimates can be traced to the model assumption, maintained in the Monte Carlo samples, that x_t^* is independent of the endogenous state variable *St* . Finally, Tables 2 and 3 also demonstrate that the endogenous estimator produces very accurate estimates of the endogenous switching model. Indeed, for both sample sizes and all values of the transition probabilities and ρ considered, the mean parameter estimates are nearly identical to their true values.

Tables 4 and 5 present results for DGP2, that is when the joint density between ε_t and η_t is non-normal. For the particular joint density function considered, the approximation provided by the normality assumption is quite good. Again, for both sample sizes and all values of the transition probabilities and ρ considered, the mean parameter estimates from the endogenous estimator are very close to their true values. While this result may not generalize to non-normal distributions more generally, it is suggestive that the quality of the endogenous estimator procedure is not hyper-sensitive to the joint-normality assumption. Not surprisingly, the exogenous estimator, which ignores the potential for the state variable to be endogenous all together, continues to produce biased parameter estimates under DGP2.

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⁶ Model estimation also produces estimates of the transition probabilities, and, in the case of the endogenous estimator, the correlation parameter ρ . Although not reported, results for these parameter estimates are qualitatively similar to those for the conditional mean and variance parameters of the regression model.

 Tables 6 and 7 report the empirical size and size-adjusted power of the Wald and likelihood ratio test of $\rho = 0$. From Table 6, the 5% Wald test is somewhat oversized, with rejection rates as high as 12% when $T = 200$. However, the 5% likelihood ratio test has roughly correct size for both sample sizes considered. Table 7 demonstrates that the likelihood ratio and Wald test have similar size-adjusted power against the alternatives considered.

Overall, the Monte Carlo experiments confirm that maximum likelihood estimates using the endogenous estimator are quite good for the examples considered, while the exogenous estimator produces substantially biased parameter estimates when the true process has endogenous switching. Also, the likelihood ratio test appears to be a fairly reliable test for endogenous switching. In the next section we turn to an empirical application of the endogenous switching model.

5. Application: Measurement Error and Estimation of the Volatility Feedback Effect

A stylized fact of U.S. equity return data is that the volatility of realized returns is timevarying and predictable. Given this, classic portfolio theory would imply that the equity risk premium should also be time-varying and respond positively to the expectation of future volatility. However, the data suggest that realized returns and realized volatility, as measured by squared returns, are negatively correlated.⁷

One explanation for the observed data is that while investors do require an increase in expected return in exchange for expected future volatility, they are often surprised by news about realized volatility. This "volatility feedback effect" creates a reduction in prices in the period in which the increase in volatility is realized. If the volatility feedback effect is strong enough, it

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 7 For a recent discussion of this result, see Brandt and Kang (2004).

may create a negative contemporaneous correlation between realized returns and volatility in the data. The volatility feedback effect has been investigated extensively in the literature, see for example French, Schwert and Stambaugh (1987), Turner, Startz and Nelson (1989), Campbell and Hentschell (1992), Bekaert and Wu (2000) and Kim, Morley and Nelson (2002).

Turner, Startz and Nelson (1989), hereafter TSN, model the volatility feedback effect with a Markov-switching model:

$$
r_{t} = \theta_{1} E \Big(\sigma_{S_{t}}^{2} \mid \Psi_{t-1} \Big) + \theta_{2} \Big(E \Big(\sigma_{S_{t}}^{2} \mid \Psi_{t}^{*} \Big) - E \Big(\sigma_{S_{t}}^{2} \mid \Psi_{t-1} \Big) \Big) + \sigma_{S_{t}} \varepsilon_{t},
$$
\n
$$
\varepsilon_{t} \sim i.i.d.N(0,1),
$$
\n(5.1)

where S_t is a discrete Markov-switching variable taking on values 1 or 2, with transition probabilities p_{ij} parameterized as in equation (2.4). For normalization we assume $\sigma_2^2 > \sigma_1^2$, so that $S_t = 2$ is the high volatility state.

