

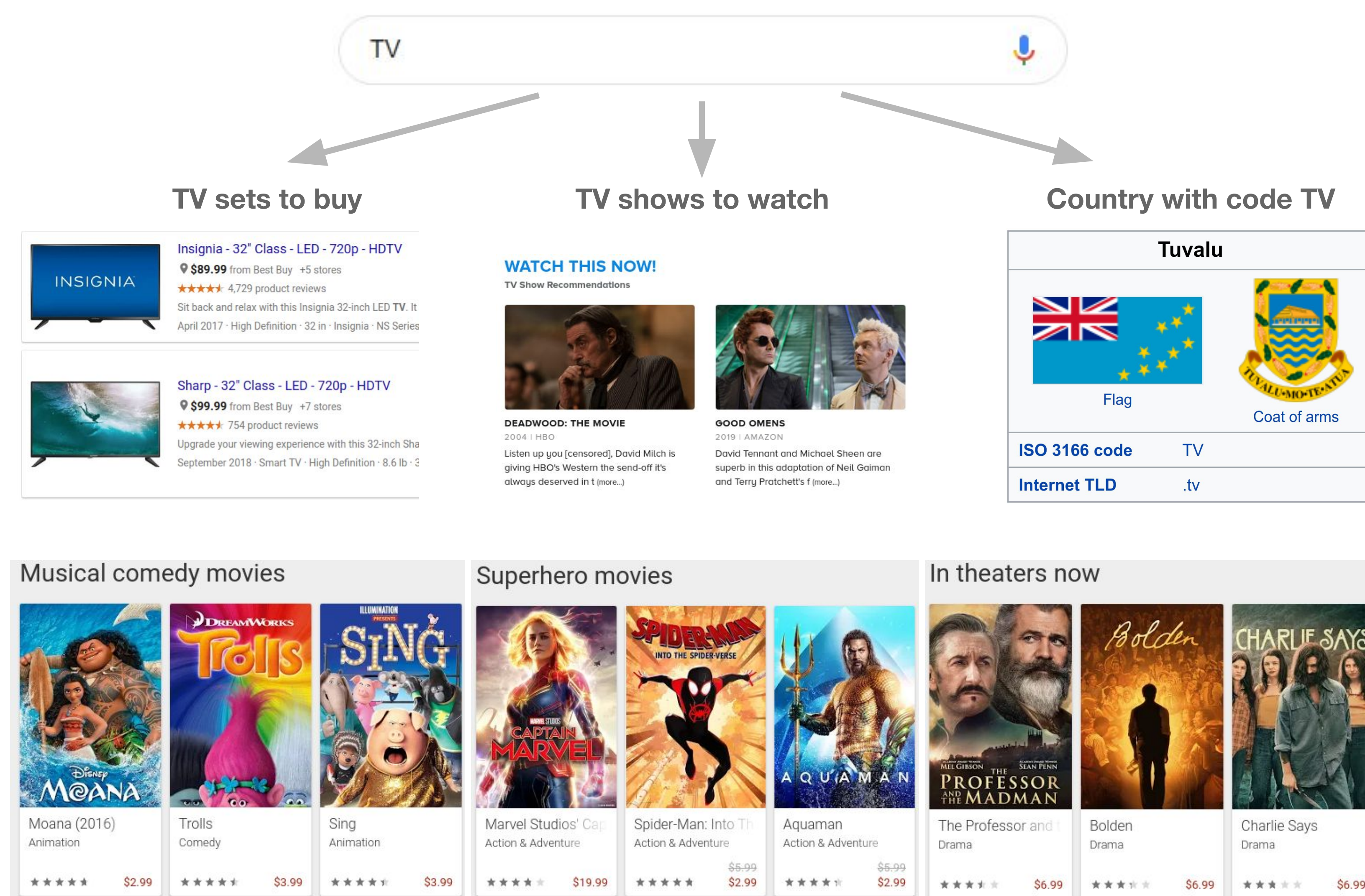
# A Tree-Based Method for Fast Repeated Sampling of Determinantal Point Processes

Jennifer Gillenwater<sup>1</sup>, Alex Kulesza<sup>1</sup>, Zelda Mariet<sup>1,2</sup>, Sergei Vassilvitskii<sup>1</sup>