 The model in (5.1) is motivated as follows. At the beginning of period *t*, the risk premium, $\theta_1 E(\sigma_{S_t}^2 \mid \Psi_{_{t-1}})$, $\theta_1 E(\sigma_{S_t}^2 | \Psi_{t-1})$, is determined based on the expectation of period *t* volatility formed with information available at the end of period *t-*1. During period *t* additional information regarding volatility is observed. By the end of period *t*, this information is collected in the information set Ψ_t^* . When $E(\sigma_{S_t}^2 | \Psi_t^*) \neq$ $E(\sigma_{S_t}^2 | \Psi_t^*) \neq E(\sigma_{S_t}^2 | \Psi_{t-1})$, information about volatility revealed during the period has surprised agents. If $\theta_2 < 0$, surprises that reveal greater probability of the high-variance state are viewed negatively by investors, and thus reduce the contemporaneous return.

 One estimation difficulty with the model in (5.1) is that there exists a discrepancy between the investors' and the econometrician's data set. In particular, while Ψ_{*t*−1} may be summarized by all data up to *t*-1, that is $\Psi_t = \{r_{t-1}, r_{t-2}, ...\}$, the information set Ψ_t^* includes information that is not summarized in the researcher's data set on observed returns. This is because, while the researcher's data set is collected discretely at the beginning of each period, the market participants continuously observe trades that occur during the period.

To handle this estimation difficulty, TSN use the actual volatility, $\sigma_{S_t}^2$, as a proxy for $E(\sigma_{S_t}^2 | \Psi_t^*)$. That is, they estimate:

$$
r_{t} = \theta_{1} E \Big(\sigma_{S_{t}}^{2} \mid \Psi_{t-1} \Big) + \theta_{2} \Big(\sigma_{S_{t}}^{2} - E \Big(\sigma_{S_{t}}^{2} \mid \Psi_{t-1} \Big) \Big) + \sigma_{S_{t}} u_{t}
$$
\n
$$
u_{t} \sim N(0,1)
$$
\n
$$
(5.2)
$$

In essence, this approximation replaces the estimated probability of the state, $P(S_t = i | \Psi_t^*)$, with one if $S_t = i$ and zero otherwise. Assuming these differ, this introduces classical measurement error into the state variable in the estimated equation, thus rendering it endogenous.

 The existing literature estimates (5.2) assuming the state variable is exogenous. However, the techniques developed in Section 2 can be used to estimate the volatility feedback model allowing for endogeneity, as well as to test for endogeneity. Here we estimate (5.2) using monthly returns for a value-weighted portfolio of all NYSE-listed stocks in excess of the onemonth Treasury Bill rate over the sample period 1952-1999, the same data as used in Kim, Morley and Nelson (2002). Table 8 summarizes the results.

The first panel of Table 8 shows estimates when endogeneity is ignored. These estimates, which are similar to those in TSN, are consistent with both a positive relationship between the risk premium and expected future volatility ($\theta_1 > 0$) and a substantial volatility feedback effect ($\theta_2 \ll 0$). The estimates also suggest a dominant volatility feedback effect, that is θ_1 is very small relative to θ_2 . The second panel shows the estimates when endogeneity is allowed, so that the correlation parameter ρ is estimated. The estimate of ρ is substantial, equaling -0.40. Both the Wald and likelihood ratio test reject the null hypothesis that $\rho = 0$ at the 10% level (the p-values are 0.026 and 0.081 respectively). The primary difference in the parameter estimates is for the volatility feedback coefficient θ_2 , which is estimated to be about one-third smaller when endogeneity is allowed than when it is ignored. Thus, while there is still evidence of a strong volatility feedback effect, it is substantially smaller than that implied by the model with no allowance for endogeneity.

6. Conclusion

We have developed a model of Markov-switching in which the latent state variable controlling the regime shifts is endogenously determined. The model is quite parsimonious, and admits a test for endogenous switching as a simple parameter restriction. The model parameters can be estimated via maximum likelihood with relatively small modifications to the recursive filter in Hamilton (1989). Monte Carlo experiments suggest that maximum likelihood estimation of the endogenous switching model and the likelihood ratio test for endogeneity performed quite well for the data generating processes considered. We apply the model to test for endogenous switching in the volatility feedback model of equity returns given in Turner, Startz and Nelson (1989).