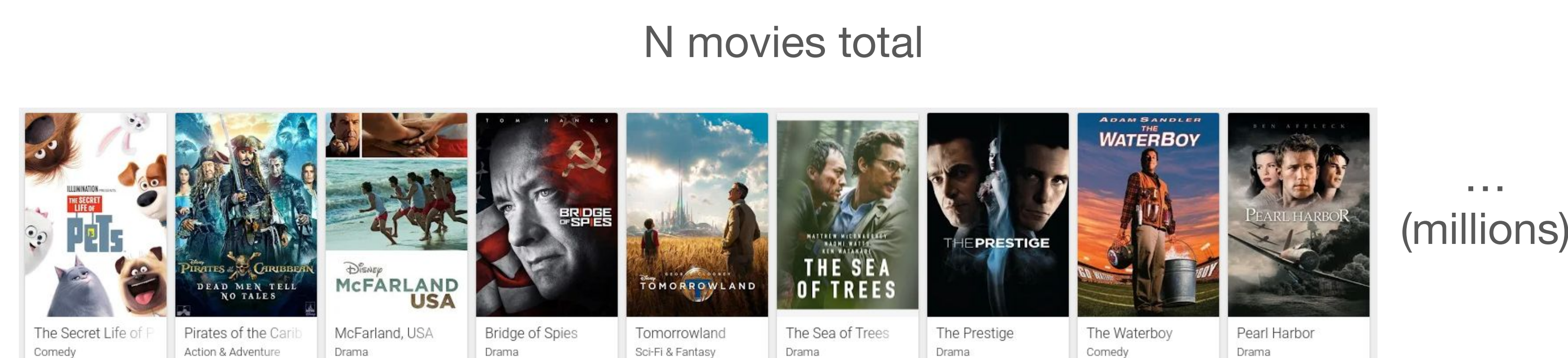
<sup>1</sup>Google Research NYC, <sup>2</sup>Massachusetts Institute of Technology

## Motivation

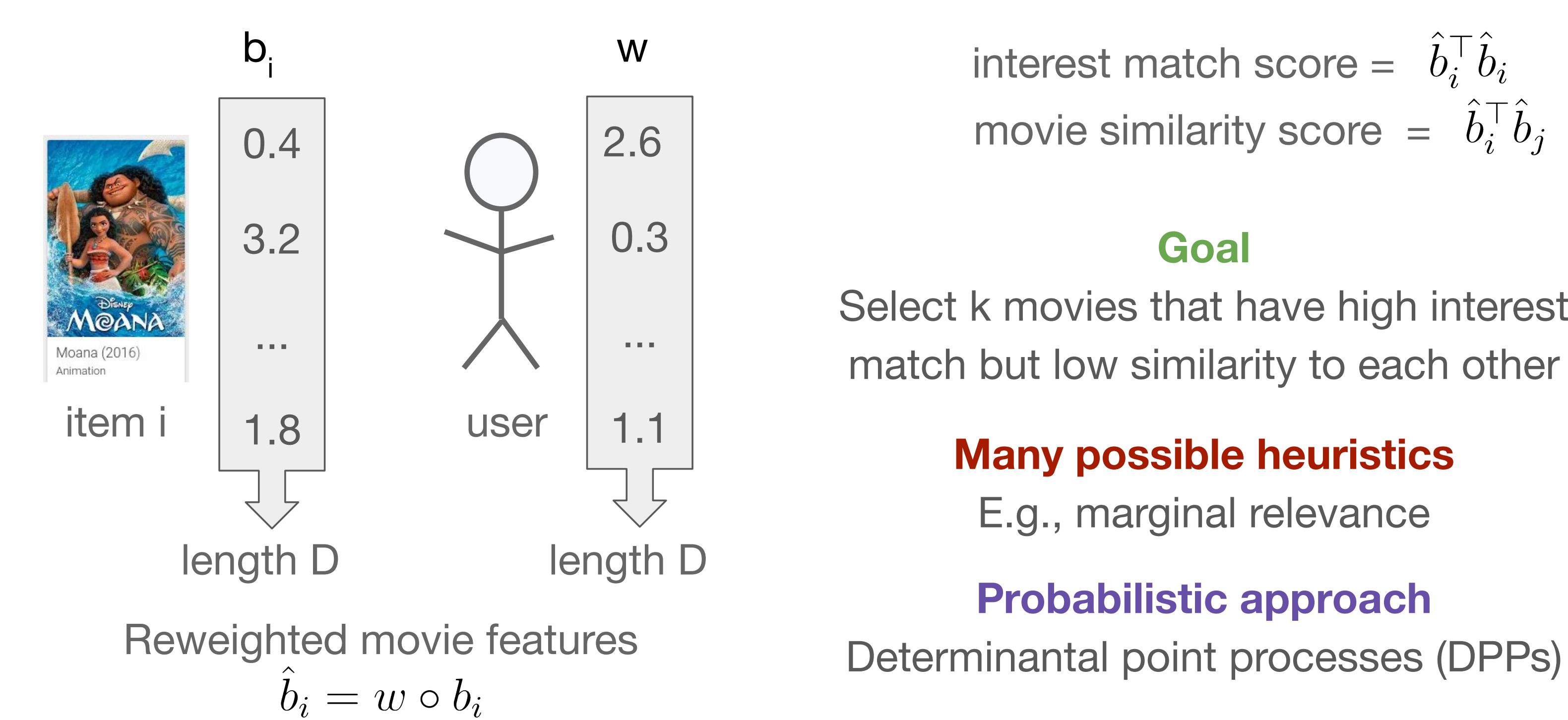
Diverse results are desirable in information retrieval and recommender systems



## Determinantal Point Processes



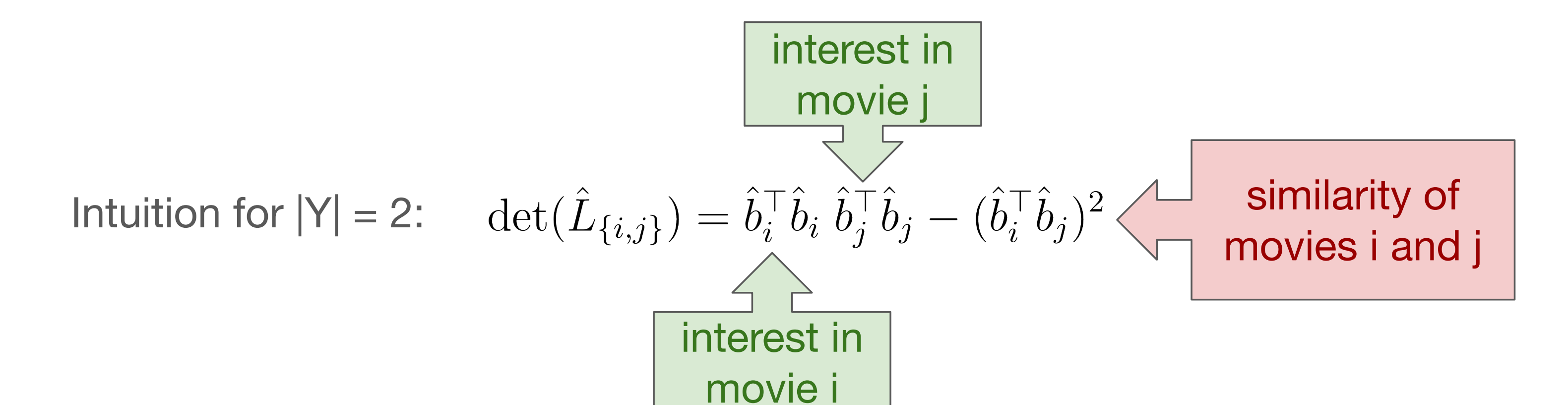
Goal: Select  $k \ll N$  movies to recommend to a user



Diagonal user matrix  $W \in \mathbb{R}^{D \times D}$   $\otimes$  Movie feature matrix  $B \in \mathbb{R}^{D \times N}$  = Re-weighted movie feature matrix  $\hat{B} = WB$

Positive semi-definite kernel  $\hat{L} = \hat{B}^T \hat{B}$ ,  $\hat{L}_{ij} = \hat{b}_i^T \hat{b}_j$

Distribution over all subsets  $Y \subseteq [N]$ :  $\mathcal{P}_L(Y) \propto \det(\hat{L}_Y)$   $\rightarrow$  determinantal point process (DPP)