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Appendix

Derivation of (2.9) and (3.3):

We proceed by generalizing the derivation of the univariate skew-normal density function given in Arnold and Beaver (2002). The random variables described in (2.5) can be written as:

$$
\begin{bmatrix} \varepsilon_t \\ \eta_t \end{bmatrix} = A \begin{bmatrix} \varepsilon_t \\ \omega_t \end{bmatrix}, \tag{A.1}
$$

where $\omega_t \sim i.i.d.N(0,1)$, and $A = \begin{bmatrix} 1 & 0 \\ 0 & \sqrt{1 - \sigma^2} \end{bmatrix}$ ⎦ ⎤ I ⎣ $\mathsf L$ $=\begin{vmatrix} 1 & 0 \\ \rho & \sqrt{1-\rho^2} \end{vmatrix}$ 1 0 $\rho \sqrt{1-\rho}$ $A = \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{pmatrix}$ is the Cholesky decomposition of Σ , so that

 $AA' = \Sigma$. From (A.1):

$$
\eta_t = \rho \varepsilon_t + \sqrt{1 - \rho^2} \omega_t. \tag{A.2}
$$

We can then write, suppressing Ω_t , ξ_{t-1} , and θ from the conditioning set for convenience:

$$
f(y_t | S_t = i, S_{t-1} = j)
$$

= $f(y_t | (c_{i-1,j,t}) \le \eta_t < (c_{i,j,t})$)
= $f\left(y_t | \frac{(c_{i-1,j,t}) - \rho \varepsilon_t}{\sqrt{1 - \rho^2}} \le \omega_t < \frac{(c_{i,j,t}) - \rho \varepsilon_t}{\sqrt{1 - \rho^2}} \right)$, (A.3)

where $c_{i-1,j,t}$ and $c_{i,j,t}$ are defined in Section 3. Consider the cumulative probability distribution function:

$$
\Pr\left(y_{t} < g \mid \frac{(c_{i-1,j,t}) - \rho \varepsilon_{t}}{\sqrt{1 - \rho^{2}}} \leq \omega_{t} < \frac{(c_{i,j,t}) - \rho \varepsilon_{t}}{\sqrt{1 - \rho^{2}}}\right)
$$
\n
$$
= \frac{\Pr\left(y_{t} < g, \frac{(c_{i-1,j,t}) - \rho \varepsilon_{t}}{\sqrt{1 - \rho^{2}}} \leq \omega_{t} < \frac{(c_{i,j,t}) - \rho \varepsilon_{t}}{\sqrt{1 - \rho^{2}}}\right)}{\Pr\left(\frac{(c_{i-1,j,t}) - \rho \varepsilon_{t}}{\sqrt{1 - \rho^{2}}} \leq \omega_{t} < \frac{(c_{i,j,t}) - \rho \varepsilon_{t}}{\sqrt{1 - \rho^{2}}}\right)}
$$
\n(A.4)

The denominator of (A.4) is:

$$
\Pr\left(\frac{\left(c_{i-1,j,t}\right) - \rho \varepsilon_t}{\sqrt{1 - \rho^2}} \le \omega_t < \frac{\left(c_{i,j,t}\right) - \rho \varepsilon_t}{\sqrt{1 - \rho^2}}\right) = p_{ij}(z_t) = \Phi\left(c_{i,j,t}\right) - \Phi\left(c_{i-1,j,t}\right). \tag{A.5}
$$

The numerator of (A.4) is:

$$
\Pr\left(y_{t} < g, \frac{\left(c_{i-1,j,t}\right) - \rho \varepsilon_{t}}{\sqrt{1 - \rho^{2}}} \leq \omega_{t} < \frac{\left(c_{i,j,t}\right) - \rho \varepsilon_{t}}{\sqrt{1 - \rho^{2}}}\right)
$$
\n
$$
= \int_{-\infty}^{g} \int_{((c_{i-1,j,t}) - \rho \varepsilon_{t})/\sqrt{1 - \rho^{2}}}^{((c_{i,j,t}) - \rho \varepsilon_{t})/\sqrt{1 - \rho^{2}}} f(y_{t}, \omega_{t}) d\omega d\varepsilon
$$
\n
$$
= \int_{-\infty}^{g} \int_{((c_{i-1,j,t}) - \rho \varepsilon_{t})/\sqrt{1 - \rho^{2}}}^{((c_{i,j,t}) - \rho \varepsilon_{t})/\sqrt{1 - \rho^{2}}} \frac{1}{\sigma_{i}} \phi\left(\frac{y_{t} - x_{t}^{\prime} \beta_{t}}{\sigma_{i}}\right) f(\omega_{t}) d\omega d\varepsilon
$$

$$
= \int_{-\infty}^{s} \frac{1}{\sigma_i} \phi \left(\frac{y_i - x_i \beta_i}{\sigma_i} \right) \left(\Phi \left(\frac{c_{i,j,t} - \rho \left(\frac{y_i - x_i \beta_i}{\sigma_i} \right)}{\sqrt{1 - \rho^2}} \right) - \Phi \left(\frac{c_{i-1,j,t} - \rho \left(\frac{y_i - x_i \beta_i}{\sigma_i} \right)}{\sqrt{1 - \rho^2}} \right) \right) d\varepsilon. \tag{A.6}
$$

Combining (A.5)-(A.6) and differentiating with respect to *g* yields:

$$
f(y_t | S_t = i, S_{t-1} = j)
$$
\n
$$
\phi\left(\frac{y_t - x_t \beta_i}{\sigma_i}\right) \phi\left(\frac{c_{i,j,t} - \rho\left(\frac{y_t - x_t \beta_i}{\sigma_i}\right)}{\sqrt{1 - \rho^2}}\right) - \phi\left(\frac{c_{i-1,j,t} - \rho\left(\frac{y_t - x_t \beta_i}{\sigma_i}\right)}{\sqrt{1 - \rho^2}}\right)
$$
\n
$$
= \frac{\sigma_i p_{ij}(z_t)}{\sqrt{1 - \rho^2}},
$$
\n(3.3)

which is the density function (3.3). In the case where $N = 2$, we have:

$$
f(y_{t} | S_{t} = 1, S_{t-1} = j) = \frac{\phi\left(\frac{y_{t} - x_{t} \beta_{1}}{\sigma_{1}}\right) \phi\left(\frac{(a_{1, j} + z_{t} b_{1, j}) - \rho\left(\frac{y_{t} - x_{t} \beta_{1}}{\sigma_{1}}\right)}{\sqrt{1 - \rho^{2}}}\right)}{\sigma_{1} p_{1j}(z_{t})}
$$
\n
$$
f(y_{t} | S_{t} = 2, S_{t-1} = j) = \frac{\phi\left(\frac{y_{t} - x_{t} \beta_{2}}{\sigma_{2}}\right) \phi\left(\frac{-(a_{1, j} + z_{t} b_{1, j}) + \rho\left(\frac{y_{t} - x_{t} \beta_{2}}{\sigma_{2}}\right)}{\sqrt{1 - \rho^{2}}}\right)}{\sigma_{2} p_{2j}(z_{t})},
$$

which, upon renaming $a_{1,j} = a_j$ and $b_{1,j} = b_j$, is the density function in (2.9).

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Table 6 Monte Carlo Results: Empirical Size of 5% Nominal Size Test of $\rho = 0$

Table 7 Monte Carlo Results: Empirical Size-Adjusted Power of 5% Nominal Size Test of $\rho = 0$

$T = 200$ DGP 1, $\rho = 0.5$		Empirical Power: Wald Test Empirical Power: LR Test	
$p_{11} = 0.7$ $p_{22} = 0.7$		39.9%	46.3%
$p_{11} = 0.7$ $p_{22} = 0.9$		65.4%	67.0%
$p_{11} = 0.9$ $p_{22} = 0.9$		86.3%	85.8%
DGP 1, $\rho = 0.9$			
$p_{11} = 0.7$ $p_{22} = 0.7$		99.8%	100.0%
$p_{11} = 0.7$ $p_{22} = 0.9$		100.0%	99.9%
$p_{11} = 0.9$ $p_{22} = 0.9$		100.0%	100.0%
DGP 2, $\rho = 0.5$			
$p_{11} = 0.7$ $p_{22} = 0.7$		65.9%	68.1%
$p_{11} = 0.7$ $p_{22} = 0.9$		67.0%	69.2%
$p_{11} = 0.9$ $p_{22} = 0.9$		79.4%	79.7%
DGP 2, $\rho = 0.9$			
$p_{11} = 0.7$ $p_{22} = 0.7$		100.0%	100.0%
$p_{11} = 0.7$ $p_{22} = 0.9$		99.8%	99.8%
$p_{11} = 0.9$	$p_{22} = 0.9$	99.9%	99.9%

Table 7 (cont.)

Monte Carlo Results: Empirical Size-Adjusted Power of 5% Nominal Size Test for $\rho = 0$

Table 8 Maximum Likelihood Estimates of the Turner, Startz, and Nelson (1989) Volatility-Feedback Model

Notes: Maximum likelihood estimates computed in GAUSS 6.0 using the OPTMUM numerical optimization package. Standard errors, reported in parentheses, were based on second derivatives of the log-likelihood function.