## Sampling DPPs

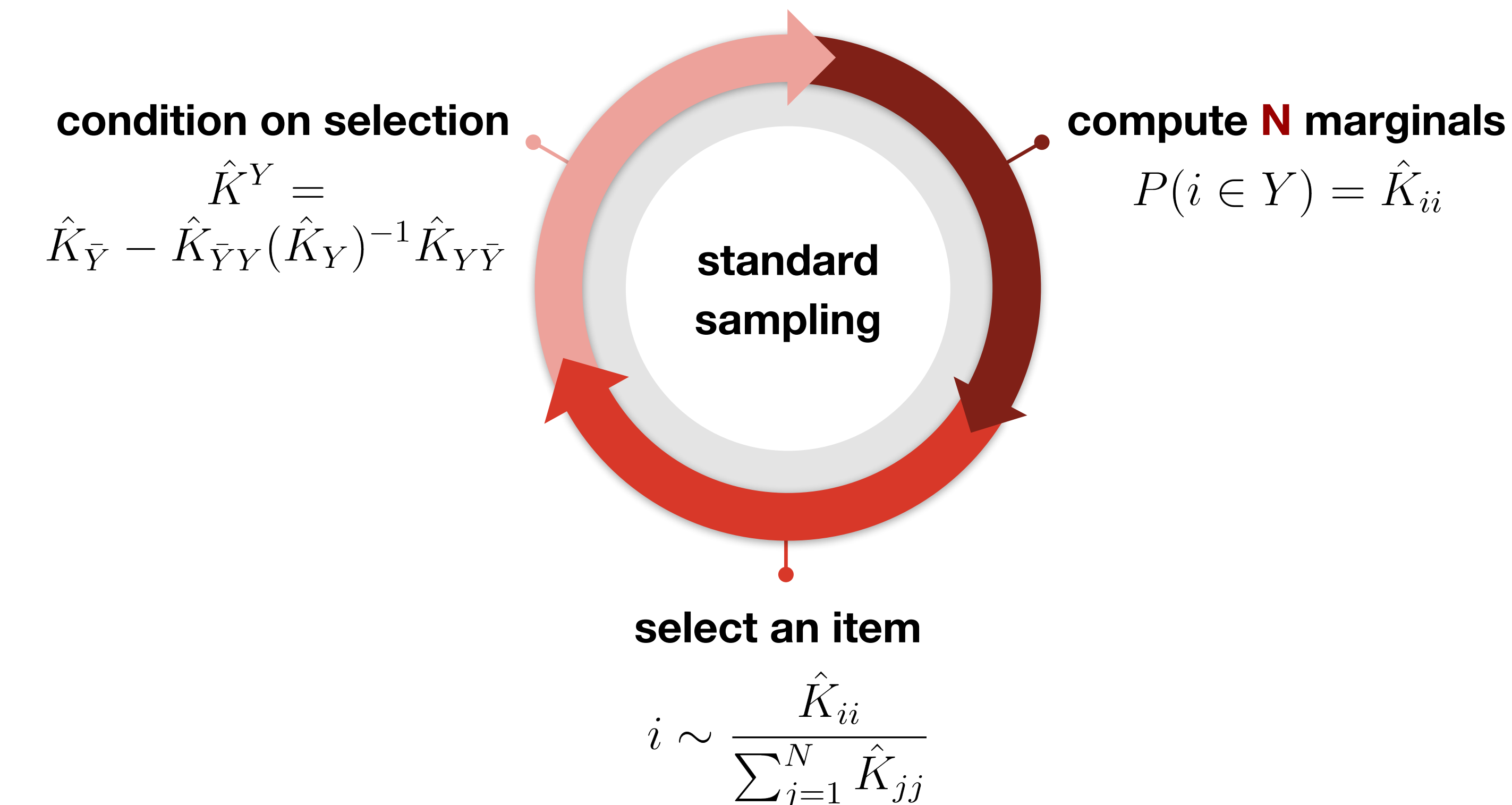
- Goal: For each user, draw a size- $k$  sample from their DPP
- Problem: Existing algorithms for  $k$ -DPP sampling are too expensive
  - $D \ll N$  by construction or random projection
  - $O(ND^2)$  preprocessing on  $L = B^T B$
  - $O(Nk^2 + D^3)$  per personalized ( $W$ -weighted) sample afterwards
- Our contribution: Making repeated, personalized  $k$ -DPP sampling efficient:
  - $O(ND^2)$  preprocessing on  $L = B^T B$
  - $O(D^2 k^2 \log N + D^3)$  per personalized ( $W$ -weighted) sample afterwards

## Standard dual algorithm

- Pre-processing: Build dual kernel  $C = BB^T$ ,  $O(ND^2)$
- Step 1: Personalize and eigendecompose,  $O(D^3)$ 
  - eigendecomposition  $\{\hat{v}_i, \hat{\lambda}_i\}_{i=1}^D$  of  $\hat{C} = WCW$
- Step 2: Select a set  $E$  consisting of  $k$  of the eigenvectors,  $O(Dk)$ ; now marginal probabilities of items are defined as follows:

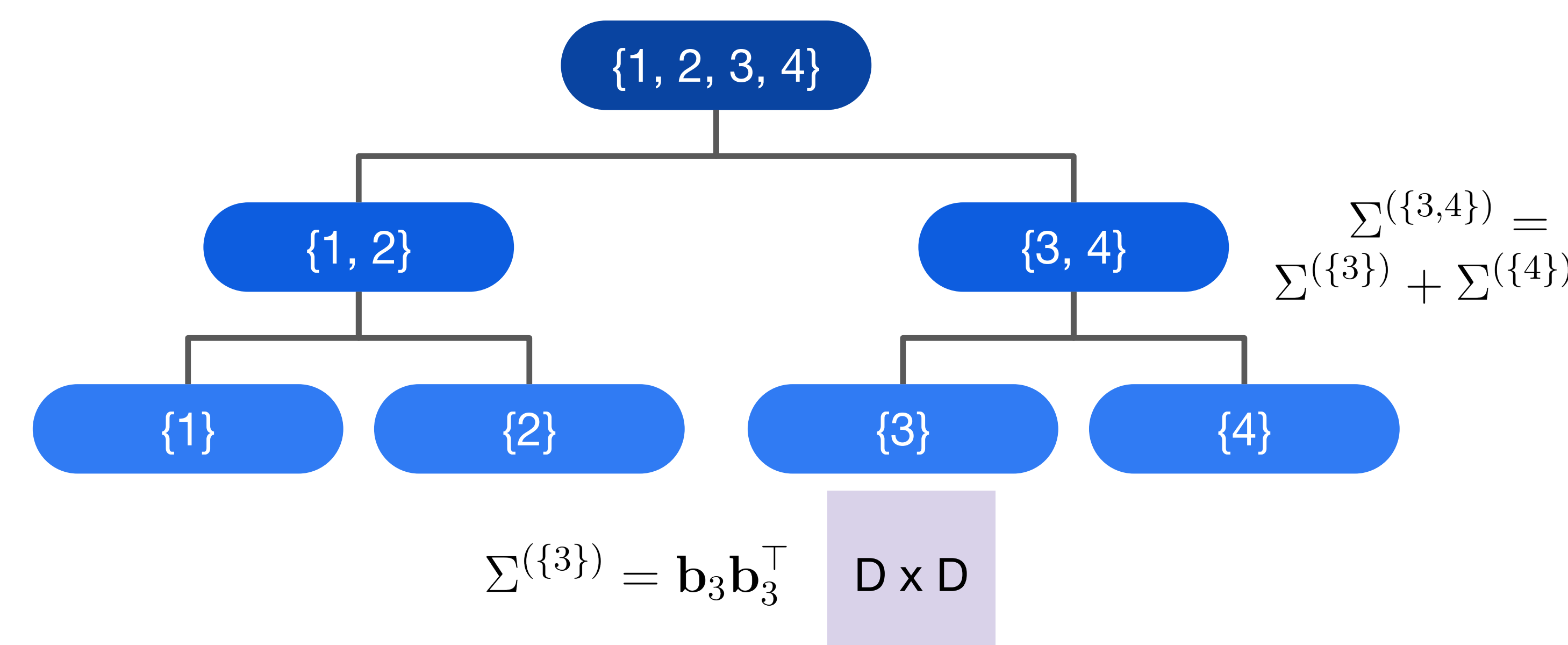
$$\hat{K} = \sum_{i \in E} \frac{1}{\hat{\lambda}_i} (\hat{B}^T \hat{v}_i) (\hat{B}^T \hat{v}_i)^T$$

$$P(i \in Y) = \hat{K}_{ii}$$



## Our tree-based algorithm

Key idea: In pre-processing, create a balanced binary tree of depth  $\log N$ .



Given tree  $T$  and  $C = BB^T$ , sample from  $k$ -DPP with kernel  $\hat{L} = (WB)^T WB$

Add items one at a time, starting from  $Y = \{\}$

Traverse tree once for each item addition:

$$\Pr(S_\ell | Y) = \frac{\sum_{j \in S_\ell} \hat{K}_{jj}^Y}{\sum_{j \in S} \hat{K}_{jj}^Y}$$

$$\sum_{j \in S} \hat{K}_{jj}^Y = \mathbf{1}^T [R \circ \Sigma^{(S)}] \mathbf{1} - \mathbf{1}^T [(\hat{K}_Y)^{-1} \circ (F \Sigma^{(S)} F^T)] \mathbf{1} = f(\Sigma^{(S)}, \hat{\lambda}, \hat{V}, W)$$

where:  $\hat{\Gamma} = (1/\hat{\lambda})$ ,  $M = \hat{V}_{:,E}^T W$ ,  $\hat{H} = \hat{\Gamma}_E M B_{:,Y}$

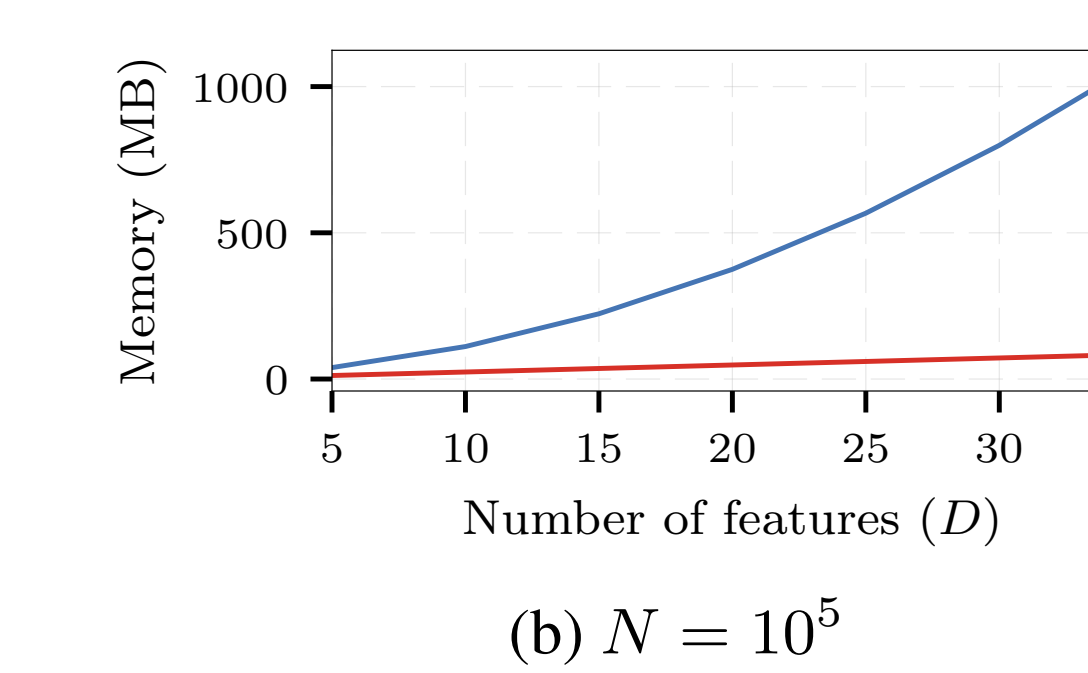
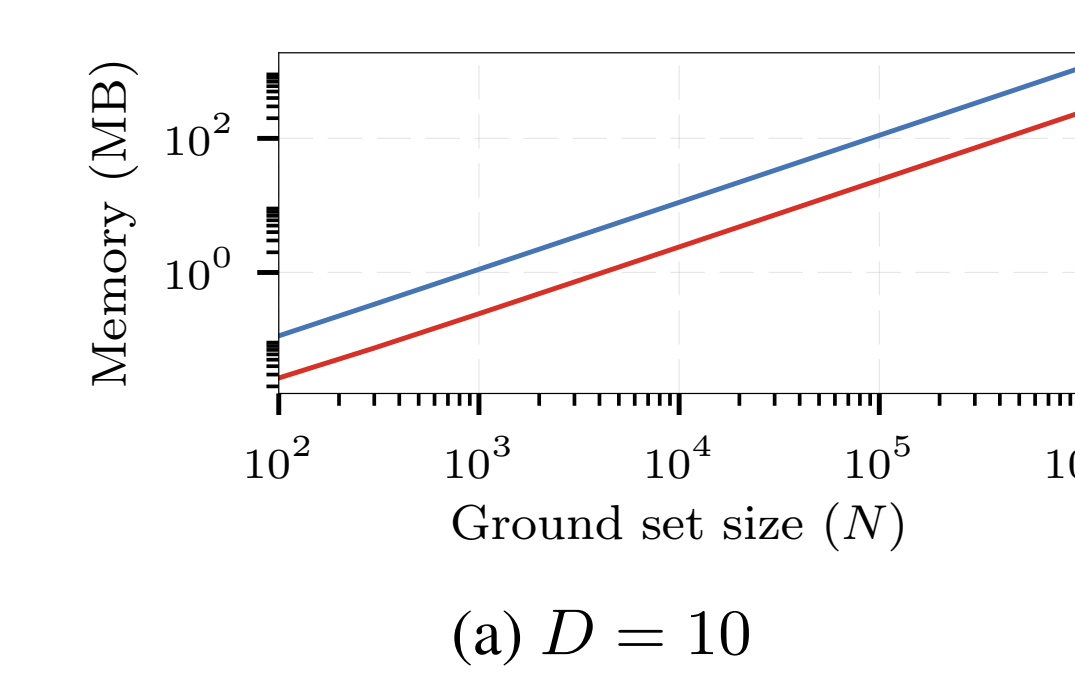
$$R = M^T \hat{\Gamma}_E M, \quad F = \hat{H}^T M$$

Computable in  $O(kD^2)$  time  $\Rightarrow O(kD^2 \log N)$  per tree traversal

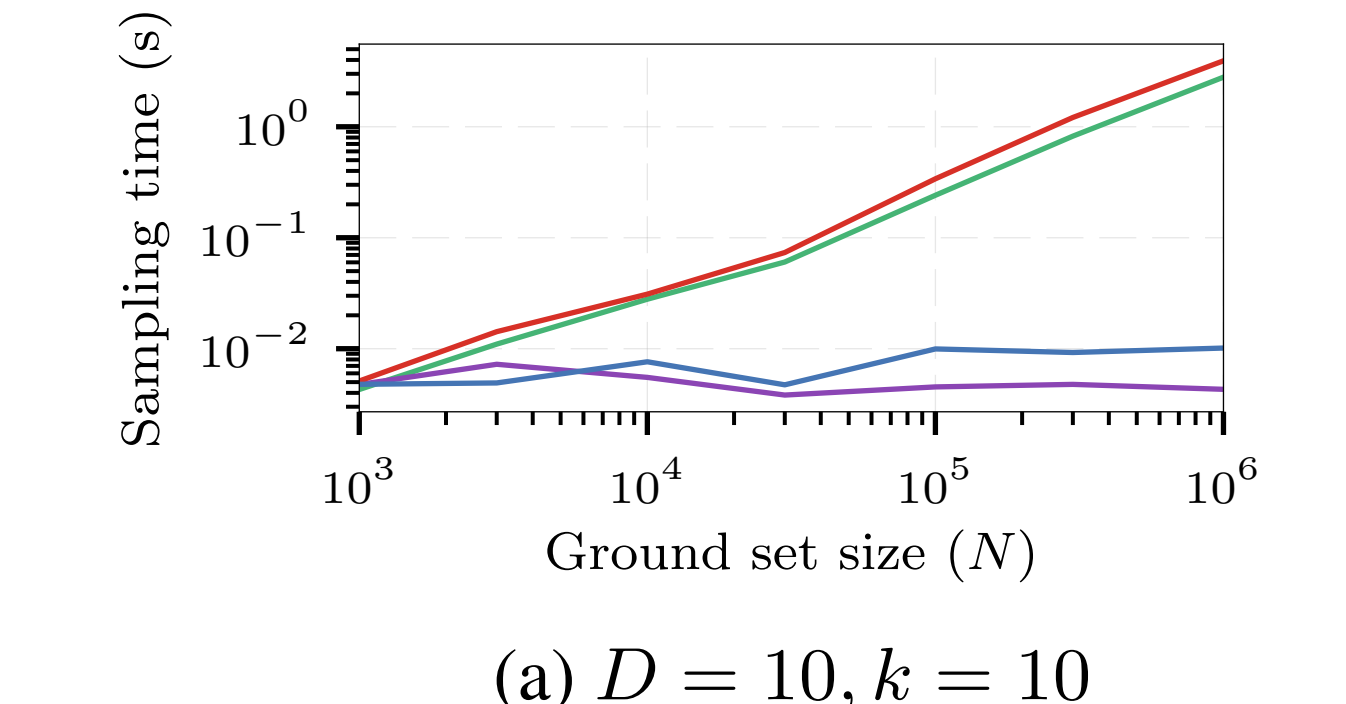
Overall:  $O(k^2 D^2 \log N + D^3)$  time to sample

## Experiments

### Preprocessing:



### Sampling:

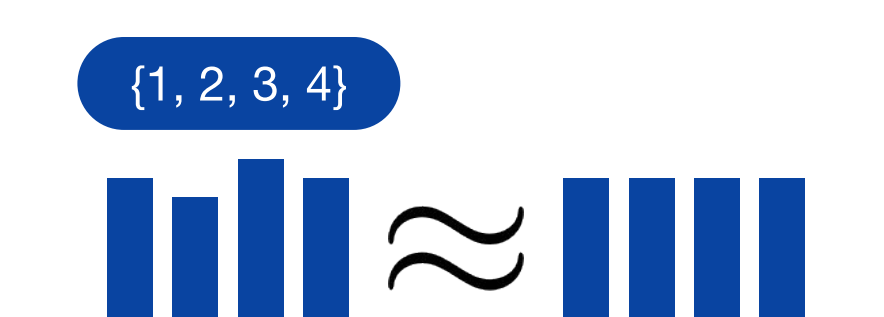


At  $N = 1$  million: standard sampling takes 4 secs; tree-based takes 0.01 secs

Cost: Memory required to store the tree

## Approximation

Main idea: If the distribution over items at a tree node is close to uniform, then don't bother moving further down the tree.



$$D \times D \quad \Sigma_{\ell_1 \ell_2}^{(S)} = \max_{j \in S} \left| \Sigma_{\ell_1 \ell_2}^{(j)} - \frac{1}{|S|} \Sigma_{\ell_1 \ell_2}^{(S)} \right|$$

$\{1, 2, 3, 4\}$

$$\left| \Pr(j | S, Y) - \frac{1}{|S|} \right| \leq \frac{f(\hat{\Sigma}^{(S)}, \hat{\lambda}, \hat{V}, W)}{f(\Sigma^{(S)}, \hat{\lambda}, \hat{V}, W)}$$

$\hat{\Sigma}_{\ell_1 \ell_2}^{\{1,2,3,4\}} = \max \left( \left| \Sigma_{\ell_1 \ell_2}^{\{1\}} - \frac{1}{4} \Sigma_{\ell_1 \ell_2}^{\{1,2,3,4\}} \right|, \left| \Sigma_{\ell_1 \ell_2}^{\{2\}} - \frac{1}{4} \Sigma_{\ell_1 \ell_2}^{\{1,2,3,4\}} \right|, \dots \right)$

Early stopping algorithm: f-ratio  $< \epsilon / |S|$

Sampling  $Y$  in order  $y_1, y_2, \dots, y_k$ :  
 $|(true\ probability) - (probability\ with\ early\ stopping)| \leq (1 + \epsilon)^k - 1$

Idea: Use node-splitting stage of tree construction to increase uniformity

Example: Find distinct items, seed left and right subtrees with these.

